

Notebook

Para el regional elegimos nombre

21 de octubre de 2025

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1. Template

```

1 #include <bits/stdc++.h>
2 using namespace std;
3
4 #define forr(i, a, b) for (int i = int(a); i < int(b); i++)
5 #define forn(i, n) forr(i,0,n)
6 #define dforr(i, a, b) for (int i = int(b)-1; i >= int(a); i--)
7 #define dforn(i, n) dforr(i,0,n)
8 #define all(v) begin(v),end(v)
9 #define sz(v) (int(size(v)))
10 #define pb push_back
11 #define fst first
12 #define snd second
13 #define mp make_pair
14 #define endl '\n'
15 #define dprint(v) cerr << __LINE__ << ": " #v " = " << v << endl
16
17 using ll = long long;
18 using pii = pair<int,int>;
19
20 int main() {
21     ios::sync_with_stdio(0); cin.tie(0);
22 }
```

1.1. run.sh

```

1 clear
2 make -s $1 && ./ $1 < $2
```

1.2. comp.sh

```

1 clear
2 make -s $1 2>&1 | head -$2
```

1.3. Makefile

```

1 CXXFLAGS = -std=gnu++2a -O2 -g -Wall -Wextra -Wshadow -Wconversion\
2 -fsanitize=address -fsanitize=undefined
```

2. Estructuras de datos

2.1. Sparse Table

```
1 #define oper min
2 Elem st[K][1<<K]; // K tal que (1<<K) > n
3 void st_init(vector<Elem>& a) {
4     int n = sz(a); // assert(K >= 31-__builtin_clz(2*n));
5     forn(i,n) st[0][i] = a[i];
6     forr(k,1,K) forn(i,n-(1<<k)+1)
7         st[k][i] = oper(st[k-1][i], st[k-1][i+(1<<(k-1))]);
8 }
9 Elem st_query(int l, int r) { // assert(l<r);
10     int k = 31-__builtin_clz(r-l);
11     return oper(st[k][l], st[k][r-(1<<k)]);
12 }
13 // si la operacion no es idempotente
14 Elem st_query(int l, int r) {
15     int k = 31-__builtin_clz(r-l);
16     Elem res = st[k][l];
17     for (l+=(1<<k), k--; l<r; k--) {
18         if (l+(1<<k)<=r) {
19             res = oper(res, st[k][l]);
20             l += (1<<k);
21         }
22     }
23     return res;
24 }
```

2.2. Segment Tree

```
1 // Dado un array y una operacion asociativa con neutro, get(i,j)
   opera en [i,j)
2 #define oper(x, y) max(x, y)
3 const int neutro=0;
4 struct RMQ{
5     int sz;
6     tipo t[4*MAXN];
7     tipo &operator[](int p){return t[sz+p];}
8     void init(int n){ // O(nlgn)
```

```
9         sz = 1 << (32-__builtin_clz(n));
10        forn(i, 2*sz) t[i]=neutro;
11    }
12    void updall(){dforn(i, sz) t[i]=oper(t[2*i], t[2*i+1]);} //
   O(N)
13    tipo get(int i, int j){return get(i,j,1,0,sz);}
14    tipo get(int i, int j, int n, int a, int b){ // O(lgn)
15        if(j<=a || i>=b) return neutro;
16        if(i<=a && b<=j) return t[n];
17        int c=(a+b)/2;
18        return oper(get(i, j, 2*n, a, c), get(i, j, 2*n+1, c, b));
19    }
20    void set(int p, tipo val){ // O(lgn)
21        for(p+=sz; p>0 && t[p]!=val;){
22            t[p]=val;
23            p/=2;
24            val=oper(t[p*2], t[p*2+1]);
25        }
26    }
27 }rmq;
28 // Usage:
29 cin >> n; rmq.init(n); forn(i, n) cin >> rmq[i]; rmq.updall();
```

2.3. Segment Tree Lazy

```
1 //Dado un arreglo y una operacion asociativa con neutro, get(i, j)
   opera sobre el rango [i, j).
2 typedef int Elem; //Elem de los elementos del arreglo
3 typedef int Alt; //Elem de la alteracion
4 #define oper(x,y) x+y
5 #define oper2(k,a,b) k*(b-a) //Aplicar actualizacion sobre [a, b)
6 const Elem neutro=0; const Alt neutro2=-1;
7 struct RMQ{
8     int sz;
9     Elem t[4*MAXN];
10    Alt dirty[4*MAXN]; //las alteraciones pueden ser distintas a
   Elem
11    Elem &operator[](int p){return t[sz+p];}
12    void init(int n){ //O(nlgn)
13        sz = 1 << (32-__builtin_clz(n));
```

```

14     forn(i, 2*sz) t[i]=neutro;
15     forn(i, 2*sz) dirty[i]=neutro2;
16 }
17 void push(int n, int a, int b){//propaga el dirty a sus hijos
18     if(dirty[n]!=0){
19         t[n]+=oper2(dirty[n], a, b);//altera el nodo
20         if(n<sz){//cambiar segun el problema
21             dirty[2*n] = dirty[n];
22             dirty[2*n+1] = dirty[n];
23         }
24         dirty[n]=0;
25     }
26 }
27 Elem get(int i, int j, int n, int a, int b){//O(lgn)
28     if(j<=a || i>=b) return neutro;
29     push(n, a, b);
30     if(i<=a && b<=j) return t[n];
31     int c=(a+b)/2;
32     return oper(get(i, j, 2*n, a, c), get(i, j, 2*n+1, c, b));
33 }
34 Elem get(int i, int j){return get(i,j,1,0,sz);}
35 //altera los valores en [i, j) con una alteracion de val
36 void alterar(Alt val,int i,int j,int n,int a,int b){//O(lgn)
37     push(n, a, b);
38     if(j<=a || i>=b) return;
39     if(i<=a && b<=j){
40         dirty[n]+=val;
41         push(n, a, b);
42         return;
43     }
44     int c=(a+b)/2;
45     alterar(val, i, j, 2*n, a, c);
46     alterar(val, i, j, 2*n+1, c, b);
47     t[n]=oper(t[2*n], t[2*n+1]);
48 }
49 void alterar(Alt val, int i, int j){alterar(val,i,j,1,0,sz);}
50 }rmq;

```

2.4. Segment Tree Persistente

```

1  const int LOG2N = 19; // ceil(log2(MAXN))
2  const int STLEN = 1<<LOG2N;
3
4  struct Mono {
5      // TODO agregar data
6      static Mono zero() { /* TODO */ } // neutro de la suma
7  };
8  Mono operator+ (Mono a, Mono b) { /* TODO */ } // asociativo
9
10 struct N {
11     N(Mono x_, N* l_, N* r_)
12     : x{x_}, l{l_}, r{r_} {}
13     Mono x; N* l; N* r;
14 };
15 N empty_node(Mono::zero(), &empty_node, &empty_node);
16
17 deque<N> st_alloc; // optimizacion: >30% mas rapido que 'new
   N(x,l,r)'
18 N* make_node(Mono x, N* l, N* r) {
19     st_alloc.emplace_back(x, l, r);
20     return &st_alloc.back();
21 }
22
23 N* u_(N* t, int l, int r, int i, Mono x) {
24     if (i+1 <= l || r <= i) return t;
25     if (r-l == 1) return make_node(x, nullptr, nullptr);
26     int m = (l+r)/2;
27     auto lt = u_(t->l, l, m, i, x);
28     auto rt = u_(t->r, m, r, i, x);
29     return make_node(lt->x + rt->x, lt, rt);
30 }
31
32 int ql, qr;
33 Mono q_(N* t, int l, int r) {
34     if (qr <= l || r <= ql) return Mono::zero();
35     if (ql <= l && r <= qr) return t->x;
36     int m = (l+r)/2;
37     return q_(t->l, l, m) + q_(t->r, m, r);
38 }
39

```

```

40 // suma en rango: t[l,r)
41 Mono query(N* t, int l, int r) { ql = l; qr = r; return q_(t, 0,
    STLEN); }
42
43 // asignacion en punto: t[i]=x
44 N* update(N* t, int i, Mono x) { return u_(t, 0, STLEN, i, x); }
45
46 /* uso:
47 auto t = Empty_node;
48 t = update(t, 0, Mono{10});
49 t = update(t, 5, Mono{5});
50 auto x = query(t, 0, 5); // devuelva Mono{10}
51 auto y = query(t, 0, 6); // devuelva Mono{10} + Mono{5}
52 auto z = query(t, 1, 6); // devuelva Mono{5}
53 */

```

2.5. Fenwick Tree

```

1 struct Fenwick { // 0-indexed, query [0, i), update [i]
2     int ft[MAXN+1]; // Uso: ft.u(idx, val); cout << ft.q(idx);
3     int u(int i0, int x) { for (int i=i0+1; i<=MAXN; i+=i&-i)
        ft[i]+=x; }
4     ll q(int i0){ ll x=0; for (int i=i0; i>0; i-=i&-i) x+=ft[i];
        return x; } };
5
6 struct RangeFT { // 0-indexed, query [0, l), update [l, r)
7     Fenwick rate, err; // Uso: ft.u(l, r, val); cout << ft.q(l, r);
8     void u(int l, int r, int x) { // range update
9         rate.u(l, x); rate.u(r, -x); err.u(l, -x*1); err.u(r, x*r);
10        }
11     ll q(int i) { return rate.q(i) * i + err.q(i); } }; // prefix
        query

```

2.6. Union Find

```

1 vector<int> uf(MAXN, -1);
2 int uf_find(int x) { return uf[x]<0 ? x : uf[x] = uf_find(uf[x]); }
3 bool uf_join(int x, int y){ // True sii x e y estan en !=
    componentes
4     x = uf_find(x); y = uf_find(y);
5     if(x == y) return false;

```

```

6     if(uf[x] > uf[y]) swap(x, y);
7     uf[x] += uf[y]; uf[y] = x; return true;
8 }

```

2.7. Chull Trick

```

1 struct line { int a, b; }; // y = ax + b
2 vector<line> cht(vector<line> a) {
3     sort(all(a), [](line x, line y) {
4         return make_pair(x.a, x.b) < make_pair(y.a, y.b); });
5     vector<line> b = {a[0]};
6     forr(i, 1, sz(a)) { line z = a[i];
7         if (b.back().a == z.a) b.pp();
8         while (sz(b) >= 2) { line x = b[sz(b)-2], y = b[sz(b)-1];
9             if (ll(x.b-y.b)*(z.a-x.a) < ll(x.b-z.b)*(y.a-x.a))
10                break;
11                b.pp();
12            }
13            b.pb(z);
14        }
15    }

```

2.8. Chull Trick Dinámico

```

1 struct Entry {
2     using It = set<Entry>::iterator;
3     bool is_query;
4     ll m, b; mutable It it, end;
5     ll x;
6 };
7 bool operator< (Entry const& a, Entry const& b) {
8     if (!b.is_query) return a.m < b.m;
9     auto ni = next(a.it);
10    if (ni == a.end) return false;
11    auto const& c = *ni;
12    return (c.b-a.b) > b.x * (a.m-c.m);
13 }
14 struct ChullTrick {
15     using It = Entry::It;
16     multiset<Entry> lines;

```

```

17 bool covered(It it) {
18     auto begin = lines.begin(), end = lines.end();
19     auto ni = next(it);
20     if (it == begin && ni == end) return false;
21     if (it == begin) return ni->m==it->m && ni->b>=it->b;
22     auto pi = prev(it);
23     if (ni == end) return pi->m==it->m && pi->b>=it->b;
24     return (it->m-pi->m)*(ni->b-pi->b) >=
        (pi->b-it->b)*(pi->m-ni->m);
25 }
26 bool add(ll m, ll b) {
27     auto it = lines.insert({false, m, b});
28     it->it = it; it->end = lines.end();
29     if (covered(it)) { lines.erase(it); return false; }
30     while (next(it) != lines.end() && covered(next(it)))
        lines.erase(next(it));
31     while (it != lines.begin() && covered(prev(it)))
        lines.erase(prev(it));
32     return true;
33 }
34 ll eval(ll x) {
35     auto l = *lines.lower_bound({true, -1, -1, {}, {}, x});
36     return l.m*x+l.b;
37 }
38 };

```

3. Matemática

3.1. Criba Lineal

```

1 const int N = 10'000'000;
2 vector<int> lp(N+1);
3 vector<int> pr;
4 for (int i=2; i <= N; ++i) {
5     if (lp[i] == 0) lp[i] = i, pr.push_back(i);
6     for (int j = 0; i * pr[j] <= N; ++j) {
7         lp[i * pr[j]] = pr[j];
8         if (pr[j] == lp[i]) break;
9     }
10 }

```

3.2. Phollard's Rho

```

1 ll mulmod(ll a, ll b, ll m) { return ll(__int128(a) * b % m); }
2
3 ll expmod(ll b, ll e, ll m) { // O(log b)
4     if (!e) return 1;
5     ll q=expmod(b,e/2,m); q=mulmod(q,q,m);
6     return e%2 ? mulmod(b,q,m) : q;
7 }
8
9 bool es_primo_prob(ll n, int a) {
10     if (n == a) return true;
11     ll s = 0, d = n-1;
12     while (d%2 == 0) s++, d/=2;
13     ll x = expmod(a,d,n);
14     if ((x == 1) || (x+1 == n)) return true;
15     forn(i,s-1){
16         x = mulmod(x,x,n);
17         if (x == 1) return false;
18         if (x+1 == n) return true;
19     }
20     return false;
21 }
22
23 bool rabin(ll n) { // devuelve true sii n es primo
24     if (n == 1) return false;
25     const int ar[] = {2,3,5,7,11,13,17,19,23};
26     forn(j,9) if (!es_primo_prob(n,ar[j])) return false;
27     return true;
28 }
29
30 ll rho(ll n) {
31     if ((n & 1) == 0) return 2;
32     ll x = 2, y = 2, d = 1;
33     ll c = rand() % n + 1;
34     while (d == 1) {
35         x = (mulmod(x,x,n)+c)%n;
36         y = (mulmod(y,y,n)+c)%n;
37         y = (mulmod(y,y,n)+c)%n;
38         d=gcd(x-y,n);

```

```

39     }
40     return d==n ? rho(n) : d;
41 }
42
43 void factRho(map<ll,ll>&prim, ll n){ //O (lg n)^3. un solo numero
44     if (n == 1) return;
45     if (rabin(n)) { prim[n]++; return; }
46     ll factor = rho(n);
47     factRho(factor, prim); factRho(n/factor, prim);
48 }
49 auto fact(ll n){
50     map<ll,ll>prim;
51     factRho(prim,n);
52     return prim;
53 }

```

3.3. Divisores

```

1 // Usar asi: divisores(fac, divs, fac.begin()); NO ESTA ORDENADO
2 void divisores(const map<ll,ll> &f, vector<ll> &divs, auto it, ll
   n=1){
3     if (it==f.begin()) divs.clear();
4     if (it==f.end()) { divs.pb(n); return; }
5     ll p=it->fst, k=it->snd; ++it;
6     forn(_, k+1) divisores(f,divs,it,n), n*=p;
7 }
8
9 ll sumDiv (ll n){ //suma de los divisores de n
10     ll rta = 1;
11     map<ll,ll> f=fact(n);
12     for(auto it = f.begin(); it != f.end(); it++) {
13         ll pot = 1, aux = 0;
14         forn(i, it->snd+1) aux += pot, pot *= it->fst;
15         rta*=aux;
16     }
17     return rta;
18 }

```

3.4. Inversos Modulares

```

1 pair<ll,ll> extended_euclid(ll a, ll b) {

```

```

2     if (b == 0) return {1, 0};
3     auto [y, x] = extended_euclid(b, a%b);
4     y -= (a/b)*x;
5     if (a*x + b*y < 0) x = -x, y = -y;
6     return {x, y}; // a*x + b*y = gcd(a,b)
7 }
8
9 constexpr ll MOD = 1000000007; // tmb es comun 998'244'353
10 ll invmod[MAXN]; // inversos mdulo MOD hasta MAXN
11 void invmods() { // todo entero en [2,MAXN] debe ser coprimo con
   MOD
12     inv[1] = 1;
13     forr(i, 2, MAXN) inv[i] = MOD - MOD/i*inv[MOD%i] %MOD;
14 }
15
16 // si MAXN es demasiado grande o MOD no es fijo:
17 // versin corta, m debe ser primo. O(log(m))
18 ll invmod(ll a, ll m) { return expmod(a,m-2,m); }
19 // versin larga, a y m deben ser coprimos. O(log(a)), en general
   ms rpido
20 ll invmod(ll a, ll m) { return (extended_euclid(a,m).fst % m + m)
   % m; }

```

3.5. Catalan

```

1 ll Cat(int n){
2     return ((F[2*n] *FI[n+1])%M *FI[n])%M;
3 }

```

3.6. Lucas

```

1 const ll MAXP = 3e3+10; //68 MB, con 1e4 int son 380 MB
2 ll C[MAXP][MAXP], P; //inicializar con el primo del input <
   MAXP
3 void llenar_C(){
4     forn(i, MAXP) C[i][0] = 1;
5     forr(i, 1, MAXP) forr(j, 1, i+1)
        C[i][j]=addmod(C[i-1][j-1],C[i-1][j], P);
6 }
7 // Calcula nCk (mod p) con n, k arbitrariamente grandes y p primo
   <= 3000

```

```

8 ll lucas(ll N, ll K){ // llamar a llenar_C() antes
9     ll ret = 1;
10    while(N+K){
11        ret = ret * C[N%P][K%P] % P;
12        N /= P, K /= P;
13    }
14    return ret;
15 }

```

3.7. Stirling-Bell

```

1 ll STR[MAXN][MAXN], Bell[MAXN];
2 //STR[n][k] = formas de particionar un conjunto de n elementos en
   k conjuntos
3 //Bell[n] = formas de particionar un conjunto de n elementos
4 forr(i, 1, MAXN)STR[i][1] = 1;
5 forr(i, 2, MAXN)STR[1][i] = 0;
6 forr(i, 2, MAXN)forr(j, 2, MAXN){
7     STR[i][j] = (STR[i-1][j-1] + j*STR[i-1][j] %MOD) %MOD;
8 }
9 forn(i, MAXN){
10     Bell[i] = 0;
11     forn(j, MAXN){
12         Bell[i] = (Bell[i] + STR[i][j]) %MOD;
13     }
14 }

```

3.8. DP Factoriales

```

1 ll F[MAXN], INV[MAXN], FI[MAXN];
2 // ...
3 F[0] = 1; forr(i, 1, MAXN) F[i] = F[i-1]*i %M;
4 INV[1] = 1; forr(i, 2, MAXN) INV[i] = M - (ll)(M/i)*INV[M%i] %M;
5 FI[0] = 1; forr(i, 1, MAXN) FI[i] = FI[i-1]*INV[i] %M;

```

3.9. Estructura de Fracción

```

1 tipo mcd(tipo a, tipo b){return a?mcd(b%a, a):b;}
2 struct frac{
3     tipo p,q;
4     frac(tipo p=0, tipo q=1):p(p),q(q) {norm();}

```

```

5     void norm(){
6         tipo a = mcd(p,q);
7         if(a) p/=a, q/=a;
8         else q=1;
9         if (q<0) q=-q, p=-p;}
10    frac operator+(const frac& o){
11        tipo a = mcd(q,o.q);
12        return frac(p*(o.q/a)+o.p*(q/a), q*(o.q/a));}
13    frac operator-(const frac& o){
14        tipo a = mcd(q,o.q);
15        return frac(p*(o.q/a)-o.p*(q/a), q*(o.q/a));}
16    frac operator*(frac o){
17        tipo a = mcd(q,o.p), b = mcd(o.q,p);
18        return frac((p/b)*(o.p/a), (q/a)*(o.q/b));}
19    frac operator/(frac o){
20        tipo a = mcd(q,o.q), b = mcd(o.p,p);
21        return frac((p/b)*(o.q/a), (q/a)*(o.p/b));}
22    bool operator<(const frac &o) const{return p*o.q < o.p*q;}
23    bool operator==(frac o){return p==o.p&&q==o.q;}
24 };

```

3.10. Gauss

```

1 double reduce(vector<vector<double>> &a){ //Devuelve determinante
   si m == n
2     int m=sz(a), n=sz(a[0]), i=0, j=0; double r = 1.0;
3     while(i < m and j < n){
4         int h = i;
5         forr(k, i+1, m) if(abs(a[k][j]) > abs(a[h][j])) h = k;
6         if(abs(a[h][j]) < EPS){ j++; r=0.0; continue; }
7         if(h != i){ r = -r; swap(a[i], a[h]); }
8         r *= a[i][j];
9         dforr(k, j, n) a[i][k] /= a[i][j];
10        forr(k, 0, m) if(k != i)
11            dforr(l_, j, n) a[k][l_] -= a[k][j] * a[i][l_];
12        i ++; j ++;
13    }
14    return r;
15 }

```


3.11. FFT

```

1 // MAXN must be power of 2 !!, MOD-1 needs to be a multiple of
  // MAXN !!
2 typedef ll tf;
3 typedef vector<tf> poly;
4 //const tf MOD = 2305843009255636993, RT = 5;
5 const tf MOD = 998244353, RT = 3;
6 // const tf MOD2 = 897581057, RT2 = 3; // Chinese Remainder Theorem
7 /* FFT */ struct CD {
8     double r, i;
9     CD(double r_ = 0, double i_ = 0) : r(r_), i(i_) {}
10    void operator/=(const int c) { r/=c, i/=c; }
11 };
12 CD operator*(const CD& a, const CD& b){
13     return CD(a.r*b.r-a.i*b.i, a.r*b.i+a.i*b.r);}
14 CD operator+(const CD& a, const CD& b) { return CD(a.r+b.r,
15     a.i+b.i); }
16 CD operator-(const CD& a, const CD& b) { return CD(a.r-b.r,
17     a.i-b.i); }
18 /* NTT */ struct CD { tf x; CD(tf x_) : x(x_) {} CD() {} };
19 CD operator+(const CD& a, const CD& b) { return CD(addmod(a.x,
20     b.x)); } //ETC
21 vector<tf> rts(MAXN+9,-1);
22 CD root(int n, bool inv){
23     tf r = rts[n]<0 ? rts[n] = expmod(RT,(MOD-1)/n) : rts[n];
24     return CD(inv ? expmod(r, MOD-2) : r);
25 }
26 /* AMBOS */ CD cp1[MAXN+9], cp2[MAXN+9];
27 int R[MAXN+9];
28 void dft(CD* a, int n, bool inv){
29     double pi = acos(-1.0);
30     for(int i = 0; i < n; i++) swap(a[R[i]], a[i]);
31     for(int m = 2; m <= n; m *= 2){
32         /* FFT */ double z = 2*pi/m * (inv?-1:1);
33         /* FFT */ CD wi = CD(cos(z), sin(z));
34         /* NTT */ CD wi = root(m, inv);
35         for(int j = 0; j < n; j += m){
36             CD w(1);
37             for(int k = j, k2 = j+m/2; k2 < j+m; k++, k2++){

