

Discrete Systems (Part I) - Theory

Assume a domain Ω and on which we formulate a weak formulation of the diffusion-reaction equation

$$\int_{\Omega} u \phi + a \nabla u \nabla \phi = \int_{\Omega} f \phi \quad (1)$$

where f is an external force $f: \Omega \rightarrow \mathbb{R}$, $u \in V$ is the response we wish to find. We have $a, c > 0 \in V$ as chosen constants and ϕ as the test function $\forall \phi \in V$. For this part we assume boundary conditions $\partial\Omega$ as $u=0$. Therefore $V = \{u \in H_0^1 \mid u=0 \text{ on } \partial\Omega\}$.

By a full finite element discretization we have a discrete function space V_h given by a Lagrangian basis $\{\phi_i\}_{i=0}^{N_p-1}$, where N_p is the number of points. We want to find a discrete solution $u_h = \sum_{i=0}^{N_p-1} U_i \phi_i$ such that

$$\sum_{i=0}^{N_p-1} U_i \int_{\Omega} c \phi_i \phi_j + a \nabla \phi_i \nabla \phi_j = \int_{\Omega} f \phi_j \quad \forall_j \text{ free DOF} \quad (2)$$

1. Lemma of Lax-Milgram

We assume that the domain Ω can be divided into a mesh \mathcal{T}_h of triangles T_i and the Dirichlet boundary condition. We define

$$V_h = \{v \in V_0 : \phi|_{T_i} \text{ is linear } \forall T_i \in \mathcal{T}_h, \phi \text{ is continuous on } \Omega\}$$

We need to find a unique discrete solution $u_h \in V_h$ for eq. (2), such that

$$A(u_h, \phi) = L(\phi) \quad \forall \phi \in V_h$$

We choose a basis for V_h : $\phi_j \in V_h$ such that

$$\phi_j(x_i) = \begin{cases} 1 & i=j \\ 0 & i \neq j \end{cases} \quad i, j = 1, 2, \dots, N_p-1$$

where x_i are the vertices of the triangles.

For the unique solution we solve the system

$$u_h(x) = \sum_{j=1}^{N_p-1} U_j \phi_j(x) \quad \text{where } U_j = u_h(x_j).$$

We can write in matrix form:

$$AU = L \quad \text{where } A_{ji} = A(\phi_i, \phi_j) \quad \text{and } L_j = L(\phi_j).$$

where A is a bounded, coercive bilinear form and L a linear bounded form. Following Lax-Milgram's Lemma, the problem has a unique solution.

2. Approximation of the integral

↳ optional task:

The approximation property can be characterized by Galerkin-Orthogonality. We search for the approximation to $u \approx u_n \in V_n \subset V$, where V_n is a finite dimensional subset of V . In the Galerkin method we search for the best approximation u_n with respect to the bilinear form $A = A(u, v)$ as defined previously.

The Galerkin-Orthogonality states that

$$A(u - u_n, v_n) = 0$$

which implies orthogonality of the error with respect to A .

The proof is given as:

$$A(u - u_n, v_n) = A(u, v_n) - A(u_n, v_n) = L(v_n) - L(v_n) = 0$$

↳ derive step by step the approximation:

$$\int_{\Omega} f(x, y) \cdot \phi_j(x, y) \, dx dy \approx$$

$$= \sum_{T \in \mathcal{T}_h} \int_T f(x, y) \cdot \phi_{D(j, T)}^T(x, y) \, dx dy =$$

$$= \sum_{T \in \mathcal{T}_h} \int_T f(x, y) \cdot \hat{\phi}_{D(j, T)}(F_T^{-1}(x, y)) \, dx dy =$$

$$= \sum_{T \in \mathcal{T}_h} |\det(D F_T)| \int_{\hat{T}} f(F_T(\hat{x}, \hat{y})) \cdot \hat{\phi}_{D(j, T)}(\hat{x}, \hat{y}) \, d\hat{x} d\hat{y} =$$

$$= \sum_{T \in \mathcal{T}_h} |\det(D F_T)| \sum_{\hat{x}, \hat{y}, \hat{\omega}} \hat{\omega} \cdot f(F_T(\hat{x}, \hat{y})) \cdot \hat{\phi}_{D(j, T)}(\hat{x}, \hat{y}) \quad \forall j \in \text{Dof}$$

3. Optimal Approximation

The approximation above is exact when the function f is linear on domain Ω , such that the selected test function $\phi_j(x, y)$ which is a Lagrangian hat function with values $\hat{\omega}$ evaluate to an exact function.