Foundations of Linear Regression

2. Review, Properties and Assumptions, Matrix Form

GOVT 6029 - Spring 2021

Cornell University

Outline

· Office Hours

- · Office Hours
- · Slide Deck

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- Questions, comments?

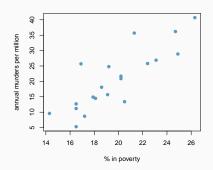
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Your turn

Which of the following is the best guess for the correlation between annual murders per million and percentage living in poverty?

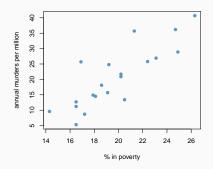
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- (b) -0.63
- (c) -0.12
- (d) 0.02
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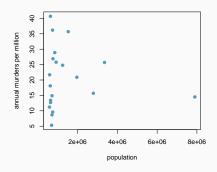
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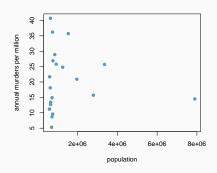
- (a) -0.97
- (b) -0.61
- (c) -0.06
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- (e) 0.97



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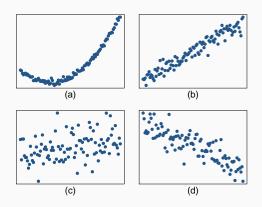
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Assessing the correlation

Your turn

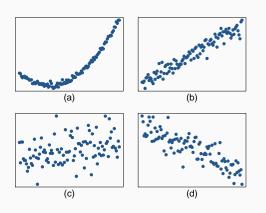
Which of the following is has the strongest correlation, i.e. correlation coefficient closest to +1 or -1?



Assessing the correlation

Your turn

Which of the following is has the strongest correlation, i.e. correlation coefficient closest to +1 or -1?



(b) →
correlation
means
linear
association

Play the game!

http://guessthecorrelation.com/

Spurious correlations

Remember: correlation does not always imply causation! http://www.tylervigen.com/

Outline

(2) Least squares line minimizes squared residuals

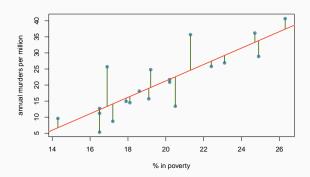
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Interpreting the last squares line

• *Slope*: For each <u>unit</u> increase in <u>x</u>, <u>y</u> is expected to behigher/lower on average by the slope.

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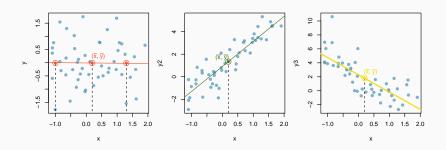
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• The calculation of the intercept uses the fact the a regression line always passes through (\bar{x}, \bar{y}) .

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What is the interpretation of the slope?

$$\widehat{murders} = -29.91 + 2.56$$
 poverty

- (a) Each additional percentage in those living in poverty increases number of annual murders per million by 2.56.
- (b) For each percentage increase in those living in poverty, the number of annual murders per million is expected to be higher by 2.56 on average.
- (c) For each percentage increase in those living in poverty, the number of annual murders per million is expected to be lower by 29.91 on average.
- (d) For each percentage increase annual murders per million, the percentage of those living in poverty is expected to be higher by 2.56 on average.

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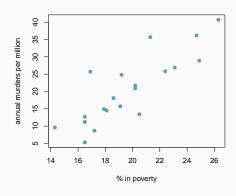
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Your turn

Suppose you want to predict annual murder count (per million) for a series of districts that were not included in the dataset. For which of the following districts would you be most comfortable with your prediction?

A district where % in poverty =

- (a) 5%
- (b) 15%
- (c) 20%
- (d) 26%
- (e) 40%

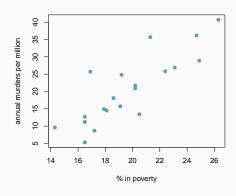


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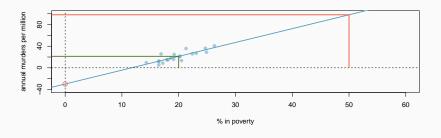
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A note about the intercept

Sometimes the intercept might be an extrapolation: useful for adjusting the height of the line, but meaningless in the context of the data.



