

Dr. D. Y. Patil Unitech Society
Dr. D. Y. Patil Science & Computer Science College,
Akurdi, Pune - 411 044

DEPARTMENT OF ELECTRONICS

Name : Patil Sudeep Shantaram.			REMARKS
Class : sybcs	Roll No. :	Batch :	
Experiment No. :	Performed Date : / /20		
Title of Experiment : digital to analog converter to 8051 microcontroller.			

Aim :- to study how to interface DAC to 8051 microcontroller.

Software :- Keil, Flash magic.

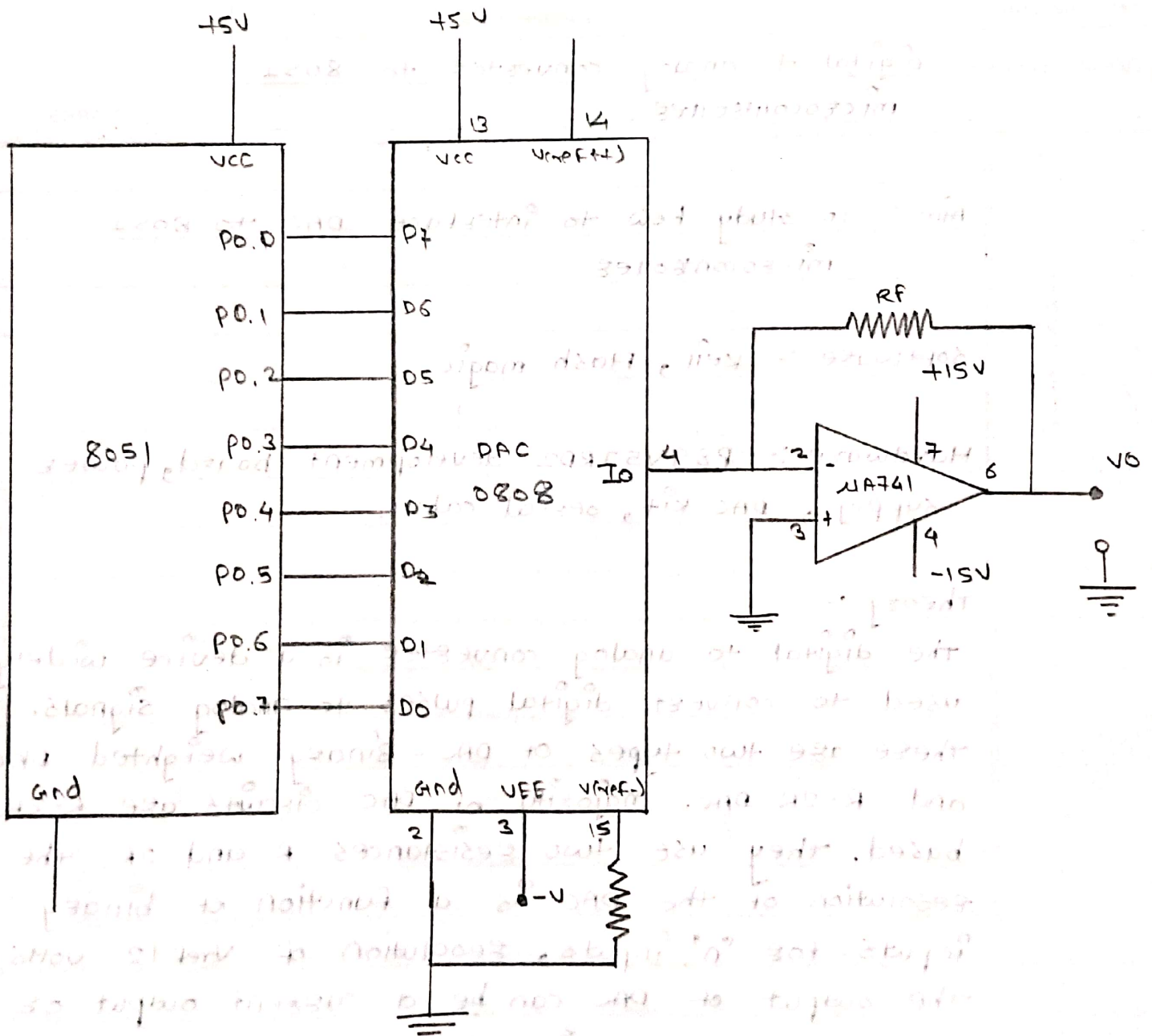
Hardware :- P89V51RD2 development board, power supply, DAC kit, serial cable.

