Stan

a Probabilistic Programming Language

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http://mc-stan.org/workshops/vanderbilt2016

Male Birth Ratio

Example I

Birth Rate by Sex

· Laplace's data on live births in Paris from 1745-1770:

sex	live births
female	241 945
male	251 527

- Question 1 (Estimation)
 What is the birth rate of boys vs. girls?
- Question 2 (Event Probability)
 Is a boy more likely to be born than a girl?
- · Bayes (1763) set up the "Bayesian" model
- · Laplace (1781, 1786) solved for the posterior

Calculating Laplace's Answers

```
transformed data {
  int male;
  int female;
  male <- 251527;
  female <- 241945:
parameters {
  real<lower=0. upper=1> theta:
}
model {
  male ~ binomial(male + female, theta);
generated quantities {
  int<lower=0, upper=1> theta_gt_half;
  theta_gt_half <- (theta > 0.5);
```

And the Answer is...

theta_gt_half

- Q1: θ is 99% certain to lie in (0.508, 0.512)
- · Q2: Laplace "morally certain" boys more prevalent

1.00 1.000 1.000

Parameter Estimates

 Estimate probability that a parameter value in interval, e.g.,

$$\Pr[\theta \in (0.508, 0.512) \mid y]$$

Conditions on observed data y

Bayesian parameter estimates are probabilistic

Event Probabilities

· Random variable defined by indicator function

```
theta_gt_half <- (theta > 0.5);
```

- · Indicators are random variables
 - with boolean (0 or 1) values
 - defined in terms of parameters (and data)
- · For Laplace's problem, calculus shows

$$Pr[\theta \le 0.5 | v] \approx 10^{-42}$$

Event probabilities are expectations of indicators

Warmup Exercise I

Sample Variation

Repeated i.i.d. Trials

- Suppose we repeatedly generate a random outcome from among several potential outcomes
- Suppose the outcome chances are the same each time
 - i.e., outcomes are independent and identically distributed (i.i.d.)
- For example, spin a fair spinner (without cheating), such as one from Family Cricket.



Repeated i.i.d. Binary Trials

- Suppose the outcome is binary and assigned to 0 or 1; e.g.,
 - 20% chance of outcome 1: ball in play
 - 80% chance of outcome 0: ball not in play
- · Consider different numbers of bowls delivered.
- How will proportion of successes in sample differ?

Simulating Repeated Binary Trials

```
    R Code: rbinom(10, N, 0.3)
    N = 10 trials (10% to 50% success rate)
    2 2 1 3 3 2 3 2 2 5
    N = 100 trials (27% to 34% success rate)
```

29 34 27 31 25 31 27 29 32 26

N = 1000 trials (29% to 32% success rate)
 291 297 289 322 305 296 294 297 314 292

- N = 10,000 trials (29.5% to 30.7% success rate) 3014 3031 3017 2886 2995 2944 3067 3069 3051 3068

· Deviation goes down at rate: $\mathcal{O}(1/\sqrt{N})$

Simple Point Estimation

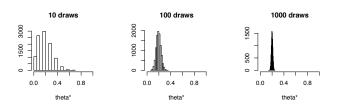
• Estimate chance of success θ by proportion of successes:

$$\theta^* = \frac{\text{successes}}{\text{attempts}}$$

- · Simulation shows accuracy depends on the amount of data.
- · Statistical inference includes quantifying uncertainty.
- · Bayesian statistics is about using uncertainty in inference.

Estimation Uncertainty

- · Simulation of estimate variation due to sampling
- · not a Bayesian posterior



Estimator Bias

• **Bias:** expected difference of estimate $(\hat{\theta})$ from true value (θ)

bias =
$$\mathbb{E}[\theta - \hat{\theta}]$$

· Continuing previous example

- > sims <- rbinom(10000, 1000, 0.2) / 1000
 > mean(sims)
- [1] 0.2002536
- · Value of 0.2 is estimate of expectation
- · Shows this estimator is unbiased

Simple Point Estimation (cont.)

- Central Limit Theorem: $\emph{expected}$ error in θ^* goes down

as

$$\frac{1}{\sqrt{N}}$$

- · Each decimal place of accuracy requires $100 \times$ more draws.
- · Width of confidence intervals shrinks at the same rate.

· Can also use theory to show this estimator is unbiased.

Pop Quiz! Cancer Clusters

· Why do lowest and highest cancer clusters look so similar?



