

# Digital Signal Processing $\, \Pi \,$

# 10<sup>th</sup> EXPERIMENT

# Report

(WEEK11 report of DSP2 course)

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# **Exercises**

In this part, there are several exercise questions. Each exercise consists of code and its result. All documents including MATLAB code, result, and this report are uploaded in this website :

https://github.com/Gaon-Choi/ELE3077/tree/main/lab\_experiment10

#### **Exercise 1**

#### exercise1-a)

Group the complex conjugate pairs and sort them in increasing real part order for the following sequence by using 'cplxpair' which is a MATLAB built-in function.

(MATLAB Code) lab11\_exercise1\_a.m

```
% exercise1 - a
complex = [4-1j, -3-2j, 1, -3+2j, 2+5j, 2, 4+1j, 2-5j];
c pair = cplxpair(complex) % sort by real number in increasing order
```

#### (Results)

```
명령창

>> lab11_experiment1

c_pair =

1 ~ 7번 열

-3.0000 - 2.0000i -3.0000 + 2.0000i 2.0000 - 5.0000i 2.0000 + 5.0000i 4.0000 - 1.0000i 4.0000 + 1.0000i 1.0000 + 0.0000i

8번 열|

2.0000 + 0.0000i
```

### exercise1-b)

Given the coefficients  $\{b_n\}$  and  $\{a_n\}$  of the direct form filter, we have to obtain the coefficient  $b_0$ ,  $\{B_{k,i}\}$ , and  $\{A_{k,i}\}$ . For doing this computation, make the function 'dir2cas'.

#### (MATLAB Code) dir2cas.m

```
function [b0, B, A] = dir2cas(b, a)
b0 = b(1); b = b/b0; a0 = a(1); a = a/a0; b0 = b0/a0;
M = length(b); N = length(a);
if N > M
   b = [b zeros(1, N-M)];
elseif M > N
   a = [a zeros(1, M-N)]; N = M;
else
   NM = 0;
end
K = floor(N/2); B = zeros(K, 3); A = zeros(K, 3);
if K*2 == N
   b = [b \ 0]; a = [a \ 0];
end
broots = cplxpair(roots(b));
aroots = cplxpair(roots(a));
for i = 1:2:2*K
   B row = broots(i:1:i+1,:);
   B row = real(poly(B row));
   B(fix((i+1)/2),:) = B row;
   A row = aroots(i:1:i+1,:);
   A row = real(poly(A row));
   A(fix((i+1)/2),:) = A row;
end
```

# exercise1-c)

Make the function 'casfiltr' which will be used to implement digital filtering of the cascaded form.

#### (MATLAB Code) casfiltr.m

```
function y = casfiltr(b0, B, A, x)
[K, L] = size(B);
N = length(x);
w = zeros(K+1, N);
w(1,:) = x;

for i = 1:1:K
    w(i+1,:) = filter(B(i,:), A(i,:), w(i,:));
end

y = b0 * w(K+1,:);
end
```

# **Exercise 2**

# exercise2-a)

A filter is described by the following difference equation:

$$16y(n) + 12y(n-1) + 2y(n-2) - 4y(n-3) - y(n-4)$$
$$= x(n) + 3x(n-1) + 11x(n-2) - 27x(n-3) - 18x(n-4)$$

determine its cascaded form structure by using the function 'dir2cas' that you made in 'exercise1'.

# (MATLAB Code) lab11\_exercise2\_a.m

```
coef_a = [16 12 2 -4 -1];
coef_b = [1 -3 11 -27 18];
[b0, coef_b, coef_a] = dir2cas(coef_b, coef_a)
```

# (Result)

```
>> lab11_exercise2_a

b0 =

0.0625

coef_b =

1.0000 0.0000 9.0000
1.0000 -3.0000 2.0000

coef_a =

1.0000 1.0000 0.5000
1.0000 -0.2500 -0.1250
```

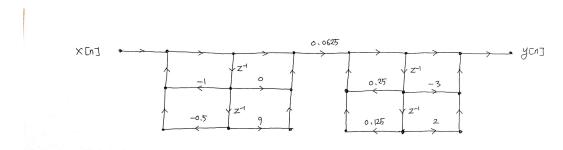
# exercise2-b)

Draw the block diagram of Q2-a by using the signal-flow graph(SGF) with your own hands.

# (MATLAB Code)

(No CODE)

# (Result)



#### exercise2-c)

Generate an impulse response (the length of sequence = 8) and filter it by the cascaded form ('casfiltr') and the direct form ('filter') respectively. And check the result is same.

## (MATLAB Code) lab11\_exercise2\_c.m

```
coef_a = [16 12 2 -4 -1];
coef_b = [1 -3 11 -27 18];

[b0, B, A] = dir2cas(coef_b, coef_a)

delta = [1 0 0 0 0 0 0 0];

hcas = casfiltr(b0, B, A, delta);
hdir = filter(coef_b, coef_a, delta);
err = abs(max(hcas-hdir))
```

#### (Result)

As the value of err is very small, it can be understood that they are the same.