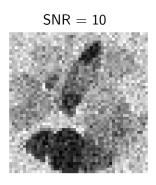
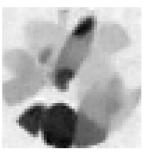
## **Denoising**

#### Adaptive non-local means denoising method



SNR = 10 Denoised



SNR = 30



[Manjón, Coupé et al., 2010]

#### Multi-Tensor Model

The Multi-Tensor (MT) generative model:

$$S(b,g) = \sum_{i=0}^{N-1} f_i e^{-bg^t D_i g}$$

where

b, g are the gradient b-value and unit orientation,  $f_i$  is the volume fraction of the  $i^{th}$  compartement,  $D_i$  is the symmetric rank-2 tensor of the  $i^{th}$  compartement, N is the number of compartement,

S(b,g) is the signal generated by the MT model with parameters (f,D,N) at (b,g).

## MT Fitting

Constrained MT model:

$$S_{b,g}^{C} = f_0 e^{-bD_0} + \sum_{i=1}^{3} f_i e^{-bg^t D_i g}$$

constraints: 4 compartement (1 isotropic, 3 prolate).

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• Fit by minimizing  $\sum_{k} (S_{b_k,g_k}^c - Y_{b_k,g_k})^2$  where Y is the measured diffusion signal.

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#### **PSO**

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$$\Omega_j^{t+1} = \Omega_j^t + v_j^{t+1}$$

[Kennedy and Eberhart, 1995]

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- Velocity:  $v_j^{t+1} = wv_j^t + \phi_p r_p (p_j^t \Omega_j^t) + \phi_g r_g (g^t \Omega_j^t)$
- where w,  $\phi_p$  and  $\phi_g$  are user tuned parameters,  $p_j^t$  is the  $j^{th}$  particle's best known position at iteration t,  $g^t$  is the swarm's best known position at iteration t,  $r_p$ ,  $r_g$  are uniform random variable.

[Kennedy and Eberhart, 1995]

## Model Complexity