Pop Quiz Answer

 Hint: mix earlier simulations of repeated i.i.d. trials with 20% success and sort:

1/10	1/10	1/10	15/100	16/100
17/100	175/1000	179/1000	18/100	181/1000
188/1000	194/1000	198/1000	2/10	2/10
2/10	2/10	21/100	21/100	21/100
212/1000	213/1000	216/1000	223/1000	23/100
26/100	26/100	3/10	4/10	5/10

- · More variation in observed rates with smaller sample sizes
- Answer: High cancer and low cancer counties are small populations

Repeated Binary Trials

Stan Example

R: Simulate Data

· Generate data

· Calculate MLE as sample mean from data

```
> sum(y) / N
Γ17 0.4
```

RStan: Fit

```
> library(rstan);
> fit <- stan("bern.stan".</pre>
              data = list(y = y, N = N));
> print(fit, probs=c(0.1, 0.9));
Inference for Stan model: bern.
4 chains, each with iter=2000; warmup=1000; thin=1;
post-warmup draws per chain=1000,
total post-warmup draws=4000.
```

mean se_mean sd 10% 90% n_eff Rhat theta 0.41 0.00 0.10 0.28 0.55 1580 1

Plug in Posterior Draws

· Extracting the posterior draws

```
> theta_draws <- extract(fit)$theta;</pre>
```

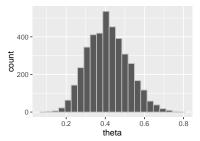
· Calculating posterior mean (estimator)

```
> mean(theta_draws);
[1] 0.4128373
```

Calculating posterior intervals

ggplot2: Plotting

```
theta_draws_df <- data.frame(list(theta = theta_draws));
plot <-
    ggplot(theta_draws_df, aes(x = theta)) +
    geom_histogram(bins=20, color = "gray");
plot;</pre>
```



Maximum Likelihood

Estimation

Warmup Exercise II

Observations, Counterfactuals, and Random Variables

- · Assume we observe data $y = y_1, \dots, y_N$
- Statistical modeling assumes even though y is observed, the values could have been different
- John Stuart Mill first characterized this counterfactual nature of statistical modeling in:
 - A System of Logic, Ratiocinative and Inductive (1843)
- · In measure-theoretic language, y is a random variable

Likelihood Functions

 A likelihood function is a probability function (density, mass, or mixed)

$$p(y|\theta,x)$$
,

where

- θ is a vector of **parameters**,
- x is some fixed unmodeled data (e.g., regression predictors or "features"),
- y is some fixed **modeled data** (e.g., observations)
- · considered as a function $\mathcal{L}(\theta)$ of θ for fixed x and y.
- can think of as a generative process for y how data y is generated

Maximum Likelihood Estimation

- **Estimate** parameters θ given observations y.
- Maximum likelihood estimation (MLE) chooses estimate that maximizes the likelihood function, i.e.,

$$\theta^* = \operatorname{arg\,max}_{\theta} \mathcal{L}(\theta) = \operatorname{arg\,max}_{\theta} p(y|\theta, x)$$

• This function of \mathcal{L} and y (and x) is called an **estimator**

Example of MLE

· The frequency-based estimate

$$\theta^* = \frac{1}{N} \sum_{i=1}^{N} y_n,$$

is the observed rate of "success" (outcome 1) observations.

· This is the MLF for the model

$$p(y|\theta) = \prod_{n=1}^{N} p(y_n|\theta) = \prod_{n=1}^{N} \text{Bernoulli}(y_n|\theta)$$

where for $u \in \{0, 1\}$,

Bernoulli
$$(u|\theta) = \begin{cases} \theta & \text{if } u = 1\\ 1 - \theta & \text{if } u = 0 \end{cases}$$

Example of MLE (cont.)

· First modeling assumption is that data are i.i.d.,

$$p(y|\theta) = \prod_{n=1}^{N} p(y_n|\theta)$$

· Second modeling assumption is form of likelihood,

$$p(y_n|\theta) = Bernoulli(y_n|\theta)$$

Example of MLE (cont.)

- · The frequency-based estimate is the MLE
- · First derivative is zero (indicating min or max),

$$\mathcal{L}_{y}'(\theta^{*})=0,$$

· Second derivative is negative (indicating max),

$$\mathcal{L}_{\nu}^{\prime\prime}(\theta^*) < 0.$$

MLEs can be Dangerous!