```

```

35             CD u = a[k]; CD v = a[k2]*w; a[k] = u+v; a[k2] =
36                 u-v; w = w*wi;
37         }
38     }
39     /* FFT */ if(inv) forn(i, n) a[i] /= n;
40     /* NTT */ if(inv){
41         CD z(expmod(n, MOD-2));
42         forn(i, n) a[i] = a[i]*z;
43     }
44 }
45 poly multiply(poly& p1, poly& p2){
46     int n = sz(p1)+sz(p2)+1;
47     int m = 1, cnt = 0;
48     while(m <= n) m *= 2, cnt++;
49     forn(i, m) { R[i] = 0; forn(j, cnt) R[i] =
50         (R[i]<<1)|((i>>j)&1); }
51     forn(i, m) cp1[i] = 0, cp2[i] = 0;
52     forn(i, sz(p1)) cp1[i] = p1[i];
53     forn(i, sz(p2)) cp2[i] = p2[i];
54     dft(cp1, m, false); dft(cp2, m, false);
55     // fast eval: forn(i, sz(p1)) p1(expmod(RT, (MOD-1)/m*i)) ==
56         cp1[i].x
57     forn(i, m) cp1[i] = cp1[i]*cp2[i];
58     dft(cp1, m, true);
59     poly res;
60     n -= 2;
61     /* FFT */ forn(i, n) res.pb((tf)floor(cp1[i].r+0.5));
62     /* NTT */ forn(i, n) res.pb(cp1[i].x);
63     return res;
64 }

```

4. Geometria

4.1. Punto

```

1 using T = double;
2 bool iszero(T u) { return abs(u)<=EPS; }
3 struct Pt {
4     T x, y;

```

```

5   T z; // only for 3d
6   Pt() {}
7   Pt(T _x, T _y) : x(_x), y(_y) {}
8   Pt(T _x, T _y, T _z) : x(_x), y(_y), z(_z) {} // for 3d
9   T norm2(){ return *this**this; }
10  T norm(){ return sqrt(norm2()); }
11  Pt operator+(Pt o){ return Pt(x+o.x,y+o.y); }
12  Pt operator-(Pt o){ return Pt(x-o.x,y-o.y); }
13  Pt operator*(T u){ return Pt(x*u,y*u); }
14  Pt operator/(T u) {
15      if (iszero(u)) return Pt(INF,INF);
16      return Pt(x/u,y/u);
17  }
18  T operator*(Pt o){ return x*o.x+y*o.y; }
19  Pt operator^(Pt p){ // only for 3D
20      return Pt(y*p.z-z*p.y, z*p.x-x*p.z, x*p.y-y*p.x); }
21  T operator%(Pt o){ return x*o.y-y*o.x; }
22  T angle(Pt o){ return atan2(*this%o, *this*o); }
23  // T angle(Pt o){ // accurate around 90 degrees
24  //     if (*this%o>0) return acos(*this*o);
25  //     return 2*M_PI-acos(*this*o); }
26  Pt unit(){ return *this/norm(); }
27  bool left(Pt p, Pt q){ // is it to the left of directed line
    pq?
28      return ((q-p)%(*this-p))>EPS; }
29  bool operator<(Pt p)const{ // for convex hull
30      return x<p.x-EPS||(iszero(x-p.x)&&y<p.y-EPS); }
31  bool collinear(Pt p, Pt q){
32      return iszero((p-*this)%(q-*this)); }
33  bool dir(Pt p, Pt q){ // does it have the same direction of pq?
34      return this->collinear(p, q)&&(q-p)*(*this-p)>EPS; }
35  Pt rot(Pt r){ return Pt(*this*r,*this*r); }
36  Pt rot(T a){ return rot(Pt(sin(a),cos(a))); }
37  };
38  Pt ccw90(1,0);
39  Pt cw90(-1,0);

```

4.2. Linea

```
1 using T = double;
```

```

2 int sgn2(T x){return x<0?-1:1;}
3 struct Ln {
4     Pt p,pq;
5     Ln(Pt p, Pt q):p(p),pq(q-p){}
6     Ln(){}
7     bool has(Pt r){return dist(r)<=EPS;}
8     bool seghas(Pt r){return has(r)&&(r-p)*(r-(p+pq))<=EPS;}
9     // bool operator/(Ln l){return
    (pq.unit()^l.pq.unit()).norm()<=EPS;} // 3D
10    bool operator/(Ln l){return abs(pq.unit()^l.pq.unit())<=EPS;}
    // 2D
11    bool operator==(Ln l){return *this/l&&has(l.p);}
12    Pt operator^(Ln l){ // intersection
13        if(*this/l)return Pt(INF,INF);
14        T a=-pq.y, b=pq.x, c=p.x*a+p.y*b;
15        T la=-l.pq.y, lb=l.pq.x, lc=l.p.x*la+l.p.y*lb;
16        T det = a * lb - b * la;
17        Pt r((lb*c-b*lc)/det, (a*lc-c*la)/det);
18        return r;
19        // Pt r=l.p+l.pq*(((p-l.p)^pq)/(l.pq^pq));
20        // if(!has(r)){return Pt(NAN,NAN,NAN);} // check only for 3D
21    }
22    T angle(Ln l){return pq.angle(l.pq);}
23    int side(Pt r){return has(r)?0:sgn2(pq^(r-p));} // 2D
24    Pt proj(Pt r){return p+pq*((r-p)*pq/pq.norm2());}
25    Pt segclosest(Pt r) {
26        T l2 = pq.norm2();
27        if(l2==0.) return p;
28        T t =((r-p)*pq)/l2;
29        return p+(pq*min(1,max(0,t)));
30    }
31    Pt ref(Pt r){return proj(r)*2-r;}
32    T dist(Pt r){return (r-proj(r)).norm();}
33    // T dist(Ln l){ // only 3D
34    //     if(*this/l)return dist(l.p);
35    //     return abs((l.p-p)*(pq^l.pq))/(pq^l.pq).norm());
36    // }
37    Ln rot(auto a){return Ln(p,p+pq.rot(a));} // 2D
38  };
39  Ln bisector(Ln l, Ln m){ // angle bisector

```

```

40 Pt p=l^m;
41 return Ln(p,p+l.pq.unit()+m.pq.unit());
42 }
43 Ln bisector(Pt p, Pt q){ // segment bisector (2D)
44 return Ln((p+q)*.5,p).rot(ccw90);
45 }

```

4.3. Poligono

```

1 using T = double;
2 struct Pol {
3     int n;vector<Pt> p;
4     Pol(){}
5     Pol(vector<Pt> _p){p=_p;n=p.size();}
6     T area() {
7         ll a = 0;
8         forr (i, 1, sz(p)-1) {
9             a += (p[i]-p[0])^(p[i+1]-p[0]);
10        }
11        return abs(a)/2;
12    }
13    bool has(Pt q){ // O(n), winding number
14        forr (i,0,n)if(Ln(p[i],p[(i+1)%n]).seghas(q))return true;
15        int cnt=0;
16        forr (i,0,n){
17            int j=(i+1)%n;
18            int k=sgn((q-p[j])^(p[i]-p[j]));
19            int u=sgn(p[i].y-q.y),v=sgn(p[j].y-q.y);
20            if(k>0&&u<0&&v>=0)cnt++;
21            if(k<0&&v<0&&u>=0)cnt--;
22        }
23        return cnt!=0;
24    }
25    void normalize(){ // (call before haslog, remove collinear
26        // first)
27        if(n>=3&&p[2].left(p[0],p[1]))reverse(p.begin(),p.end());
28        int pi=min_element(p.begin(),p.end())-p.begin();
29        vector<Pt> s(n);
30        forr (i,0,n)s[i]=p[(pi+i)%n];
31        p.swap(s);

```

```

31 }
32 bool haslog(Pt q){ // O(log(n)) only CONVEX. Call normalize
33     // first
34     if(q.left(p[0],p[1])||q.left(p.back(),p[0]))return false;
35     int a=1,b=p.size()-1; // returns true if point on boundary
36     while(b-a>1){ // (change sign of EPS in left
37         // to return false in such case)
38         int c=(a+b)/2;
39         if(!q.left(p[0],p[c]))a=c;
40         else b=c;
41     }
42     return !q.left(p[a],p[a+1]);
43 }
44 bool isconvex(){//O(N), delete collinear points!
45     if(n<3) return false;
46     bool isLeft=p[0].left(p[1], p[2]);
47     forr (i, 1, n)
48         if(p[i].left(p[(i+1)%n], p[(i+2)%n])!=isLeft)
49             return false;
50     return true;
51 }
52 Pt farthest(Pt v){ // O(log(n)) only CONVEX
53     if(n<10){
54         int k=0;
55         forr (i,1,n)if(v*(p[i]-p[k])>EPS)k=i;
56         return p[k];
57     }
58     if(n==sz(p))p.pb(p[0]);
59     Pt a=p[1]-p[0];
60     int s=0,e=n,ua=v*a>EPS;
61     if(!ua&&v*(p[n-1]-p[0])<=EPS)return p[0];
62     while(1){
63         int m=(s+e)/2;Pt c=p[m+1]-p[m];
64         int uc=v*c>EPS;
65         if(!uc&&v*(p[m-1]-p[m])<=EPS)return p[m];
66         if(ua&&(!uc||v*(p[s]-p[m])>EPS))e=m;
67         else if(ua||uc||v*(p[s]-p[m])>=-EPS)s=m,a=c,ua=uc;
68         else e=m;
69         assert(e>s+1);
70     }
71 }

```

```

70 Pol cut(Ln l){ // cut CONVEX polygon by line l
71     vector<Pt> q; // returns part at left of l.pq
72     forr(i,0,n){
73         int
74             d0=sgn(l.pq^(p[i]-l.p)),d1=sgn(l.pq^(p[(i+1)%n]-l.p));
75         if(d0>=0)q.pb(p[i]);
76         Ln m(p[i],p[(i+1)%n]);
77         if(d0*d1<0&&!(1/m))q.pb(l^m);
78     }
79     return Pol(q);
80 }
81 T intercircle(circle c){ // area of intersection with circle
82     T r=0.;
83     forr(i,0,n){
84         int j=(i+1)%n;T w=c.intertriangle(p[i],p[j]);
85         if((p[j]-c.o)^(p[i]-c.o)>EPS)r+=w;
86         else r-=w;
87     }
88     return abs(r);
89 }
90 T callipers(){ // square distance of most distant points
91     T r=0; // prereq: convex, ccw, NO COLLINEAR POINTS
92     for(int i=0,j=n<2?0:1;i<j;++i){
93         for(;j=(j+1)%n){
94             r=max(r,(p[i]-p[j]).norm2());
95             if(((p[(i+1)%n]-p[i])^(p[(j+1)%n]-p[j]))<=EPS)break;
96         }
97     }
98     return r;
99 };

```

4.4. Circulo

```

1 using T = double;
2 struct Circle {
3     Pt o;T r;
4     Circle(Pt o, T r):o(o),r(r){}
5     Circle(Pt x, Pt y, Pt
        z){o=bisector(x,y)^bisector(x,z);r=(o-x).norm();}