Theory :-

The digital to analog converter is a device widely used to convert digital pulses to analog signals. There are two types of DAC - Binary weighted DAC and R-2R DAC. Majority of DAC circuits are R-2R based. They use two resistances R and 2R. The resolution of the DAC is a function of binary inputs. For 'n' inputs, resolution of $V_{ref}/2$ volts. The output of DAC can be a current output or voltage output. By using I to V converter a current output can be converted to the corresponding voltage output.

In DAC0808, the digital inputs are converted

Block Diagram :-

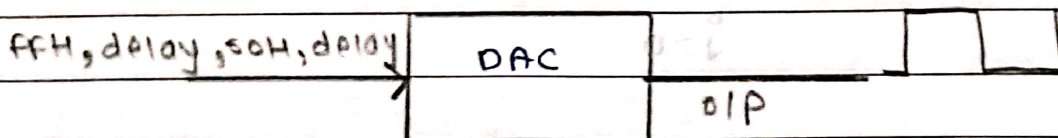
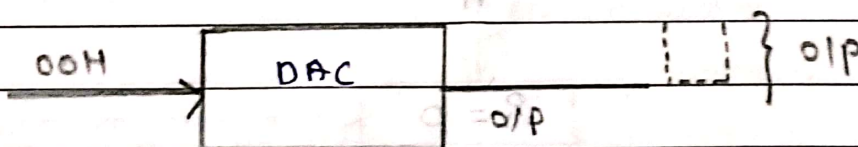
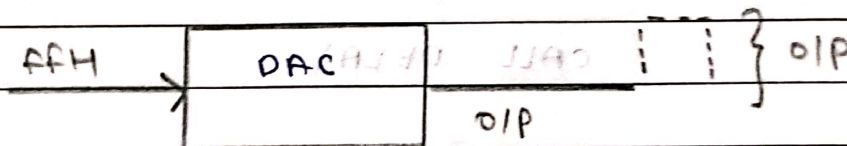


to current (I_0), and by connecting a resistor to the I_0 pin, it can be converted into voltage. For an 8-bit R-2R network providing current outputs the analog current I_0 is given by,

$$I_0 = I_{ref} [D_7/2 + D_6/4 + D_5/8 + D_4/16 + D_3/32 + D_2/64 + D_1/128 + D_0/256]$$

where D_7 to D_0 represent digital data, I_{ref} is the reference current.

To generate square wave, send FF to port 1 give some delay, then send 00 to port 1 and repeat the process after some delay.



observation table :-

T_{ON}	T_{OFF}	λ	t	T	frequency
2	3	5	10ms	50ms	20 Hz

Flowchart :-

Start

Initialize port 0

PO = FFH

CALL DELAY

PO = 00H

CALL DELAY

A

i = 0

j = 0

j++

i is
j < 100

yes

i++

i is
i < MS

yes

RET

PAC program :-

```
#include <reg51.h>
```

```
void delay_ms(unsigned int);
```

```
void main(void)
```

```
{
```

```
    P0 = 0xFF;
```

```
    while (1)
```

```
    {
```

```
        P0 = 0xFF;
```

```
        delay_ms(10);
```

```
        P0 = 0x00;
```

```
        delay_ms(10);
```

```
    }
```

```
}
```

```
void delay_ms(unsigned int ms)
```

```
{
```

```
    unsigned int i, j;
```

```
    for(i=0; i<ms; i++)
```

```
    {
```

```
        for(j=0; j<0x100; j++);
```

```
    }
```

```
}
```

Result :-

$$T = 50 \text{ ms}$$

$$f = \frac{1}{T} = \frac{1}{50 \text{ ms}}$$

$$= 0.02 \times 10^3$$

$$= 20 \text{ Hz}$$

conclusion :-

- 1] we have studied and executed program for DAC.
- 2] By using DAC, we can generate different types of waveform such as square, triangle and sine wave.
- 3] we can vary the period of sequence wave using control delay.