


Moving Charges & Magnetism

→ Ampere's Right hand rule

Thumb indicates direction of current.
Curling fingers indicates direction of magnetic lines.

flow clockwise → ⊗ in
anticlockwise → ⊙ out

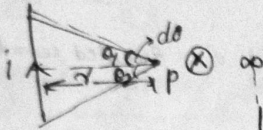
$$\oint \vec{B} \cdot d\vec{l} = \mu_0 (I_1 + I_2 - I_3)$$


→ Biot-Savart's law

$$dB = \frac{\mu_0}{4\pi} \frac{idl \sin \theta}{r^2}$$

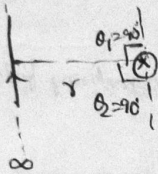
Vector → $\frac{\mu_0}{4\pi} \frac{id\vec{l} \times \vec{r}}{r^3}$

i) for finite wire

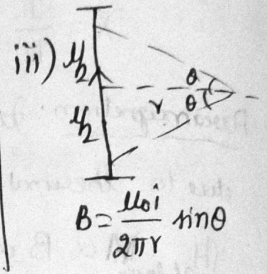


$$B = \frac{\mu_0 i}{4\pi r} (\sin \theta_1 + \sin \theta_2)$$

ii) infinite wire



$$B = \frac{\mu_0 i}{2\pi r}$$



$$B = \frac{\mu_0 i}{2\pi r} \sin \theta$$

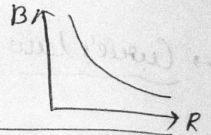
iv) for polygon of 'n' sides

$$B = \frac{\mu_0 i}{\pi L} \sin(\pi/n) \tan(\pi/n)$$

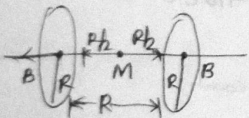
v) for circular coil

$$B = \frac{\mu_0 N i R^2}{2(x^2 + R^2)^{3/2}} \quad N = \text{no. of turns}$$

$$\frac{\mu_0 N i}{2R} = B_{\text{centre}}$$



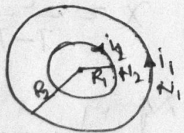
vi) Helm-Holtz coils



$$B_{MP} = \frac{8}{5\sqrt{5}} \frac{\mu_0 N i}{R}$$

$$\frac{B_{\text{axial}}}{B_{\text{central}}} = \left(\frac{R^2}{x^2 + R^2} \right)^{3/2}$$

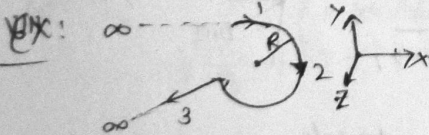
vii) Concentric coils:



$$B_1 = \frac{\mu_0 N_1 i_1}{2R_2} \odot$$

$$B_2 = \frac{\mu_0 N_2 i_2}{2R_1} \otimes$$

$$B_{\text{net}} = B_1 - B_2$$



$$B_1 = \frac{\mu_0 i}{4\pi R} (-\hat{k})$$

$$B_2 = \frac{3\mu_0 i}{8R} (-\hat{k})$$

$$B_3 = \frac{\mu_0 i}{4\pi R} (\hat{j})$$

$$B_1 + B_2 + B_3 = \frac{\mu_0 i}{8\pi R} (2(-\hat{k}) + \hat{j})$$

$$B = \frac{\mu_0 i}{4\pi R} \theta$$

→ force experienced on a moving charge

$$\vec{F}_E = q\vec{E} \quad (\text{particle either at rest or in motion})$$

$$\vec{F}_B = q(\vec{v} \times \vec{B}) \quad (\text{No force on stationary charged particle})$$

$$|\vec{F}_B| = F_B = qvB \sin \theta$$

$$(F_B)_{\text{max}} = qvB \quad (\text{if } \vec{v} \perp \vec{B} \Rightarrow \theta = 90^\circ), \quad F_B = 0 \quad (\text{if } v \neq 0 \text{ then } \vec{v} \parallel \vec{B} \Rightarrow \theta = 0^\circ)$$

pitch = $v_{||} \times T$

Time(T) = $\frac{2\pi m}{qB}$



clockwise flow $\vec{B} \otimes$ inside
anticlockwise flow $\vec{B} \odot$ out

→ when max force acted on particle, it moves in circular path.