- · Recall the cancer cluster example
- · Accuracy is low with small counts
- · What we need are hierarchical models (stay tuned)

Part I

Bayesian Inference

Bayesian Data Analysis

- "By Bayesian data analysis, we mean practical methods for making inferences from data using probability models for quantities we observe and about which we wish to learn."
- "The essential characteristic of Bayesian methods is their explict use of probability for quantifying uncertainty in inferences based on statistical analysis."

Bayesian Methodology

- · Set up full probability model
 - for all observable & unobservable quantities
 - consistent w. problem knowledge & data collection
- · Condition on observed data
 - to caclulate posterior probability of unobserved quantities (e.g., parameters, predictions, missing data)
- Evaluate
 - model fit and implications of posterior
- · Repeat as necessary

Where do Models Come from?

- Sometimes model comes first, based on substantive considerations
 - toxicology, economics, ecology, ...
- · Sometimes model chosen based on data collection
 - traditional statistics of surveys and experiments
- · Other times the data comes first
 - observational studies, meta-analysis, ...
- Usually its a mix

(Donald) Rubin's Philosophy

- · All statistics is inference about missing data
- · Question 1: What would you do if you had all the data?
- · Question 2: What were you doing before you had any data?

(as relayed in course notes by Andrew Gelman)

Model Checking

- · Do the inferences make sense?
 - are parameter values consistent with model's prior?
 - does simulating from parameter values produce reasoable fake data?
 - are marginal predictions consistent with the data?
- Do predictions and event probabilities for new data make sense?
- Not: Is the model true?
- · Not: What is Pr[model is true]?
- · Not: Can we "reject" the model?

Model Improvement

- Expanding the model
 - hierarchical and multilevel structure ...
 - more flexible distributions (overdispersion, covariance)
 - more structure (geospatial, time series)
 - more modeling of measurement methods and errors
 - ...
- · Including more data
 - breadth (more predictors or kinds of observations)
 - depth (more observations)

Using Bayesian Inference

- Finds parameters consistent with prior info and data*
 - * if such agreement is possible
- · Automatically includes uncertainty and variability
- Inferences can be plugged in directly
 - risk assesment
 - decision analysis

Notation for Basic Quantities

Basic Quantities

- y: observed data
- θ : parameters (and other unobserved quantities)
- x: constants, predictors for conditional (aka "discriminative") models

Basic Predictive Quantities

- \tilde{y} : unknown, potentially observable quantities
- \tilde{x} : constants, predictors for unknown quantities

Naming Conventions

- · **Joint**: $p(y, \theta)$
- · Sampling / Likelihood: $p(y|\theta)$
 - Sampling is function of y with θ fixed (prob function)
 - Likelihood is function of θ with y fixed (not prob function)
- · Prior: $p(\theta)$
- Posterior: $p(\theta|y)$
- Data Marginal (Evidence): p(y)
- Posterior Predictive: $p(\tilde{y}|y)$

Bayes's Rule for Posterior

$$p(\theta|y) = \frac{p(y,\theta)}{p(y)} \qquad [def of conditional]$$

$$= \frac{p(y|\theta) p(\theta)}{p(y)} \qquad [chain rule]$$

$$= \frac{p(y|\theta) p(\theta)}{\int_{\Theta} p(y,\theta') d\theta'} \qquad [law of total prob]$$

$$= \frac{p(y|\theta) p(\theta)}{\int_{\Theta} p(y|\theta') p(\theta') d\theta'} \qquad [chain rule]$$

Inversion: Final result depends only on sampling distribution (likelihood) $p(y|\theta)$ and prior $p(\theta)$

Bayes's Rule up to Proportion

· If data y is fixed, then

$$p(\theta|y) = \frac{p(y|\theta) p(\theta)}{p(y)}$$

$$\propto p(y|\theta) p(\theta)$$

$$= p(y,\theta)$$

- · Posterior proportional to likelihood times prior
- Equivalently, posterior proportional to joint
- · The nasty integral for data marginal p(y) goes away

Posterior Predictive Distribution

- · Predict new data \tilde{y} based on observed data y
- · Marginalize out parameters from posterior

$$p(\tilde{y}|y) = \int_{\Theta} p(\tilde{y}|\theta) p(\theta|y) d\theta.$$

- Averages predictions $p(\tilde{y}|\theta)$, weight by posterior $p(\theta|y)$
 - $\Theta = \{\theta \mid p(\theta|y) > 0\}$ is support of $p(\theta|y)$
- · Allows continuous, discrete, or mixed parameters
 - integral notation shorthand for sums and/or integrals

