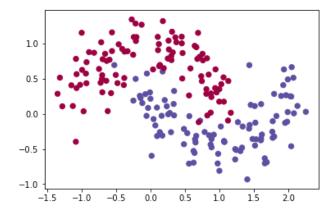
Implement a 2-layer Neural Network using Backpropagation

```
In [8]: # Import packages
   import numpy as np
   import sklearn
   from sklearn import datasets
   import matplotlib.pyplot as plt
%matplotlib inline
```

```
In [9]: # Generate a toy dataset and plot it
    np.random.seed(0)
    X, y = sklearn.datasets.make_moons(200, noise=0.20)
    plt.scatter(X[:,0], X[:,1], s=40, c=y, cmap=plt.cm.Spectral)
```

Out[9]: <matplotlib.collections.PathCollection at 0x7fc2cc028438>



```
In [10]: # Define helper functions
          def predict(W, X):
              # Forward pass
              z_h1 = np.dot(X, W['W_input_h1']) + W['b_input_h1']
              a_h1 = np.tanh(z_h1)
              z_h2 = np.dot(a_h1, W['W_h1_h2']) + W['b_h1_h2']
              a h2 = np.tanh(z h2)
              output = np.dot(a_h2, W['W_h2_output']) + W['b_h2_output']
              probs = sigmoid(output)
              probs = probs.squeeze()
              predictions = np.zeros(probs.shape[0])
              predictions[probs>0.5] = 1
              return predictions
          def cross_entropy_loss(t_hat, t):
              return np.sum(-(t*np.log(t_hat) + (1-t)*np.log(1-t_hat)))
          def sigmoid(x):
              return 1/(1 + np.exp(-x))
          def sigmoid_grad(x):
              return sigmoid(x)*(1-sigmoid(x))
          def tanh grad(x):
               return 1 - np.tanh(x)**2
          def plot_decision_boundary(W):
              # Set min and max values and give it some padding 
x_min, x_max = X[:, 0].min() - .5, X[:, 0].max() + .5 
y_min, y_max = X[:, 1].min() - .5, X[:, 1].max() + .5
              h = 0.01
              # Generate a grid of points with distance h between them
              xx, yy = np.meshgrid(np.arange(x_min, x_max, h), np.arange(y_min, y_max
          , h))
              # Predict the function value for the whole gid
              Z = predict(W, np.c_[xx.ravel(), yy.ravel()])
              Z = Z.reshape(xx.shape)
              # Plot the contour and training examples
              plt.contourf(xx, yy, Z, cmap=plt.cm.Spectral)
              plt.scatter(X[:, 0], X[:, 1], c=y, cmap=plt.cm.Spectral)
```

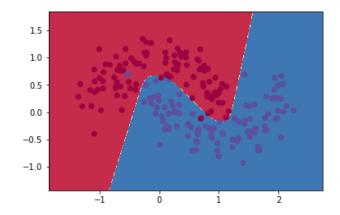
```
In [11]: # Create the model architecture
input_dim = 2
nodes_hidden_1 = 3
nodes_hidden_2 = 3
output_dim = 1

W = {
    'W_input_h1' : np.random.rand(input_dim, nodes_hidden_1),
    'b_input_h1' : np.random.rand(nodes_hidden_1),
    'W_h1_h2' : np.random.rand(nodes_hidden_1),
    'b_h1_h2' : np.random.rand(nodes_hidden_2),
    'b_h1_h2' : np.random.rand(nodes_hidden_2),
    'W_h2_output' : np.random.rand(nodes_hidden_2, output_dim),
    'b_h2_output' : np.random.rand(output_dim)
}
```

```
In [12]: # Train using Gradient Descent
          learning_rate = 0.01
          no_{epochs} = 2000
          for epoch in range(no_epochs):
              # Forward pass
              z_h1 = np.dot(X, W['W_input_h1']) + W['b_input_h1']
              #print(z h1[1,1])
              a h1 = np.tanh(z h1)
              #print( W['W_input_h1'])
              z_h2 = np.dot(a_h1, W['W_h1_h2']) + W['b_h1_h2']
              #print(z h2.shape)
              a h2 = np.tanh(z h2)
              #print(a h2.shape)
              output = np.dot(a_h2, W['W_h2_output']) + W['b_h2_output']
              #print(W['W_input_h1'].shape)
              probs = sigmoid(output)
              probs = probs.squeeze()
              #~~~~~ YOUR CODE BEGINS HERE ~~~~~~~
              delta3 = (probs - y).reshape(200,1)
              delta2 = delta3 @ W['W_h2_output'].T * (1 - np.power(a_h2, 2))
              delta1 = delta2 @ W['W_h1_h2'].T * (1 - np.power(a_h1, 2))
              dWout = a h2.T @ delta3
              dbout = np.sum(delta3, axis=0, keepdims=True).reshape(output_dim,)
              dW2 = a_h1.T @ delta2
              db2 = np.sum(delta2, axis=0, keepdims=True).reshape(nodes_hidden_2,)
              dW1 = X.T @ delta1
              db1 = np.sum(delta1, axis=0, keepdims=True).reshape(nodes hidden 1,)
              # Gradient Descent
              W['W_input_h1'] += -1 * learning_rate * dW1
W['b_input_h1'] += -1 * learning_rate * db1
              W['W_h1_h2'] += -1 * learning_rate * dW2
W['b_h1_h2'] += -1 * learning_rate * db2
              W['W_h2_output'] += -1 * learning_rate * dWout
              W['b_h2_output'] += -1 * learning_rate * dbout
              #~~~~~ YOUR CODE ENDS HERE ~~~~~~~~
              loss = cross_entropy_loss(probs, y)
              if epoch%100 == 0:
                  print("Loss after epoch ", epoch, " : ", loss)
```

```
Loss after epoch 0 : 157.625124238
                 100 : 58.0230836875
Loss after epoch
Loss after epoch
                      :
                          47.8963790291
                 200
Loss after epoch
                 300 :
                          14.3334810612
Loss after epoch
                          13.2279477282
                 400
Loss after epoch
                  500
                          12.717457716
Loss after epoch
                  600
                          18.5371437118
                  700
                          12.141548192
Loss after epoch
Loss after epoch
                  800
                          11.7234249244
Loss after epoch
                  900 :
                          11.5023376869
Loss after epoch
                           11.7606812565
                  1000 :
Loss after epoch
                  1100
                           16.3219752991
                  1200
                           11.2307388833
Loss after epoch
Loss after epoch
                  1300
                           10.947078349
Loss after epoch
                  1400
                           11.0909588534
Loss after epoch
                  1500
                           14.587772505
Loss after epoch
                  1600
                           10.7264706409
Loss after epoch
                  1700
                           10.568560292
Loss after epoch
                  1800
                           12.7525283002
Loss after epoch
                  1900
                           10.6848849173
```

In [13]: # Plot the decision boundary plot_decision_boundary(W)



In []: