

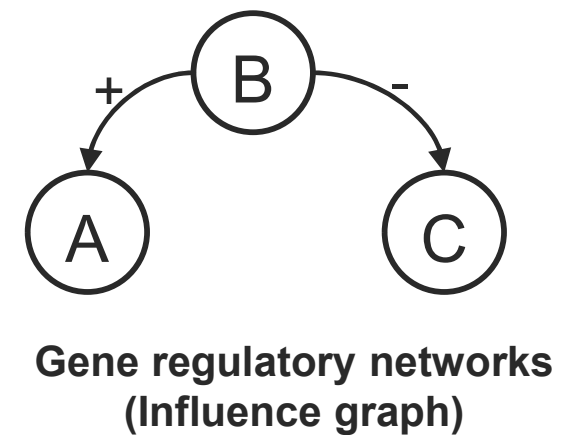
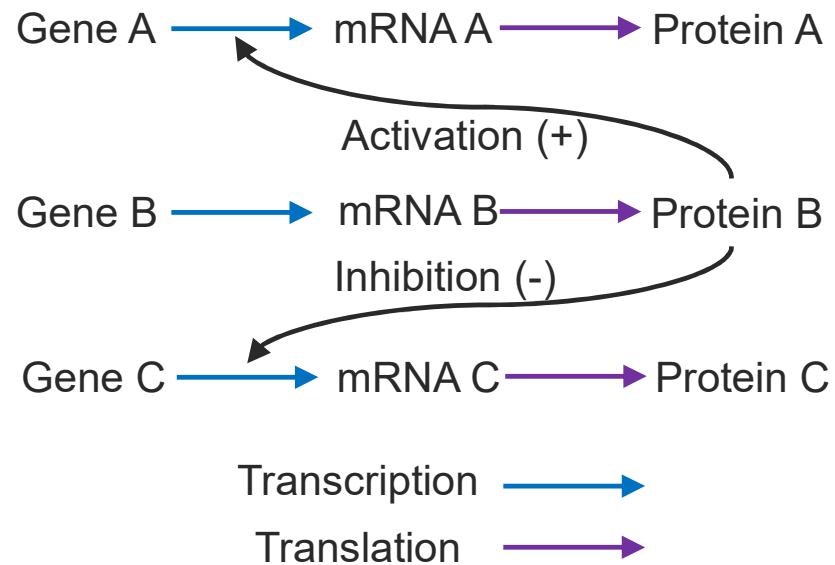


Identification des paramètres d'une classe de réseaux de régulation de gènes hybrides

Honglu SUN ¹, Morgan Magnin ¹

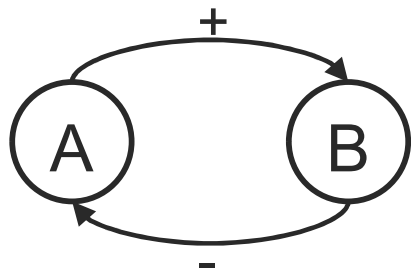
¹ Nantes Université, École Centrale Nantes, CNRS, LS2N, Nantes, France

Introduction of gene regulatory networks





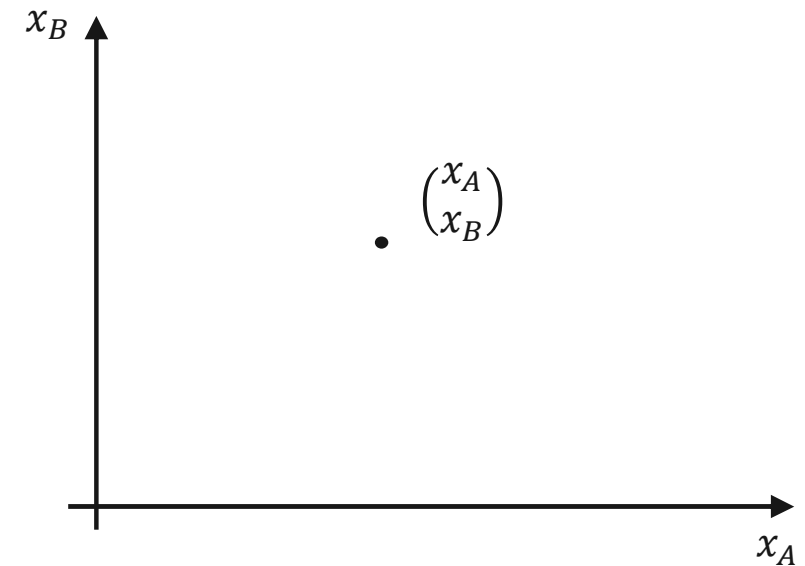
Different formalisms of gene regulatory networks