Event Probabilities

- · Recall that an event A is a collection of outcomes
- \cdot Suppose event A is determined by indicator on parameters

$$f(\theta) = \begin{cases} 1 & \text{if } \theta \in A \\ 0 & \text{if } \theta \notin A \end{cases}$$

- e.g., $f(\theta) = I(\theta_1 > \theta_2)$ for $Pr[\theta_1 > \theta_2 | y]$
- Bayesian event probabilities calculate posterior mass

$$Pr[A] = \int_{\Omega} f(\theta) \, p(\theta|y) \, d\theta.$$

· Not frequentist, because involves parameter probabilities

Male Birth Ratio

Example I

Laplace's Data and Problems

Laplace's data on live births in Paris from 1745-1770:

sex	live births
female	241 945
male	251 527

- Question 1 (Event Probability)
 Is a boy more likely to be born than a girl?
- Question 2 (Estimate)What is the birth rate of boys vs. girls?
- · Bayes formulated the basic binomial model
- · Laplace solved the integral

Binomial Distribution

- Binomial distribution is number of successes y in N i.i.d. Bernoulli trials with chance of success θ
- · If $y_1, ..., y_N \sim \text{Bernoulli}(\theta)$, then $(y_1 + \cdots + y_N) \sim \text{Binomial}(N, \theta)$
- · The analytic form is

Binomial
$$(y|N,\theta) = \binom{N}{y} \theta^y (1-\theta)^{N-y}$$

where the binomial coefficient normalizes for permutations (i.e., which subset of n has $y_n = 1$),

$$\binom{N}{y} = \frac{N!}{y! (N-y)!}$$

Bayes's Binomial Model

- · Data
 - y: total number of male live births (data: 241 945)
 - N: total number of live births (data: 493 472)
- Parameter
 - $\theta \in (0,1)$: proportion of male live births
- Likelihood

$$p(y|N,\theta) = \text{Binomial}(y|N,\theta) = \binom{N}{y} \theta^{y} (1-\theta)^{N-y}$$

Prior

$$p(\theta) = \text{Uniform}(\theta \mid 0, 1) = 1$$

Detour: Beta Distribution

· For parameters $\alpha, \beta > 0$ and $\theta \in (0, 1)$,

$$Beta(\theta | \alpha, \beta) \propto \theta^{\alpha-1} (1-\theta)^{\beta-1}$$

Euler's Beta function is used to normalize.

$$B(\alpha,\beta) = \int_0^1 u^{\alpha-1} (1-u)^{\beta-1} du = \frac{\Gamma(\alpha)\Gamma(\beta)}{\Gamma(\alpha+\beta)}$$

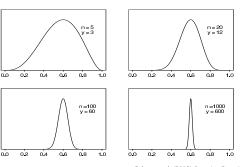
so that

Beta
$$(\theta | \alpha, \beta) = \frac{1}{\mathsf{R}(\alpha, \beta)} \theta^{\alpha-1} (1-\theta)^{\beta-1}$$

- Note: Beta $(\theta|1,1)$ = Uniform $(\theta|0,1)$
- Note: $\Gamma()$ is continuous generalization of factorial

Beta Distribution — Examples

 Unnormalized posterior density assuming uniform prior and y successes out of n trials (all with mean 0.6).



Gelman et al. (2013) Bayesian Data Analysis, 3rd Edition.

Laplace Turns the Crank

From Bayes's rule, the posterior is

$$p(\theta|y,N) = \frac{\mathsf{Binomial}(y|N,\theta) \, \mathsf{Uniform}(\theta|0,1)}{\int_{\Theta} \mathsf{Binomial}(y|N,\theta') \, p(\theta') \, d\theta'}$$

Laplace calculated the posterior analytically

$$p(\theta|y,N) = \text{Beta}(\theta|y+1, N-y+1).$$

Estimation

- Posterior is Beta $(\theta | 1 + 241945, 1 + 251527)$
- · Posterior mean:

$$\frac{1 + 241945}{1 + 241945 + 1 + 251527} \approx 0.4902913$$

Maximum likelihood estimate same as posterior mode (because of uniform prior)

$$\frac{241\,945}{241\,945+251\,527}\approx 0.490291\mathbf{2}$$

As number of observations approaches ∞,
 MLE approaches posterior mean

Event Probability Inference

 What is probability that a male live birth is more likely than a female live birth?

$$\Pr[\theta > 0.5] = \int_{\Theta} I[\theta > 0.5] p(\theta|y, N) d\theta$$
$$= \int_{0.5}^{1} p(\theta|y, N) d\theta$$
$$= 1 - F_{\theta|y, N}(0.5)$$
$$\approx 10^{-42}$$

- $I[\phi] = 1$ if condition ϕ is true and 0 otherwise.
- · $F_{\theta|\gamma,N}$ is posterior cumulative distribution function (cdf).

Mathematics vs. Simulation

- · Luckily, we don't have to be as good at math as Laplace
- Nowadays, we calculate all these integrals by computer using tools like Stan

If you wanted to do foundational research in statistics in the mid-twentieth century, you had to be bit of a mathematician, whether you wanted to or not. ... if you want to do statistical research at the turn of the twenty-first century, you have to be a computer programmer.

—from Andrew's blog

Bayesian "Fisher Exact Test"

· Suppose we observe the following data on handedness

	sinister	dexter	TOTAL
male	9 (<i>y</i> ₁)	43	52 (N ₁)
female	4 (y ₂)	44	48 (N ₂)

- · Assume likelihoods Binomial $(y_k|N_k,\theta_k)$, uniform priors
- Are men more likely to be lefthanded?

$$\Pr[\theta_1 > \theta_2 \mid y, N] = \int_{\Theta} \mathsf{I}[\theta_1 > \theta_2] \, p(\theta \mid y, N) \, d\theta$$

$$\approx 0.91$$

· Directly interpretable result; not a frequentist procedure

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· Directly interpretable result; not a frequentist procedure

Stan Binomial Comparison

```
data {
 int y[2];
  int N[2];
parameters {
  vector<lower=0,upper=1> theta[2];
model {
  y ~ binomial(N, y);
generated quantities {
  real boys_minus_girls;
  int boys_gt_girls;
  boys_minus_girls <- theta[1] - theta[2];
  boys_gt_girls <- (theta[1] > theta[2]);
```

Results

```
    mean
    2.5%
    97.5%

    theta[1]
    0.22
    0.12
    0.35

    theta[2]
    0.11
    0.04
    0.21

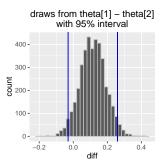
    boys_minus_girls
    0.12
    -0.03
    0.26

    boys_gt_girls
    0.93
    0.00
    1.00
```

- $\cdot \Pr[\theta_1 > \theta_2 \mid y] \approx 0.93$
- · $Pr[(\theta_1 \theta_2) \in (-0.03, 0.26) | y] = 95\%$

Visualizing Posterior Difference

· Plot of posterior difference, $p(\theta_1 - \theta_2 \mid y, N)$ (men - women)



Vertical bars: central 95% posterior interval (-0.03, 0.26)

Technical Interlude

Conjugate Priors

Conjugate Priors

- · Family \mathcal{F} is a conjugate prior for family \mathcal{G} if
 - prior in ${\mathcal F}$ and
 - likelihood in *G*,
 - entails posterior in ${\mathcal F}$
- Before MCMC techniques became practical, Bayesian analysis mostly involved conjugate priors
- Still widely used because analytic solutions are more efficient than MCMC

Beta is Conjugate to Binomial

- Prior: $p(\theta|\alpha,\beta) = \text{Beta}(\theta|\alpha,\beta)$
- · Likelihood: $p(y|N,\theta) = \text{Binomial}(y|N,\theta)$
- · Posterior:

$$\begin{split} p(\theta|y,N,\alpha,\beta) & \propto & p(\theta|\alpha,\beta) \, p(y|N,\theta) \\ & = & \operatorname{Beta}(\theta|\alpha,\beta) \operatorname{Binomial}(y|N,\theta) \\ & = & \frac{1}{\mathsf{B}(\alpha,\beta)} \theta^{\alpha-1} \, (1-\theta)^{\beta-1} \, \begin{pmatrix} N \\ y \end{pmatrix} \theta^y (1-\theta)^{N-y} \\ & \propto & \theta^{y+\alpha-1} \, (1-\theta)^{N-y+\beta-1} \end{split}$$

