

AIDS Assignment

04/05

1) What is AI? considering the COVID-19 pandemic situation, how AI helped to survive & renovated our way of life with different applications?

→ AI is a branch of computer science that focuses on creating intelligent systems capable of performing tasks that typically requires human intelligence. AI systems uses techniques such as machine-learning, NLP, etc.

AI can be categorised into:-

1. Narrow AI (Weak AI):-
2. General AI
3. Super AI.

Role in surviving & renovating life during covid.

- i) Healthcare & medical diagnosis.
- CT Scan analysis & x-ray diagnosis helped in rapid detection of COVID cases.
- ii) Virus spread control.
- Social distance monitoring tools helped to monitor & enforce laws in public places
- iii) remote work & education.
- Work from home optimization & AI is online education help people continue with their work.

2. What are AI agents terminology & explain with examples.

- Environment:-
- Everything which surrounds the agent & influences its action. It can be complete or partially observable.

... the ...

... the ...

... the ...

... the ...

... the ...

... the ...

... the ...

... the ...

... the ...

... the ...

Initial State :-	1	2	3	Goal State :-	1	2	3
	5	6	0		4	5	6
	4	7	8		7	8	0

- compute heuristic of each possible move.
- expand the state with the lowest (cn) & repeat

4. What is PEAS description? give PEAS description for following?

→ Performance Measure :- How success of agent is evaluated

Environment :- Surrounding in which agent operates.

Actuators :- Component that allows agent to take actions

Sensors :- Component that allows agent to perceive the environment

i) Taxi driver agent :-

performance measure	Environment	Actuators	Sensors
- safe driving	- Traffic Signal	- Steering wheel	- camera
- travel time	- roads	- accelerator	- GPS
- traffic rules	- weather	- brakes	- fuel gauge

ii) Medical Diagnostic Agents :-

perf. measure	Environment	Actuator	sensors
- health of patient	- patient data	display screen	- heart rate monitor
- accuracy of diagnosis	- symptoms	alarm system	
- recommended treatment	- test reports	robotic arms	- lab results

iii) Music component Agent :-

perf. measure	Environment	Actuator	Sensors
- originality	- music db	- Speaker	- microphones
- listener enjoyment	- user preferences	- digital music interface	- user feedback
- quality			- recognition sw.

iv) Aircraft autolander.

Perf. measure	Environment	Actuator	Sensors
- Smooth landing	- runway	- landing gear	- altimeter
- accuracy in touchdown	- wind condition	- flap	- GPS
	- air traffic	- air brakes	- camera

v) Essay evaluator.

Perf. measure	Environment	Actuator	Sensors
- grading	- plagiarism database	- display	- optical
- grammar	- rubric criteria	Screen	Character
- paradigm check		- text to speech system	recognition (OCR).

vi) Robotic sentry gun.

Perf. measure	Environment	Actuators	Sensors
- neutralize threats	- lab area	- gun mech	- camera
- target tracking	- potential intruders	anism.	- thermal
- false alarms		- alarm siren	Sensors.
		- tracking system	

5. Categorize a shopping bot for a shopping bot for an offline bookstore according to the following system.

- - observability: Partially observable. Relies on limited sensors input.
- Deterministic or stochastic: Stochastic: Customer pref. is unpredictable
- Episodic v/s sequential: Sequential decisions affect future actions.
- static v/s dynamic: Dynamic, customer behaviour is always evolving
- Discrete v/s continuous: Finite no. of choices such as books

6. Differentiate between model based & utility based agent.

- | | |
|---------------------|---------------------|
| → model based Agent | utility based Agent |
|---------------------|---------------------|
- Agent that maintains the internal model of the env based on the utility function to understand its current aiming to maximize long term state & predict future state satisfaction or benefit
 - model updates its information. measures how desirable about the environment different states are.
 - less complex.
 - more complex.
 - Doesn't concern long term reward
 - e.g. self driving cars.
 - e.g. shopping recommendation system

7. Explain the architecture of knowledge based agent & learning agent.

- - knowledge based agent: stores knowledge & reasons based on logical inference
- knowledge base: stores facts, rules & heuristic function about the environment
- inference engine: uses logical reasoning techniques like forward & backward chaining.
- perception: gathers data from the environment
- actions: executes actions based on internal knowledge.
- knowledge update mechanism: updates itself as new facts are learned.

- learning Based agents:- agent that improves
perf. overtime by learning from experience, data
& feedback.

- learning element:- responsible for improving
improving agents perf by analyzing past experience
using ml techniques.
- critic:- provides feedback on agents actions
by evaluating success or failure
- problem generation:- supports new experiences for
learning & explanation.