An influence graph

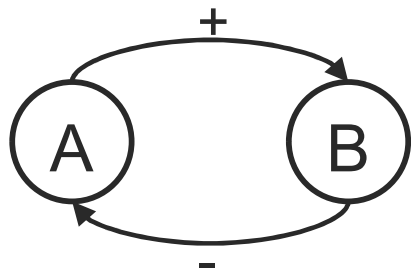
Differential equation

$$\begin{aligned}\frac{d x_A}{d t} &= -k_1 x_A + K_1 \frac{\theta_B^n}{\theta_B^n + x_B^n} \\ \frac{d x_B}{d t} &= -k_2 x_B + K_2 \frac{x_A^n}{\theta_A^n + x_A^n}\end{aligned}$$





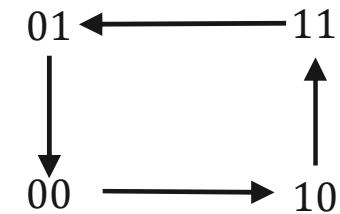
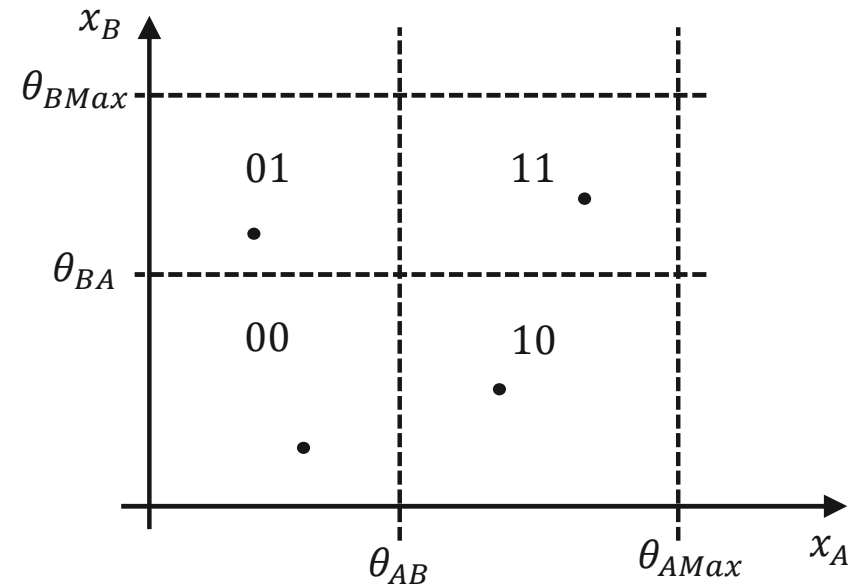
Different formalisms of gene regulatory networks



An influence graph

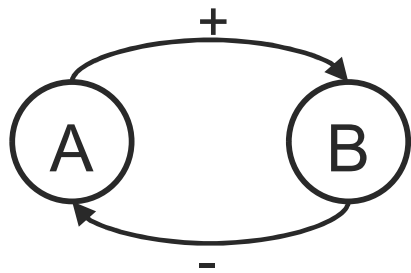
Boolean networks

$$\begin{aligned} b_A^{t+1} &\leftarrow \neg b_B^t \\ b_B^{t+1} &\leftarrow b_A^t \end{aligned}$$