 \propto Beta $(\theta | \alpha + \nu, \beta + (N - \nu))$

Chaining Updates

- · Start with prior Beta($\theta | \alpha, \beta$)
- · Receive binomial data in K statges $(y_1, N_1), \ldots, (y_K, N_K)$
- After (y_1, N_1) , posterior is Beta $(\theta | \alpha + y_1, \beta + N_1 y_1)$
- Use as prior for (y_2, N_2) , with posterior $Beta(\theta | \alpha + y_1 + y_2, \quad \beta + (N_1 y_1) + (N_2 y_2))$
- Lather, rinse, repeat, until final posterior $Beta(\theta | \alpha + y_1 + \dots + y_K, \ \beta + (N_1 + \dots + N_K) (y_1 + \dots + y_K))$
- · Same result as if we'd updated with combined data $Beta(y_1 + \cdots + y_K, N_1 + \cdots + N_K)$

Part II

(Un-)Bayesian

Point Estimation

MAP Estimator

• For a Bayesian model $p(y, \theta) = p(y|\theta) p(\theta)$, the max a posteriori (MAP) estimate maximizes the posterior,

$$\begin{array}{ll} \theta^* &=& \arg\max_{\theta}\,p(\theta|y) \\ &=& \arg\max_{\theta}\,\frac{p(y|\theta)p(\theta)}{p(y)} \\ &=& \arg\max_{\theta}\,p(y|\theta)p(\theta). \\ &=& \arg\max_{\theta}\,\log p(y|\theta) + \log p(\theta). \end{array}$$

- not Bayesian because it doesn't integrate over uncertainty
- · not frequentist because of distributions over parameters

MAP and the MLE

 MAP estimate reduces to the MLE if the prior is uniform, i.e.,

$$p(\theta) = c$$

because

$$\theta^* = \arg \max_{\theta} p(y|\theta) p(\theta)$$

$$= \arg \max_{\theta} p(y|\theta) c$$

= $arg max_{\theta} p(y|\theta)$.

Penalized Maximum Likelihood

- The MAP estimate can be made palatable to frequentists via philosophical sleight of hand
- · Treat the negative log prior $-\log p(\theta)$ as a "penalty"
- \cdot e.g., a Normal $(\theta|\mu,\sigma)$ prior becomes a penalty function

$$\lambda_{\theta,\mu,\sigma} = -\left(\log \sigma + \frac{1}{2} \left(\frac{\theta - \mu}{\sigma}\right)^2\right)$$

· Maximize sum of log likelihood and negative penalty

$$\begin{array}{ll} \theta^* & = & \arg\max_{\theta} \; \log p(y|\theta,x) - \lambda_{\theta,\mu,\sigma} \\ \\ & = & \arg\max_{\theta} \; \log p(y|\theta,x) + \log p(\theta|\mu,\sigma) \end{array}$$

Proper Bayesian Point Estimates

- · Choose estimate to minimize some loss function
- To minimize expected squared error (L2 loss), $\mathbb{E}[(\theta-\theta')^2 \mid y]$, use the posterior mean

$$\hat{\theta} \ = \ \arg\min_{\theta'} \mathbb{E}[(\theta - \theta')^2 \,|\, y] \ = \ \int_{\Theta} \theta \times p(\theta|y) \,d\theta.$$

- To minimize expected absolute error (L1 loss), $\mathbb{E}[|\theta-\theta'|]$, use the posterior median.
- Other loss (utility) functions possible, the study of which falls under decision theory
- · All share property of involving full Bayesian inference.

Point Estimates for Inference?

- Common in machine learning to generate a point estimate θ^* , then use it for inference, $p(\tilde{y}|\theta^*)$
- · This is **defective** because it

underestimates uncertainty.

- · To properly estimate uncertainty, apply full Bayes
- A major focus of statistics and decision theory is estimating uncertainty in our inferences

Philosophical Interlude

What is Statistics?

