

→ First, naive method:

bool IsPrime (int N) /* N ≥ 2 */

{ /* DIVIDE N BY ALL INTS UP TO N */

int no Divisors, eg

no Divisors = 0;

for (i = 1; i ≤ N; i++)

{ if (N % i == 0)

{ no Divisors += 1;

}
return (no Divisors == 2);
}

- UNAMBIGUOUS
- EFFECTIVE
- TERMINATES

→ Improve EFFICIENCY:

1) STOP when divisor ≠ 1, N found

2) 2 is PRIME, but all other even numbers are not

→ check only odd numbers

3) for loop can STOP @ $i \leq \sqrt{N}$ /* WHY? */
(→ p. 190)

bool IsPrime (int N) /* N ≥ 2 */

int i, limit;

if (N == 2) return (TRUE);

if (N % 2 == 0) return (FALSE);

limit = (int) sqrt(N) + 1; /* N = 16 ⇒ sqrt "might" return 3.9999 */

for (i = 3; i ≤ limit; i += 2)

{ if (N % i == 0) return (FALSE);

}
return (TRUE);

FIG. 6-3

EX.: GREATEST COMMON DIVISOR (GCD)

GCD (10, 15) → 5

GCD (12, 24) → 12

GCD (49, 35) → 7

→ Prototype: `int GCD (int x, int y);`

(i) CLEAR 'BRUTE-FORCE':

INP: $X=10, Y=15$ ($X < Y$)

10? $10 < 15$

$10 \% 10 = 0, 15 \% 10 = 5$

9? $10 \% 9 = 1, 15 \% 9 = 6$

8? $10 \% 8 = 2, 15 \% 8 = 7$

5? $10 \% 5 = 0, 15 \% 5 = 0$ ✓

→ $GCD(X, Y) = 5$

`int GCD (...)`

`{ int gcd;`

`gcd = x; / x < y`

`while (x % gcd != 0 || y % gcd != 0)`

`{ gcd--;`

`return (gcd);`

→ EUCLED'S ALGORITHM: MORE EFFICIENT

Theorem: "GCD of x and y is also the GCD of y and $x \% y$."

→ Algorithm Design ...

EX. $X=25, Y=15$

$X=36, Y=28$

	$i=0$	$i=1$	$i=2$
X	25	15	10
Y	15	10	5
R	10	5	0 ✓

(R "remainder") done

GCD is 5.

	$i=0$	$i=1$	$i=2$
X	36	28	8
Y	28	8	4
R	8	4	0 ✓

done

GCD is 4.

	$X=15, Y=25$			
X	15	25	15	10
Y	25	15	10	5
R	15	10	5	0 ✓

DOES NOT MATTER
WHETHER:

$X < Y$ OR $X > Y$

→ EUCLID'S ALGORITHM

- (1) Compute remainder $r = x \% y$.
- (2) If $r = 0$ then $GCD = y$,
else: $x = y, y = r$, repeat...

```

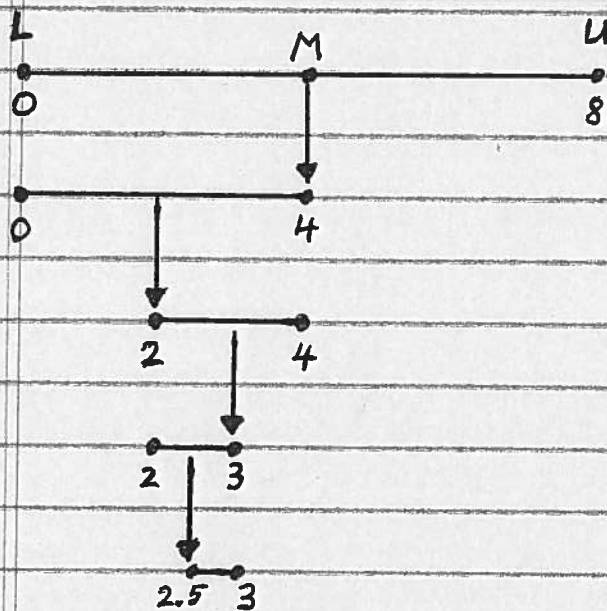
int GCD (int x, int y)
{
    int r;
    while (TRUE)
    {
        r = x % y;
        if (r == 0) break;
        x = y;
        y = r;
    }
    return (y);
}