1. Convert the following to predicates.
→

Anita travels by car if available otherwise
travels by bus.

travels(*xy*) → person *x* travels by *y*.
Available(*xy*) → *yca* vehicle is available
goes via(*xy*) → vehicle goes via *x*.
puncture(*xy*) → *yca* vehicle.

available(car) → Travels(*Anita*, bus).

b. Bus goes via andheri & Goregaon.
goes via(*bus*, andheri)
goes via(*bus*, Goregaon).

c. Car has a puncture, so it's not available.
puncture(car)
~ available(car).

10. What do you mean by depth limit search? Explain iterative Deepening search with example Depth limit search(DLS):-

DLS is a DFS variant with a fixed depth L. Preventing infinite loop & saving memory.

Advantages:-

- 1) Avoids infinite recursion.
- 2) Memory efficient.

Disadvantages:-

- 1) May miss less deeper solutions.
- 2) Need for good L choice (Limit).

Iterative Deepening search (IDS):-

IDS runs DLS repeatedly, increasing L until the goal is found.

Advantages:-

- 1) Completes the whole search.
- 2) Gives most optimized answer.
- 3) Memory efficient.

Disadvantages:-

- 1) Redundant computation.
- 2) Higher time cost.

example:- Searches level by level until the goal appears.

- 110) Explain hill climbing & its drawback in detail with example. Also state limitations of steepest ascent hill climbing.
- Algorithm
- It is an optimization problem that moves towards higher values (better solution) until a peak (local optimum) is reached.

Algorithm:-

1. Start with an initial state.
2. Move to the best neighbouring state.
3. Repeat until no strictly better neighbour exists.

Example:- 8-Queens problem:-

- Adjust queen's position to minimize conflicts.
- Stop when no improvements are possible.

Drawbacks:-

- Local maxima:- stuck at suboptimal points.
- Plateau:- no directions for improvement.
- Ridge:- needs special move to progress.
- Variational solution:-
- Steepest Ascent:- Evaluates all neighbours but still get stuck.

12)

- Explain simulated annealing & write its example.
- It improves hill climbing by accepting occasionally bad moves to escape local maxima, inspired by metal annealing.

Algorithm:-

1. Start with an initial solution & Temperature T .

2. pick a random neighbour s , compute ΔE .
3. Accept s is better; otherwise with probability $P = e^{-\Delta E / T}$

4. Reduce T until stopping condition.

Advantages:-

- 1) Escapes local minima.
- 2) Handles large problems
- 3) Near-optimal solutions

Disadvantages:-

- 1) Tricky cooling schedule.
- 2) No guarantee of best solution.

- 12) Explain A* algorithm with an example.

A* is a best-first search algorithm for path finding combining:

- 1) Uniform cost search (cheapest path).

- 2) Greedy best-first search (heuristic-based speed)

Key-formulae:-

$$f(n) = g(n) + h(n).$$

$g(n)$: cost from start to n .

$h(n)$: cost from n to goal. (estimated)

Steps:-

1. Start with the initial node, compute $f(n)$.
2. Expand the node with lowest $f(n)$.
3. If goal is reached, return the path; else, update & continue.

Advantages:-

- 1) Optimal paths.
- 2) Efficient in AI applications

Disadvantages:-

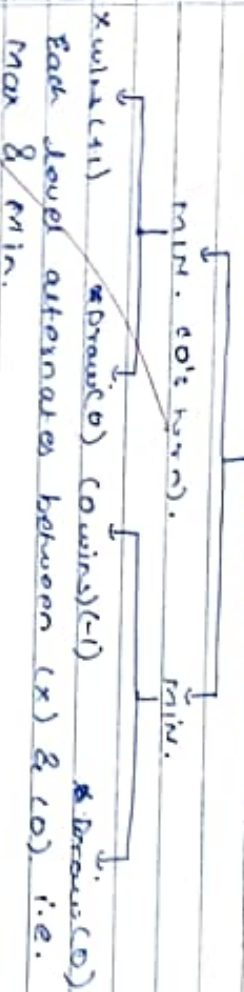
- 1) High memory usage.
- 2) Depends on heuristic.

4) Explain minimax algorithm & draw game tree for tic-tac-toe game.

Minimax is a game strategy for 2 player games like tic-tac-toe.

How it works?

- $\text{maximize}(x)$ aims to increase the score (+1 for win).
- $\text{minimize}(o)$ aims for lowest score (-1 for loss).
- Explore all possible moves, assign score & picking the best one.
- Game tree: $\text{max}(x\text{'s turn})$.



Advantage:-

- 1) Always finds the best moves

Disadvantage:-

- 1) Slow for deep tree (Alpha-beta pruning helps).

5) Explain alpha beta pruning for adversarial search.