Exchangeability

• Roughly, an exchangeable probability function is such that for a sequence of random variables $y = y_1, ..., y_N$,

$$p(y) = p(\pi(y))$$

for every N-permutation π (i.e, a one-to-one mapping of $\{1,\ldots,N\}$)

i.i.d. implies exchangeability, but not vice-versa

Exchangeability

• Roughly, an exchangeable probability function is such that for a sequence of random variables $y = y_1, ..., y_N$,

$$p(y) = p(\pi(y))$$

for every N-permutation π (i.e, a one-to-one mapping of $\{1,\ldots,N\}$ to itself)

- · i.i.d. implies exchangeability, but not vice-versa
 - (y_1, y_2) exchangeable, but not independent in

$$(y_1, y_2) \sim \mathsf{MultiNormal} \left(0, \begin{bmatrix} 1 & 0.5 \\ 0.5 & 1 \end{bmatrix} \right)$$

Exchangeability Assumptions

- Models almost always make some kind of exchangeability assumption
- · Typically when other knowledge is not available
 - e.g., treat voters as conditionally i.i.d. given their age, sex, income, education level, religous affiliation, and state of residence
 - But voters have many more properties (hair color, height, profession, employment status, marital status, car ownership, gun ownership, etc.)
 - Missing predictors introduce additional error (on top of measurement error)

Random Parameters: Doxastic or Epistemic?

- Bayesians treat distributions over parameters as epistemic (i.e., about knowledge)
- They do not treat them as being doxastic (i.e., about beliefs)
- · Priors encode our knowledge before seeing the data
- · Posteriors encode our knowledge after seeing the data
- · Bayes's rule provides the way to update our knowledge
- People like to pretend models are ontological (i.e., about what exists)

Arbitrariness: Priors vs. Likelihood

- · Bayesian analyses often criticized as subjective (arbitrary)
- · Choosing priors is no more arbitrary than choosing a likelihood function (or an exchangeability/i.i.d. assumption)
- · As George Box famously wrote (1987),

"All models are wrong, but some are useful."

· This does not just apply to Bayesian models!

Part IV

Hierarchical Models

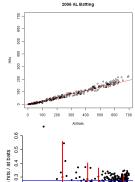
Part IV

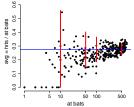
Baseball At-Bats

- · For example, consider baseball batting ability.
 - Baseball is sort of like cricket, but with round bats, a one-way field, stationary "bowlers". four bases, short games, and no draws
- · Batters have a number of "at-bats" in a season, out of which they get a number of "hits" (hits are a good thing)
- Nobody with higher than 40% success rate since 1950s.
- No player (excluding "bowlers") bats much less than 20%.
- Same approach applies to hospital pediatric surgery complications (a BUGS example), reviews on Yelp, test scores in multiple classrooms, . . .

Baseball Data

- Hits versus at bats for the 2006 American League season
- Not much variation in ability!
- · Ignore skill vs. at-bats relation
- · Note uncertainty of MLE





Pooling Data

- How do we estimate the ability of a player who we observe getting 6 hits in 10 at-bats? Or 0 hits in 5 at-bats? Estimates of 60% or 0% are absurd!
- Same logic applies to players with 152 hits in 537 at bats.
- · No pooling: estimate each player separately
- Complete pooling: estimate all players together (assume no difference in abilities)
- Partial pooling: somewhere in the middle
 - use information about other players (i.e., the population) to estimate a player's ability

Hierarchical Models

- Hierarchical models are principled way of determining how much pooling to apply.
- Pull estimates toward the population mean based on amount of variation in population
 - low variance population: more pooling
 - high variance population: less pooling
- · In limit
 - as variance goes to 0, get complete pooling
 - as variance goes to ∞, get no pooling

Hierarchical Batting Ability

- Instead of fixed priors, estimate priors along with other parameters
- · Still only uses data once for a single model fit
- · Data: y_n, B_n : hits, at-bats for player n
- · Parameters: θ_n : ability for player n
- · Hyperparameters: α, β : population mean and variance
- · Hyperpriors: fixed priors on α and β (hardcoded)

Hierarchical Batting Model (cont.)

$$y_n \sim \operatorname{Binomial}(B_n, \theta_n)$$
 $\theta_n \sim \operatorname{Beta}(\alpha, \beta)$
 $\frac{\alpha}{\alpha + \beta} \sim \operatorname{Uniform}(0, 1)$
 $(\alpha + \beta) \sim \operatorname{Pareto}(1.5)$

· Sampling notation syntactic sugar for:

$$p(y,\theta,\alpha,\beta) \ = \ \mathsf{Pareto}(\alpha+\beta|1.5) \ \textstyle\prod_{n=1}^{N} \Big(\mathsf{Binomial}(y_n|B_n,\theta_n) \ \mathsf{Beta}(\theta_n|\alpha,\beta) \Big)$$

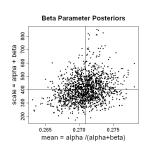
- Pareto provides power law: Pareto $(u|\alpha) \propto \frac{\alpha}{u^{\alpha+1}}$
- · Should use more informative hyperpriors!

