

# CMSE 820 HW 10

Hao Lin

November 27, 2018

## 1 Question 1

Define the local charts on  $S^2 = \{(x, y, z) : x^2 + y^2 + z^2 = 1\}$  using: (1) polar coordinate representation; (2) stereographical projection.

Let  $\Omega_1 = S^2 \setminus \{0, 0, 1\}$  and  $\Omega_2 = S^2 \setminus \{0, 0, -1\}$  be two open sets in  $\mathbb{R}^3$ . Then  $C = \{\Omega_i : i \in \{1, 2\}\}$  is an open cover of  $S^2$ .

Applying **stereographical projection** for these two open sets, we can define the following mappings

$$\phi_1 : \Omega_1 \rightarrow \mathbb{R}^2, \phi_1(x, y, z) = \left( \frac{x}{1-z}, \frac{y}{1-z} \right),$$

$$\phi_1^{-1} : \mathbb{R}^2 \rightarrow \Omega_1, \phi_1^{-1}(X, Y) = \left( \frac{2X}{1+X^2+Y^2}, \frac{2Y}{1+X^2+Y^2}, \frac{-1+X^2+Y^2}{1+X^2+Y^2} \right),$$

$$\phi_2 : \Omega_2 \rightarrow \mathbb{R}^2, \phi_2(x, y, z) = \left( \frac{x}{1+z}, \frac{y}{1+z} \right),$$

$$\phi_2^{-1} : \mathbb{R}^2 \rightarrow \Omega_2, \phi_2^{-1}(X, Y) = \left( \frac{2X}{1+X^2+Y^2}, \frac{2Y}{1+X^2+Y^2}, \frac{1-X^2-Y^2}{1+X^2+Y^2} \right).$$

It is easy to check that  $\phi_1$  and  $\phi_2$  are homeomorphisms, so they are two local charts under the stereographical projection that form an atlas of  $S^2$ .

Rewriting the Cartesian coordinate representation of  $S^2$  in the **polar coordinate representation**, we have a different set of local charts (Technically speaking, these are *not* homeomorphisms, because  $[0, \infty) \times [0, 2\pi)$  is not open in  $\mathbb{R}^2$ .),

$$\psi_1 : \Omega_1 \rightarrow [0, \infty) \times [0, 2\pi), \psi_1(x, y, z) = \left( \frac{\sqrt{x^2 + y^2}}{1-z}, \arccos \frac{y}{x} \right),$$

$$\psi_1^{-1} : [0, \infty) \times [0, 2\pi) \rightarrow \Omega_1, \psi_1^{-1}(r, \theta) = \left( \frac{2r \cos \theta}{1+r^2}, \frac{2r \sin \theta}{1+r^2}, \frac{r^2-1}{1+r^2} \right),$$

$$\psi_2 : \Omega_2 \rightarrow [0, \infty) \times [0, 2\pi), \quad \psi_2(x, y, z) = \left( \frac{\sqrt{x^2 + y^2}}{1 + z}, \arccos \frac{y}{x} \right),$$

$$\psi_2^{-1} : [0, \infty) \times [0, 2\pi) \rightarrow \Omega_2, \quad \psi_2^{-1}(r, \theta) = \left( \frac{2r \cos \theta}{1 + r^2}, \frac{2r \sin \theta}{1 + r^2}, \frac{-r^2 + 1}{1 + r^2} \right).$$

## 2 Question 2

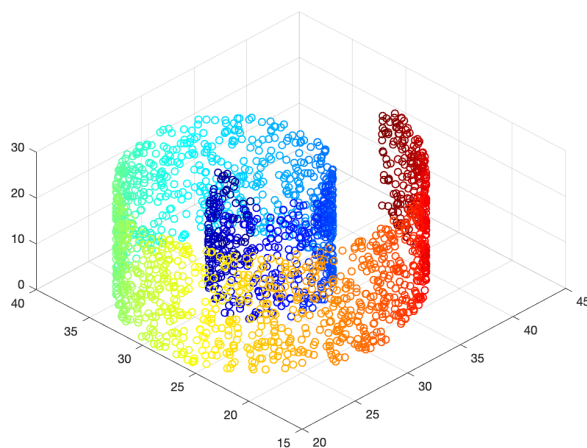


Figure 1: Original data in 3D.

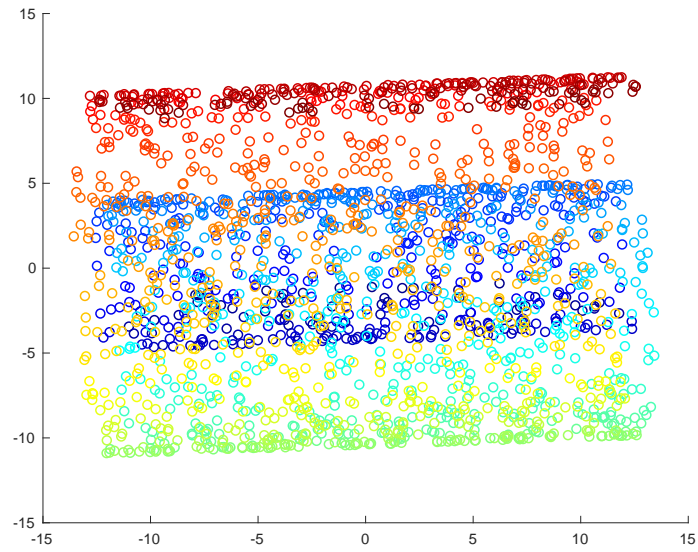


Figure 2: PCA. Data projected onto the top 2 PCs.

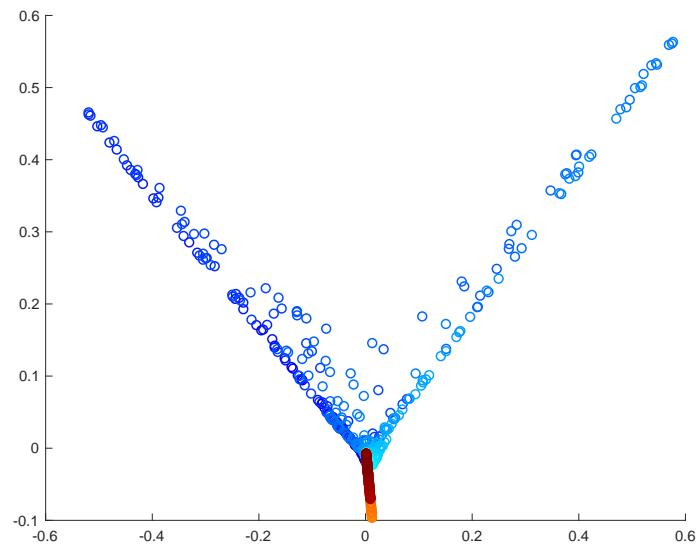


Figure 3: Kernel PCA. Data projected onto the top 2 PCs.  $\sigma = 1.3$  is used.

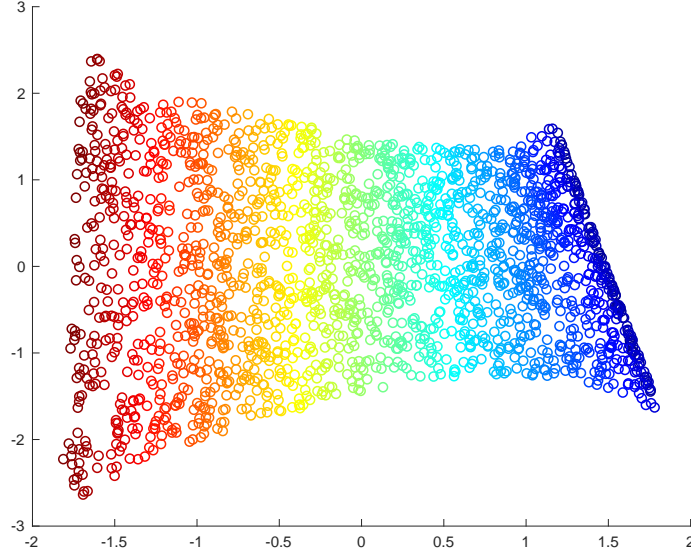


Figure 4: LLE with 12-nearest neighbours. Data reduced to 2D is plotted.

Kernel PCA is only able to separate the data points into 3 rays of similar color, which still differs quite a great deal from the original data. LLE, on the other hand, is capable of “unrolling” the data, restoring the 2D-manifold features (almost perfectly). When the high-dimensional data resembles some low-dimensional manifold embedded in the high-dimensional space, LLE outperforms plain kernel PCA.

### 3 Question 3

Laplacian Eigenmaps (LE).

Let  $x_1, \dots, x_n \in \mathbb{R}^p$  be the high dimensional data points. For any fixed scalar  $\epsilon > 0$ ,  $x_i$  and  $x_j$  are called  $\epsilon$ -neighbours of each other if and only if  $\|x_i - x_j\|_2 \leq \epsilon$ . Fix another scalar  $\sigma^2 > 0$ , and we can define a weight  $w_{ij} = \exp(-\frac{\|x_i - x_j\|_2^2}{\sigma^2})$  if  $x_i$  and  $x_j$  are  $\epsilon$ -neighbours and  $w_{ij} = 0$  otherwise. A reasonable low dimensional embedding  $y_1, \dots, y_n$  minimizes the following objective function

$$\sum_{i,j} w_{ij} \|y_i - y_j\|_2^2.$$

#### 3.1 a

Prove that  $\min \frac{1}{2} \sum w_{ij} \|y_i - y_j\|_2^2 = \min \text{Tr}(YLY^T)$ , where  $Y = [y_1, \dots, y_n]$  and  $L = D - A$  with  $A_{ij} = w_{ij}$  and  $D$  being a diagonal matrix with  $D_{ii} = \sum_j w_{ij}$ . The matrix  $L$  is called graph laplacian.