```

```

6 bool has(Pt p){return (o-p).norm()<=r+EPS;}
7 vector<Pt> operator^(Circle c){ // ccw
8     vector<Pt> s;
9     T d=(o-c.o).norm();
10    if(d>r+c.r+EPS||d+min(r,c.r)+EPS<max(r,c.r))return s;
11    T x=(d*d-c.r*c.r+r*r)/(2*d);
12    T y=sqrt(r*r-x*x);
13    Pt v=(c.o-o)/d;
14    s.pb(o+v*x-v.rot(ccw90)*y);
15    if(y>EPS)s.pb(o+v*x+v.rot(ccw90)*y);
16    return s;
17 }
18 vector<Pt> operator^(Ln l){
19     vector<Pt> s;
20     Pt p=l.proj(o);
21     T d=(p-o).norm();
22     if(d-EPS>r)return s;
23     if(abs(d-r)<=EPS){s.pb(p);return s;}
24     d=sqrt(r*r-d*d);
25     s.pb(p+l.pq.unit()*d);
26     s.pb(p-l.pq.unit()*d);
27     return s;
28 }
29 vector<Pt> tang(Pt p){
30     T d=sqrt((p-o).norm2()-r*r);
31     return *this^Circle(p,d);
32 }
33 bool in(Circle c){ // non strict
34     T d=(o-c.o).norm();
35     return d+r<=c.r+EPS;
36 }
37 T intertriangle(Pt a, Pt b){ // area of intersection with oab
38     if(abs((o-a)%(o-b))<=EPS)return 0.;
39     vector<Pt> q={a},w=*this^Ln(a,b);
40     if(w.size()==2)for(auto p:w)if((a-p)*(b-p)<-EPS)q.pb(p);
41     q.pb(b);
42     if(q.size()==4&&(q[0]-q[1])*(q[2]-q[1])>EPS)swap(q[1],q[2]);
43     T s=0;
44     fore(i,0,q.size()-1){
45         if(!has(q[i])||!has(q[i+1]))s+=r*r*(q[i]-o).angle(q[i+1]-o)/2;

```

```

46         else s+=abs((q[i]-o)%(q[i+1]-o)/2);
47     }
48     return s;
49 }
50 };

```

4.5. Convex Hull

```

1 // CCW order
2 // Includes collinear points (change sign of EPS in left to
  // exclude)
3 vector<Pt> chull(vector<Pt> p){
4     if(sz(p)<3)return p;
5     vector<Pt> r;
6     sort(p.begin(),p.end()); // first x, then y
7     forr(i,0,p.size()){ // lower hull
8         while(r.size()>=2&&r.back().left(r[r.size()-2],p[i]))r.pop_back();
9         r.pb(p[i]);
10    }
11    r.pop_back();
12    int k=r.size();
13    for(int i=p.size()-1;i>=0;--i){ // upper hull
14        while(r.size()>=k+2&&r.back().left(r[r.size()-2],p[i]))r.pop_back();
15        r.pb(p[i]);
16    }
17    r.pop_back();
18    return r;
19 }

```

4.6. Orden Radial

```

1 struct Radial {
2     Pt o;
3     Radial(Pt _o) : o(_o) {}
4     int cuad(Pt p) {
5         if (p.x>0 && p.y>=0) return 1;
6         if (p.x<=0 && p.y>0) return 2;
7         if (p.x<0 && p.y<=0) return 3;
8         if (p.x>=0 && p.y<0) return 4;
9         assert(p.x == 0 && p.y == 0);
10        return 0; // origen < todos

```

```

11    }
12    bool comp(Pt p, Pt q) {
13        int c1 = cuad(p), c2 = cuad(q);
14        if (c1 == c2) return p%q>EPS;
15        return c1 < c2;
16    }
17    bool operator()(const Pt &p, const Pt &q) const {
18        return comp(p-o,q-o);
19    }
20 };

```

4.7. Par de puntos más cercano

```

1 #define dist(a, b) ((a-b).norm_sq())
2 bool sortx(pt a, pt b) {
3     return mp(a.x,a.y)<mp(b.x,b.y); }
4 bool sorty(pt a, pt b) {
5     return mp(a.y,a.x)<mp(b.y,b.x); }
6 ll closest(vector<pt> &ps, int l, int r) {
7     if (l == r-1) return INF;
8     if (l == r-2) {
9         if (sorty(ps[l+1], ps[l]))
10            swap(ps[l+1], ps[l]);
11        return dist(ps[l], ps[l+1]);
12    }
13    int m = (l+r)/2; ll xm = ps[m].x;
14    ll min_dist = min(closest(ps, l, m),closest(ps, m, r));
15    vector<pt> left(&ps[l], &ps[m]), right(&ps[m], &ps[r]);
16    merge(all(left), all(right), &ps[l], sorty);
17    ll delta = ll(sqrt(min_dist));
18    vector<pt> strip;
19    forr (i, l, r) if (ps[i].x>=xm-delta&&ps[i].x<=xm+delta)
20        strip.pb(ps[i]);
21    forn (i, sz(strip)) forr (j, 1, 8) {
22        if (i+j >= sz(strip)) break;
23        min_dist = min(min_dist, dist(strip[i], strip[i+j]));
24    }
25    return min_dist;
26 }
27 ll closest(vector<pt> &ps) { // devuelve dist^2

```

```

28     sort(all(ps), sortx);
29     return closest(ps, 0, sz(ps));
30 }

```

4.8. Arbol KD

```

1  // given a set of points, answer queries of nearest point in
   O(log(n))
2  bool onx(pt a, pt b){return a.x<b.x;}
3  bool ony(pt a, pt b){return a.y<b.y;}
4  struct Node {
5      pt pp;
6      ll x0=INF, x1=-INF, y0=INF, y1=-INF;
7      Node *first=0, *second=0;
8      ll distance(pt p){
9          ll x=min(max(x0,p.x),x1);
10         ll y=min(max(y0,p.y),y1);
11         return (pt(x,y)-p).norm2();
12     }
13     Node(vector<pt>&& vp):pp(vp[0]){
14         for(pt p:vp){
15             x0=min(x0,p.x); x1=max(x1,p.x);
16             y0=min(y0,p.y); y1=max(y1,p.y);
17         }
18         if(sz(vp)>1){
19             sort(all(vp),x1-x0>y1-y0?onx:ony);
20             int m=sz(vp)/2;
21             first=new Node({vp.begin(),vp.begin()+m});
22             second=new Node({vp.begin()+m,vp.end()});
23         }
24     }
25 };
26 struct KDTree {
27     Node* root;
28     KDTree(const vector<pt>& vp):root(new Node({all(vp)})) {}
29     pair<ll,pt> search(pt p, Node *node){
30         if(!node->first){
31             //avoid query point as answer
32             //if(p==node->pp) {INF,pt()};
33             return {(p-node->pp).norm2(),node->pp};

```

```

34     }
35     Node *f=node->first, *s=node->second;
36     ll bf=f->distance(p), bs=s->distance(p);
37     if(bf>bs)swap(bf,bs),swap(f,s);
38     auto best=search(p,f);
39     if(bs<best.fst) best=min(best,search(p,s));
40     return best;
41 }
42 pair<ll,pt> nearest(pt p){return search(p,root);}
43 };

```

4.9. Suma de Minkowski

```

1  vector<Pt> minkowski_sum(vector<Pt> &p, vector<Pt> &q){
2      int n=sz(p),m=sz(q),x=0,y=0;
3      forr(i,0,n) if(p[i]<p[x]) x=i;
4      forr(i,0,m) if(q[i]<q[y]) y=i;
5      vector<Pt> ans={p[x]+q[y]};
6      forr(it,1,n+m){
7          Pt a=p[(x+1)%n]+q[y];
8          Pt b=p[x]+q[(y+1)%m];
9          if(b.left(ans.back(),a)) ans.pb(b), y=(y+1)%m;
10         else ans.pb(a), x=(x+1)%n;
11     }
12     return ans;
13 }
14 vector<Pt> do_minkowski(vector<Pt> &p, vector<Pt> &q) {
15     normalize(p); normalize(q);
16     vector<Pt> sum = minkowski_sum(p, q);
17     return hull(sum); // no normalizado
18 }
19 // escalar poligono
20 vector<Pt> operator*(vector<Pt> &p, td u) {
21     vector<Pt> r; forn (i, sz(p)) r.pb(p[i]*u);
22     return r;
23 }

```

5. Strings

5.1. Hashing

```

1 struct StrHash { // Hash polinomial con exponentes decrecientes.
2     static constexpr ll ms[] = {1'000'000'007, 1'000'000'403};
3     static constexpr ll b = 500'000'000;
4     vector<ll> hs[2], bs[2];
5     StrHash(string const& s) {
6         int n = sz(s);
7         forn(k, 2) {
8             hs[k].resize(n+1), bs[k].resize(n+1, 1);
9             forn(i, n) {
10                 hs[k][i+1] = (hs[k][i] * b + s[i]) % ms[k];
11                 bs[k][i+1] = bs[k][i] * b % ms[k];
12             }
13         }
14     }
15     ll get(int idx, int len) const { // Hashes en 's[idx,
16         // idx+len)'.
17         ll h[2];
18         forn(k, 2) {
19             h[k] = hs[k][idx+len] - hs[k][idx] * bs[k][len] % ms[k];
20             if (h[k] < 0) h[k] += ms[k];
21         }
22         return (h[0] << 32) | h[1];
23     };

```

5.2. Suffix Array

```

1 #define RB(x) ((x) < n ? r[x] : 0)
2 void csort(vector<int>& sa, vector<int>& r, int k) {
3     int n = sz(sa);
4     vector<int> f(max(255, n)), t(n);
5     forn(i, n) ++f[RB(i+k)];
6     int sum = 0;
7     forn(i, max(255, n)) f[i] = (sum += f[i]) - f[i];
8     forn(i, n) t[f[RB(sa[i]+k)]]++ = sa[i];
9     sa = t;
10 }
11 vector<int> compute_sa(string& s){ // O(n*log2(n))
12     int n = sz(s) + 1, rank;
13     vector<int> sa(n), r(n), t(n);

```

```

14     iota(all(sa), 0);
15     forn(i, n) r[i] = s[i];
16     for (int k = 1; k < n; k *= 2) {
17         csort(sa, r, k), csort(sa, r, 0);
18         t[sa[0]] = rank = 0;
19         forr(i, 1, n) {
20             if(r[sa[i]] != r[sa[i-1]] || RB(sa[i]+k) !=
21                 RB(sa[i-1]+k)) ++rank;
22             t[sa[i]] = rank;
23         }
24         r = t;
25         if (r[sa[n-1]] == n-1) break;
26     }
27     return sa; // sa[i] = i-th suffix of s in lexicographical order
28 }
29 vector<int> compute_lcp(string& s, vector<int>& sa){
30     int n = sz(s) + 1, L = 0;
31     vector<int> lcp(n), plcp(n), phi(n);
32     phi[sa[0]] = -1;
33     forr(i, 1, n) phi[sa[i]] = sa[i-1];
34     forn(i, n) {
35         if (phi[i] < 0) { plcp[i] = 0; continue; }
36         while(s[i+L] == s[phi[i]+L]) ++L;
37         plcp[i] = L;
38         L = max(L - 1, 0);
39     }
40     forn(i, n) lcp[i] = plcp[sa[i]];
41     return lcp; // lcp[i] = longest common prefix between sa[i-1]
42     // and sa[i]

```

5.3. String Functions

```

1 template<class Char=char>vector<int> pfun(basic_string<Char>const&
2     w) {
3     int n = sz(w), j = 0; vector<int> pi(n);
4     forr(i, 1, n) {
5         while (j != 0 && w[i] != w[j]) {j = pi[j - 1];}
6         if (w[i] == w[j]) {++j;}
7         pi[i] = j;

