

Derivation of Backpropagation in Convolutional Neural Network (CNN)

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Abstract— Derivation of backpropagation in convolutional neural network (CNN) is conducted based on an example with two convolutional layers. The step-by-step derivation is helpful for beginners. First, the feedforward procedure is claimed, and then the backpropagation is derived based on the example.

1 Feedforward

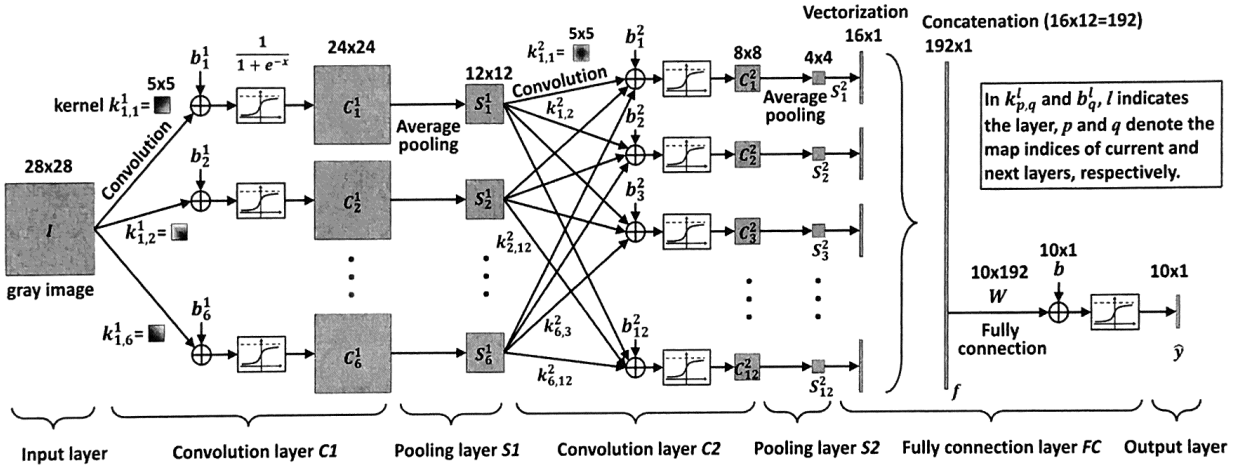


Figure 1: The structure of CNN example that will be discussed in this paper. It is exactly the same to the structure used in the demo of Matlab DeepLearnToolbox [1]. All later derivation will use the same notations in this figure.

1.1 Initialization of Parameters

The parameters are:

- **C1 layer**, $k_{1,p}^1$ (size 5×5) and b_p^1 (size 1×1), $p = 1, 2, \dots, 6$
- **C2 layer**, $k_{2,q}^2$ (size 5×5) and b_q^2 (size 1×1), $q = 1, 2, \dots, 12$
- **FC layer**, W (size 10×192) and b (size 10×1)

All bias, b_p^1 , b_q^2 , and b , are initialize to zero. The others are drew randomly from a uniform distribution defined based on the kernel size and number of input and output maps on corresponding layers [2] (see section 4.6 of [2]).

$$k_{1,p}^1 \sim U\left(\pm\sqrt{\frac{6}{(1+6) \times 5^2}}\right) \quad \checkmark \quad (1)$$

$$k_{p,q}^2 \sim U\left(\pm\sqrt{\frac{6}{(6+12) \times 5^2}}\right) \quad \checkmark \quad (2)$$

$$W \sim U\left(\pm\sqrt{\frac{6}{192+10}}\right) \quad \checkmark \quad (3)$$

where $U(\pm x)$ denotes a uniform distribution with upper and lower bounds of $\pm x$. Totally, the number of parameters is $(5 \times 5 + 1) \times 6 + (5 \times 5 \times 6 + 1) \times 12 + 10 \times 192 + 10 = 3898$.

1.2 Convolution Layer C1

$$C_p^1 = \sigma(I * k_{1,p}^1 + b_p^1), \text{ where } \sigma(x) = \frac{1}{1 + \exp^{-x}} \quad (4)$$

$$C_p^1(i, j) = \sigma\left(\sum_{u=-2}^2 \sum_{v=-2}^2 I(i-u, j-v) \cdot k_{1,p}^1(u, v) + b_p^1\right) \quad (5)$$

where $p = 1, 2, \dots, 6$ because there are 6 feature maps on C1 layer, $*$ denotes the convolution, and i, j are row and column indices of the feature map. Only keeping those parts of the convolution that are computed without the zero-padded edges, the size of C_p^1 is 24×24 , rather than 28×28 like I .