Calculating predicted values

By hand:
$$\widehat{murder} = -29.91 + 2.56$$
 poverty

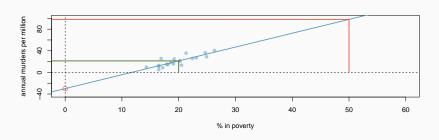
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$$\widehat{murder} = -29.91 + 2.56 \times 20 = 21.29$$



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We can think of social science variables as comprised of two parts:

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Random variables contain both components

We can best understand random variables using probability distributions

Outline

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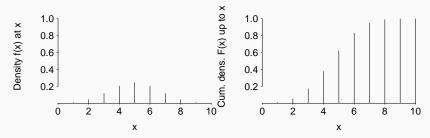
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Thus, for discrete distributions, the cdf is the <u>cumulative sum</u> of the pdf:

$$F(Y) = \sum_{\forall Y \le y} f(Y)$$

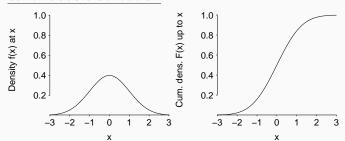
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Thus for continuous distributions, the cdf is the <u>integral</u> of the pdf:

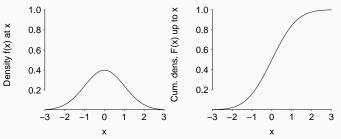
$$F(Y) = \int_{-\infty}^{y} f(Y) dy$$

The Normal (Gaussian) distribution

$$f_{\mathcal{N}}(y|\mu,\sigma^2) = (2\pi\sigma^2)^{-1/2} \exp\left[\frac{-(y_i - \mu)^2}{2\sigma^2}\right]$$

Moments: $E(y) = \mu$ $Var = \sigma^2$

The Normal distribution is continuous and symmetric, with positive probability everywhere from $-\infty$ to ∞



The Normal distribution

What's the big deal about the Normal distribution?

One point of view: perhaps most continuous data are roughly Normally distributed

Why do people believe this?

They think the Central Limit Theorem applies to most data

The Central Limit Theorem

Suppose we have N independent random variables x_1, x_2, x_3, \dots

Each x has an arbitrary probability distribution with mean μ_i and variance $\sigma_i^2 < \infty$

That is to say, these variables are not only independent, they could each have totally different distributions

Now suppose we average them all together into one super-variable,

$$X = \frac{1}{N} \sum_{i} x_{i}$$

The CLT shows that the distribution of this new variable, X, approaches a Normal distribution as $N \to \infty$

The Central Limit Theorem

Proofs of the CLT are somewhat involved, so let's "verify" this by experiment

Flipping coins

The distribution of a coin flip is $\Pr(\mathrm{Heads}) = 0.5$, $\Pr(\mathrm{Tails}) = 0.5$, which is not bell-shaped at all

Suppose we flip M coins, and sum the number of heads.

If we repeat this exercise many times, the CLT says the resulting distribution of counts of heads should be approximately Normal.

For a proof and links on the CLT, see http://mathworld.wolfram.com/CentralLimitTheorem.ht

The Central Limit Theorem

Dropping balls

Dropping a ball through a pegboard mirrors the construction of a Normal random variable

Systematic component: the spot from which the balls are dropped

Stochastic component: the sum of all the random effects of the pegs

Result: a Normal distribution of ball locations

The Normal distribution

So why would many people think most continuous variables in the social sciences are Normal?

They are appealing to a "fuzzy" version of the CLT:

Data generated from many small and unrelated random shocks are approximately normally distributed

One can see why, say, economic growth would be a good candidate for a Normally distributed variable

Application of the main tool introduced in this class, linear regression, usually based on this assumption

Review of simple linear regression

With the Normal distribution in mind, recall the linear regression model

$$y_i = \beta_0 + \beta_1 x_i + \varepsilon_i$$

 $arepsilon_i$ is a normally distributed disturbance with mean 0 and variance σ^2

Equivalently, we write $\varepsilon_i \sim N(0, \sigma^2)$

Note that:

The stochastic component has mean zero: $E(\varepsilon_i) = 0$

The systematic component is: $E(y_i) = \beta_0 + \beta_1 x_i$

The errors are assumed uncorrelated: $E(\varepsilon_i \times \varepsilon_j) = 0$ for all $i \neq j$

Review of simple linear regression

Recalling the definition of variance, note that in linear regression:

$$\sigma^{2} = E\left((\varepsilon - E(\varepsilon))^{2}\right)$$
$$= E\left((\varepsilon - 0)^{2}\right)$$
$$= E(\varepsilon^{2})$$

The square root of σ^2 is known as the standard error of the regression

It is how much we expect y to differ from its expected value, $\beta_0 + \beta_1 x_i$, on average

