

Digital Signal Processing I

3rd Week EXPERIMENT

Report

(1st report of DSP1 course)

Subject	Digital Signal Processing I
Professor	Joon-Hyuk Chang
Submission Date	March 23rd, 2021
University	Hanyang University
School	College of Engineering
Department	Department of Computer Science & Engineering
Student ID	Name
2019009261	최가온(CHOI GA ON)

-Contents-

I. Abstraction

- 1. Discrete-time signal
 - 1-1. Definition and its implementation with Matlab
 - 1-2. Types of discrete-time signal
 - 1-3. Operations on discrete-time signal

Ⅱ. Exercises

- 1. Matlab codes of each exercise
- 2. Results

I. Abstraction

1. Discrete-time signal

1-1. Definition and its implementation with Matlab

Discrete-time signal is a time series consisting of a sequence of quantities. It views values of variables as occuring at distinct, separate "points in time", or equivalently as being unchanged throughout each non-zero region of time("time period")—that is, time is viewd as a discrete variable.¹

Its form can be regarded as a number sequence,

$$x(n) = \{ x(n) \} = \{ \dots, x(-1), \overline{x(0)}, x(1), \dots \}$$

where the highlighted part indicates the sample at n = 0.

Matlab is a mathematics tool, which can be used in Engineering Lab or experiment involving statistic knowledge. With Matlab, discrete-time signal can be implemented as a data structure called "list". Here is an example.

All signal can be represented with two components. One is "time" and the other is "information". Thus, a discrete-time signal can be implemented with two list data structure in CS field.

```
Example: x[n] = { 2, 1, 1, 0, 1, 4, 3, 7 }
>> n = [3, 2, 1, 0, 1, 2, 3, 4]; x = [2, 1, 1, 0, 1, 4, 3, 7];
```

_

¹ https://en.wikipedia.org/wiki/Discrete_time_and_continuous_time

1-2. Types of discrete-time signal

1. Unit sample sequence

$$\delta(n) = \begin{cases} 1, & n = 0 \\ 0, & n \neq 0 \end{cases} = \{ \dots, 0, 0, 1, 0, 0, \dots \}$$

In Matlab, the function zeros(1, N) generates a row vector of N zeros, which can be used to implement $\delta(n)$ over a finite interval. However, the logical relation n = 0 is an elegant way of implementing $\delta(n)$. For example, to implement

$$\delta(n-n_0) = \begin{cases} 1, & n=n_0 \\ 0, & n \neq n_0 \end{cases}$$

over the $n_1 \le n_0 \le n_2$ interval, we will use the following MATLAB function.

2. Unit step sequence

In MATLAB the function ones(1, N) generates a row vector of N ones. It can be used to generate u(n) over a finite interval. Once again an elegant approach is to use the logical relation $n \ge 0$. To implement

$$u(n-n_0) = \begin{cases} 1, & n \ge n_0 \\ 0, & n < n_0 \end{cases}$$

over the $n_1 \leq n_0 \leq n_2$ interval, we will use the following MATLAB function.

3. Real-valued exponential sequence

$$x(n) = a^n$$
, $\forall n; a \in R$

```
Example: x[n] = (0.9)^n
>>> n = [0:10];   x = (0.9) .^ n;
```

4. Complex-valued exponential sequence

$$x(n) = e^{(\sigma + j\omega_0)n}, \ \forall n$$

```
Example: x[n] = exp([2+j3]n]
>>> n = [0:10]; x = exp((2+3j) * n);
```

1-3. Operations on discrete-time signal

1. Signal Addition

$${x_1(n)} + {x_2(n)} = {x_1(n) + x_2(n)}$$

2. Signal Multiplication

$${x_1(n)} \cdot {x_2(n)} = {x_1(n)x_2(n)}$$

3. Scaling

$$\alpha\{x(n)\} = \{ ax(n) \}$$

4. Shifting

$$y(n) = \{ x(n-k) \}$$

```
function [y, n] = sigshift(x, m, k)
function [y, n] = sigshif
```

5. Folding

$$y(n) = \{x(-n)\}$$

II. Exercises

In this part, there are 7 exercise questions. Each exercise consists of code and its result. All documents including Matlab code, result, and this report are uploaded in this website:

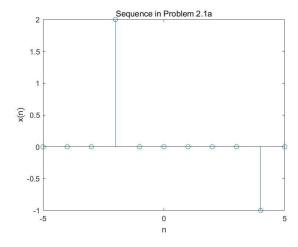
https://github.com/Gaon-Choi/ELE3076/tree/main/1_discrete_time_signal

Example 2.1-a

$$x(n) = 2\delta(n+2) - \delta(n-4), -5 \le n \le 5$$

(Matlab code)

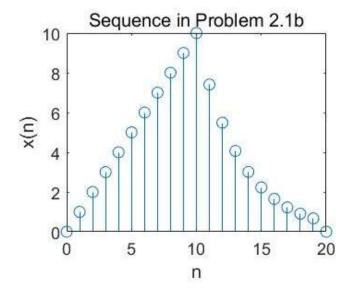
```
| 전집기 - C:\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Users\Undangers\Users\Undangers\Users\Undangers\Users\Undangers\U
```



Example2-1.b

$$x(n) = n[u(n) - u(n-10) + 10e^{-0.3(n-10)}[u(n-10) - u(n-20)], 0 \le n \le 20$$