Stan Program

```
data {
 int<lower=0> N:
                               // items
 int<lower=0> K[N];
                               // initial trials
 int<lower=0> y[N];
                               // initial successes
parameters {
  real<lower=0, upper=1> phi;
                                      // population chance of suc
  real<lower=1> kappa;
                                     // population concentration
 vector<lower=0, upper=1>[N] theta; // chance of success
model {
  kappa \sim pareto(1, 1.5);
                                                 // hyperprior
  theta ~ beta(phi * kappa, (1 - phi) * kappa); // prior
 y ~ binomial(K, theta);
                                                 // likelihood
```

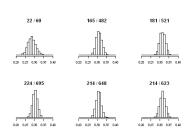
Hierarchical Prior Posterior

- Draws from posterior (crosshairs at posterior mean)
- · Prior population mean: 0.271
- · Prior population scale: 400
- Together yield prior std dev of 0.022
- Mean is better estimated than scale (typical)



Posterior Ability (High Avg Players)

- Histogram of posterior draws for high-average players
- Note uncertainty grows with lower atbats





Multiple Comparisons

- · Who has the highest ability (based on this data)?
- Probabilty player n is best is

Average	At-Bats	Pr[best]	
.347	521	0.12	
.343	623	0.11	
.342	482	0.08	
.330	648	0.04	
.330	607	0.04	
.367	60	0.02	
.322	695	0.02	

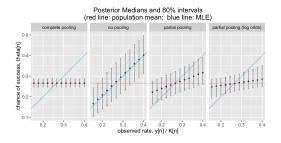
- No clear winner—sample size matters.
- · In last game (of 162), Mauer (Minnesota) edged out Jeter (NY)

Efron & Morris (1975) Data

	FirstName	LastName	Hits	At.Bats	Rest.At.Bats	Rest.Hits
1	Roberto	Clemente	18	45	367	127
2	Frank	Robinson	17	45	426	127
3	Frank	Howard	16	45	521	144
4	Jay	Johnstone	15	45	275	61
5	Ken	Berry	14	45	418	114
6	Jim	Spencer	14	45	466	126
7	Don	Kessinger	13	45	586	155
8	Luis	Alvarado	12	45	138	29
9	Ron	Santo	11	45	510	137
10	Ron	Swaboda	11	45	200	46
11	Rico	Petrocelli	10	45	538	142

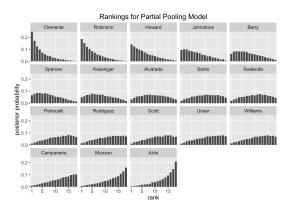
Pooling Estimates

· Case Study: Repeated Binary Trials (mc-stan.org)



Ranking

Posterior Ranks

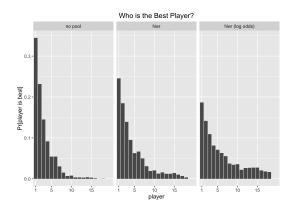


Who is Best? Stan Code

. . .

```
generated quantities {
    ...
    int<lower=0, upper=1> is_best[N]; // Pr[player n highest chand
    ...
    for (n in 1:N)
        is_best[n] <- (rnk[n] == 1);</pre>
```

Who is Best? Posterior



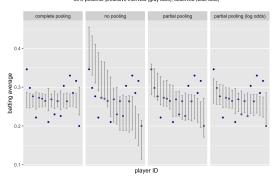
Posterior Predictive Inference

· How do we predict new outcomes (e.g., rest of season)?

Posterior Predictions

Posterior Predictions for Batting Average in Remainder of Season

50% posterior predictive intervals (gray bars); observed (blue dots)



Posterior Predictive Check

· Replicate data from paraemters

```
generated quantities {
  . . .
  for (n in 1:N)
    v_rep[n] <- binomial_rng(K[n], theta[n]);</pre>
  for (n in 1:N)
    v_pop_rep[n] <- binomial_rng(K[n],</pre>
                                     beta_rng(phi * kappa,
                                               (1 - phi) * kappa)):
  min_y_rep <- min(y_rep);</pre>
  sd_y_rep <- sd(to_vector(y_rep));</pre>
  p_min <- (min_y_rep >= min_y);
  p_sd <- (sd_y_rep >= sd_y);
```

Posterior *p***-Values**