```

```

7     } // pi[i] = length of longest proper suffix of w[0..i] that is
        also prefix
8     return pi;
9 }
10 template<class Char=char>vector<int> zfun(const
    basic_string<Char>& w) {
11     int n = sz(w), l = 0, r = 0; vector<int> z(n);
12     forr(i, 1, n) {
13         if (i <= r) {z[i] = min(r - i + 1, z[i - 1]);}
14         while (i + z[i] < n && w[z[i]] == w[i + z[i]]) {++z[i];}
15         if (i + z[i] - 1 > r) {l = i, r = i + z[i] - 1;}
16     } // z[i] = length of longest prefix of w that also begins at
        index i
17     return z;
18 }

```

5.4. Kmp

```

1 template<class Char=char>struct Kmp {
2     using str = basic_string<Char>;
3     vector<int> pi; str pat;
4     Kmp(str const& _pat): pi(move(pfun(_pat))), pat(_pat) {}
5     vector<int> matches(str const& txt) const {
6         if (sz(pat) > sz(txt)) {return {}};
7         vector<int> occs; int m = sz(pat), n = sz(txt);
8         if (m == 0) {occs.push_back(0);}
9         int j = 0;
10        forn(i, n) {
11            while (j != 0 && txt[i] != pat[j]) {j = pi[j-1];}
12            if (txt[i] == pat[j]) {++j;}
13            if (j == m) {occs.push_back(i - j + 1);}
14        }
15        return occs;
16    }
17 };

```

5.5. Manacher

```

1 struct Manacher {
2     vector<int> p;
3     Manacher(string const& s) {

```

```

4         int n = sz(s), m = 2*n+1, l = -1, r = 1;
5         vector<char> t(m); forn(i, n) t[2*i+1] = s[i];
6         p.resize(m); forr(i, 1, m) {
7             if (i < r) p[i] = min(r-i, p[l+r-i]);
8             while (p[i] <= i && i < m-p[i] && t[i-p[i]] ==
                t[i+p[i]]) ++p[i];
9             if (i+p[i] > r) l = i-p[i], r = i+p[i];
10        }
11    } // Retorna palindromos de la forma {comienzo, largo}.
12    pii at(int i) const {int k = p[i]-1; return pair{i/2-k/2, k};}
13    pii odd(int i) const {return at(2*i+1);} // Mayor centrado en
        s[i].
14    pii even(int i) const {return at(2*i);} // Mayor centrado en
        s[i-1, i].
15 };

```

5.6. Mínima Rotación Lexicográfica

```

1 // nica secuencia no-creciente de strings menores a sus rotaciones
2 vector<pii> lyndon(string const& s) {
3     vector<pii> fs;
4     int n = sz(s);
5     for (int i = 0, j, k; i < n; i++) {
6         for (k = i, j = i+1; j < n && s[k] <= s[j]; ++j)
7             if (s[k] < s[j]) k = j; else ++k;
8         for (int m = j-k; i <= k; i += m) fs.emplace_back(i, m);
9     }
10    return fs; // retorna substrings de la forma {comienzo, largo}
11 }
12
13 // ltimo comienzo de la mnima rotacin
14 int minrot(string const& s) {
15     auto fs = lyndon(s+s);
16     int n = sz(s), start = 0;
17     for (auto f : fs) if (f.fst < n) start = f.fst; else break;
18     return start;
19 }

```

5.7. Trie

```

1 // trie genrico. si es muy lento, se puede modificar para que los

```



```

    hijos sean
2 // representados con un array del tamaño del alfabeto
3 template<class Char> struct Trie {
4     struct Node {
5         map<Char, Node*> child;
6         bool term;
7     };
8     Node* root;
9     static inline deque<Node> nodes;
10    static Node* make() {
11        nodes.emplace_back();
12        return &nodes.back();
13    }
14    Trie() : root{make()} {}
15    // retorna el largo del mayor prefijo de s que es prefijo de
    // algun string
16    // insertado en el trie
17    int find(basic_string<Char> const& s) const {
18        Node* curr = root;
19        forn(i,sz(s)) {
20            auto it = curr->child.find(s[i]);
21            if (it == end(curr->child)) return i;
22            curr = it->snd;
23        }
24        return sz(s);
25    }
26    // inserta s en el trie
27    void insert(basic_string<Char> const& s) {
28        Node* curr = root;
29        forn(i,sz(s)) {
30            auto it = curr->child.find(s[i]);
31            if (it == end(curr->child)) curr = curr->child[s[i]] =
                make();
32            else curr = it->snd;
33        }
34        curr->term = true;
35    }
36    // elimina s del trie
37    void erase(basic_string<Char> const& s) {
38        auto erase = [&](auto&& me, Node* curr, int i) -> bool {

```

```

39            if (i == sz(s)) {
40                curr->term = false;
41                return sz(curr->child) == 0;
42            }
43            auto it = curr->child.find(s[i]);
44            if (it == end(curr->child)) return false;
45            if (!me(me,it->snd,i+1)) return false;
46            curr->child.erase(it);
47            return sz(curr->child) == 0;
48        };
49        erase(erase,root,0);
50    }
51 };

```

5.8. Suffix Automaton

```

1 /// Minimal DFA that accepts all suffixes of a string.
2 /// - Any path starting at '0' forms a substring.
3 /// - Every substring corresponds to a path starting at '0'.
4 /// - Each state corresponds to the set of all substrings that
    // have the same
5 /// ending positions in the string, that is, each state 'u'
    // represents an
6 /// equivalence class according to their ending positions
    // 'endpos(u)'.
7 /// Given a state 'u', we can define the following concepts:
8 /// - 'longest(u)': longest substring corresponding to 'u'.
9 /// - 'len(u)': length of 'longest(u)'.
10 /// - 'shortest(u)': shortest substring corresponding to 'u'.
11 /// - 'minlen(u)': length of 'shortest(u)'.
12 /// Any state 'u' corresponds to all suffixes of 'longest(u)' no
    // shorter
13 /// than 'minlen(u)'.
14 /// For state 'u', 'link(u)' points to the state 'v' such that
    // 'longest(v)'
15 /// is a suffix of 'longest(u)' with 'len(v) == minlen(u) - 1'.
    // These links
16 /// form a tree with the root in '0' and an inclusion
    // relationship between
17 /// all 'endpos'.

```

```

18 template<class Char=char>class SuffixAutomaton {
19     using str = basic_string<Char>;
20     void extend(Char c, int& last) {
21         txt.pb(c); int p = last; last = new_state();
22         len[last] = len[p] + 1, firstpos[last] = len[p];
23         do {next[p][c] = last, p = link[p];} while (p >= 0 &&
24             !next[p].count(c));
25         if (p == -1) {link[last] = 0;} else {
26             int q = next[p][c];
27             if (len[q] == len[p] + 1) {link[last] = q;} else {
28                 int cl = copy_state(q);
29                 len[cl] = len[p] + 1; link[last] = link[q] = cl;
30                 do {next[p][c] = cl, p = link[p];} while (p >= 0 &&
31                     next[p].at(c) == q);
32             }
33         }
34     }
35     int new_state() {
36         next.pb({}), link.pb(-1), len.pb(0), firstpos.pb(-1);
37         return size++;
38     }
39     int copy_state(int state) {
40         next.pb(next[state]), link.pb(link[state]);
41         len.pb(len[state]), firstpos.pb(firstpos[state]);
42         return size++;
43     }
44     void dfs(int curr=0) {
45         terminal_paths_from[curr] = term[curr];
46         paths_from[curr] = 1;
47         fore(edge, next[curr]) {
48             int other = edge.snd;
49             if (!paths_from[other]) {dfs(other);}
50             terminal_paths_from[curr] += terminal_paths_from[other];
51             paths_from[curr] += paths_from[other];
52             substrings_from[curr] += substrings_from[other];
53         }
54         substrings_from[curr] += terminal_paths_from[curr];
55     }
56     void compute(int last) {
57         term.resize(size);

```

```

56         for (int curr = last; curr != -1; curr = link[curr])
57             {term[curr] = true;}
58         inv_link.resize(size);
59         forr(curr, 1, size) {inv_link[link[curr]].pb(curr);}
60     }
61     public:
62         vector<bool> term; // Terminal statuses.
63         vector<vector<int>> inv_link; // Inverse suffix links.
64         vector<map<Char, int>> next{{{}}}; // Automaton transitions.
65         vector<int> len{0}; // len[u] = length of longest(u)
66         vector<int> link{-1}; // Suffix links.
67         vector<int> firstpos{-1}; // First endpos element of each
68             state.
69         // Number of paths starting at each state and ending in a
70             terminal state.
71         // For '0', this is the number of suffixes (including the
72             empty suffix).
73         vector<int> terminal_paths_from;
74         // Number of paths starting at each state. For '0', this is
75             the number of
76             distinct substrings (including the empty substring).
77         vector<ll> paths_from;
78         // Number of substrings starting at each state. For '0', this
79             is the number
80             of substrings counting repetitions (including the empty
81             substring
82             repeated 'n+1' times, where 'n' is the length of the
83             original string).
84         vector<ll> substrings_from;
85         int size = 1; // Number of states.
86         str txt; // Original string.
87         SuffixAutomaton(str const& _txt) {
88             int last = 0;
89             fore(c, _txt) {extend(c, last);}
90             compute(last); terminal_paths_from.resize(size);
91             paths_from.resize(size); substrings_from.resize(size);
92             dfs();
93         }
94         pair<int, int> run(str const& pat) const {
95             int curr = 0, read = 0; // curr = last visited state

```

```

87     for (
88         auto it = pat.begin();
89         it != pat.end() && next[curr].count(*it);
90         curr = next[curr].at(*(it++))
91     ) {++read;} // read = number of traversed transitions
92     return {curr, read};
93 }
94 bool is_suff(str const& pat) const
95     {auto [state, read] = run(pat); return term[state] && read
96     == sz(pat);}
97 bool is_substr(str const& pat) const {return run(pat).snd ==
98     sz(pat);}
99 int num_occs(str const& pat) const {
100     auto [state, read] = run(pat);
101     return read == sz(pat) ? terminal_paths_from[state] : 0;
102 }
103 int fst_occ(str const& pat) const {
104     int m = sz(pat); auto [state, read] = run(pat);
105     return read == m ? firstpos[state] + 1 - m : -1;
106 }
107 vector<int> all_occs(str const& pat) const {
108     vector<int> occs; int m = sz(pat); auto [node, read] =
109     run(pat);
110     if (read == m) {
111         stack<int> st{{node}};
112         while (!st.empty()) {
113             int curr = st.top(); st.pop();
114             occs.pb(firstpos[curr] + 1 - m);
115             fore(child, inv_link[curr]) {st.push(child);}
116         }
117     }
118     // sort(all(occs)); occs.erase(unique(all(occs)),
119     // occs.end());
120     return occs; // unsorted and nonunique by default
121 }
122 };

```

5.9. Utilidades

```

1 getline(cin, linea); // tomar toda la linea

```

```

2 stringstream ss(linea); // tratar una linea como stream
3 ss >> s; ss << s; // leer solo hasta un espacio, escribir a ss
4 tipo n; ss >> n; // leer de un stringstream (float, int, etc.)
5 int pos = s.find_first_of("aeoiu"); // devuelve -1 si no encuentra
6 int next = s.find_first_of("aeoiu", pos);
7 // s.find_first_not_of("aeoiu"); s.find_last_of();
8 s.substr(pos, next-pos); // substr(pos, len)
9 s.c_str(); // devuelve un puntero de C
10 ss.str(); // devuelve el string en ss
11 // isspace(); islower(); isupper(); isdigit(); isalpha();
12 // tolower(); toupper();