Scalar representation:

$$y_i = \beta_0 + \beta_1 x_{1i} + \beta_2 x_{2i} + \varepsilon_i$$

Equivalent matrix representation:

$$\mathbf{y} = \mathbf{X} \quad \boldsymbol{\beta} + \boldsymbol{\varepsilon}$$

$$n \times 1 \quad n \times k \quad k \times 1 \quad n \times 1$$

Writing out the matrices:

$$\begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} 1 & x_{11} & x_{21} & \dots & x_{k1} \\ 1 & x_{12} & x_{22} & \dots & x_{k2} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & x_{1n} & x_{2n} & \dots & x_{kn} \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \\ \vdots \\ \beta_k \end{bmatrix} + \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \vdots \\ \varepsilon_n \end{bmatrix}$$

Note that we now have a vector of disturbances.

They have the same properties as before, but we will write them in matrix form.

The disturbances are still mean zero.

$$E(\boldsymbol{\varepsilon}) = \begin{bmatrix} E(\varepsilon_1) \\ E(\varepsilon_2) \\ \vdots \\ E(\varepsilon_n) \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

But now we have an entire matrix of variances and covariances, Σ

$$\Sigma = \begin{bmatrix} \operatorname{var}(\varepsilon_{1}) & \operatorname{cov}(\varepsilon_{1}, \varepsilon_{2}) & \dots & \operatorname{cov}(\varepsilon_{1}, \varepsilon_{n}) \\ \operatorname{cov}(\varepsilon_{2}, \varepsilon_{1}) & \operatorname{var}(\varepsilon_{2}) & \dots & \operatorname{cov}(\varepsilon_{2}, \varepsilon_{n}) \\ \vdots & \vdots & \ddots & \vdots \\ \operatorname{cov}(\varepsilon_{n}, \varepsilon_{1}) & \operatorname{cov}(\varepsilon_{n}, \varepsilon_{2}) & \dots & \operatorname{var}(\varepsilon_{n}) \end{bmatrix}$$

$$= \begin{bmatrix} \operatorname{E}(\varepsilon_{1}^{2}) & \operatorname{E}(\varepsilon_{1}\varepsilon_{2}) & \dots & \operatorname{E}(\varepsilon_{1}\varepsilon_{n}) \\ \operatorname{E}(\varepsilon_{2}\varepsilon_{1}) & \operatorname{E}(\varepsilon_{2}^{2}) & \dots & \operatorname{E}(\varepsilon_{2}\varepsilon_{n}) \\ \vdots & \vdots & \ddots & \vdots \\ \operatorname{E}(\varepsilon_{n}\varepsilon_{1}) & \operatorname{E}(\varepsilon_{n}\varepsilon_{2}) & \dots & \operatorname{E}(\varepsilon_{n}^{2}) \end{bmatrix}$$

However, the above matrix can be written far more compactly as an outer product

$$oldsymbol{\Sigma} = arepsilon arepsilon'$$

Recall $E(\varepsilon_i \varepsilon_j) = 0$ for all $i \neq j$, so all of the off-diagonal elements above are zero by assumption

Recall also that all ε_i are assumed to have the same variance, σ^2

So *if* the linear regression assumptions hold, the variance-covariance matrix has a simple form:

$$\mathbf{\Sigma} = \begin{bmatrix} \sigma^2 & 0 & \dots & 0 \\ 0 & \sigma^2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \sigma^2 \end{bmatrix} = \sigma^2 \mathbf{I}$$

When these assumptions do not hold, we will need more complex models than simple linear regression

So how do we solve for β ?

Let's use the least squares principle: choose $\hat{\beta}$ such that the sum of the squared errors is minimized

In symbols, we want

$$\underset{\beta}{\operatorname{arg \, min}} \sum_{i} \varepsilon_{i}^{2} \quad \text{or, in matrix form} \quad \underset{\beta}{\operatorname{arg \, min}} \varepsilon' \varepsilon$$

This is a straightforward minimization (calculus) problem. The trick is using matrices to simplify notation.

The sum of squared errors can be written out as

$$\varepsilon' \varepsilon = (\mathbf{y} - \mathbf{X} \boldsymbol{\beta})' (\mathbf{y} - \mathbf{X} \boldsymbol{\beta})$$

(what is this notation doing? why do we need the transpose?)

