

Human Activity Recongnition Using LSTM

October 23, 2018

1 Human Activity Recognition

2 Description

These days Smartphones have become an integral part of our life. We cannot assume our life without a mobile phone. Since, the advent of Smartphones, a revolution has been created in the mobile communication industry. Smartphones are not just restricted for calling these days. Infact, they are more often used for entertainment purpose.

Smartphone manufacturing companies load Smartphones with various sensors to enhance the user experinece. Two of the such sensors are Accelerometer and Gyroscope. Accelerometer measures acceleration while Gyroscope measures angular velocity.

Here, we will try to use the data provided by accelerometer and gyroscope of Smartphone to classify the activity which a Smartphone user is performing

3 Why this is Useful?

These days, in addition to Smartphones, we are also using Smart-Watches like Fitbit or Apple-Watch, which help us to track our health. They monitor our each activity throughout the day check how many calories we have burnt. How many hours have we slept. However, in addition to Accelerometer and Gyroscope, they also use Heart-Rate data to monitor our activity. Since, we only have Smartphone data so just by using Accelerometer and Gyroscope data we will monitor the activity of a person. This software can then be converted into an App which can be downloaded in Smartphone. Hence, a person who has Smartphone can monitor his/her health using this App

4 Information about Data

5 How Data is recorded

The experiments have been carried out with a group of 30 volunteers within an age bracket of 19-48 years. Each person performed six activities (WALKING, WALKING-UPSTAIRS, WALKING-DOWNSTAIRS, SITTING-DOWN, STANDING-UP, LAYING-DOWN) wearing a smartphone (Samsung Galaxy S II) on the waist. Using its embedded accelerometer and gyroscope, we captured 3-axial linear acceleration and 3-axial angular velocity at a constant rate of 50Hz. The experiments have been video-recorded to label the data manually. The obtained dataset has been

randomly partitioned into two sets, where 70% of the volunteers was selected for generating the training data and 30% the test data. 5.2. Features

These sensor signals are pre-processed by applying noise filters and then sampled in fixed-width windows(sliding windows) of 2.56 seconds each with 50% overlap. i.e., each window has 128 readings. A 128 size vector is created from each window. From Each window or to be more precise, from each 128 readings domain experts from signal processing have engineered feature vector of size 561 by calculating variables from the time and frequency domain. In our dataset, each data-point represents a window with different readings. 561 features are stored in the file "Features.docx". Check it out. Check out 561 features here.(In your blog give here the link of the docx file of features which you upload on github). The acceleration signal was separated into Body and Gravity acceleration signals(tBodyAcc-XYZ and tGravityAcc-XYZ) using some low pass filter with corner frequency of 0.3Hz. After that, the body linear acceleration and angular velocity were derived in time to obtain jerk signals (tBodyAccJerk-XYZ and tBodyGyroJerk-XYZ). The magnitude of these 3-dimensional signals were calculated using the Euclidian norm. This magnitudes are represented as features with names like tBodyAccMag, tGravityAccMag, tBodyAccJerkMag, tBodyGyroMag and tBodyGyroJerkMag. Finally, We've got frequency domain signals from some of the available signals by applying a FFT (Fast Fourier Transform). These signals obtained were labelled with prefix 'f' just like original signals with prefix 't'. These signals are labelled as fBodyAcc-XYZ, fBodyGyroMag etc.

These are the signals that we got so far.

tBodyAcc-XYZ tGravityAcc-XYZ tBodyAccJerk-XYZ tBodyGyro-XYZ tBodyGyroJerk-XYZ tBodyAccMag tGravityAccMag tBodyAccJerkMag tBodyGyroMag tBodyGyroJerkMag fBodyAcc-XYZ fBodyAccJerk-XYZ fBodyGyro-XYZ fBodyAccMag fBodyAccJerkMag fBodyGyroMag fBodyGyroJerkMag

9 We can estimate some set of variables from the above signals. i.e., We will estimate the following properties on each and every signal that we recorded so far.

mean(): Mean value std(): Standard deviation mad(): Median absolute deviation max(): Largest value in array min(): Smallest value in array sma(): Signal magnitude area energy(): Energy measure. Sum of the squares divided by the number of values. iqr(): Inter-quartile range entropy(): Signal entropy arCoeff(): Auto-regression coefficients with Burg order equal to 4 correlation(): correlation coefficient between two signals maxInds(): index of the frequency component with largest magnitude meanFreq(): Weighted average of the frequency components to obtain a mean frequency skewness(): skewness of the frequency domain signal kurtosis(): kurtosis of the frequency domain signal bandsEnergy(): Energy of a frequency interval within the 64 bins of the FFT of each window. angle(): Angle between to vectors.

