

Ruochen WU

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EDUCATION BACKGROUND

Delft University of Technology (TU Delft)

09/2023 - today

MSc. in Multi-Machine Engineering (MME), Mechanical Engineering | Weighted Average Score: 8.2/10.0

Courses: Control System Design | Reliability & Maintenance of Transport Equipment | Operation & Maintenance | Measurement Technology | Machine Learning for Transport and Multi-Machine System | System Analysis and Simulation

Central South University (CSU)

09/2018 - 06/2022

B.Eng. in Transportation Equipment and Control Engineering | **GPA:** 3.47/4.0 (WES)

Courses: Advanced Mathematics | Linear Algebra | Probability and Statistics | Analog Electronics Technology | Digital Electronics Technology | Artificial Intelligence and Automatic Drive | Vehicle Structural Strength and Dynamics (ANSYS)

RESEARCH EXPERIENCES

TU Delft, AI Energy Lab & Austrian Institute of Technology (AIT)

09/2024 - today

AI for Science - Interpretable Intraday Price Prediction Integrating Kolmogorov-Arnold Networks (KANs) and Large Language

Master Graduation, Supervisor: Dr. Jochen CREMER & Dr. Peyman Mohajerin Esfahani

- Designed a price prediction model for intraday electricity market with actionable trading insights.
 - Built a Torch-based *deep learning* predictive model for intraday electricity prices using time-series data.
 - Enhanced model transparency & interpretability with KANs, integrating the concept of AI for science.
 - Utilized LLMs to analyze training outcomes and derive interpretable predictive formulas.

TU Delft, AI Energy Lab & Austrian Institute of Technology (AIT)

10/2024 - 12/2024

Feasibility Study – Review of Forecasting Continuous Intraday (CID) Electricity Prices

Literature Research, Supervisor: Dr. Jochen CREMER & Dr. Peyman Mohajerin Esfahani

- Reviewed CID price forecasting literature and proposed new forecasting schemes.
 - Conducted a comprehensive analysis of existing statistical and deep learning models for CID prices forecasting.
 - Redefined the ideal CID forecasting model to capture regional characteristics of EU markets.
 - Proposed a unified multi-layered forecasting model concept, demonstrating high feasibility and interpretability.

TU Delft, Adaptive Metastructures, Mechanisms and Machines Lab (JAM Lab)

09/2024 -01/2025

Robotic Optimization - Multi-Sensor Fusion for Soft Robot Pose Estimation Using Co-Training Method Core Member, Supervisor: Dr. Jovana JOVANOVA

- Perceived and detected the dynamic posture of a novel soft robotic arm.
 - Utilized a 3D camera module to detect the *multi-directional posture* of a soft robotic arm.
 - Integrated IMU and 3D camera data into a semi-supervised mutual supervision framework to minimize errors.

TU Delft, Adaptive Metastructures, Mechanisms and Machines Lab (JAM Lab)

06/2024 - 10/2024

Robot Creation – Integration System Design of SMA-SMP Based Morphing Structure for Soft Robotics MSc Research Assignment, Supervisor: Dr. Jovana JOVANOVA & Dr. Aaron Chen

- Developed a morphing structure and integrated control systems for advanced transformations.
 - Designed and fabricated the first SMM-based soft robotic system enabling dynamic and continuous operations.
 - Developed an unsupervised learning system with image recognition based on IR cameras for temperature detection.
- Implemented a closed-loop *control system* with a PID controller for real-time and accurate shape adjustments.
- Expected Publication: IEEE/ASME Transactions on Mechatronics (submitted)

CSU, Key Laboratory for Rail Traffic Safety

02/2021 - 07/2021

Robot Creation – An Automatic Service Robot in Train Compartments

Team Leader. Advisor: Dr. Fan WU

- Designed an autonomous service robot prototype for high-speed railway systems with multiple functions.
 - Implemented SLAM-based navigation with LIDAR and RRT for positioning and obstacle avoidance.
 - Developed mechanical and electronic systems for wheeled locomotion for omnidirectional, smooth movement.
 - Developed a real-time system for air bacteria monitoring and disinfection.

PUBLICATIONS

Multi-Sensor Fusion for Soft Robot Pose Estimation Using Co-Training Method

Submitted

Integration System Design of SMA-SMP Based Morphing Structure for Soft Robotics

Under Review

Numerical comparison of ventilation modes on the transmission of coughing droplets in a train compartment. Journal of Wind Engineering and Industrial Aerodynamics. 231. 105240. 10.1016/j.jweia.2022.105240.

SKILLS & PROFICIENCIES

Python, C++ programming, Deep Learning, Robotics Design and Control, Image Recognition, FEM **Technical Skills:**

Mandarin (Native speaker), English (Proficient, IELTS 7, GRE 330+4.0) Languages:

Basketball, Saxophone **Hobbies:**