Kernel K-Means Clustering

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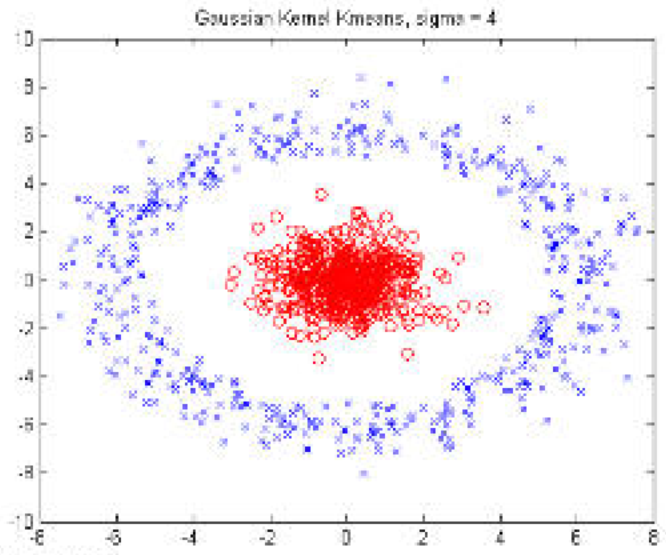


- *Kernel K-Means* can be used to detect non-convex clusters
    - *K-Means* can only detect clusters that are linearly separable
- Idea: Project data onto the high-dimensional kernel space, and then perform *K-Means* clustering
    - Map data points in the input space onto a high-dimensional feature space using the kernel function
    - Perform *K-Means* on the mapped feature space
- Computational complexity is higher than K-Means
    - Need to compute and store n x n kernel matrix generated from the kernel function on the original data
- The widely studied spectral clustering can be considered as a variant of Kernel K-Means clustering

Kernel Functions and Kernel K-Means Clustering

- Typical kernel functions:
  - Polynomial kernel of degree h: $K(\boldsymbol{X_i}, \boldsymbol{X_j}) = (\boldsymbol{X_i} \cdot \boldsymbol{X_j} + 1)^h$
  - Gaussian radial basis function (RBF) kernel: $K(\boldsymbol{X_i}, \boldsymbol{X_j}) = e^{-\|X_i - X_j\|^2 / 2\sigma^2}$
  - Sigmoid kernel: $K(\boldsymbol{X_i}, \boldsymbol{X_j}) = \tanh(\kappa \boldsymbol{X_i} \cdot \boldsymbol{X_j} - \delta)$
- The formula for kernel matrix K for any two points x_i, $x_j \in C_k$ is $K_{x_i x_j} = \phi(x_i) \bullet \phi(x_j)$
- The SSE criterion of *kernel K-means*: $SSE(C) = \sum_{k=1}^{K} \sum_{x_{i \in C_k}} \| \phi(x_i) - c_k \|^2$
  - The formula for the cluster centroid:

$$c_k = \frac{\sum_{x_{i \in C_k}} \phi(x_i)}{|C_k|}$$

- Clustering can be performed without the actual individual projections $\phi(x_i)$ and $\phi(x_j)$ for the data points x_i, $x_j \in C_k$

Example: Kernel Functions and Kernel K-Means Clustering

- Gaussian radial basis function (RBF) kernel: $K(\boldsymbol{X}_i, \boldsymbol{X}_j) = e^{-\|X_i - X_j\|^2/2\sigma^2}$
- Suppose there are 5 original 2-dimensional points:
  - $x_1(0, 0)$, $x_2(4, 4)$, $x_3(-4, 4)$, $x_4(-4, -4)$, $x_5(4, -4)$
- If we set σ to 4, we will have the following points in the kernel space
  - E.g., $||x_1 - x_2||^2 = (0-4)^2 + (0-4)^2 = 32$, therefore, $K(x_1, x_2) = e^{-\frac{32}{2\cdot 4^2}} = e^{-1}$

Original Space

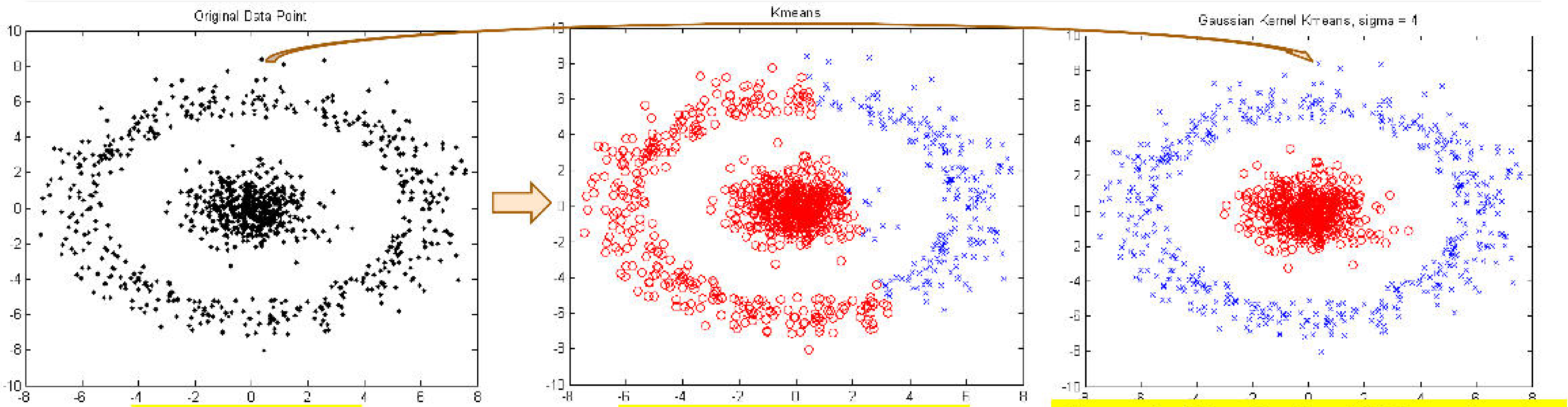
	x	y
x_1	0	0
x_2	4	4
x_3	-4	4
x_4	-4	-4
x_5	4	-4

RBF Kernel Space ($\sigma = 4$)

$K(x_i, x_1)$	$K(x_i, x_2)$	$K(x_i, x_3)$	$K(x_i, x_4)$	$K(x_i, x_5)$
0	$e^{-\frac{4^2+4^2}{2\cdot 4^2}} = e^{-1}$	e^{-1}	e^{-1}	e^{-1}
e^{-1}	0	e^{-2}	e^{-4}	e^{-2}
e^{-1}	e^{-2}	0	e^{-2}	e^{-4}
e^{-1}	e^{-4}	e^{-2}	0	e^{-2}
e^{-1}	e^{-2}	e^{-4}	e^{-2}	0

n×n 矩阵

Example: Kernel K-Means Clustering



The original data set | The result of K-Means clustering | The result of Gaussian Kernel K-Means clustering

- The above data set cannot generate quality clusters by K-Means since it contains non-covex clusters
- Gaussian RBF Kernel transformation maps data to a kernel matrix K for any two points x_i, x_j: $K_{x_i x_j} = \phi(x_i) \bullet \phi(x_j)$ and Gaussian kernel: $K(\boldsymbol{X}_i, \boldsymbol{X}_j) = e^{-\|X_i - X_j\|^2 / 2\sigma^2}$
- K-Means clustering is conducted on the mapped data, generating quality clusters

Recommended Readings

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