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Topic: Topic4 Source: Lecture 4

Why are the Forward and Viterbi algorithms considered to be dynamic programming, and why do we care?

Topic: Topic3 Source: Lecture 3

Describe the noisy channel model, and how it can be used to represent POS-Tagging.

Topic: Topic3 Source: Lecture 3

If our vocabulary consists of just symbols A and B, and our corpus consists of the sequence: B A B A, and we build a bigram language model by applying add-one smoothing to the MLE from the corpus, what is the probability of P(B||A)? Please show your work.

Topic: Topic2 Source: Lecture 2

Imagine we were using k-means to cluster misspelling around their correct spellings. How many clusters would we need, and what would be a good distance function? Explain.

Topic: Topic1 Source: Lecture 1

Discuss why one might do unsupervised learning instead of supervised learning.

Topic: Topic4 Source: Lecture 4

How is it that EM can arrive at a good solution, even if we have a random initialization of parameters?

Topic: Topic1 Source: Lecture 1

When is Manhattan distance more appropriate than Euclidean distance?

Topic: Topic2 Source: Lecture 2

Why is the Forgy initialization sub-optimal?

Topic: Coding Source: Lecture 4

Please answer the following question.

Imagine we have the following randomly-initialized probabilities:

```
1 2 3 4 5
EMIT: 1 [0.2 0.3 0.3 0.2 0.0]
2 [0.3 0.1 0.1 0.1 0.4]
3 [0.0 0.5 0.4 0.0 0.1]

1 2 3
<s>[0.3 0.4 0.3]
TRAN: 1 [0.0 0.3 0.7]
2 [0.4 0.1 0.5]
3 [0.5 0.3 0.2]
```

And imagine we had 3 sentences in our corpus that were tagged in the following way after the E-step

- 1 3 2: 2 3 1 1 4 5: 3 2 3
- 5 4 2: 2 1 3

Is the initial probability for state 2 going to be higher or lower after this iteration? What about the transition probability from state 3 to state 1? And finally, the emission probability of word 4 given state 2? Briefly explain.

END OF QUIZ