



# Early Stop, Dropout

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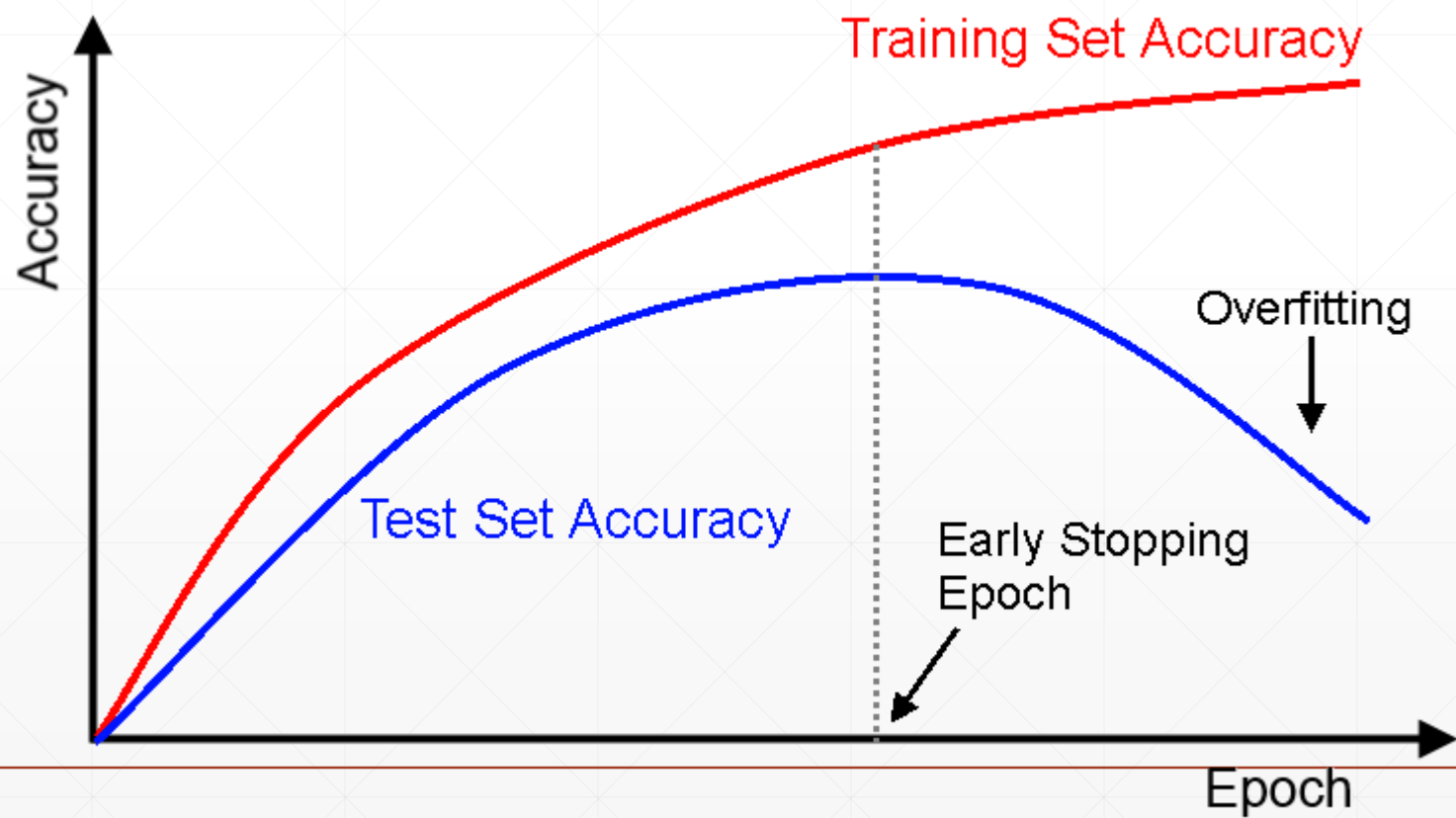
主讲人：龙良曲

# Tricks

- Early Stopping
  - Dropout
  - Stochastic Gradient Descent
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# Early Stopping

- Regularization

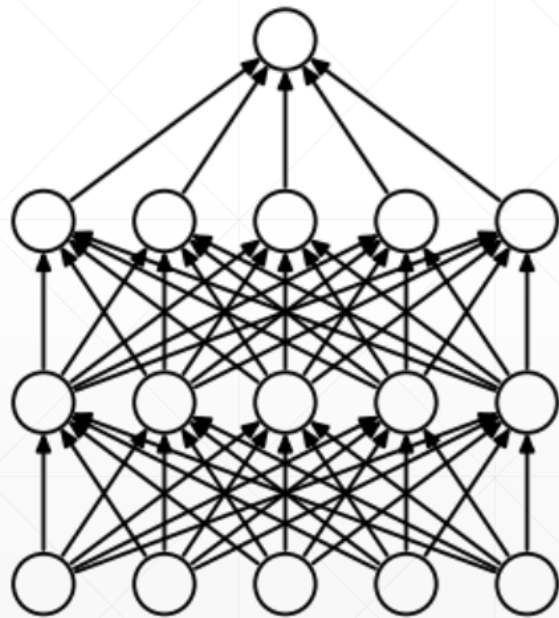


# How-To

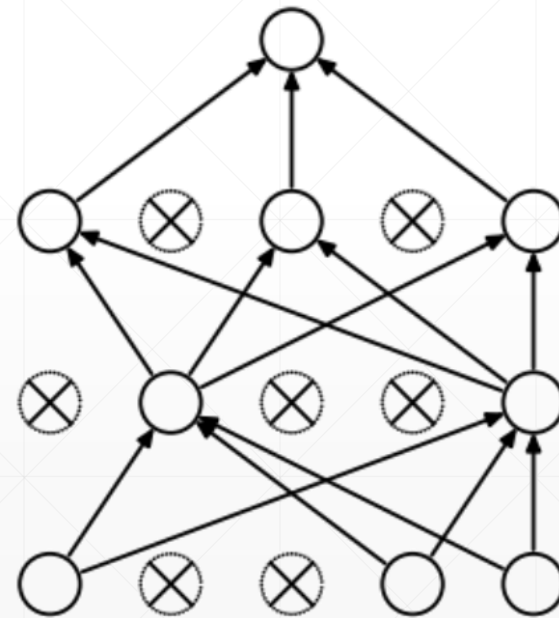
- Validation set to select parameters
  - Monitor validation performance
  - Stop at the highest val perf.
-

