



Tingbot assembly:

- Push the buttons onto the button board.
- 2 Flip up the ribbon cable connector on the screen module.
- 3 Slide the **ribbon cable** into the connector (ensure the blue tab is face up).

 Lock the **ribbon cable** in place by flipping the connector back down.
- (4) Push the screen module onto the Raspberry Pi GPIO pins (ensure cable passes between the module and the Pi).
- (5) Place cap A on a flat surface. Push the assembled screen module & Raspberry Pi into the slots that grip the circuit boards.

- $ig(oldsymbol{6} ig)$ Push the **button board** into the slot.
- (7) Repeat step (5) for cap B.

the connector back in.

- 8 Connect the micro USB cable from the button board to the Raspberry Pi.
- Pull out the ribbon cable connector on the button board.
 Slide the ribbon cable into the connector and click into place (ensure cable is not twisted and the blue tab is facing the Raspberry Pi).
 Lock the ribbon cable in place by pushing
- 10 Place the **wrap** face down. Fold the seven score lines back to form the outer shell.
- 11) Attach **sticky feet** to the etched circles on the bottom of the **wrap**.

- (12) Fold the **wrap** around the structure and clip into place.
- Use a Philips #00 screwdriver to screw the mini screws in place.
- (14) Insert a Wi-Fi dongle into one of the Raspberry Pi USB ports (or connect an ethernet cable to the ethernet port).
- (15) Time to set up Tide and Tingbot OS.
- Once setup is complete, eject the **micro SD** card and insert it into **Tingbot**.
- (17) Plug a micro USB charger into the back of Tingbot and you're good to go!



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