```

■ Numerical Algorithms

Ex: Square-root approximation: $\sqrt{8} = ? \rightarrow 0 < \sqrt{8} < 8$

→ "REPEATED BISECTION"



L, L^2	U, U^2	M, M^2
0, 0	8, 64	4, 16
0, 0	4, 16	2, 4
2, 4	4, 16	3, 9
2, 4	3, 9	2.5, 6.25

- M converges to $\sqrt{8}$.
- STOP when $|L^2 - U^2| < \epsilon$.

→ double sqrt (double x) /* x ≥ 1 */

{ double l, u, m; /* lower bound, upper bound, middle */

l = 0;

u = x;

m = (l+u)/2;

while " |m² - x| > ε "

/* REPEATED BISECTION */

{ if (m * m ≤ x)

{ l = m;

}

else

{ u = m;

}

m = (l+u)/2;

}

} return (m);

/* Convergence Speed ? */

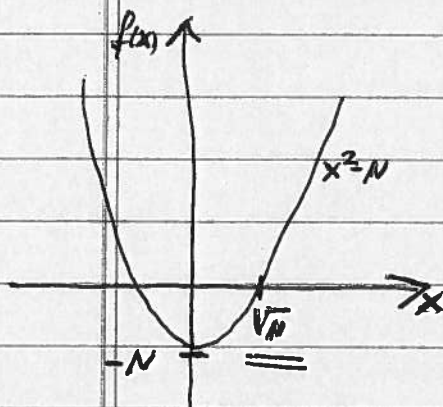
/* Intervals 50% smaller per step */

■ NEWTON'S METHOD : Increased efficiency !

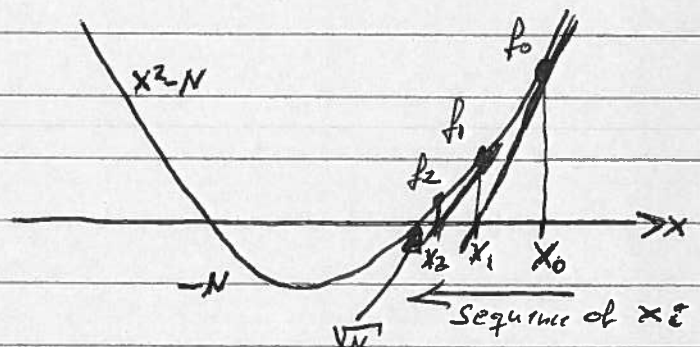
$$x^2 = N$$

$$\Leftrightarrow x^2 - N = 0$$

Find zero of function $f(x) = x^2 - N$!



• Iteration principle:



• FORMULA:

x_0 = "initial value"

$$x_{i+1} = x_i - \frac{f(x_i)}{f'(x_i)}$$

$$= x_i - \frac{x_i^2 - N}{2x_i} = \frac{2x_i^2 - x_i^2 + N}{2x_i} = \frac{x_i^2 + N}{2x_i} = \frac{1}{2} \left(x_i + \frac{N}{x_i} \right)$$

→ double sqrt (double x)

{ double app; /* approximate value of \sqrt{x} */

if (x == 0) return (0);

if (x < 0) Error ("... \n");

↑ DEFINED IN "genlib.h"

→ PROGRAM TERMINATES WITH THIS ERROR MESSAGE.

app = x;

while (! ApproxEqual (x, app*app))

/* MUST BE ROBUST! */

{ app = 0.5*(app + x/app);

/* Roberts p. 181 */

return (app);

{ bool ApproxEqual (double x, double y)

{ return (AbsValue (x-y)

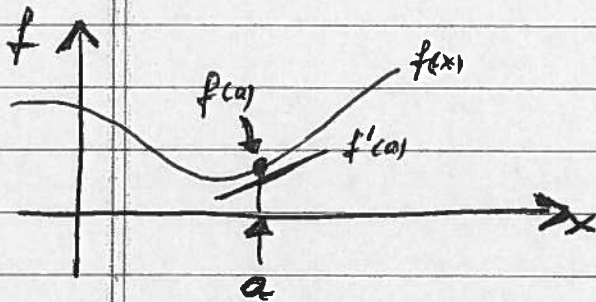
/* Minimum (AbsValue(x), AbsValue(y))

< EPSILON);

↑ DEFINE AS 0.000001 ???