Alpha Beta pruning optimizes the minimax algorithm by skipping unnecessary branches, making it faster without affecting the result.

Explanation:-

- 1) Alpha (o):- Best max value found so far.

1) Beta(P): Best min value found so far

2) If a move worse than α or β is found then the further exploration is stopped (pruned).

Example (simplified game tree):-



Here, if min finds move worse than 5, it stops exploring that branch

Advantages:-

1) speeds up minimax by ignoring bad choices.

2) Same result as minimax but faster

5) Explain Wumpus world environment giving its PEAS description. Explain how percept sequence is generated?

Wumpus world is a grid based game environment where an agent navigates a cave to find gold while avoiding pits & the wumpus monster.

PEAS description:-

P (performance measure):- +1000 (Gold), -1000 (wumpus), -1000 (pit), -1 (move)

E (environment):- Grid world with Wumpus, Gold, Pits & Agents.

A (actuators):- Move, Grab (Gold), Shoot (Arrow), Climb.

S (sensors):- a) Breeze (near pit) b) Stench (near wumpus) c) Glitter (near Gold)

Percept sequence generation:-

The agent receives sensory input at each step based on its current location

2. Example:- If agent move next to pit, it perceive Breeze.
3. Using percept history it infer safe path & avoid danger.

(7)

Solve the following crypto arithmetic problem.

1. ~~SEND~~ SEND + MORE = MONEY.

Each letter represents a unique digit (0-9).

Step 1:- Evaluation setup

$$(1000S) + (100E) + (10M) + D + (1000M + 100O + 10R + E) = (10000M + 1000O + 100N + 10E + Y)$$

Step 2:- Constraints.

- $m \neq 1$. (since money is a 5 digit number)
- $S \neq 0$ (It's the first digit in SEND).
- All letters have unique values.

Step 3:- Assigning digits.

Letters	Digits
S	9
E	5
M	6
D	7
N	1
O	0
R	8
Y	2

19)

Consider the following axioms.

All people who are graduating are happy.
All happy people are smiling.
Someone is graduating.

Explain the following:-

- 1) Represent these axioms in first order predicate
- 2) Convert each formula to clause form
- 3) Prove that "is someone smiling?" using resolution technique. Draw the resolution tree

1) FOL :-

Let $G(x) \rightarrow x$ is graduating, $H(x) \rightarrow x$ is happy, $S(x) \rightarrow x$ is smiling.

Axioms :- 1. $\forall x (G(x) \rightarrow H(x))$

2. $\forall x (H(x) \rightarrow S(x))$

3. $\exists x G(x)$

2. Convert to clause form

1. $\neg G(x) \vee H(x)$

2. $\neg H(x) \vee S(x)$

3. $G(x)$ set x be a person graduating

3. prove "is someone smiling?"

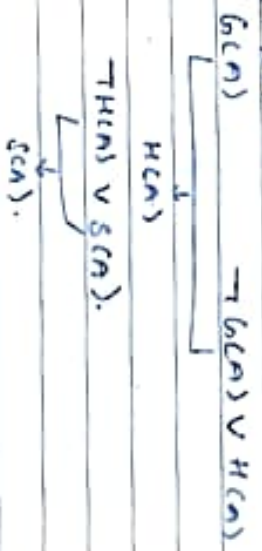
1. $G(x)$ given

2. $\neg G(x) \vee H(x) \rightarrow$ axiom 1

3. $\neg H(x) \vee S(x) \rightarrow$ axiom 2

Since we derived $S(x)$, the proof confirms that someone is smiling.

Resolution tree:-



20) Explain Modus Ponens with suitable example.

Modus ponens is a fundamental rule of inference in logic. It states:

If $P \rightarrow Q$ (if P , then Q) is true.

& P is true, then Q must be true.

Symbolically:-

$P \rightarrow Q, P \vdash Q$

Example:-

1) If it rains, ground will be wet.

2) It is raining. (P)

3) Therefore, the ground is wet. (Q).

This rule is widely used in mathematical proofs & AI reasoning systems.

2.10) Explain Forward & Backward chaining with an example.

→ These are inference techniques used in rule-based systems & AI reasoning.

1. Forward chaining (Data-Driven):-

Starts with known facts & applies rules to infer new facts until the goal is reached.

Example:-
Masks from cause \rightarrow effect (bottom-up approach).

1. If it is raining then the ground is wet ($R \rightarrow W$)

2. If ground is wet then traffic is slow ($W \rightarrow T$)

2. Backward chaining (Goal driven).

P starts with the goal & goes backwards to find supporting facts.

• Works from effect to cause. (top-down approach).

Example:-
 $W \rightarrow T$: Is the ground wet?

$P \rightarrow W$:- Is it raining? ✓