$m \frac{v^2}{r} = qvB$, $r = \frac{mv}{qB}$, $r = \frac{p}{qB} = \frac{\sqrt{2mke}}{qB}$

KE = $\frac{B^2 q^2 r^2}{2m}$

Energy per 1 rev of e⁻ in cyclotron
KE = $2\pi V q$

→ Lorentz force (\vec{F}_L) = $\vec{F}_E + \vec{F}_B = q[\vec{E} + (\vec{v} \times \vec{B})]$

Circular coils

B_{axial}

for solenoid

for toroid

$B_{center} = \frac{(R^2)^{3/2}}{(x^2 + R^2)^{3/2}}$

$B = \frac{\mu_0 n I}{2Ba}$

$B = \frac{\mu_0 N I_0}{2\pi a}$

→ Magnetic moment (M) = $iA = \frac{q}{T} A = \frac{q}{T} \pi r^2 = \frac{qV}{2\pi Y} \pi r^2 = \frac{qVr}{2}$

$M_e = \frac{eVr}{2} = \frac{e r^2 \omega}{2}$

→ angular momentum $L = \vec{r} \times \vec{p} = Bq \left(\frac{mv}{Bq} \right)^2$

→ Force (F) = $q(\vec{v} \times \vec{B})$

if $\vec{v} \parallel \vec{B}$ path of e⁻ is st. line

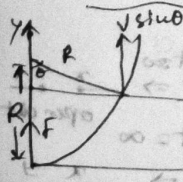
$\vec{v} \perp \vec{B}$ path of e⁻ is circle

\vec{v} inclined to \vec{B} at θ the path is helical.

pitch = $(v \cos \theta) \times T$

eqn of motion

$\vec{v} = v \cos \frac{Bq t}{m} \hat{i} + v \sin \frac{Bq t}{m} \hat{j}$

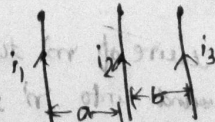


→ Force b/w 2 current carrying conductors

$F = \frac{\mu_0 i_1 i_2 l}{2\pi d}$

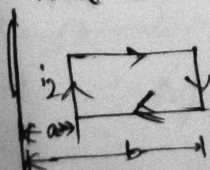
→ Force acts b/w 3 current carrying conductors

$F = \frac{\mu_0 l}{2\pi} \left(\frac{i_1 i_2}{a} - \frac{i_2 i_3}{b} \right)$




→ Force acts b/w a current carrying rectangular loop

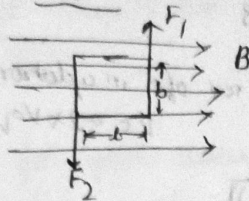
$F = \frac{\mu_0 i_1 i_2 l}{2\pi} \left(\frac{1}{a} - \frac{1}{b} \right)$



→ Force acting on a current carrying wire placed in uniform magnetic field. $F = i(\vec{l} \times \vec{B})$

→ $B = \frac{\mu_0 i}{2R} \left(\frac{\theta}{360} \right)$ 

→ Torque



$$T = B i \sin 90^\circ (b l)$$

$$T = B i A$$

$$T = B A N i = M B$$

$$T = N i \vec{A} \times \vec{B} = \vec{M} \times \vec{B}$$

→ Moving coil galvanometer

$$T = C \theta = M H \sin \theta$$

$$N i B A = C \theta \Rightarrow i = \left(\frac{C}{N B A} \right) \theta$$

$$i = k \theta \Rightarrow i \propto \theta$$

$$\text{sensitivity } (S) = \frac{d\theta}{di} = \frac{N B A}{C}$$

$$di = \left(\frac{C}{N B A} \right) d\theta$$

Tangent galvanometer: $i = k \tan \theta$, $i \propto \tan \theta$

$$di = k \sec^2 \theta d\theta$$

$$K = \frac{2 r B_H}{\mu_0 n}$$

$$S = \frac{d\theta}{di} = \frac{1}{k \sec^2 \theta} = \frac{\mu_0 n \cos^2 \theta}{2 r B_H}$$

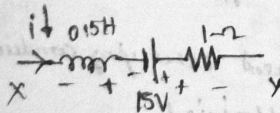
B for solenoid

$$B = \mu_0 n i$$

for toroid

$$B = \mu_0 \frac{n i}{2 \pi r}$$

F.M.T. Battery polarity



$$i = 5A$$

$$\frac{di}{dt} = 10 A/s$$

$$\mathcal{E} = L \frac{di}{dt}$$

$$V_x - V_y = 5 - 15 - 5 = -15V$$

→ If wire of m turn is unwound & rewound into n turn then

Ex: at centre of coil

$$B \propto \frac{\mu_0 m I}{2 R / n} \Rightarrow B_{\text{centre}} \propto \frac{\mu_0 m n I}{2 R}$$

