Omniduino APP communication protocol

Control rotation	1:Spin left	2:Spin right	3:stop ratate			
$Spin,XX#	$Spin,11#	$Spin,21#	$Spin,00#			
Adjust speed	1: Accelerate	2: Decelerate				
$Speed,XX#	$Speed,11#	$Speed,21#				
Buzzer	1:whistle					
$Buzzer,XX#	$Buzzer,11#					
RGB light diplay	1:Breathing light	2: Marquee	3:Water light	4: Colorful light	5: Close light	
$RGB,XX#	$RGB,11#	$RGB,21#	$RGB,31#	$RGB,41#	$RGB,00#	
Choose music	1:Star	2: Bingo	3:Merry Christmas	4:Ode	5:Birthday	Close music
$Music,XX#	$Music,11#	$Music,21#	$Music,31#	$Music,41#	$Music,51#	$Music,00#
Choose mode	1:Around mode	2:Avoid mode	3:Translation mode	Close mode		
$Mode,XX#	$Mode,11#	$Mode,21#	$Mode,31#	$Mode,00#		
Rocker: eg:$X128,Y128# (stop), $X000,Y128# (right)						
X axis:	(000~255)					
Y axis:	(000~255)					
Sliding control servo up and down angle 000-180: Example: $Servo, 090# middle position						
$Servo,XXX#						
I2C chip	I2C address					
PCA9685PW	0X40					
MPU6050	0X68					