Proof: Starting from the summation, we have

$$\begin{aligned}
\frac{1}{2} \sum_{ij} w_{ij} \|y_i - y_j\|_2^2 &= \frac{1}{2} \sum_{ij} w_{ij} (y_i^T y_i - y_i^T y_j - y_j^T y_i + y_j^T y_j) \\
&= \frac{1}{2} [2 \sum_i (\sum_j w_{ij}) y_i^T y_i - 2 \sum_{ij} w_{ij} y_i^T y_j] \\
&= \sum_i (\sum_j w_{ij}) y_i^T y_i - \sum_{ij} w_{ij} y_i^T y_j.
\end{aligned}$$

Starting from the trace, we have

$$\begin{aligned}
\text{Tr}(YLY^T) &= \sum_i (YLY^T)_{ii} \\
&= \sum_i [\sum_{jk} Y_{ij} L_{jk} (Y^T)_{ki}] \\
&= \sum_i (\sum_{jk} Y_{ij} L_{jk} Y_{ik}) \\
&= \sum_{jk} L_{jk} (\sum_i Y_{ij} Y_{ki}) \\
&= \sum_{jk} L_{jk} y_j^T y_k \\
&= \sum_{ij} (D_{ij} - A_{ij}) y_i^T y_j \\
&= \sum_{ij} (\sum_k w_{ik}) \delta_{ij} y_i^T y_j - \sum_{ij} w_{ij} y_i^T y_j \\
&= \sum_i (\sum_j w_{ij}) y_i^T y_i - \sum_{ij} w_{ij} y_i^T y_j \\
&= \frac{1}{2} \sum_{ij} w_{ij} \|y_i - y_j\|_2^2.
\end{aligned}$$

### 3.2 b

$$\hat{Y} = \arg \min_Y \text{Tr}(YLY^T) \text{ subject to } YDY^T = I \text{ and } YD\mathbf{1} = \mathbf{0}.$$

Show that the solutions  $\hat{Y} \in \mathbb{R}^{d \times n}$  are given by the eigenvectors corresponding to the lowest  $d$  eigenvalues of the generalized eigenvalue problem

$$Ly = \lambda Dy.$$

Proof: We ignore the constraint  $YD\mathbf{1} = \mathbf{0}$  for the time being and write down the Lagrangian

$$L(Y, \Lambda) = \text{Tr}(YLY^T) + \langle \Lambda, I - YDY^T \rangle,$$

where  $\Lambda$  is the symmetric Lagrangian matrix coefficients, because  $YDY^T$  is symmetric. Taking the derivative respect to  $Y$ , we have

$$\frac{\partial L}{\partial Y} = 2(LY^T - \Lambda DY^T).$$

Setting the derivative to be 0 and rewriting  $\Lambda = U\Sigma U^T$  in terms of its eigenvalue decomposition with  $\Sigma$  being diagonal and  $U$  being orthogonal,

$$LY^T - \Lambda DY^T = LY^T - U\Sigma U^T DY^T = LY^T - U\Sigma DU^T Y^T = 0 \implies LY' = DY'\Sigma, (*)$$

where  $Y' = (UY)^T$  and we have used the fact that matrix multiplication with any diagonal matrix is commutative.

Note that for any  $Y$  and any orthogonal matrix  $O$ ,  $\text{Tr}(YLY^T) = \text{Tr}((OY)L(OY)^T)$ .  $\hat{Y}$  can be determined at most up to rotations. This suggests that we should solve the generalized eigenvalue problem

$$Ly = \lambda Dy. (**)$$

Furthermore, we should show that for any  $y^*$  satisfying equation (\*\*),  $\mathbf{1}^T Dy^* = 0$ .

$$\begin{aligned} \mathbf{1}^T Dy^* &= \mathbf{1}^T \frac{1}{\lambda} Ly = 0 \\ \iff \mathbf{1}^T L &= \mathbf{0}^T \\ \iff \forall j, \sum_i L_{ij} &= \sum_i D_{ij} - A_{ij} = D_{ii} - \sum_j W_{ij} = \sum_j W_{ij} - \sum_j W_{ij} = 0. \end{aligned}$$

So we can let  $\hat{Y} = [y_1, \dots, y_d]^T$  such that  $y_1, \dots, y_d$  are solutions to the generalized eigenvalue problem corresponding to the smallest eigenvalues (arranged in ascending order). It is clear that  $\hat{Y}D\hat{Y}^T = I$  and  $\hat{Y}D\mathbf{1} = \mathbf{0}$ .

## 4 Question 4

In the derivation of LLE, we define

$$M = (I_N - W)^T(I_N - W).$$

Prove that  $M\mathbf{1} = \mathbf{0}$ .

Proof: Recall that

$$\forall i, \sum_j W_{ij} = W_{i,\cdot}\mathbf{1} = 1.$$

It follows that

$$W\mathbf{1} = \mathbf{1}.$$

Hence,

$$M\mathbf{1} = (I_N - W)^T(I_N - W)\mathbf{1} = (I_N - W)^T(\mathbf{1} - \mathbf{1}) = \mathbf{0}.$$