1.3 Pooling Layer S1

$$S_p^1(i, j) = \frac{1}{4} \sum_{u=0}^1 \sum_{v=0}^1 C_p^1(2i-u, 2j-v), \quad i, j = 1, 2, \dots, 12 \quad (6)$$

1.4 Convolution Layer C2

$$C_q^2 = \sigma\left(\sum_{p=1}^6 S_p^1 * k_{p,q}^2 + b_q^2\right) \quad (7)$$

$$C_q^2(i, j) = \sigma\left(\sum_{p=1}^6 \sum_{u=-2}^2 \sum_{v=-2}^2 S_p^1(i-u, j-v) \cdot k_{p,q}^2(u, v) + b_q^2\right) \quad (8)$$

where $q = 1, 2, \dots, 12$ because there are 12 feature maps on C2 layer. Only keeping those parts of the convolution that are computed without the zero-padded edges, the size of C_q^2 is 8×8 , rather than 12×12 like S_p^1 .

1.5 Pooling Layer S2

$$S_q^2(i, j) = \frac{1}{4} \sum_{u=0}^1 \sum_{v=0}^1 C_q^2(2i-u, 2j-v), \quad i, j = 1, 2, \dots, 4 \quad (9)$$

1.6 Vectorization and Concatenation

Each S_q^2 is a 4×4 matrix, and there are 12 such matrices on the S2 layer. First, each S_q^2 is vectorized by column scan, then all 12 vectors are concatenated to form a long vector with the length of $4 \times 4 \times 12 = 192$. We denote this process by

$$f = F(\{S_q^2\}_{q=1,2,\dots,12}), \quad (10)$$

and the reverse process is

$$\{S_q^2\}_{q=1,2,\dots,12} = F^{-1}(f). \quad (11)$$

1.7 Fully Connection Layer FC

$$\hat{y} = \sigma(W \times f + b) \quad (12)$$

1.8 Loss Function

Assuming the true label is y , the loss function is express by

$$L = \frac{1}{2} \sum_{i=1}^{10} (\hat{y}(i) - y(i))^2 \quad (13)$$

2 Backpropagation

In the backpropagation, we'll update the parameters from the back to start, namely W and b , $k_{p,q}^2$ and b_q^2 , $k_{1,p}^1$ and b_p^1 .

2.1 ΔW (size 10×192)

$$\Delta W(i, j) = \frac{\partial L}{\partial W(i, j)} \quad (14)$$

$$= \frac{\partial L}{\partial \hat{y}(i)} \cdot \frac{\partial \hat{y}(i)}{\partial W(i, j)} \quad (15)$$

$$= (\hat{y}(i) - y(i)) \cdot \frac{\partial}{\partial W(i, j)} \sigma \left(\sum_{j=1}^{192} W(i, j) \times f(j) + b(i) \right) \quad (16)$$

$$= (\hat{y}(i) - y(i)) \cdot \hat{y}(i)(1 - \hat{y}(i)) \cdot f(j) \quad (17) \quad \checkmark$$

Let $\Delta \hat{y}(i) = (\hat{y}(i) - y(i)) \cdot \hat{y}(i)(1 - \hat{y}(i))$, whose size is 10×1 , then

$$\Delta W(i, j) = \Delta \hat{y}(i) \cdot f(j) \quad (18)$$

$$\implies \Delta W = \Delta \hat{y} \times f^T \quad (19)$$

2.2 Δb (size 10×1)

$$\Delta b(i) = \frac{\partial L}{\partial b(i)} \quad (20)$$

$$= \frac{\partial L}{\partial \hat{y}(i)} \cdot \frac{\partial \hat{y}(i)}{\partial b(i)} \quad (21)$$

$$= (\hat{y}(i) - y(i)) \cdot \frac{\partial}{\partial b(i)} \sigma \left(\sum_{j=1}^{192} W(i, j) \times f(j) + b(i) \right) \quad (22)$$

$$= (\hat{y}(i) - y(i)) \cdot \hat{y}(i)(1 - \hat{y}(i)) \quad (23)$$

$$\Rightarrow \Delta b = \Delta \hat{y} \quad (24)$$

2.3 $\Delta k_{p,q}^2$ (size 5×5)

Because of concatenation, vectorization, and pooling, we need to compute the back-propagation error ΔC_q^2 on C2 layer before calculating $\Delta k_{p,q}^2$.

$$\Delta f(j) = \frac{\partial L}{\partial f} \quad (25)$$

$$= \sum_{i=1}^{10} \frac{\partial L}{\partial \hat{y}(i)} \cdot \frac{\partial \hat{y}(i)}{\partial f(j)} \quad (26)$$

$$= (\hat{y}(i) - y(i)) \cdot \frac{\partial}{\partial f(j)} \sigma \left(\sum_{j=1}^{192} W(i, j) \times f(j) + b(i) \right) \quad (27)$$

$$= \sum_{i=1}^{10} (\hat{y}(i) - y(i)) \cdot \hat{y}(i)(1 - \hat{y}(i)) \cdot W(i, j) \quad (28)$$

$$= \sum_{i=1}^{10} \Delta \hat{y}(i) \cdot W(i, j) \quad \Rightarrow \Delta f = W^T \times \Delta \hat{y}$$

Handwritten notes: $\Delta f = \begin{bmatrix} \Delta f(1) \\ \vdots \\ \Delta f(192) \end{bmatrix} = \begin{bmatrix} W_{j1} \Delta y_1 + W_{j2} \Delta y_2 + \dots + W_{j10} \Delta y_{10} \\ \vdots \\ W_{n1} \Delta y_1 + W_{n2} \Delta y_2 + \dots + W_{n10} \Delta y_{10} \end{bmatrix} = W^T \cdot \Delta y$ (30) ✓

From section 1.6, we reshape the long error vector Δf (size 192×1) by $\Delta S_q^2 = F^{-1}(\Delta f)$, \checkmark

which gets the error on S2 layer (twelve 4×4 error maps). Because there is no parameters on S2 layer, we do not need to do any derivative stuff. Then, upsampling is performed to obtain the error on C2 layer.

$$\Delta C_q^2(i, j) = \frac{1}{4} \Delta S_q^2(\lceil i/2 \rceil, \lceil j/2 \rceil), \quad i, j = 1, 2, \dots, 8 \quad (32)$$

in my cnn: $8 \times 8 \xrightarrow{\text{upsampling}} 16 \times 16$

floor?

where $\lceil \cdot \rceil$ denotes the ceiling function. Note that the size of ΔS_q^2 and ΔC_q^2 are 4×4 and 8×8 , respectively. Now, we are ready to derive $\Delta k_{p,q}^2$.

$$\Delta k_{p,q}^2(u, v) = \frac{\partial L}{\partial k_{p,q}^2(u, v)} \quad (33)$$

$$= \sum_{i=1}^8 \sum_{j=1}^8 \frac{\partial L}{\partial C_q^2(i, j)} \cdot \frac{\partial C_q^2(i, j)}{\partial k_{p,q}^2(u, v)} \quad (34)$$

$$= \sum_{i=1}^8 \sum_{j=1}^8 \Delta C_q^2(i, j) \cdot \frac{\partial}{\partial k_{p,q}^2(u, v)} \sigma \left(\sum_{p=1}^6 \sum_{u=-2}^2 \sum_{v=-2}^2 S_p^1(i-u, j-v) \cdot k_{p,q}^2(u, v) + b_q^2 \right) \quad (35)$$

$$= \sum_{i=1}^8 \sum_{j=1}^8 \Delta C_q^2(i, j) \cdot C_q^2(i, j) (1 - C_q^2(i, j)) \cdot S_p^1(i-u, j-v) \quad (36)$$

Let

$$\Delta C_{q,\sigma}^2(i, j) = \Delta C_q^2(i, j) \cdot C_q^2(i, j) (1 - C_q^2(i, j)), \quad (37)$$

which is actually the error before sigmoid function on C2 layer. Therefore,

$$C_{q,\sigma}^2(i, j) = \sum_{p=1}^6 \sum_{u=-2}^2 \sum_{v=-2}^2 S_p^1(i-u, j-v) \cdot k_{p,q}^2(u, v) + b_q^2 \quad (38)$$

Rotating S_p^1 180 degrees, we get $S_{p,rot180}^1$, thus $S_{p,rot180}^1(u-i, v-j) = S_p^1(i-u, j-v)$. Therefore, $\Delta k_{p,q}^2$ can be expressed by

$$\Delta k_{p,q}^2(u, v) = \sum_{i=1}^8 \sum_{j=1}^8 S_{p,rot180}^1(u-i, v-j) \cdot \Delta C_{q,\sigma}^2(i, j) \quad (39)$$

$$\Rightarrow \Delta k_{p,q}^2 = S_{p,rot180}^1 * \Delta C_{q,\sigma}^2 \quad \text{see equation (5) for definition of convolution} \quad (40)$$

2.4 Δb_q^2 (size 1×1) $\Delta C_{q,\sigma}^2$: d_l2_output_before_activation, shape = (12, 16, 16)

$$\Delta b_q^2 = \frac{\partial L}{\partial b_q^2} \quad (41)$$

$$= \sum_{i=1}^8 \sum_{j=1}^8 \frac{\partial L}{\partial C_q^2(i, j)} \cdot \frac{\partial C_q^2(i, j)}{\partial b_q^2} \quad (42)$$

$$= \sum_{i=1}^8 \sum_{j=1}^8 \Delta C_q^2(i, j) \cdot \frac{\partial}{\partial b_q^2} \sigma \left(\sum_{p=1}^6 \sum_{u=-2}^2 \sum_{v=-2}^2 S_p^1(i-u, j-v) \cdot k_{p,q}^2(u, v) + b_q^2 \right) \quad (43)$$

$$= \sum_{i=1}^8 \sum_{j=1}^8 \Delta C_q^2(i, j) \cdot C_q^2(i, j) (1 - C_q^2(i, j)) \quad (44)$$

$$= \sum_{i=1}^8 \sum_{j=1}^8 \Delta C_{q,\sigma}^2(i, j) \quad q=1, 2, \dots, 12 \quad (45) \quad \checkmark$$

2.5 $\Delta k_{1,p}^1$ (size 5×5)

Similar to the derivation of $\Delta k_{p,q}^2$, we should first obtain ΔS_p^1 , the error on S1 layer. Then, upsampling will be performed to get ΔC_p^1 , the error on C1 layer. Finally, following the same

way, we can calculate $\Delta k_{1,p}^1$.

$$\Delta S_p^1(i, j) = \frac{\partial L}{\partial S_p^1(i, j)} \quad \text{size } 5 \times 5 \quad \begin{matrix} \bar{j}-2 & \bar{j} & \bar{j}+2 \\ \bar{i}-2 & \bar{i} & \bar{i}+2 \end{matrix} \quad (46)$$

$$i, j = 1, \dots, 20 \quad = \sum_{q=1}^{12} \sum_{u=-2}^2 \sum_{v=-2}^2 \frac{\partial L}{\partial C_{q,\sigma}^2(i+u, j+v)} \cdot \frac{\partial C_{q,\sigma}^2(i+u, j+v)}{\partial S_p^1(i, j)} \quad (47)$$

$$u = -2, \dots, 2 \quad = \sum_{q=1}^{12} \sum_{u=-2}^2 \sum_{v=-2}^2 \Delta C_{q,\sigma}^2(i+u, j+v) \cdot \frac{\partial}{\partial S_p^1(i, j)} \left(\sum_{p=1}^6 \sum_{u=-2}^2 \sum_{v=-2}^2 S_p^1(i, j) \cdot k_{p,q}^2(u, v) + b_q^2 \right) \quad (48)$$

$$j+u = -1, 0, \dots, 22 \quad \text{长度是24} \quad = \sum_{q=1}^{12} \sum_{u=-2}^2 \sum_{v=-2}^2 \Delta C_{q,\sigma}^2(i+u, j+v) \cdot k_{p,q}^2(u, v) \quad (49)$$

Rotating $k_{p,q}^2$ 180 degrees, we get $k_{p,q,rot180}^2(-u, -v) = k_{p,q}^2(u, v)$. Therefore,

$$C_{p,\sigma}^2 \text{ 索引了 } i+u, j+v \quad \Delta S_p^1(i, j) = \sum_{q=1}^{12} \sum_{u=-2}^2 \sum_{v=-2}^2 \Delta C_{q,\sigma}^2(i - (-u), j - (-v)) \cdot k_{p,q,rot180}^2(-u, -v) \quad (50)$$

$$\Rightarrow \Delta S_p^1 = \sum_{q=1}^{12} \Delta C_{q,\sigma}^2 * k_{p,q,rot180}^2 \quad (51) \checkmark$$

(paddle, size=4)

By upsampling, we get the error on C1 layer,

矩阵四周各加4行0
(paddle)

$$\Delta C_p^1(i, j) = \frac{1}{4} \Delta S_p^1(\lceil i/2 \rceil, \lceil j/2 \rceil), \quad i, j = 1, 2, \dots, 24 \quad (52) \checkmark$$