We need two bits of matrix algebra:

$$(\mathbf{A} + \mathbf{B})' = \mathbf{A}' + \mathbf{B}'$$

$$\left(\begin{bmatrix} 10 \\ 3 \end{bmatrix} + \begin{bmatrix} 2 \\ 6 \end{bmatrix} \right)' = \begin{bmatrix} 10 & 3 \end{bmatrix} + \begin{bmatrix} 2 & 6 \end{bmatrix}$$

$$\begin{bmatrix} 12 & 9 \end{bmatrix} = \begin{bmatrix} 12 & 9 \end{bmatrix}$$

and

$$(\mathbf{X}\boldsymbol{\beta})' = \boldsymbol{\beta}'\mathbf{X}'$$

$$\begin{bmatrix} 2 & 1 \\ 5 & 6 \end{bmatrix} \begin{bmatrix} 3 \\ 4 \end{bmatrix} = \begin{bmatrix} 3 & 4 \end{bmatrix} \begin{bmatrix} 2 & 5 \\ 1 & 6 \end{bmatrix}$$

$$\begin{bmatrix} (2 \times 3) + (1 \times 4) \\ (5 \times 3) + (6 \times 4) \end{bmatrix}' = \begin{bmatrix} (3 \times 2) + (4 \times 1) & (3 \times 5) + (4 \times 6) \end{bmatrix}$$

$$\begin{bmatrix} 10 & 39 \end{bmatrix} = \begin{bmatrix} 10 & 39 \end{bmatrix}$$

$$\varepsilon' \varepsilon = (\mathbf{y} - \mathbf{X} \boldsymbol{\beta})' (\mathbf{y} - \mathbf{X} \boldsymbol{\beta})$$

First, we distribute the transpose:

$$\varepsilon' \varepsilon = (\mathbf{y}' - (\mathbf{X}\boldsymbol{\beta})')(\mathbf{y} - \mathbf{X}\boldsymbol{\beta})$$

Next, let's substitute $\beta' X'$ for $(X\beta)'$

$$\varepsilon' \varepsilon = (\mathbf{y}' - \boldsymbol{\beta}' \mathbf{X})(\mathbf{y} - \mathbf{X} \boldsymbol{\beta})$$

Multiplying this out, we get

$$\varepsilon' \varepsilon = y'y - \beta'X'y - y'X\beta + \beta'X'X\beta$$

Simplifying, we get

$$\varepsilon' \varepsilon = \mathbf{y}' \mathbf{y} - 2\beta' \mathbf{X}' \mathbf{y} + \beta' \mathbf{X}' \mathbf{X} \beta$$

Now we need to take the derivative with respect to β , to see which β minimize the sum of squares.

How do we take the derivative of a scalar with respect to a vector?

It's just a bunch of scalar derivatives stacked together:

$$\frac{\partial y}{\partial \mathbf{x}} = \begin{bmatrix} \frac{\partial y}{\partial x_1} & \frac{\partial y}{\partial x_2} & \dots & \frac{\partial y}{\partial x_n} \end{bmatrix}'$$

For example, for a and x both $n \times 1$ vectors

$$y = \mathbf{a}'\mathbf{x} = a_1x_1 + a_2x_2 + \dots + a_nx_n$$

$$\frac{\partial y}{\partial \mathbf{x}} = \begin{bmatrix} a_1 & a_2 & \dots & a_n \end{bmatrix}'$$

$$\frac{\partial y}{\partial \mathbf{x}} = \mathbf{a}$$

A similar pattern holds for quadratic expresssions.

Note the vector analogue of x^2 is the inner product $\mathbf{x}'\mathbf{x}$

And the vector analogue of ax^2 is $\mathbf{x}'\mathbf{A}\mathbf{x}$, where \mathbf{A} is an $n \times n$ matrix of coefficients

$$\frac{\partial ax^2}{\partial x} = 2ax$$

$$\frac{\partial \mathbf{x}' \mathbf{A} \mathbf{x}}{\partial \mathbf{x}} = 2\mathbf{A} \mathbf{x}$$

The details are a bit more complicated (x'Ax) is the sum of a lot of terms, but the intuition is the same.

$$\varepsilon' \varepsilon = \mathbf{y}' \mathbf{y} - 2\beta' \mathbf{X}' \mathbf{y} + \beta' \mathbf{X}' \mathbf{X} \beta$$

Taking the derivative of this expression, and setting it equal to 0, we get

$$\frac{\partial \varepsilon' \varepsilon}{\partial \beta} = -2\mathbf{X}'\mathbf{y} + 2\mathbf{X}'\mathbf{X}\beta = 0$$

This is a mimimum, and the β 's that solve this equation thus minimize the sum of squares.

So let's solve for β :

$$X'X\beta = X'y$$

$$\hat{\boldsymbol{\beta}} = (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{y}$$

This is the least squares estimator for β

As long as we have software to help us with matrix inversion, it is easy to calculate.