```

6. Grafos

6.1. Dijkstra

```

1 vector<pair<int,int>> g[MAXN]; // u->[(v,cost)]
2 ll dist[MAXN];
3 void dijkstra(int x){
4     memset(dist,-1,sizeof(dist));
5     priority_queue<pair<ll,int> > q;
6     dist[x]=0;q.push({0,x});
7     while(!q.empty()){
8         x=q.top().snd;ll c=-q.top().fst;q.pop();
9         if(dist[x]!=c)continue;
10        forn(i,g[x].size()){
11            int y=g[x][i].fst; ll c=g[x][i].snd;
12            if(dist[y]<0||dist[x]+c<dist[y])
13                dist[y]=dist[x]+c,q.push({-dist[y],y});
14        }
15    }
16 }

```

6.2. LCA

```

1 int n;
2 vector<int> g[MAXN];
3
4 vector<int> depth, etour, vtime;
5

```

```

6 // operacin de la sparse table, escribir '#define oper lca_oper'
7 int lca_oper(int u, int v) { return depth[u]<depth[v] ? u : v; };
8
9 void lca_dfs(int u) {
10     vtime[u] = sz(etour), etour.push_back(u);
11     for (auto v : g[u]) {
12         if (vtime[v] >= 0) continue;
13         depth[v] = depth[u]+1; lca_dfs(v); etour.push_back(u);
14     }
15 }
16 auto lca_init(int root) {
17     depth.assign(n,0), etour.clear(), vtime.assign(n,-1);
18     lca_dfs(root); st_init(etour);
19 }
20
21 auto lca(int u, int v) {
22     int l = min(vtime[u],vtime[v]);
23     int r = max(vtime[u],vtime[v])+1;
24     return st_query(l,r);
25 }
26 int dist(int u, int v) { return
    depth[u]+depth[v]-2*depth[lca(u,v)]; }

```

6.3. Binary Lifting

```

1 vector<int> g[1<<K]; int n; // K such that 2^K>=n
2 int F[K][1<<K], D[1<<K];
3 void lca_dfs(int x){
4     forn(i, sz(g[x])){
5         int y = g[x][i]; if(y==F[0][x]) continue;
6         F[0][y]=x; D[y]=D[x]+1;lca_dfs(y);
7     }
8 }
9 void lca_init(){
10     D[0]=0;F[0][0]=-1;
11     lca_dfs(0);
12     forr(k,1,K)forn(x,n)
13         if(F[k-1][x]<0)F[k][x]=-1;
14         else F[k][x]=F[k-1][F[k-1][x]];
15 }

```

```

16 int lca(int x, int y){
17     if(D[x]<D[y])swap(x,y);
18     for(int k = K-1;k>=0;--k) if(D[x]-(1<<k) >=D[y])x=F[k][x];
19     if(x==y)return x;
20     for(int k=K-1;k>=0;--k)if(F[k][x]!=F[k][y])x=F[k][x],y=F[k][y];
21     return F[0][x];
22 }
23
24
25 int dist(int x, int y){
26     return D[x] + D[y] - 2*D[lca(x,y)];
27 }

```

6.4. Toposort

```

1 vector<int> g[MAXN];int n;
2 vector<int> tsort(){ // lexicographically smallest topological sort
3     vector<int> r;priority_queue<int> q;
4     vector<int> d(2*n,0);
5     forn(i,n)forn(j,g[i].size())d[g[i][j]]++;
6     forn(i,n)if(!d[i])q.push(-i);
7     while(!q.empty()){
8         int x=-q.top();q.pop();r.pb(x);
9         forn(i,sz(g[x])){
10             d[g[x][i]]--;
11             if(!d[g[x][i]])q.push(-g[x][i]);
12         }
13     }
14     return r; // if not DAG it will have less than n elements
15 }

```

6.5. Deteccion ciclos negativos

```

1 // g[i][j]: weight of edge (i, j) or INF if there's no edge
2 // g[i][i]=0
3 ll g[MAXN][MAXN];int n;
4 void floyd(){ // O(n^3) . Replaces g with min distances
5     forn(k,n)forn(i,n)if(g[i][k]<INF)forn(j,n)if(g[k][j]<INF)
6         g[i][j]=min(g[i][j],g[i][k]+g[k][j]);
7 }
8 bool inNegCycle(int v){return g[v][v]<0;}

```

```

9 bool hasNegCycle(int a, int b){ // true iff there's neg cycle in
    between
10     forn(i,n)if(g[a][i]<INF&&g[i][b]<INF&&g[i][i]<0)return true;
11     return false;
12 }

```

6.6. Camino Euleriano

```

1 // Directed version (uncomment commented code for undirected)
2 struct edge {
3     int y;
4     // list<edge>::iterator rev;
5     edge(int y):y(y){}
6 };
7 list<edge> g[MAXN];
8 void add_edge(int a, int b){
9     g[a].push_front(edge(b));//auto ia=g[a].begin();
10    // g[b].push_front(edge(a));auto ib=g[b].begin();
11    // ia->rev=ib;ib->rev=ia;
12 }
13 vector<int> p;
14 void go(int x){
15     while(g[x].size()){
16         int y=g[x].front().y;
17         //g[y].erase(g[x].front().rev);
18         g[x].pop_front();
19         go(y);
20     }
21     p.push_back(x);
22 }
23 vector<int> get_path(int x){ // get a path that begins in x
24 // check that a path exists from x before calling to get_path!
25     p.clear();go(x);reverse(p.begin(),p.end());
26     return p;
27 }

```

6.7. Camino Hamiltoniano

```

1 constexpr int MAXN = 20;
2 int n;
3 bool adj[MAXN][MAXN];

```

```

4
5 bool seen[1<<MAXN][MAXN];
6 bool memo[1<<MAXN][MAXN];
7 // true sii existe camino simple en el conjunto s que empieza en u
8 bool hamilton(int s, int u) {
9     bool& ans = memo[s][u];
10    if (seen[s][u]) return ans;
11    seen[s][u] = true, s ^= (1<<u);
12    if (s == 0) return ans = true;
13    forn(v,n) if (adj[u][v] && (s&(1<<v)) && hamilton(s,v)) return
        ans = true;
14    return ans = false;
15 }
16 // true sii existe camino hamiltoniano. complejidad O((1<<n)*n*n)
17 bool hamilton() {
18     forn(s,1<<n) forn(u,n) seen[s][u] = false;
19     forn(u,n) if (hamilton((1<<n)-1,u)) return true;
20     return false;
21 }

```

6.8. Tarjan SCC

```

1 vector<int> g[MAXN], ss;
2 int n, num, order[MAXN], lnk[MAXN], nsc, cmp[MAXN];
3 void scc(int u) {
4     order[u] = lnk[u] = ++num;
5     ss.pb(u); cmp[u] = -2;
6     for (auto v : g[u]) {
7         if (order[v] == 0) {
8             scc(v);
9             lnk[u] = min(lnk[u], lnk[v]);
10        }
11        else if (cmp[v] == -2) {
12            lnk[u] = min(lnk[u], lnk[v]);
13        }
14    }
15    if (lnk[u] == order[u]) {
16        int v;
17        do { v = ss.back(); cmp[v] = nsc; ss.pop_back(); }
18        while (v != u);

```

```

19     nsc++;
20 }
21 }
22 void tarjan() {
23     memset(order, 0, sizeof(order)); num = 0;
24     memset(cmp, -1, sizeof(cmp)); nsc = 0;
25     forn (i, n) if (order[i] == 0) scc(i);
26 }

```

6.9. Bellman-Ford

```

1  const int INF=2e9; int n;
2  vector<pair<int,int> > g[MAXN]; // u->[(v,cost)]
3  ll dist[MAXN];
4  void bford(int src){ // O(nm)
5      fill(dist,dist+n,INF);dist[src]=0;
6      forr(_,0,n)forr(x,0,n)if(dist[x]!=INF)for(auto t:g[x]){
7          dist[t.fst]=min(dist[t.fst],dist[x]+t.snd);
8      }
9      forr(x,0,n)if(dist[x]!=INF)for(auto t:g[x]){
10         if(dist[t.fst]>dist[x]+t.snd){
11             // neg cycle: all nodes reachable from t.fst have
12             // -INF distance
13             // to reconstruct neg cycle: save "prev" of each
14             // node, go up from t.fst until repeating a node.
15             // this node and all nodes between the two
16             // occurences form a neg cycle
17         }
18     }
19 }

```

6.10. Puentes y Articulacion

```

1  // solo para grafos no dirigidos
2  vector<int> g[MAXN];
3  int n, num, order[MAXN], lnk[MAXN], art[MAXN];
4  void bridge_art(int u, int p) {
5      order[u] = lnk[u] = ++num;
6      for (auto v : g[u]) if (v != p) {
7          if (order[v] == 0) {
8              bridge_art(v, u);

```

```

9          if (lnk[v] >= order[u]) // para puntos de
10             art[u] = 1; // articulacion.
11             if (lnk[v] > order[u]) // para puentes.
12                 handle_bridge(u, v);
13         }
14         lnk[u] = min(lnk[u], lnk[v]);
15     }
16 }
17 void run() {
18     memset(order, 0, sizeof(order));
19     memset(art, 0, sizeof(art)); num = 0;
20     forn (i, n) {
21         if (order[i] == 0) {
22             bridge_art(i, -1);
23             art[i] = (sz(g[i]) > 1);
24         }
25     }
26 }

```

6.11. Kruskal

```

1  int uf[MAXN];
2  void uf_init(){memset(uf,-1,sizeof(uf));}
3  int uf_find(int x){return uf[x]<0?x:uf[x]=uf_find(uf[x]);}
4  bool uf_join(int x, int y){
5      x=uf_find(x);y=uf_find(y);
6      if(x==y)return false;
7      if(uf[x]>uf[y])swap(x,y);
8      uf[x]+=uf[y];uf[y]=x;
9      return true;
10 }
11 vector<pair<ll,pair<int,int> > > es; // edges (cost,(u,v))
12 ll kruskal(){ // assumes graph is connected
13     sort(es.begin(),es.end());uf_init();
14     ll r=0;
15     forr(i,0,es.size()){
16         int x=es[i].snd.fst,y=es[i].snd.snd;
17         if(uf_join(x,y))r+=es[i].fst; // (x,y,c) belongs to mst
18     }
19     return r; // total cost

```

```
20 }
```

6.12. Chequeo Bipartito

```
1 int n;
2 vector<int> g[MAXN];
3
4 bool color[MAXN];
5 bool bicolor() {
6     vector<bool> seen(n);
7     auto dfs = [&](auto&& me, int u, bool c) -> bool {
8         color[u] = c, seen[u] = true;
9         for (int v : g[u]) {
10             if (seen[v] && color[v] == color[u]) return false;
11             if (!seen[v] && !me(me,v,!c)) return false;
12         }
13         return true;
14     };
15     forn(u,n) if (!seen[u] && !dfs(dfs,u,0)) return false;
16     return true;
17 }
```

6.13. Centroid Decomposition

```
1 bool vis[MAXN]; //para centroides
2 vector<int> g[MAXN]; int size[MAXN];
3 vector<int> g1[MAXN]; //para centroides
4 void calcsz(int u, int p) {
5     size[u] = 1;
6     for (int v : g[u]) if (v != p && !vis[v]) {
7         calcsz(v, u); size[u] += size[v]; }
8 }
9 int cendfs(int u, int p, int ts) {
10     int maximo = 0, pesado, r;
11     for (int v : g[u]) if (v != p && !vis[v]) {
12         if (maximo < size[v]) {
13             maximo = size[v]; pesado = v; }
14     }
15     if (maximo <= (ts/2)) {
16         vis[u] = true;
17         for (int v : g[u]) if (!vis[v]) {
```

```
18             if (v == p) calcsz(v, u);
19             r = cendfs(v, u, hijos[v]);
20             add_edge(g1, u, r);
21         }
22         r = u;
23     }
24     else r = cendfs(pesado, u, ts);
25     return r;
26 }
27 // euler para responder en el arbol de centroides
28 int te[MAXN], ts[MAXN]; vector<Partial> euler;
29 void do_euler(int u, int p, Partial &p) {
30     te[u] = sz(euler); euler.pb(c);
31     for (int v : g[u]) if (v != p && !vis[v]) {
32         do_euler(v, u, p); } //cambiar p
33     ts[u] = sz(euler);
34 }
35 Sol oncen(int u, int p) {
36     do_euler(u, p, Partial{});
37     vis[u] = true; //no tocar visitados
38     Sol r{};
39     for (int v : g1[u]) if (v != p) {
40         r = max(r, oncen(v, u)); }
41     return r;
42 }
```

