## **Generating Random Samples**

We will now generate samples of the Gaussian Distribution with  $\mathcal{N}(\mu).\$  For this we first need to generate the  $\mu\$  and  $\mathcal{N}(\mu).\$  matrices.

In [1]:

```
import numpy as np
import sklearn.datasets as skdataset
```

In [2]:

```
def getMeanAndCovMatrices(dim):
    cov_mat=skdataset.make_spd_matrix(dim)
    mean_vec=np.random.randn(1,dim)[0]
    return mean_vec, cov_mat
```

In [3]:

```
def generateRandomSamples(dim,num_of_samples):
    mean_vec, cov_mat = getMeanAndCovMatrices(dim)
    return np.random.multivariate_normal(mean_vec, cov_mat,(num_of_samples)).reshape(dim,num_of_samples)
```

Generating random samples of 5 dimension

```
In [4]:
```

## **Procedure to claculate Discriminant Function**

For a given Normal Distribution  $\mathcal{N}(\mu,\Sigma)$  and Prior probability  $P(\omega,\Sigma)$  the discriminant function is given by the equation

```
 \$g_i(x)\$ = \$-\frac{1}{2}(x-\mu)^t\Sigma^{-1}(x-\mu)-\frac{d}{2}\ln(2\pi)-\frac{1}{2}\ln|\Sigma_i|+\ln(P(\omega_i)))\$
```

In [5]:

## **Mahalanobis Distance**

```
In [6]:
```

```
def mahalanobis(x_vec,mean_vec,cov_mat):
    difference = x_vec - mean_vec
    cov_inv = np.linalg.inv(cov_mat)
    return np.dot(np.dot(difference.T,cov_inv),difference)
```

## **Euclidean Distance**

```
In [7]:
```

```
def euclidean(p1,p2):
    return mahalanobis(p1,p2,np.identity(p1.shape[0]))
```

## Reading dataset from csv file

```
In [8]:
```

```
data = np.genfromtxt("./synthetic_data.csv",delimiter=',', skip_header=1)
class1_data=data[:10]
class2_data=data[10:20]
class3_data=data[20:30]
```

## Univarite and Multivariate Excersises: (2a, 2b, 2c, 2d)

Given prior probabilities are  $P(\omega_1)=P(\omega_2)=0.5$ 

```
In [9]:
```

```
def dichotomiser(feature_dim, features, labels, prior1, prior2):
   class1 mean = np.mean(features[:10],axis=0).reshape(feature dim,1)
   class2_mean = np.mean(features[10:20],axis=0).reshape(feature_dim,1)
   if(feature dim > 1):
        class1_covariance = np.cov(features[:10].T)
        class2 covariance = np.cov(features[10:20].T)
        class1_covariance = np.var(features[:10],axis=0)
        class2 covariance = np.var(features[10:20],axis=0)
   class1_prior = prior1
   class2 prior = prior2
   prediction = []
   for feature in features:
        feature = feature.reshape(feature_dim,1)
        g1 = discriminant_function(feature_dim, feature, class1_mean, class1_covariance,class1_prior)
        g2 = discriminant function(feature dim, feature, class2 mean, class2 covariance, class2 prior)
        if(g1 - g2 > 0):
           prediction.append(0)
        elif(g1 - g2 < 0):
            prediction.append(1)
   print predictions(labels, prediction)
   print("The Empirical Training error is : ", empirical_error(labels, prediction), "%")
def print_predictions(actual,prediction):
   print("Actual\t\t:\t", actual)
   print("Predicted\t:\t", prediction)
def empirical_error(actual,prediction):
   error_count=0
   for i,val in enumerate(prediction):
        if(actual[i] - val):
            error count += 1
   return (error_count/actual.shape[0]) * 100
```

```
In [10]:
```

```
dichotomiser(1, data[:20,0], data[:20,3], 0.5, 0.5)

Actual : [0. 0. 0. 0. 0. 0. 0. 0. 0. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1.]
Predicted : [1, 1, 0, 0, 0, 1, 0, 0, 1, 0, 0, 0, 1, 1, 1, 0, 1, 1, 1]
The Empirical Training error is : 35.0 %
```

```
In [11]:
dichotomiser(2, data[:20,:2], data[:20,3], 0.5, 0.5)
Actual
                    [\, 0,\ 1,\ 0,\ 0,\ 1,\ 1,\ 1,\ 0,\ 1,\ 0,\ 0,\ 0,\ 1,\ 1,\ 1,\ 0,\ 1,\ 1,\ 1,\ 0\,]
Predicted
The Empirical Training error is: 45.0 %
In [12]:
dichotomiser(3, data[:20,:3], data[:20,3], 0.5, 0.5)
Actual
                    Predicted
                    [0, 0, 0, 0, 1, 0, 0, 0, 1, 0, 1, 1, 1, 1, 1, 0, 1, 1, 1]
The Empirical Training error is : 15.0 %
2e. Claculating the test points Mahalanobis Distances
In [13]:
test points = np.genfromtxt("./test-points.csv",delimiter=",",skip header=1,dtype=int)
test\_points
Out[13]:
```