TAYLOR APPROXIMATION

Idea: Use Taylor approx. of a function 'centered' at a to estimate \sqrt{x} .



"Developing" function $f(x)$ for $x = a$:

$$f(x) = f(a) + f'(a)(x-a) + \frac{f''(a)}{2}(x-a)^2 + \frac{f'''(a)}{6}(x-a)^3 + \dots$$

$$= \sum_{i=0}^{\infty} \frac{f^{(i)}(a)}{i!} (x-a)^i$$

"Approximate a function only in terms of polynomials!"

"Taylor Expansion of $f(x)$ " - Used in math.c

$$f(x) = f(a) + f'(a)(x-a) + \frac{f''(a)}{2}(x-a)^2 + \frac{f'''(a)}{6}(x-a)^3 + \dots = \underline{\underline{t_0 + t_1 + t_2 + t_3 + \dots}}$$

• HERE: $f(x) = \sqrt{x} = x^{1/2}$

$f = x^{1/2}$	$a = x = 1$	$t_0 = 1 \cdot \frac{(x-1)^0}{0!}$
$f' = \frac{1}{2} x^{-1/2}$	$\frac{1}{2} \cdot 1$	$\Rightarrow t_1 = \left(\frac{1}{2}\right) \cdot 1 \cdot \frac{(x-1)^1}{1!}$
$f'' = \left(-\frac{1}{2}\right) \frac{1}{2} x^{-3/2}$	$\left(-\frac{1}{2}\right) \frac{1}{2} \cdot 1$	$t_2 = \left(-\frac{1}{2}\right) \left(-\frac{1}{2}\right) \cdot 1 \cdot \frac{(x-1)^2}{2!}$
$f''' = \left(-\frac{3}{2}\right) \left(-\frac{1}{2}\right) \frac{1}{2} x^{-5/2}$	$\left(-\frac{3}{2}\right) \left(-\frac{1}{2}\right) \frac{1}{2} \cdot 1$	$t_3 = \left(-\frac{3}{2}\right) \left(-\frac{1}{2}\right) \left(-\frac{1}{2}\right) \cdot 1 \cdot \frac{(x-1)^3}{3!}$



$$t_0 = 1$$

$$t_i = \left(\frac{3}{2} - i\right) \cdot \frac{x-1}{i} \cdot t_{i-1}$$

"Initialize \sqrt{x} as t_0 , then add terms t_i
until $(\text{approx})^2 \approx x$."

(Note: Convergence radius: $(0, 2)$; \Rightarrow use $\sqrt{x} = \sqrt{4\hat{x}} = 2\sqrt{\hat{x}}$
 \Rightarrow lead to problem in $(0, 2)$.)

double sqrt(double x)

{ double sqRt, term;

int i;

term = 1;

sqRt = 1.0;

for (i = 1; !ApproxEqual(x, sqRt * sqRt); i++)

{ term *= (1.5 - i) * (x - 1) / i;

sqRt += term;

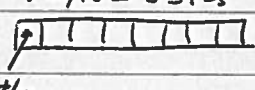
}

return (sqRt);

}

FIG. 6-8

Range of Numerical Types

① int → at least up to $32767 = 2^{15}-1$
 (2 bytes = 16 bits, 1 bit for sign)
 "ANSI C"
 (sometimes up to $2^{31}-1$, 4 bytes)
 (1 byte = 8 bits)
 $2^7-1 = 128-1 = \underline{127}$

long → at least $2^{31}-1 = \dots$ (4-bytes repr.)
 "ANSI C"
 → printf ("in %ld", ^{long}long)

unsigned → int → 2 bytes (sometimes 4 bytes)
 → long → 4 bytes
 → short → 1 byte

unsigned int → at least (up to) $65,535 = 2^{16}-1$
 → printf ("... %u",)

② Floating-point numbers

→ float - least precise of all floating-point repr.

→ double - most commonly used

→ long double - for high-precision scientific computing

