view\_frames Result Recorded at time: 1445449890.522 base link Broadcaster: /robot state publisher Average rate: 50.207 Hz Most recent transform: 1445449891.001 ( -0.478 sec old) Buffer length: 4.959 sec top\_plate Broadcaster: /robot\_state\_publisher Broadcaster: /robot state publisher Broadcaster: /robot state publisher Broadcaster: /robot\_state\_publisher Average rate: 50.207 Hz Average rate: 50.207 Hz Average rate: 50.207 Hz Average rate: 50.207 Hz Most recent transform: 1445449891.001 (-0.478 sec old) Buffer length: 4.959 sec Buffer length: 4.959 sec Buffer length: 4.959 sec Buffer length: 4.959 sec suport\_engine0 suport\_engine1 suport\_engine3 suport\_engine2 Broadcaster: /robot\_state\_publisher Average rate: 50.207 Hz Most recent transform: 1445449891.001 (-0.478 sec old) Most recent transform: 1445449891.001 (-0.478 sec old) Most recent transform: 1445449891.001 ( -0.478 sec old) Most recent transform: 1445449891.001 (-0.478 sec old) Most recent transform: 1445449891.001 ( -0.478 sec old) Buffer length: 4.959 sec shoulder01 shoulder10 shoulder11 shoulder21 shoulder31 shoulder00 shoulder20 shoulder30 Broadcaster: /robot\_state\_publisher Broadcaster: /robot state publisher Average rate: 50.207 Hz Most recent transform: 1445449891.001 (-0.478 sec old) Most recent transform: 1445449891.001 (-0.478 sec old) Most recent transform: 1445449891.001 ( -0.478 sec old) Most recent transform: 1445449891.001 (-0.478 sec old) Buffer length: 4.959 sec elbow00 elbow\_01 elbow10 elbow11 elbow20 elbow21 elbow31 elbow30 Broadcaster: /robot state publisher Average rate: 50.207 Hz Most recent transform: 1445449891.001 (-0.478 sec old) Most recent transform: 1445449891.001 (-0.478 sec old) Most recent transform: 1445449891.001 ( -0.478 sec old) Most recent transform: 1445449891.001 ( -0.478 sec old) Most recent transform: 1445449891.001 (-0.478 sec old) Buffer length: 4.959 sec wrist00 wrist01 wrist21 wrist11 wrist20 wrist30 wrist31 Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot state publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 50.207 Hz Most recent transform: 1445449891.001 ( -0.478 sec old) Most recent transform: 1445449891.001 ( -0.478 sec old) Most recent transform: 1445449891.001 (-0.478 sec old) Buffer length: 4.959 sec engine11 engine20 engine21 engine00 engine30