6.14. HLD

```
1 vector<int> g[MAXN];
2 int wg[MAXN],dad[MAXN],dep[MAXN]; // weight,father,depth
3 void dfs1(int x){
4     wg[x]=1;
5     for(int y:g[x])if(y!=dad[x]){
6         dad[y]=x;dep[y]=dep[x]+1;dfs1(y);
7         wg[x]+=wg[y];
8     }
9 }
10 int curpos,pos[MAXN],head[MAXN];
11 void hld(int x, int c){
12     if(c<0)c=x;
```

```

13     pos[x]=curpos++;head[x]=c;
14     int mx=-1;
15     for(int y:g[x])if(y!=dad[x]&&(mx<0||wg[mx]<wg[y]))mx=y;
16     if(mx>=0)hld(mx,c);
17     for(int y:g[x])if(y!=mx&&y!=dad[x])hld(y,-1);
18 }
19 void hld_init(){dad[0]=-1;dep[0]=0;dfs1(0);curpos=0;hld(0,-1);}
20 int query(int x, int y, RMQ& rmq){
21     int r=neutro; //neutro del rmq
22     while(head[x]!=head[y]){
23         if(dep[head[x]]>dep[head[y]])swap(x,y);
24         r=oper(r,rmq.get(pos[head[y]],pos[y]+1));
25         y=dad[head[y]];
26     }
27     if(dep[x]>dep[y])swap(x,y); // now x is lca
28     r=oper(r,rmq.get(pos[x],pos[y]+1));
29     return r;
30 }
31 // hacer una vez al principio hld_init() despues de armar el grafo
   en g
32 // para querys pasar los dos nodos del camino y un stree que tiene
   en pos[x] el valor del nodo x
33 // for updating: rmq.set(pos[x],v);
34 // queries on edges: - assign values of edges to "child" node ()
   ***
35 // - change pos[x] to pos[x]+1 in query (line 28)
36 // *** if(dep[u] > dep[v]) rmq.upd(pos[u], w) para cada arista
   (u,v)

```

6.15. Max Tree Matching

```

1 int n, r, p[MAXN]; // nmero de nodos, raz, y lista de padres
2 vector<int> g[MAXN]; // lista de adyancencia
3
4 int match[MAXN];
5 // encuentra el max matching del rbol. complejidad O(n)
6 int maxmatch() {
7     fill(match,match+n,-1);
8     int size = 0;
9     auto dfs = [&](auto&& me, int u) -> int {

```

```

10         for (auto v : g[u]) if (v != p[u])
11             if (match[u] == me(me,v)) match[u] = v, match[v] = u;
12         size += match[u] >= 0;
13         return match[u];
14     };
15     dfs(dfs,r);
16     return size;
17 }

```

6.16. Min Tree Vertex Cover

```

1 int n, r, p[MAXN]; // nmero de nodos, raz, y lista de padres
2 vector<int> g[MAXN]; // lista de adyancencia
3
4 bool cover[MAXN];
5 // encuentra el min vertex cover del rbol. complejidad O(n)
6 int mincover() {
7     fill(cover,cover+n,false);
8     int size = 0;
9     auto dfs = [&](auto&& me, int u) -> bool {
10         for (auto v : g[u]) if (v != p[u] && !me(me,v)) cover[u] =
               true;
11         size += cover[u];
12         return cover[u];
13     };
14     dfs(dfs,r);
15     return size;
16 }

```

6.17. 2-SAT

```

1 struct TwoSatSolver{
2     int n_vars;
3     int n_vertices;
4     vector<vector<int>> adj, adj_t;
5     vector<bool> used;
6     vector<int> order,comp;
7     vector<bool> assignment;
8     TwoSatSolver(int _n_vars) : n_vars(_n_vars),
9         n_vertices(2*_n_vars), adj(n_vertices),
10         adj_t(n_vertices), used(n_vertices),

```



```

11     order(), comp(n_vertices, -1), assignment(n_vars){
12     order.reserve(n_vertices);
13 }
14 void dfs1(int v){
15     used[v] = true;
16     for(int u : adj[v]){
17         if(!used[u]) dfs1(u);
18     }
19     order.pb(v);
20 }
21 void dfs2(int v, int c1){
22     comp[v] = c1;
23     for(int u : adj_t[v]){
24         if(comp[u] == -1) dfs2(u, c1);
25     }
26 }
27 bool solve_2SAT(){
28     order.clear();
29     used.assign(n_vertices, false);
30     forn(i, n_vertices){
31         if(!used[i]) dfs1(i);
32     }
33     comp.assign(n_vertices, -1);
34     for(int i = 0, j = 0; i < n_vertices; ++i){
35         int v = order[n_vertices - i - 1];
36         if(comp[v] == -1) dfs2(v, j++);
37     }
38     assignment.assign(n_vars, false);
39     for(int i = 0; i < n_vertices; i+=2){
40         if(comp[i] == comp[i+1]) return false;
41         assignment[i/2] = comp[i] > comp[i+1];
42     }
43     return true;
44 }
45 void add_disjunction(int a, bool na, int b, bool nb){
46     a = 2 * a ^ na;
47     b = 2 * b ^ nb;
48     int neg_a = a ^ 1;
49     int neg_b = b ^ 1;
50     adj[neg_a].pb(b);

```

```

51     adj[neg_b].pb(a);
52     adj_t[b].pb(neg_a);
53     adj_t[a].pb(neg_b);
54 }
55 };

```

6.18. K Colas

```

1  const int K=9999; // en general, K = MAX_DIST+1
2  vector<Datos> colas[K];
3  int cola_actual = 0, ult_cola = -1;
4  // push toma la dist actual y la siguiente
5  #define push(d,nd,args...)
6      colas[(cola_actual+nd-d)%K].emplace_back(nd, args)
7  #define pop colas[cola_actual].pop_back
8  #define top colas[cola_actual].back
9  // PUSHEAR POSICION INICIAL
10 for (; ; cola_actual = (cola_actual+1)%K) {
11     if (ult_cola == cola) break; // dimos la vuelta
12     if (colas[cola_actual].size()) ult_cola = cola;
13     while (colas[cola_actual].size()) {
14     }
15 }

```

7. Flujo

7.1. Dinic

```

1 struct Dinic{
2     int nodes,src,dst;
3     vector<int> dist,q,work;
4     struct edge {int to,rev;ll f,cap;};
5     vector<vector<edge>> g;
6     Dinic(int x):nodes(x),g(x),dist(x),q(x),work(x){}
7     void add_edge(int s, int t, ll cap){
8         g[s].pb((edge){t,sz(g[t]),0,cap});
9         g[t].pb((edge){s,sz(g[s])-1,0,0});
10    }
11    bool dinic_bfs(){

```

```

12     fill(all(dist), -1); dist[src] = 0;
13     int qt = 0; q[qt++] = src;
14     for(int qh = 0; qh < qt; qh++){
15         int u = q[qh];
16         for(int i = 0; i < sz(g[u]); i++){
17             edge &e = g[u][i]; int v = g[u][i].to;
18             if(dist[v] < 0 && e.f < e.cap) dist[v] = dist[u] + 1, q[qt++] = v;
19         }
20     }
21     return dist[dst] >= 0;
22 }
23 ll dinic_dfs(int u, ll f){
24     if(u == dst) return f;
25     for(int &i = work[u]; i < sz(g[u]); i++){
26         edge &e = g[u][i];
27         if(e.cap <= e.f) continue;
28         int v = e.to;
29         if(dist[v] == dist[u] + 1){
30             ll df = dinic_dfs(v, min(f, e.cap - e.f));
31             if(df > 0){ e.f += df; g[v][e.rev].f -= df; return df; }
32         }
33     }
34     return 0;
35 }
36 ll max_flow(int _src, int _dst){
37     src = _src; dst = _dst;
38     ll result = 0;
39     while(dinic_bfs()){
40         fill(all(work), 0);
41         while(ll delta = dinic_dfs(src, INF)) result += delta;
42     }
43     return result;
44 }
45 };

```

7.2. Min Cost Max Flow

```

1  typedef ll tf;
2  typedef ll tc;
3  const tf INFFLOW = 1e9;

```

```

4  const tc INFCOST = 1e9;
5  struct MCF{
6      int n;
7      vector<tc> prio, pot; vector<tf> curflow; vector<int>
          prevedge, prevnode;
8      priority_queue<pair<tc, int>, vector<pair<tc, int>>,
          greater<pair<tc, int>>> q;
9      struct edge{int to, rev; tf f, cap; tc cost;};
10     vector<vector<edge>> g;
11     MCF(int
        n):n(n), prio(n), curflow(n), prevedge(n), prevnode(n), pot(n), g(n){}
12     void add_edge(int s, int t, tf cap, tc cost) {
13         g[s].pb((edge){t, sz(g[t]), 0, cap, cost});
14         g[t].pb((edge){s, sz(g[s]) - 1, 0, 0, -cost});
15     }
16     pair<tf, tc> get_flow(int s, int t) {
17         tf flow = 0; tc flowcost = 0;
18         while(1){
19             q.push({0, s});
20             fill(all(prio), INFCOST);
21             prio[s] = 0; curflow[s] = INFFLOW;
22             while(!q.empty()) {
23                 auto cur = q.top();
24                 tc d = cur.fst;
25                 int u = cur.snd;
26                 q.pop();
27                 if(d != prio[u]) continue;
28                 for(int i = 0; i < sz(g[u]); ++i) {
29                     edge &e = g[u][i];
30                     int v = e.to;
31                     if(e.cap <= e.f) continue;
32                     tc nprio = prio[u] + e.cost + pot[u] - pot[v];
33                     if(prio[v] > nprio) {
34                         prio[v] = nprio;
35                         q.push({nprio, v});
36                         prevnode[v] = u; prevedge[v] = i;
37                         curflow[v] = min(curflow[u], e.cap - e.f);
38                     }
39                 }
40             }

```

```

41         if(prio[t]==INFCOST) break;
42         forr(i,0,n) pot[i]+=prio[i];
43         tf df=min(curflow[t], INFFLOW-flow);
44         flow+=df;
45         for(int v=t; v!=s; v=prevnode[v]) {
46             edge &e=g[prevnode[v]][prevedge[v]];
47             e.f+=df; g[v][e.rev].f-=df;
48             flowcost+=df*e.cost;
49         }
50     }
51     return {flow,flowcost};
52 }
53 };

