# **Room-wise Unique Object Detection**

## **Project Objective**

Build a computer vision system that detects and counts unique objects in rooms, ensuring duplicates in the same room are counted only once.

## **Dataset Requirements**

- Input: Images or videos of indoor rooms (living room, bedroom, office)
- **Minimum:** 500 labeled room images (synthetic or public datasets allowed such as OpenImages or COCO Indoor scenes, or custom-annotated)
- Annotations required:
  - o Room boundaries/identification (at least per-image "room ID")
  - o Object bounding boxes with class labels (TV, sofa, chair, table, bed)

#### **Core Features**

## 1. Object Detection

• Use YOLO (v8/v11 or similar) to detect objects within rooms

## 2. Room Identification

• Tag each image/frame with a room ID (metadata or scene classification/segmentation)

## 3. Unique Object Counting

- Within a single room: If the same object appears multiple times, count it as one
- Across different rooms: Count the object separately per room

## **Example:**

- Two TVs in Room A  $\rightarrow$  Count = 1 TV
- One TV in Room B + one TV in Room A  $\rightarrow$  Count = 2 TVs

## 4. Room-wise Report Generation

Output a structured report showing each room and its unique objects list

## **Sample Test Scenarios**

## Scenario 1:

- **Input:** Photo of living room with 2 sofas, 3 chairs, 2 TVs
- Output: Room A  $\rightarrow$  Sofa: 1, Chair: 1, TV: 1

#### Scenario 2:

- Input: Apartment with 2 rooms  $\rightarrow$  Room A (2 TVs), Room B (1 TV)
- **Output:** Room A  $\rightarrow$  TV: 1, Room B  $\rightarrow$  TV: 1 (Total unique TVs = 2)

#### Scenario 3:

- Input: Studio room with bed + chair + duplicate bed annotation error
- **Output:** Room  $C \rightarrow Bed: 1$ , Chair: 1

## **Technical Stack**

- Backend/Model: Python, YOLOv8/YOLOv11 (Ultralytics or custom)
- Room Classification/Segmentation: Metadata tags or pretrained scene classification model
- Processing Pipeline:
  - YOLO for object detection
  - o Room-wise grouping logic
  - o Deduplication of objects per room
- Frontend: Simple web/desktop interface (Streamlit, React, or Flask UI)
- Output Format: JSON/CSV + visualization (bounding boxes on images)

## **Deliverables**

- 1. Working YOLO-based application that processes images and outputs room-wise unique objects
- 2. Source code with documentation
- 3. Sample annotated dataset
- 4. Demo video showing detection and deduplication logic in action
- 5. Technical report explaining:
  - o Object detection approach
  - o How room-wise deduplication was implemented

## **Evaluation Criteria**

- Accuracy: Correct detection and unique counting per room
- Robustness: Handles multiple rooms and duplicate objects correctly
- Code Quality: Clean, modular, well-documented code
- **Practicality:** Clear pipeline from image → report
- **Innovation:** Bonus if the applicant uses techniques like scene segmentation, room classification, or embeddings for uniqueness detection

Here's a simple project requirement draft for your LiDAR-based floor plan system: