15-210: Parallelism in the Real World

- · Types of paralellism
- · Parallel Thinking
- Nested Parallelism
- Examples (Cilk, OpenMP, Java Fork/Join)
- Concurrency

15-853 Page1

<u>Cray-1 (1976): the world's most</u> <u>expensive love seat</u>



<u>Data Center: Hundred's of</u> <u>thousands of computers</u>







3

Since 2005: Multicore computers

AMD Opteron (sixteen-core) Model 6274

by AMD

★★★☆

(1 customer review)

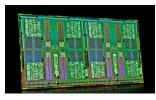
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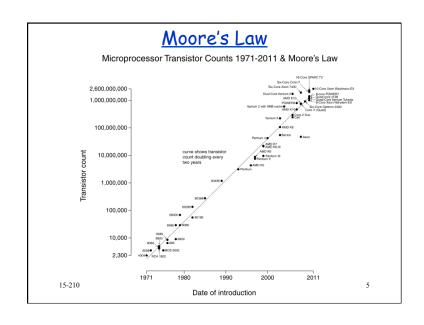
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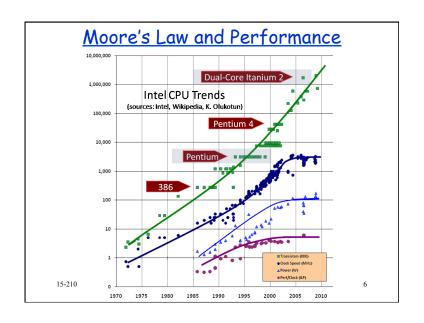


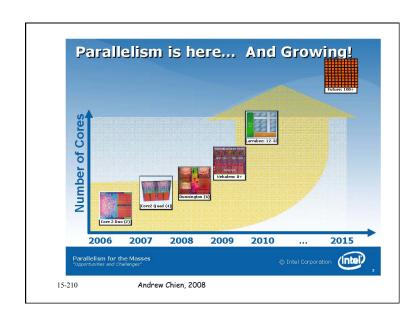
15-210

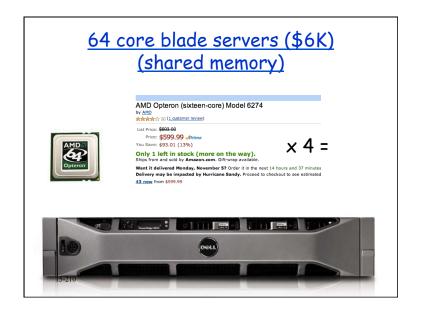
15-210

4





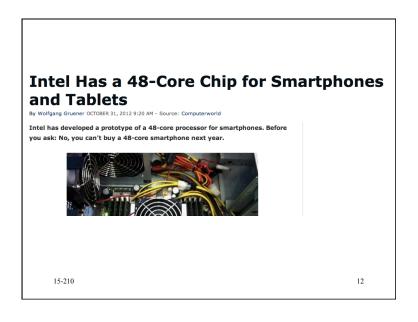












Parallel Hardware

Many forms of parallelism

- Supercomputers: large scale, shared memory
- Clusters and data centers: large-scale, distributed memory
- Multicores: tightly coupled, smaller scale
- GPUs, on chip vector units
- Instruction-level parallelism

Parallelism is important in the real world.

15-210

15-210 Approach

Enable parallel thinking by raising abstraction level

- I. Parallel thinking: Applicable to many machine models and programming languages
- II. Reason about correctness and efficiency of algorithms and data structures.

15-210

Key Challenge: Software (How to Write Parallel Code?)

At a high-level, it is a two step process:

- Design a work-efficient, low-span parallel algorithm
- Implement it on the target hardware

In reality: each system required different code because programming systems are immature

- Huge effort to generate efficient parallel code.
 - Example: Quicksort in MPI is <u>1700 lines</u> of code, and about the same in CUDA
- Implement one parallel algorithm: a whole thesis.

15-210

Parallel Thinking

Recognizing true dependences: unteach sequential programming.

Parallel algorithm-design techniques

- Operations on aggregates: map/reduce/scan
- Divide & conquer, contraction
- Viewing computation as DAG (based on dependences)

Cost model based on work and span

15-210 16

Quicksort from Aho-Hopcroft-Ullman (1974)

procedure QUICKSORT(S):

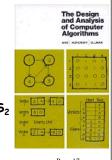
if S contains at most one element then return S else

begin

choose an element **a** randomly from **S**; **let S**₁, **S**₂ and **S**₃ be the sequences of elements in **S** less than, equal to, and greater than **a**, respectively; **return** (QUICKSORT(**S**₁) followed by **S**₂ followed by QUICKSORT(**S**₃))

end

15-210



Page 17

Quicksort from Sedgewick (2003)

```
public void quickSort(int[] a, int left, int right) {
   int i = left-1; int j = right;
   if (right <= left) return;
   while (true) {
      while (a[++i] < a[right]);
      while (a[right] < a[--j])
        if (j==left) break;
      if (i >= j) break;
      swap(a,i,j); }
   swap(a,i,right);
   quickSort(a, left, i - 1);
   quickSort(a, i+1, right); }
ROBERT SEDICEVICE

**PLINTERING MARKET NAME FAMILY.**
```

Styles of Parallel Programming

Data parallelism/Bulk Synchronous/SPMD
Nested parallelism: what we covered
Message passing
Futures (other pipelined parallelism)
General Concurrency

15-853 Page19

Nested Parallelism

Nested Parallelism =

15-210

arbitrary nesting of parallel loops + fork-join

- Assumes no synchronization among parallel tasks except at joint points.
- Deterministic if no race conditions

Advantages:

- Good schedulers are known
- Easy to understand, debug, and analyze
- Purely functional, or imperative...either works

15-853 Page20

Page 18

Nested Parallelism: parallel loops

Nested Parallelism: fork-join

```
cobegin {
                             Dates back to the 60s. Used in
  S1;
                                dialects of Algol, Pascal
  S2;}
                             Java fork-join framework
coinvoke(f1,f2)
                             Microsoft TPL (C#,F#)
Parallel.invoke(f1,f2)
#pragma omp sections
                             OpenMP (C++, C, Fortran, ...)
  #pragma omp section
  S1;
  #pragma omp section
  S2;
                          15-853
                                                     Page22
```

Nested Parallelism: fork-join

```
spawn S1;
S2;
                     cilk, cilk+
sync;
(exp1 || exp2)
                     Various functional
                       languages
plet
  x = exp1
                     Various dialects of
                       ML and Lisp
  y = exp2
in
  exp3
                      15-853
                                               Page23
```

Cilk vs. what we've covered

val $(a,b) = par(fn() \Rightarrow f(x),$ ML: $fn() \Rightarrow g(y)$ Fork Join Psuedocode: val (a,b) = (f(x) || g(y))cilk_spawn f(x); Cilk: g(y); cilk_sync; Parallel ML: S = tabulate f(i) nloops Psuedocode: $S = \langle f(i) : i \text{ in } \langle 0,..n-1 \rangle \rangle$ Cilk: cilk_for (int i = 0; i < n; i++) S[i] = f(i)Page24

Cilk vs. what we've covered

ML: S = tabulate f(i) n

Psuedocode: S = <f(i): i in <0,...n-1>>

Cilk: cilk_for (int i = 0; i < n; i++)

S[i] = f(i)

15-853 Page25

Cost Model (General)

Compositional:

Work: total number of operations

- costs are added across parallel calls

Span: depth/critical path of the computation

- Maximum span is taken across forked calls

Parallelism = Work/Span

- Approximately # of processors that can be effectively used.

15-853 Page27

Serial Parallel DAGs

Dependence graphs of nested parallel computations are series parallel

Two tasks are parallel if not reachable from each other. A data race occurs if two parallel tasks are involved in a race if they access the same location and at least one is a write.

15-853 Page26

Combining costs (Nested Parallelism)

Combining for parallel for:

$$W_{\text{pexp}}(\text{pfor }...) = \sum_{i=0}^{n-1} W_{\text{exp}}(f(i))$$
 work

$$D_{\text{pexp}}(\text{pfor }...) = \max_{i=0}^{n-1} D_{\text{exp}}(f(i))$$
 span

15-853 28

Why Work and Span

Simple measures that give us a good sense of efficiency (work) and scalability (span).

Can schedule in O(W/P + D) time on P processors.

This is within a constant factor of optimal.

Goals in designing an algorithm

- Work should be about the same as the sequential running time. When it matches asymptotically we say it is <u>work efficient</u>.
- 2. Parallelism (W/D) should be polynomial. $O(n^{1/2})$ is probably good enough

15-853

29

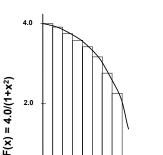
Example Cilk

```
int fib (int n) {
  if (n<2) return (n);
  else {
    int x,y;
    x = cilk_spawn fib(n-1);
    y = cilk_spawn fib(n-2);
    cilk_sync;
    return (x+y);
  }
}</pre>
```

Page30

Example OpenMP: Numerical Integration

Mathematically, we know that:



Х

0.0

15-210

$$\int_{0}^{1} \frac{4.0}{(1+x^2)} dx = \pi$$

We can approximate the integral as a sum of rectangles:

$$\sum_{i=0}^N F(x_i) \Delta x \approx \pi$$

where each rectangle has width Δx and height $F(x_i)$ at the middle of interval i.

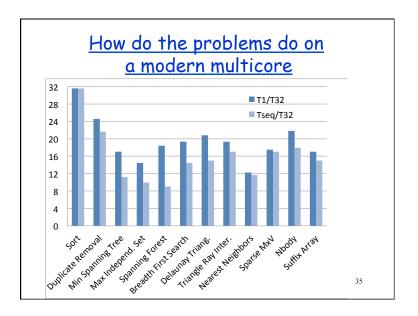
The C code for Approximating PI

15-853

```
static long num_steps = 100000;
double step;
void main ()
{     int i;     double x, pi, sum = 0.0;

     step = 1.0/(double) num_steps;
     x = 0.5 * step;
     for (i=0;i<= num_steps; i++){
          x+=step;
          sum += 4.0/(1.0+x*x);
     }
     pi = step * sum;
}</pre>
```

The C/openMP code for Approx. PI #include <omp.h> static long num steps = 100000; double step: void main () Private clause { int i; double x, pi, sum = 0.0; creates data local to step = 1.0/(double) num steps; a thread #pragma omp parallel for private(i, x) reduction(+:sum) for $(i=0;i\leq num steps; i++){$ x = (i+0.5)*step;sum = sum + 4.0/(1.0+x*x);pi = step * sum; Reduction used to manage dependencies



Example: Java Fork/Join

```
class Fib extends FJTask {
  volatile int result; // serves as arg and result
  int n;
  Fib(int _n) { n = _n; }
  public void run() {
      if (n \le 1) result = n;
      else if (n <= sequentialThreshold) number = seqFib(n);</pre>
         Fib f1 = new Fib(n - 1);
         Fib f2 = new Fib(n - 2);
         coInvoke(f1, f2);
         result = f1.result + f2.result;
                              15-853
                                                            Page34
```

Parallelism vs. Concurrency

- Parallelism: using multiple processors/cores running at the same time. Property of the machine
- Concurrency: non-determinacy due to interleaving threads. Property of the application.

		Concurrency	
		sequential	concurrent
Parallelism	serial	Traditional programming	Traditional OS
	parallel	Deterministic parallelism	General parallelism

15-853

36

concurrency: Stack Example 1 struct link {int v; link* next;} struct stack { link* headPtr; void push(link* a) { a->next = headPtr; headPtr = a; } link* pop() { link* h = headPtr; if (headPtr != NULL) headPtr = headPtr->next; return h;} }

concurrency: Stack Example 1 struct link {int v; link* next;} struct stack { link* headPtr; void push(link* a) { a->next = headPtr; headPtr = a; } link* pop() { link* h = headPtr; if (headPtr != NULL) headPtr = headPtr->next; return h;} }

```
Concurrency: Stack Example 1

struct link {int v; link* next;}

struct stack {
    link* headPtr;
    void push(link* a) {
        a->next = headPtr;
        headPtr = a; }

    link* pop() {
        link* h = headPtr;
        if (headPtr != NULL)
            headPtr = headPtr->next;
        return h;}
}
```

```
Concurrency: Stack Example 1

struct link {int v; link* next;}

struct stack {
    link* headPtr;
    void push(link* a) {
        a->next = headPtr;
        headPtr = a; }

link* pop() {
        link* h = headPtr;
        if (headPtr != NULL)
            headPtr = headPtr->next;
        return h;}
}
```

concurrency: Stack Example 2 struct stack { link* headPtr; void push(link* a) { do { link* h = headPtr; a->next = h; while (!CAS(&headPtr, h, a)); } link* pop() { do { link* h = headPtr; if (h == NULL) return NULL; link* nxt = h->next; while (!CAS(&headPtr, h, nxt)) } return h; } }

```
Concurrency: Stack Example 2
struct stack {
 link* headPtr;
 void push(link* a) {
     link* h = headPtr;
a \rightarrow next = h;
   while (!CAS(&headPtr, h, a)); }
 link* pop() {
   do {
     link* h = headPtr;
     if (h == NULL) return NULL;
     link* nxt = h->next;
   while (!CAS(&headPtr, h, nxt))}
   return h;}
                        15-853
                                                 42
```

```
Concurrency: Stack Example 2
struct stack {
 link* headPtr;
 void push(link* a) {
    do {
     link* h = headPtr;
\Rightarrow a->next = h:
    while (!CAS(&headPtr, h, a)); }
 link* pop() {
    do {
     link* h = headPtr;
     if (h == NULL) return NULL;
     link* nxt = h->next;
    while (!CAS(&headPtr, h, nxt))}
    return h;}
                        15-853
                                                  43
```

```
Concurrency: Stack Example 2
struct stack {
  link* headPtr;
  void push(link* a) {
      link* h = headPtr:
      a->next = h:
while (!CAS(&headPtr, h, a)); }
  link* pop() {
    do {
      link* h = headPtr;
      if (h == NULL) return NULL;
      link* nxt = h->next;
    while (!CAS(&headPtr, h, nxt))}
    return h;}
                        15-853
                                                 44
```

Concurrency: Stack Example 2' P1: x = s.pop(); y = s.pop(); s.push(x); P2: z = s.pop(); Before: A B C P2: h = headPtr; P2: nxt = h->next; P1: everything P2: CAS(&headPtr,h,nxt) Can be fixed with counter and 2CAS, but...

Concurrency: Stack Example 3'

```
void swapTop(stack s) {
   link* x = s.pop();
   link* y = s.pop();
   push(x);
   push(y);
}
```

Queues are trickier than stacks.

15-853

47

Concurrency: Stack Example 3

```
struct link {int v; link* next;}
struct stack {
  link* headPtr;

void push(link* a) {
    atomic {
      a->next = headPtr;
      headPtr = a; }}
link* pop() {
    atomic {
      link* h = headPtr;
      if (headPtr != NULL)
          headPtr = headPtr->next;
      return h;}
}
```