```

7.3. Hopcroft Karp

```

1  int n, m;           // nmero de nodos en ambas partes
2  vector<int> g[MAXN]; // lista de adyacencia [0,n) -> [0,m)
3
4  int mat[MAXN]; // matching [0,n) -> [0,m)
5  int inv[MAXM]; // matching [0,m) -> [0,n)
6  // encuentra el max matching del grafo bipartito
7  // complejidad  $O(\sqrt{n+m} \cdot e)$ , donde e es el nmero de aristas
8  int hopkarp() {
9      fill(mat,mat+n,-1);
10     fill(inv,inv+m,-1);
11     int size = 0;
12     vector<int> d(n);
13     auto bfs = [&] {
14         bool aug = false;
15         queue<int> q;
16         forn(u,n) if (mat[u] < 0) q.push(u); else d[u] = -1;
17         while (!q.empty()) {
18             int u = q.front();
19             q.pop();
20             for (auto v : g[u]) {
21                 if (inv[v] < 0) aug = true;
22                 else if (d[inv[v]] < 0) d[inv[v]] = d[u] + 1,
                    q.push(inv[v]);
23             }

```

```

24         }
25         return aug;
26     };
27     auto dfs = [&](auto&& me, int u) -> bool {
28         for (auto v : g[u]) if (inv[v] < 0) {
29             mat[u] = v, inv[v] = u;
30             return true;
31         }
32         for (auto v : g[u]) if (d[inv[v]] > d[u] && me(me,inv[v])) {
33             mat[u] = v, inv[v] = u;
34             return true;
35         }
36         d[u] = 0;
37         return false;
38     };
39     while (bfs()) forn(u,n) if (mat[u] < 0) size += dfs(dfs,u);
40     return size;
41 }

```

7.4. Kuhn

```

1  int n, m;           // nmero de nodos en ambas partes
2  vector<int> g[MAXN]; // lista de adyacencia [0,n) -> [0,m)
3
4  int mat[MAXN]; // matching [0,n) -> [0,m)
5  int inv[MAXM]; // matching [0,m) -> [0,n)
6  // encuentra el max matching del grafo bipartito
7  // complejidad  $O(n \cdot e)$ , donde e es el nmero de aristas
8  int kuhn() {
9      fill(mat,mat+n,-1);
10     fill(inv,inv+m,-1);
11     int root, size = 0;
12     vector<int> seen(n,-1);
13     auto dfs = [&](auto&& me, int u) -> bool {
14         seen[u] = root;
15         for (auto v : g[u]) if (inv[v] < 0) {
16             mat[u] = v, inv[v] = u;
17             return true;
18         }
19         for (auto v : g[u]) if (seen[inv[v]] < root &&

```

```

        me(me,inv[v])) {
20     mat[u] = v, inv[v] = u;
21     return true;
22 }
23 return false;
24 };
25 forn(u,n) size += dfs(dfs,root=u);
26 return size;
27 }

```

7.5. Min Vertex Cover Bipartito

```

1 // requisito: max matching bipartito, por defecto Hopcroft-Karp
2
3 vector<bool> cover[2]; // nodos cubiertos en ambas partes
4 // encuentra el min vertex cover del grafo bipartito
5 // misma complejidad que el algoritmo de max matching bipartito
  elegido
6 int konig() {
7     cover[0].assign(n,true);
8     cover[1].assign(m,false);
9     int size = hopkarp(); // alternativamente, tambien funciona con
      Kuhn
10     auto dfs = [&](auto&& me, int u) -> void {
11         cover[0][u] = false;
12         for (auto v : g[u]) if (!cover[1][v]) {
13             cover[1][v] = true;
14             me(me,inv[v]);
15         }
16     };
17     forn(u,n) if (mat[u] < 0) dfs(dfs,u);
18     return size;
19 }

```

7.6. Hungarian

```

1 typedef long double td; typedef vector<int> vi; typedef vector<td>
  vd;
2 const td INF=1e100; //for maximum set INF to 0, and negate costs
3 bool zero(td x){return fabs(x)<1e-9;} //change to x==0, for ints/ll
4 struct Hungarian{

```

```

5     int n; vector<vd> cs; vi L, R;
6     Hungarian(int N, int M):n(max(N,M)),cs(n,vd(n)),L(n),R(n){
7         forr(x,0,N)forr(y,0,M)cs[x][y]=INF;
8     }
9     void set(int x,int y,td c){cs[x][y]=c;}
10    td assign() {
11        int mat = 0; vd ds(n), u(n), v(n); vi dad(n), sn(n);
12        forr(i,0,n)u[i]=*min_element(all(cs[i]));
13        forr(j,0,n){
14            v[j]=cs[0][j]-u[0];
15            forr(i,1,n)v[j]=min(v[j],cs[i][j]-u[i]);
16        }
17        L=R=vi(n, -1);
18        forr(i,0,n)forr(j,0,n) {
19            if(R[j]==-1&&zero(cs[i][j]-u[i]-v[j])){
20                L[i]=j;R[j]=i;mat++;break;
21            } }
22        for(;mat<n;mat++){
23            int s=0, j=0, i;
24            while(L[s] != -1)s++;
25            fill(all(dad),-1);fill(all(sn),0);
26            forr(k,0,n)ds[k]=cs[s][k]-u[s]-v[k];
27            for(;;){
28                j = -1;
29                forr(k,0,n)if(!sn[k]&&(j==-1||ds[k]<ds[j]))j=k;
30                sn[j] = 1; i = R[j];
31                if(i == -1) break;
32                forr(k,0,n)if(!sn[k]){
33                    auto new_ds=ds[j]+cs[i][k]-u[i]-v[k];
34                    if(ds[k] > new_ds){ds[k]=new_ds;dad[k]=j;}
35                }
36            }
37            forr(k,0,n)if(k!=j&&sn[k]){auto
                w=ds[k]-ds[j];v[k]+=w,u[R[k]]-=w;}
38            u[s] += ds[j];
39            while(dad[j]>=0){int d =
                dad[j];R[j]=R[d];L[R[j]]=j;j=d;}
40            R[j]=s;L[s]=j;
41        }
42        td value=0;forr(i,0,n)value+=cs[i][L[i]];

```

```

43     return value;
44 }
45 };

```

8. Optimización

8.1. Ternary Search

```

1 // mnimo entero de f en (l,r)
2 ll ternary(auto f, ll l, ll r) {
3     for (ll d = r-l; d > 2; d = r-l) {
4         ll a = l+d/3, b = r-d/3;
5         if (f(a) > f(b)) l = a; else r = b;
6     }
7     return l+1; // retorna un punto, no un resultado de evaluar f
8 }
9
10 // mnimo real de f en (l,r)
11 // para error < EPS, usar iters = log((r-l)/EPS)/log(1.618)
12 double golden(auto f, double l, double r, int iters) {
13     constexpr double ratio = (3-sqrt(5))/2;
14     double x1 = l+(r-l)*ratio, f1 = f(x1);
15     double x2 = r-(r-l)*ratio, f2 = f(x2);
16     while (iters--) {
17         if (f1 > f2) l=x1, x1=x2, f1=f2, x2=r-(r-l)*ratio, f2=f(x2);
18         else r=x2, x2=x1, f2=f1, x1=l+(r-l)*ratio, f1=f(x1);
19     }
20     return (l+r)/2; // retorna un punto, no un resultado de
                       // evaluar f
21 }

```

8.2. Longest Increasing Subsequence

```

1 // subsecuencia creciente ms larga
2 // para no decreciente, borrar la linea 9 con el continue
3 template<class Type> vector<int> lis(vector<Type>& a) {
4     int n = sz(a);
5     vector<int> seq, prev(n,-1), idx(n+1,-1);
6     vector<Type> dp(n+1,INF); dp[0] = -INF;
7     forn(i,n) {

```

```

8         int l = int(upper_bound(all(dp),a[i])-begin(dp));
9         if (dp[l-1] == a[i]) continue;
10        prev[i] = idx[l-1], idx[l] = i, dp[l] = a[i];
11    }
12    dforn(i,n+1) {
13        if (dp[i] < INF) {
14            for (int k = idx[i]; k >= 0; k = prev[k]) seq.pb(k);
15            reverse(all(seq));
16            break;
17        }
18    }
19    return seq;
20 }

```

9. Otros

9.1. Mo

```

1 int n,sq,nq; // array size, sqrt(array size), #queries
2 struct qu{int l,r,id;};
3 qu qs[MAXN];
4 ll ans[MAXN]; // ans[i] = answer to ith query
5 bool qcomp(const qu &a, const qu &b){
6     if(a.l/sq!=b.l/sq) return a.l<b.l;
7     return (a.l/sq)&1?a.r<b.r:a.r>b.r;
8 }
9 void mos(){
10     forn(i,nq)qs[i].id=i;
11     sq=sqrt(n)+.5;
12     sort(qs,qs+nq,qcomp);
13     int l=0,r=0;
14     init();
15     forn(i,nq){
16         qu q=qs[i];
17         while(l>q.l)add(--l);
18         while(r<q.r)add(r++);
19         while(l<q.l)remove(l++);
20         while(r>q.r)remove(--r);
21         ans[q.id]=get_ans();
22     }

```

```
23 }
```

9.2. Divide and Conquer Optimization

```
1 vector<ll> dp_ant, dp_curr;
2
3 void compute(int l, int r, int optl, int optr){
4     if(l == r) return;
5     int m = (l+r)/2;
6     ll dpm = 1e17;
7     int optm = -1;
8     forr(i, max(m+1, optl), optr+1){
9         ll cost = C(m, i) + (i == n ? 0 : dp_ant[i]);
10        if(cost < dpm) dpm = cost, optm = i;
11    }
12    dp_curr[m] = dpm;
13    compute(l, m, optl, optm);
14    compute(m+1, r, optm, optr);
15 }
16
17
18 forn(i, k){
19     compute(0, n, 0, n);
20     dp_ant = dp_curr;
21 }
22 cout << dp_curr[0] << endl;
```

9.3. Fijar el numero de decimales

```
1 // antes de imprimir decimales, con una sola vez basta
2 cout << fixed << setprecision(DECIMAL_DIG);
```

9.4. Hash Table (Unordered Map/ Unordered Set)

```
1 #include <ext/pb_ds/assoc_container.hpp>
2 using namespace __gnu_pbds;
3 template<class Key, class Val=null_type> using
4     htable=gp_hash_table<Key,Val>;
5
6 // como unordered_map (o unordered_set si Val es vacio), pero sin
7     metodo count
```

9.5. Indexed Set

```
1 #include <ext/pb_ds/assoc_container.hpp>
2 using namespace __gnu_pbds;
3 template<class Key, class Val=null_type>
4 using indexed_set = tree<Key, Val, less<Key>, rb_tree_tag,
5     tree_order_statistics_node_update>;
6 // indexed_set<char> s;
7 // char val = *s.find_by_order(0); // acceso por indice
8 // int idx = s.order_of_key('a'); // busca indice del valor
```

9.6. Subconjuntos

```
1 // iterar por mascarar  $O(2^n)$ 
2 for(int bm=0; bm<(1<<n); bm++)
3 // subconjuntos de una mascara  $O(2^n)$ 
4 for(int sbm=bm; sbm; sbm=(sbm-1)&bm)
5 // iterar por submascaras  $O(3^n)$ 
6 for(int bm=0; bm<(1<<n); bm++)
7     for(int sbm=bm; sbm; sbm=(sbm-1)&(bm))
8 // para superconjuntos (que contienen a bm),
9 // negar la mascara: bm=~bm
```

9.7. Simpson

```
1 // integra f en [a,b] llamandola 2*n veces
2 double simpson(auto f, double a, double b, int n=1e4) {
3     double h = (b-a)/2/n, s = f(a);
4     forr(i,1,2*n) s += f(a+i*h) * ((i%2)?4:2);
5     return (s+f(b))*h/3;
6 }
```

9.8. Pragmas

```
1 #pragma GCC target("avx2")
2 #pragma GCC optimize("O3")
3 #pragma GCC optimize("unroll-loops")
```