Differential Equations Week ${f 11}$

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Problem 1 (Problem 1)

For the differential equations:

$$x' = y \tag{1.0}$$

$$y' = -x + x^3, (1.0)$$

- (a) Sketch the direction field using computer software.
- (b) Find whether the solution passing through each of the following points is periodic:

i. (0.25, 0.25)

ii. (2,2)

iii. (1,0)

Solution 1.1 (Phase planes are cool! - 1a) —

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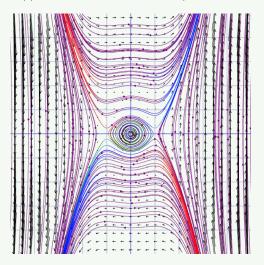


Figure 1.1: Phase plane of differential equation.

Example (Answers 1b). My answers are:

i. (0.25, 0.25): Why not?

ii. (2,2): No way.

iii. (1,0): Even better: critical point, you're never leaving.

Problem 2

For the differential equations

$$x' = y \tag{2.0}$$

$$y' = -x - x^3, \tag{2.1}$$

- (a) Sketch the direction field using computer software.
- (b) Conjecture whether all solutions are bounded.
- (c) Solve the phase plane differential equation.

Solution 2.1 (Phase planes are cool! - 2a) — Created with https://aeb019.hosted.uark.edu/pplane.html

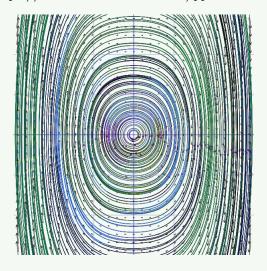


Figure 2.1: Phase plane of differential equation.

Solution 2.2 (Answer 2b) — Why not? Looks like it.

Solution 2.3 (Solution 2c) — We have:

$$\frac{dy}{dx} = \frac{-x - x^3}{y} \tag{2.2}$$

$$y^2 = C - x^2 - \frac{x^4}{2} \tag{2.3}$$

$$y = \sqrt{C - x^2 - \frac{x^4}{2}}. (2.4)$$

Also this is literally a Duffing Equation in disguise so of course it's

periodic.

Problem 3

For the differential equations:

$$x' = (x-1)(y-1) (3.0)$$

$$y' = y(y-1),$$
 (3.1)

- (a) Construct the phase plane analysis by hand, and graph, without using computer software, the asymptotic behaviour of trajectories (as $t \to \infty$).
- (b) Sketch the direction field using computer software.
- (c) Solve the differential equation.

Solution 3.1 —

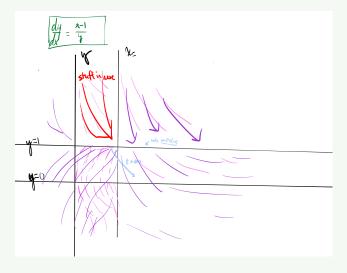
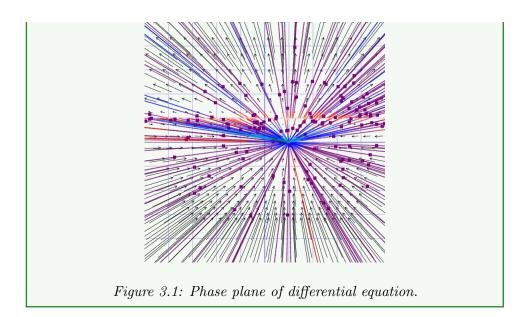


Figure 3.1: Hand-drawn phase plane of differential equation.

Solution 3.2 —

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Solution 3.3 — We solve for y, then x.

Note that by seperation of variables

$$y' = y(y-1) \tag{3.2}$$

$$\frac{y'}{y(y-1)} = 1 (3.3)$$

$$y' = y(y - 1)$$

$$\frac{y'}{y(y - 1)} = 1$$

$$\int \frac{dy}{y(y - 1)} = t$$

$$\log \left| \frac{y - 1}{y} \right| = t + C$$

$$\frac{y - 1}{y} = Ce^{t}$$

$$y(1 - Ce^{t}) = -1$$

$$y = \frac{1}{Ce^{t} - 1}$$
(3.2)
(3.3)
(3.4)
(3.5)
(3.6)

$$\log \left| \frac{y-1}{y} \right| = t + C \tag{3.5}$$

$$\frac{y-1}{y} = Ce^t \tag{3.6}$$

$$y(1 - Ce^t) = -1 (3.7)$$

$$y = \frac{1}{Ce^t - 1} \tag{3.8}$$

Problem 4

Consider the system:

$$v' = -x + \frac{1}{\lambda - x} \tag{4.0}$$

$$x' = v. (4.1)$$

- (a) Solve this equation in the phase plane.
- (b) Find the critical points of this system.
- (c) Plot the phase plane diagrams for $\lambda = 1, 3$ and describe x for $\lambda = 1, 3$ under various initial conditions.

Solution 4.1 — We note that:

$$\frac{dv}{dx} = \frac{-x + 1/(\lambda - x)}{v} \tag{4.2}$$

$$\frac{v^2}{2} = \int -x + \frac{1}{\lambda - x} \, dx \tag{4.3}$$

$$= -\frac{x^2}{2} - \log|x - \lambda| + C \cdot v^2 \qquad = C - x^2 - \log((x - \lambda)^2) \quad (4.4)$$

$$v = \pm \sqrt{C - x^2 - \log((x - \lambda)^2)}$$
 (4.5)

(4.6)

Solution 4.2 —

Observation 4.1 — v = 0 for any critical point. (obviously, bottom equation).

Now:

$$0 = -x + \frac{1}{\lambda - x} \tag{4.7}$$

$$x = \frac{1}{\lambda - x} \tag{4.8}$$

$$x^2 - \lambda x + 1 = 0 (4.9)$$

$$x = \frac{\lambda \pm \sqrt{\lambda^2 - 4}}{2}.\tag{4.10}$$

Thus to have critical points, we need $\lambda < 2$.

Solution 4.3 —

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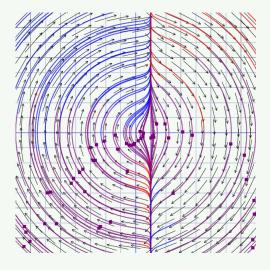


Figure 4.1: Phase plane of differential equation, $\lambda = 1$.

It acclerates, faster and faster, until it has reached the wire.

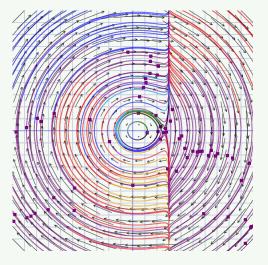


Figure 4.2: Phase plane of differential equation, $\lambda = 3$.

It will perform behaviour as earlier, but with a bit more of a detour around the zone of stability and closed paths.