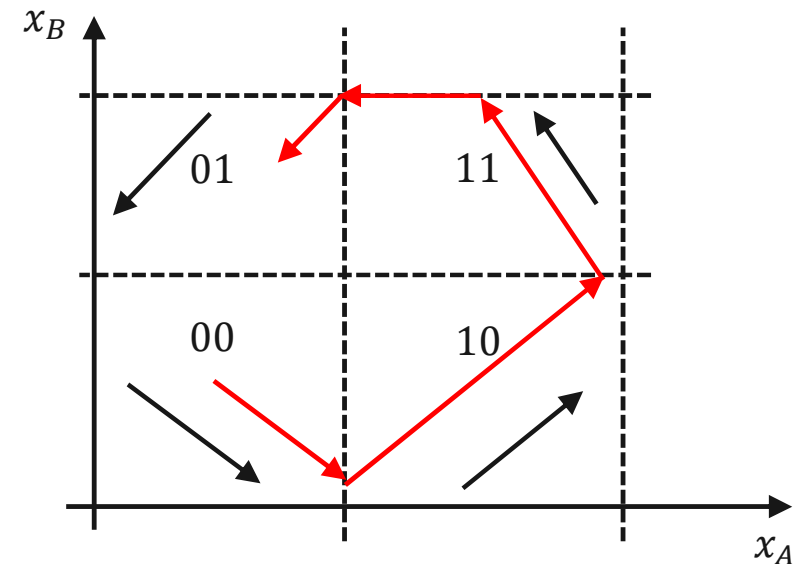
Different formalisms of gene regulatory networks



An influence graph

Hybrid gene regulatory networks (HGRN)

[Cornillon et al., advances in Systems and Synthetic Biology, 2016]



$$\begin{array}{l} \mathbf{01} \\ \frac{d x_A}{d t} = V_{ab1a0} \\ \frac{d x_B}{d t} = V_{ba0b1} \end{array}$$

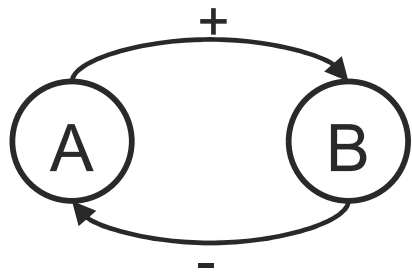
$$\begin{array}{l} \mathbf{11} \\ \frac{d x_A}{d t} = V_{ab1a1} \\ \frac{d x_B}{d t} = V_{ba1b1} \end{array}$$

$$\begin{array}{l} \mathbf{00} \\ \frac{d x_A}{d t} = V_{ab0a} \\ \frac{d x_B}{d t} = V_{ba0b0} \end{array}$$