# Dropout

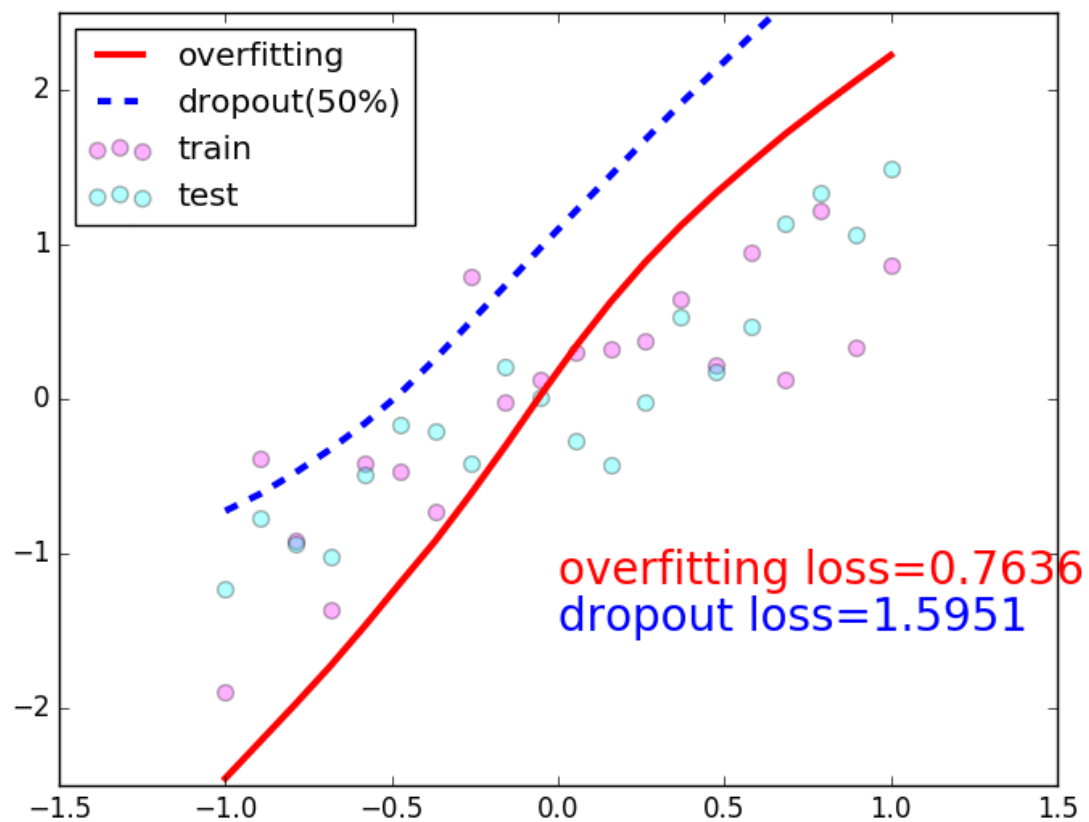
- *Learning less to learn better*
- Each connection has  $p = [0, 1]$  to lose



(a) Standard Neural Net



(b) After applying dropout.





```
net_dropped = torch.nn.Sequential(  
    torch.nn.Linear(784, 200),  
    torch.nn.Dropout(0.5), # drop 50% of the neuron  
    torch.nn.ReLU(),  
    torch.nn.Linear(200, 200),  
    torch.nn.Dropout(0.5), # drop 50% of the neuron  
    torch.nn.ReLU(),  
    torch.nn.Linear(200, 10),  
)
```

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# Clarification

- `torch.nn.Dropout(p=dropout_prob)`
  - `tf.nn.dropout(keep_prob)`
-



# Behavior between train and test



Batch-  
Norm

```
● ● ●  
  
for epoch in range(epochs):  
  
    # train  
    net_dropped.train()  
    for batch_idx, (data, target) in enumerate(train_loader):  
        ...  
    net_dropped.eval()  
    test_loss = 0  
    correct = 0  
    for data, target in test_loader:  
        ...
```

# Stochastic Gradient Descent

- Stochastic
    - not random!
  - Deterministic
-

# Gradient Descent

$$\frac{\partial}{\partial \theta_j} J(\theta) = \frac{1}{m} \sum_{i=1}^m (\hat{y}^i - y^i) \cdot x_j^i$$

② Vanilla (Batch) G.D.

$$\theta_j := \theta_j - \alpha \cdot \underbrace{\frac{\partial}{\partial \theta_j} J(\theta)}_{\frac{1}{m} \sum_{i=1}^m (\hat{y}^i - y^i) x_j^i}$$

# Gradient Descent

③ Stochastic G.D.

for  $i$  in range( $m$ ):

$$\theta_j := \theta_j - \alpha \cdot \underbrace{(\hat{y}^i - y^i) x_j^i}_{\text{only one example}} \frac{\partial J}{\partial \theta_j}$$

# Stochastic Gradient Descent

- Not single usually
- batch = 16, 32, 64, 128...



# Why

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$$P(A|B) = \frac{P(B|A) \times P(A)}{P(B)},$$

# 下一课时

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## 贝叶斯定理

**Thank You.**

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