

Algoritmos de navegación para robots móviles usando visión estéreo

Fernando Bugni, *Estudiante, UBA*, Amit Stein, *Estudiante, UBA*, and Agustín Olmedo, *Estudiante, UBA*

Abstract—The abstract goes here.

Index Terms—Computer Society, IEEEtran, journal, \LaTeX , paper, template.



1 INTRODUCCIÓN

THIS demo file is intended to serve as a “starter file” for IEEE Computer Society journal papers produced under \LaTeX using IEEEtran.cls version 1.7 and later. I wish you the best of success.

mds

Agosto 11, 2011

2 CALIBRACIÓN DE LA CAMARA ESTÉREO

3 MAPAS DE DISPARIDAD

4 NAVEGACIÓN PARA ROBOT MÓVILES UTILIZANDO LOS MAPAS DE DISPARIDAD

5 EXPERIMENTOS

Experimentos.

6 CONCLUSION

The conclusion goes here.

REFERENCES

- [1] H. Kopka and P. W. Daly, *A Guide to \LaTeX* , 3rd ed. Harlow, England: Addison-Wesley, 1999.

-
- M. Shell is with the Department of Electrical and Computer Engineering, Georgia Institute of Technology, Atlanta, GA, 30332.
E-mail: see <http://www.michaelshell.org/contact.html>
 - J. Doe and J. Doe are with Anonymous University.

Manuscript received April 19, 2005; revised January 11, 2007.