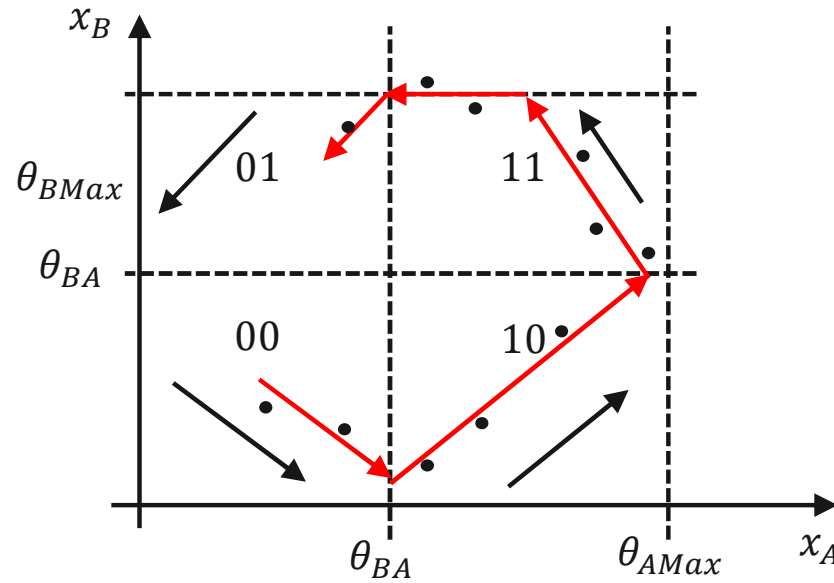
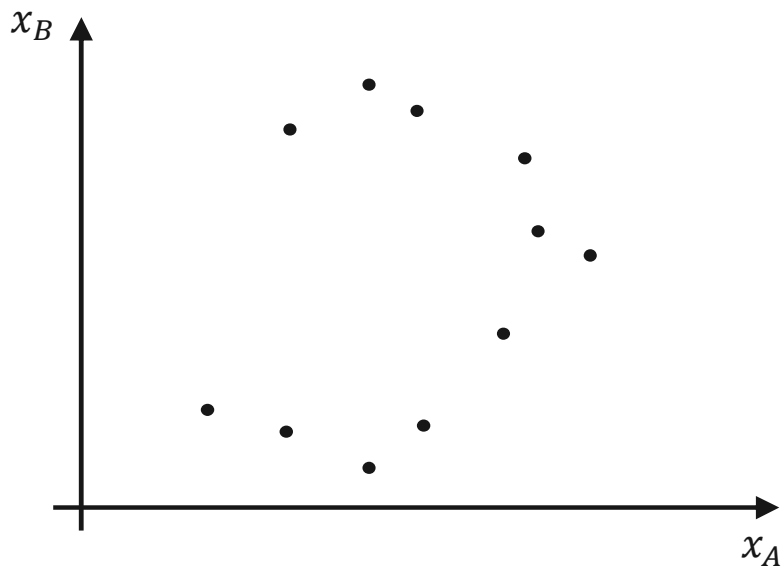
$$\begin{array}{l} \mathbf{10} \\ \frac{d x_A}{d t} = V_{ab0a1} \\ \frac{d x_B}{d t} = V_{ba1b0} \end{array}$$



Objective



An influence graph



$$\begin{matrix} \mathbf{01} \\ \frac{d x_A}{d t} = V_{ab1a0} \\ \frac{d x_B}{d t} = V_{ba0b1} \end{matrix}$$

$$\begin{matrix} \mathbf{11} \\ \frac{d x_A}{d t} = V_{ab1a1} \\ \frac{d x_B}{d t} = V_{ba1b1} \end{matrix}$$

$$\begin{matrix} \mathbf{00} \\ \frac{d x_A}{d t} = V_{ab0a0} \\ \frac{d x_B}{d t} = V_{ba0b0} \end{matrix}$$

$$\begin{matrix} \mathbf{10} \\ \frac{d x_A}{d t} = V_{ab0a1} \\ \frac{d x_B}{d t} = V_{ba1b0} \end{matrix}$$



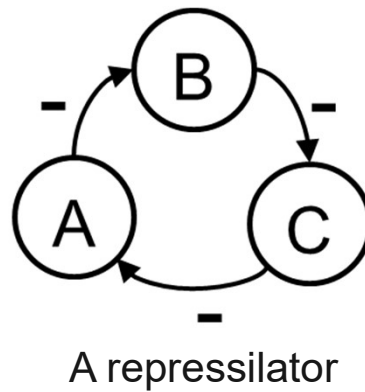
$\theta_{BA} \quad \theta_{BMax} \quad \theta_{BA} \quad \theta_{AMax}$

$V_{ab1a0} \quad V_{ba0b1} \quad \dots \dots$



Objective

Le graphe d'influence étudié dans ce projet:



https://github.com/Honglu42/Projet_RetD/blob/main/simulation.ipynb



References about HGRN

[Cornillon, E. et al., advances in Systems and Synthetic Biology., 2016] Cornillon, E., Comet, J. P., Bernot, G., & Enée, G. (2016). Hybrid gene networks: a new framework and a software environment. advances in Systems and Synthetic Biology.

[Behaegel, J. et al., Journal of bioinformatics and computational biology, 2016] Behaegel, J., Comet, J. P., Bernot, G., Cornillon, E., & Delaunay, F. (2016). A hybrid model of cell cycle in mammals. Journal of bioinformatics and computational biology, 14(01), 1640001.