### In [14]:

array([[1, 2, 1],

[5, 3, 2], [0, 0, 0], [1, 0, 0]])

```
feature_dim=3
class1_mean = np.mean(class1_data[:,:3],axis=0).reshape(feature_dim,1)
class2_mean = np.mean(class2_data[:,:3],axis=0).reshape(feature_dim,1)
class3_mean = np.mean(class3_data[:,:3],axis=0).reshape(feature_dim,1)
class1_covariance = np.cov(class1_data[:,:3].T)
class2_covariance = np.cov(class2_data[:,:3].T)
class3_covariance = np.cov(class3_data[:,:3].T)
prediction = []
for test point in test points:
   test_point=test_point.reshape(feature_dim,1)
   distances = []
   distances.append(mahalanobis(test point,class1 mean,class1 covariance))
   distances.append(mahalanobis(test_point,class2_mean,class2_covariance))
   distances.append(mahalanobis(test_point,class3_mean,class3_covariance))
   prediction.append(distances.index(min(distances)))
print("Predicted classes based on Mahalanobis distance are : ",prediction)
```

Predicted classes based on Mahalanobis distance are : [1, 2, 1, 1]

# 2f. With Change in Prior Probabilities

Now considering the prior probabilities of each of the class as  $P(\omega_1) = 0.8$ ,  $P(\omega_2) = 0.1$ ,  $P(\omega_3) = 0.1$ , predicting the class based on Mahalanobis distance has no effect. But considering the maximum value of LDF we get all the test points in class '0'.

```
In [15]:
```

```
prediction = []
for test_point in test_points:
    test_point=test_point.reshape(feature_dim,1)
    values = []
    values.append(discriminant_function(feature_dim,test_point,class1_mean,class1_covariance,0.8))
    values.append(discriminant_function(feature_dim,test_point,class2_mean,class2_covariance,0.1))
    values.append(discriminant_function(feature_dim,test_point,class3_mean,class3_covariance,0.1))
    prediction.append(values.index(max(values)))
print("Predicted classes are : ",prediction)
```

Predicted classes are : [0, 0, 0, 0]