(Matlab Code)

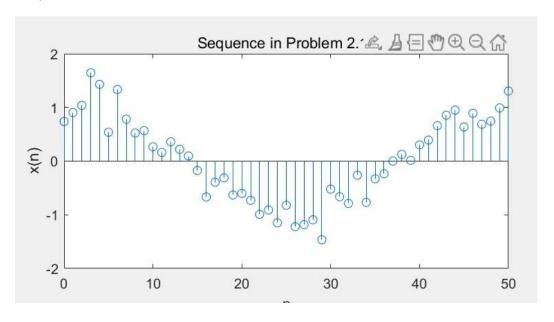


Example2-1.c

$$x(n) = \cos(0.04\pi n) = 0.2\omega(n), 0 \le n \le 50$$

(Matlab Code)

```
      ■ Manage of the state of
```



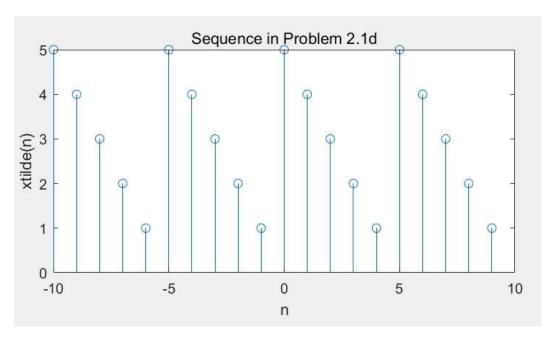
Example2-1.d

$$\tilde{x}(n) = \{\dots, 5, 4, 3, 2, 1, 5, 4, 3, 2, 1, 5, 4, 3, 2, 1, \dots\}; -10 \le n \le 9.$$

Note that over the given interval, the sequence $\tilde{x}(n)$ has four periods.

(Matlab Code)

```
| Marting | Mar
```



Example2-2.a

$$x_1(n) = 2x(n-5) - 3x(n+4)$$

The first part is obtained by shifting x(n) by 5 and the second part by shifting x(n) by -4. This shifting and the addition can be easily done using the **sigshift** and the **sigadd** functions.

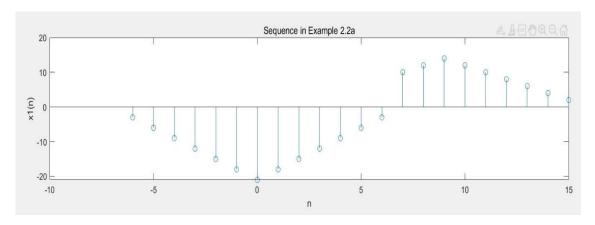
(Matlab Code)

```
      ■ MATLABWexample2_2_a.m
      ● xample2_2_a.m
      +

      1 - n = -2:10; x = [1:7, 6:-1:1];
      □

      2 3 - [x11, n11] = sigshift(x, n, 5); [x12, n12] = sigshift(x, n, -4);
      4 - [x1, n1] = sigadd(2 * x11, n11, -3 * x12, n12);

      5 - subplot(2, 1, 1); stem(n1, x1); title("Sequence in Example 2.2a")
      6 - xlabel("n"); ylabel("x1(n)");
```



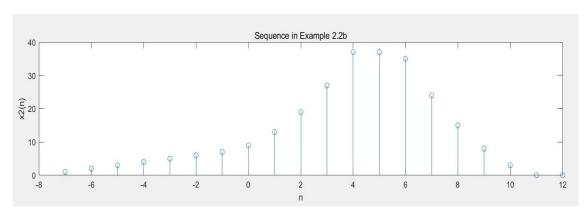
Example2-2.b

$$x_2(n) = x(3-n) + x(n)x(n-2)$$

The first term can be writeen as x(-(n-3)). Hence it is obtained by first folding x(n) and then shifting the result by 3. The second part is a multiplication of x(n) and x(n-2), both of which have the same length but different support (or sample positions). These operations can be easily done using the **sigfold** and the **sigmult** functions.

(Matlab Code)

```
| ■ | Parameter |
```



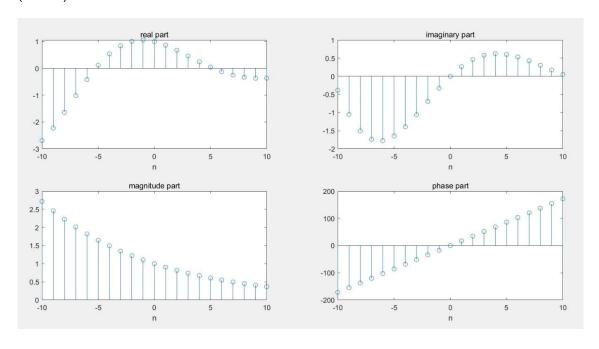
Example2-3

Generate the complex-valued signal

$$x(n) = e^{(-0.1+j0.3)n}, -10 \le n \le 10$$

and plot its magnitude, phase, the real part, and the imaginary part in four separate subplots.

(Matlab Code)



References

Wikipedia(n.d.), Discrete time and continuous time,

https://en.wikipedia.org/wiki/Discrete_time_and_continuous_time

ASML Lab., Digital Signal Processing 1 Week 3 PPT, p.2 ~ p. 29.