Now, we are ready to calculate $\Delta k_{1,p}^1$,

$$\Delta k_{1,p}^1(u, v) = \frac{\partial L}{\partial k_{1,p}^1(u, v)} \quad (53)$$

$$= \sum_{i=1}^{24} \sum_{j=1}^{24} \frac{\partial L}{\partial C_p^1(i, j)} \cdot \frac{\partial C_p^1(i, j)}{\partial k_{1,p}^1(u, v)} \quad I = \text{Image} \quad (54)$$

$$= \sum_{i=1}^{24} \sum_{j=1}^{24} \Delta C_p^1(i, j) \cdot \frac{\partial}{\partial k_{1,p}^1(u, v)} \sigma \left(\sum_{u=-2}^2 \sum_{v=-2}^2 I(i-u, j-v) \cdot k_{1,p}^1(u, v) + b_p^1 \right) \quad (55)$$

$$= \sum_{i=1}^{24} \sum_{j=1}^{24} \Delta C_p^1(i, j) \cdot C_p^1(i, j) (1 - C_p^1(i, j)) \cdot I(i-u, j-v) \quad (56)$$

By the same token, rotate I 180 degrees, and let

$$\Delta C_{p,\sigma}^1(i, j) = \Delta C_p^1(i, j) \cdot C_p^1(i, j) (1 - C_p^1(i, j)). \quad (57)$$

Finally,

$\Delta C_{p,\sigma}^1$: d-11-output-before activation, shape = (6, 40, 40)

$$\Delta k_{1,p}^1(u, v) = \sum_{i=1}^{24} \sum_{j=1}^{24} I_{rot180}(u-i, v-j) \cdot \Delta C_{p,\sigma}^1(i, j) \quad (58)$$

$$\Rightarrow \Delta k_{1,p}^1 = I_{rot180} * \Delta C_{p,\sigma}^1 \quad (59) \checkmark$$

2.6 Δb_p^1 (size 1×1)

$$\Delta b_p^1 = \frac{\partial L}{\partial b_p^1} \quad (60)$$

$$= \sum_{i=1}^{24} \sum_{j=1}^{24} \frac{\partial L}{\partial C_p^1(i, j)} \cdot \frac{\partial C_p^1(i, j)}{\partial b_p^1} \quad (61)$$

$$= \sum_{i=1}^{24} \sum_{j=1}^{24} \Delta C_p^1(i, j) \cdot \frac{\partial}{\partial b_p^1} \sigma \left(\sum_{u=-2}^2 \sum_{v=-2}^2 I(i-u, j-v) \cdot k_{1,p}^1(u, v) + b_p^1 \right) \quad (62)$$

$$= \sum_{i=1}^{24} \sum_{j=1}^{24} \Delta C_p^1(i, j) \cdot C_p^1(i, j) (1 - C_p^1(i, j)) \quad (63)$$

$$= \sum_{i=1}^{24} \sum_{j=1}^{24} \Delta C_{p,\sigma}^1(i, j) \quad (64)$$

3 Parameter Update

We need to set a learning rate $\alpha \in (0, 1]$.

$$k_{1,p}^1 \leftarrow k_{1,p}^1 - \alpha \cdot \Delta k_{1,p}^1 \quad (65) \checkmark$$

$$b_p^1 \leftarrow b_p^1 - \alpha \cdot \Delta b_p^1 \quad (66) \checkmark$$

$$k_{p,q}^2 \leftarrow k_{p,q}^2 - \alpha \cdot \Delta k_{p,q}^2 \quad (67) \checkmark$$

$$b_q^2 \leftarrow b_q^2 - \alpha \cdot \Delta b_q^2 \quad (68) \checkmark$$

$$W \leftarrow W - \alpha \cdot \Delta W \quad (69) \checkmark$$

$$b \leftarrow b - \alpha \cdot \Delta b \quad (70) \checkmark$$

References

- [1] Palm, Rasmus Berg. "Prediction as a candidate for learning deep hierarchical models of data." *Technical University of Denmark* 5 (2012).
- [2] LeCun, Yann A., Leon Bottou, Genevieve B. Orr, and Klaus-Robert MÅijller. "Efficient backprop." In *Neural networks: Tricks of the trade*, pp. 9-48. Springer Berlin Heidelberg, 2012.