### **Iris Dataset**

```
In [16]:

iris_dataset = np.genfromtxt("iris.csv",delimiter=",")
labels=["Iris-setosa","Iris-versicolor","Iris-virginica"]

iris_class1 = np.insert(iris_dataset[:50,:4],4,0,axis=1)
iris_class2 = np.insert(iris_dataset[50:100,:4],4,1,axis=1)
iris_class3 = np.insert(iris_dataset[100:150,:4],4,2,axis=1)
```

```
In [17]:

feature_dim=4
    iris_samples1 = iris_class1[:,:4]
    iris_samples2 = iris_class2[:,:4]
    iris_samples3 = iris_class3[:,:4]

    iris_class1_mean = np.mean(iris_samples1,axis=0).reshape(feature_dim,1)
    iris_class2_mean = np.mean(iris_samples2,axis=0).reshape(feature_dim,1)
    iris_class3_mean = np.mean(iris_samples3,axis=0).reshape(feature_dim,1)

#Case III Covariance matrices:
    iris_class1_covariance = np.cov(iris_samples1.T)
    iris_class2_covariance = np.cov(iris_samples2.T)
    iris_class3_covariance = np.cov(iris_samples3.T)

#Case I Covariance matrix:
    var1 = np.mean(iris_class1_covariance.diagonal())
    var2 = np.mean(iris_class2_covariance.diagonal())
```

cov\_mat2 = (1/3 )\* (iris\_class1\_covariance + iris\_class2\_covariance + iris\_class3\_covariance)

## Iris Data Case 1

#Case II Covariance matrix:

```
The LDF for Case 1 is given by the equation:
```

average var = (var1 + var2 + var3)/3

var3 = np.mean(iris\_class3\_covariance.diagonal())

[[43.33686853 19.56342547 36.52190256 13.32733692]]

cov\_mat1 = average\_var\*np.identity(feature\_dim)

#### Calculating \$W\_i^T\$

```
In [18]:
```

```
w1_t = iris_class1_mean.T / average_var
w2_t = iris_class2_mean.T / average_var
w3_t = iris_class3_mean.T / average_var
print(w1_t,w2_t,w3_t,sep="\n")
[[32.93023131 22.48412517 9.63041523 1.6050692 ]]
[[39.04791311 18.22148237 28.02292956 8.72263019]]
```

## Calculating \$W {i0}\$

```
In [19]:
```

```
w10 = (- 0.5) * (np.dot(iris_class1_mean.T,iris_class1_mean) / average_var) + np.log(1/3)
w20 = (- 0.5) * (np.dot(iris_class2_mean.T,iris_class2_mean) / average_var) + np.log(1/3)
w30 = (- 0.5) * (np.dot(iris_class3_mean.T,iris_class3_mean) / average_var) + np.log(1/3)
print(w10,w20,w30,sep="\n")
```

```
[[-129.19363357]]
[[-207.70151527]]
[[-287.82646472]]
```

By substituting the values of \$W\_i^T\$ and \$W\_{i0}\$ in equation (1) we get the Case 1 LDF for Iris dataset

```
g_1(x) = 32.93* x_1 + 22.48 * x_2 + 9.63 * x_3 + 1.60 * x_4 - 129.19$

g_2(x) = 39.05* x_1 + 18.22 * x_2 + 28.02 * x_3 + 8.72 * x_4 - 207.70$
g_3(x) = 43.34* x_1 + 19.56 * x_2 + 36.52 * x_3 + 13.33 * x_4 - 287.83$
```

## **Iris Data Case 2**

```
The LDF for Case 2 is given by the equation:
```

#### Calculating \$W i^T\$

```
In [20]:
```

```
w1_t = np.dot(iris_class1_mean.T,np.linalg.inv(cov_mat2).T)
w2_t = np.dot(iris_class2_mean.T,np.linalg.inv(cov_mat2).T)
w3_t = np.dot(iris_class3_mean.T,np.linalg.inv(cov_mat2).T)
print(w1_t,w2_t,w3_t,sep="\n")
```

```
[[ 23.46638411 23.56828007 -16.20296668 -18.02533894]]
[[15.70349917 6.95425598 5.28429325 6.29830031]]
[[12.49061995 3.44398145 12.82207622 21.06272174]]
```

