

JIAWEI TANG

(+852) 65531607 · jtangas@connect.ust.hk · <https://garyandtang.github.io/>

EDUCATION

The Hong Kong University of Science and Technology ; GPA: 4.0/4.3	2019.9 - 2021.8
<i>Master of Philosophy in Electronic & Computer Engineering</i>	<i>Supervisor: Prof. Ling Shi</i>
The Hong Kong Polytechnic University ; GPA: 3.56/4.0	2014.9 - 2019.6
<i>BEng(Hons) in Electronic & Information Engineering</i>	

POSITION INTERESTS

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- Robotics , Control(State Estimation and Optimal Control), Computer Vision, Reinforcement Learning

RESEARCH AND WORKING EXPERIENCE

Research Assistant at HKUST , Supervisor: Prof. Ling Shi	2019.9-present
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- **Multi-robot Testbed for Cyber-Physical System**
 - Built the physical multi-robot testbed from scratch, including control, localization and state estimation.
 - Developed a ROS-based multi-robot digital twin system via Gazebo and RVIZ.
 - (In progress) Research on EKF-based LQG Design for Mobile Robots with Average-cost Constraints.
- **State Estimation and Optimal Control in Networked Control System**
 - Research on projection-based linear quadratic control for positive system (Paper submitted to TAC).
 - (In progress) Research on gradient-based sparse Kalman filter (Paper in revising).

Research Intern at RI, CMU , Supervisor Prof. Michael Kaess	2018.6-2018.8
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- **Automatic Extrinsic Calibration System of a Camera and a 3D LiDAR**
 - Developed an efficient extrinsic calibration toolbox for camera and 3D LiDAR with a user-friendly GUI.
 - Improved the calibration accuracy and system robustness.

Capstone Project Student at PolyU , Supervisor Prof. Kenneth Lam	2018.9-2019.5
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- **Low Resolution Face Recognition**
 - Addressed the low-resolution face recognition with conventional method and deep-learning method.
 - Conventional method: match the LR images with HR images using multidimensional scaling.
 - DL method: guide the LR images' training with the feature difference between HR and LR images.
 - Developed a web-based demonstration system with Flask, HTML, Javascript and CSS.

Power Electronics Intern at ASM Pacific Technology	2017.6-2018.5
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- **Project 1**: Designed feed-forward & PID control algorithm for digital controlled laser diode driver.
- **Project 2**: Simulated the performance of capacitance sensor in measuring the liquid height with MATLAB.
- **Project 3**: Developed a metal length measurement system with ADI ultrasonic sensor.

ACTIVITIES

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| • Co-funder of Bright Building Project, voluntary service in Ya'an, China | 2017.9 - 2018.9 |
| • Team leader of Technology for Development, voluntary services in Phnom Penh, Cambodia | 2015.1 - 2017.7 |

AWARD & SCHOLARSHIP

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| • Postgraduate Studentship, HKUST | 2019.9-2021.8 |
| • UG Summer Research Abroad Sponsorship, PolyU | 2018.6 |
| • Mingxi Outstanding Youth Award | 2017.11 |
| • HKSAR Government Scholarship Fund - Reaching Out Award | 2016.6 |
| • Best Sem GPA Award; Dean's List; Student Hall Scholarship ; ISAS Outreaching Award | |

SKILLS

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- **Programming**: C++, Python, MATLAB, Java, HTML, JavaScript, \LaTeX
 - **Others**: Pytorch, ROS, Git, Arduino, Spice, PCB Fabrication