### Calculatin \$W\_{i0}\$

In [21]:

```
w10 = (- 0.5) * np.dot(np.dot(iris_class1_mean.T,np.linalg.inv(cov_mat2)),iris_class1_mean) + np.log(1/3)
w20 = (- 0.5) * np.dot(np.dot(iris_class2_mean.T,np.linalg.inv(cov_mat2)),iris_class2_mean) + np.log(1/3)
w30 = (- 0.5) * np.dot(np.dot(iris_class3_mean.T,np.linalg.inv(cov_mat2)),iris_class3_mean) + np.log(1/3)
print(w10,w20,w30,sep="\n")
```

```
[[-86.05349939]]
[[-72.76956007]]
[[-104.2945355]]
```

By substituting the values of \$W\_i^T\$ and \$W\_{i0}\$ in equation (2) we get the Case 2 LDF for Iris dataset

```
$g_1(x) = 23.46* x_1 + 23.57* x_2 - 16.20* x_3 - 18.025* x_4 - 86.05$
$g_2(x) = 15.70* x_1 + 6.95* x_2 + 5.28* x_3 + 6.29* x_4 - 72.77$
$g_3(x) = 12.49* x_1 + 3.44* x_2 + 12.82* x_3 + 21.06* x_4 - 104.294$
```

## Iris Case 3

The QDF for Case 3 is given by the equation:

 $g(x) = x^t + w(x) + w$ 

```
\label{eq:windows} Where, $$ W_i = -\frac{1}{2}\sigma_i $$ $$ w_i = \sum_i^{-1}\mu_i $$ $$ w_{i0} = -\frac{1}{2}\mu_i -\frac{1}{2}\mu_i -\frac{1}{2}\ln |\nabla + \ln(P(\omega_i)) $$
```

## Calculating \${W\_i}\$

```
In [22]:

W1 = (- 0.5) * iris_class1_covariance
W2 = (- 0.5) * iris_class2_covariance
W3 = (- 0.5) * iris_class3_covariance
print(W1,W2,W3,sep="\n\n")

[[-0.06212449 -0.05014898 -0.005014898 -0.00806939 -0.00527347]
[-0.05014898 -0.0725898 -0.00584082 -0.00571837]
[-0.00806939 -0.00584082 -0.01505306 -0.00284898]
[-0.00527347 -0.00571837 -0.00284898 -0.00574694]]

[[-0.13321633 -0.04259184 -0.09144898 -0.0278898 ]
[-0.04259184 -0.04923469 -0.04132653 -0.02060204]
[-0.09144898 -0.04132653 -0.11040816 -0.03655102]
[-0.0278898 -0.02060204 -0.03655102 -0.01955306]]

[[-0.20217143 -0.04688163 -0.1516449 -0.02454694]
[-0.04688163 -0.05200204 -0.0356898 -0.02381429]
```

### Calculating \$w i\$

[-0.1516449 -0.0356898 -0.15229388 -0.02441224] [-0.02454694 -0.02381429 -0.02441224 -0.03771633]]

In [23]:

6.23406948 9.66197608]]

## Calculating \$W\_{i0}\$

[[ 7.37247478 13.2452613

In [24]:

```
w10 = (- 0.5 * np.dot(np.dot(iris_class1_mean.T,np.linalg.inv(iris_class1_covariance)),iris_class1_mean)) -
(0.5 * np.log(np.linalg.det(iris_class1_covariance))) + np.log(1/3)
w20 = (- 0.5 * np.dot(np.dot(iris_class2_mean.T,np.linalg.inv(iris_class2_covariance)),iris_class2_mean)) -
(0.5 * np.log(np.linalg.det(iris_class3_covariance))) + np.log(1/3)
w30 = (- 0.5 * np.dot(np.dot(iris_class3_mean.T,np.linalg.inv(iris_class3_covariance)),iris_class3_mean)) -
(0.5 * np.log(np.linalg.det(iris_class3_covariance))) + np.log(1/3)
print(w10,w20,w30,sep="\n")
[[-113.86317185]]
```

```
[[-68.43728769]]
[[-67.7090772]]
```

By substituting these values of  $W_i$  and  $W_i$  and  $W_i$  and  $W_i$  are quation 3 we get the Quadratic Discriminant Function for Iris dataset