10 We can obtain some other vectors by taking the average of signals in a single window sample. These are used on the angle() variable.

```
In [19]: gravityMean
         tBodyAccMean
         tBodyAccJerkMean
         tBodyGyroMean
         tBodyGyroJerkMean
```

NameError

Traceback (most recent call last)

```

<ipython-input-19-d3f38673bd33> in <module>()
----> 1 gravityMean
      2 tBodyAccMean
      3 tBodyAccJerkMean
      4 tBodyGyroMean
      5 tBodyGyroJerkMean

```

```
NameError: name 'gravityMean' is not defined
```

6 Data Source

Data is downloaded from following source: <https://archive.ics.uci.edu/ml/datasets/human+activity+recognition>

7 Quick Overview of Dataset

Accelerometer and Gyroscope readings are taken from 30 volunteers(referred as subjects) while performing the following 6 Activities.

These activities are encoded as follows: WALKING-- 1 WALKING_UPSTAIRS-- 2 WALKING_DOWNSTAIRS-- 3 SITTING-- 4 STANDING-- 5 LYING-- 6

1.Readings are divided into a window of 2.56 seconds with 50% overlapping. 2.Accelerometer readings are divided into gravity acceleration and body acceleration readings, which has x, y and z components each. 3.Gyroscope readings are the measure of angular velocities which has x, y and z components. 4.Jerk signals are calculated for Body-Acceleration readings. 5.Fourier Transforms are made on the above time readings to obtain frequency readings. 6.Now, on all the base signal readings, mean, max, mad, sma, arcoefficient, energy-bands, entropy etc., are calculated for each window. 7.Extra features are calculated by taking the average of signals in a single window sample. These are used on the angle() variable. 8.Finally, we got feature vector of 561 features and these features are given in the dataset. Each window of readings is a data-point of 561 features.

8 Y-Encoded Labels

```

In [ ]: WALKING-- 1
        WALKING_UPSTAIRS-- 2
        WALKING_DOWNSTAIRS-- 3
        SITTING-- 4
        STANDING-- 5
        LYING-- 6

```

9 Business Problem

Work-flow is as follows:

1.Domain experts from the field of Signal Processing collects the data from Accelerometer and Gyroscope of Smartphone. 2.They break up the data in the time window of 2.56 seconds with 50% overlapping i.e., 128 reading 3.They engineered 561 features from each time window of 2.56 seconds.

By using either human engineered 561 feature data or raw features of 128 reading, our goal is to predict one of the six activities that a Smartphone user is performing at that 2.56 Seconds time window.

10 Problem Statement

By using either human engineered 561 feature data or raw features of 128 reading, our goal is to predict one of the six activities that a Smartphone user is performing at that 2.56 Seconds time window.

11 Objective and Constraints

1.No Low latency requirement. 2.Errors are not much costly.

All of the Accelerometer and Gyroscope are tri-axial, means that they measure acceleration and angular-velocity respectively in all the three axis namely X-axis, Y-axis and Z-axis. So, we have in total six time-series data. Given this six time-series data, we want to predict six activities namely Walking or Walking-Upstairs or Walking-Downstairs or Lying-Down or Standing-Up or Sitting-Down.

At the outset, this is a multi-class classification problem.

12 ML Problem Formulation

All of the Accelerometer and Gyroscope are tri-axial, means that they measure acceleration and angular-velocity respectively in all the three axis namely X-axis, Y-axis and Z-axis. So, we have in total six time-series data. Given this six time-series data, we want to predict six activities namely Walking or Walking-Upstairs or Walking-Downstairs or Lying-Down or Standing-Up or Sitting-Down.

At the outset, this is a multi-class classification problem.

13 Performance Metric

1.We will use Accuracy as one of the metric. 2.We will also use Confusion-Matrix to check that in which two activities our model is confused and predicting incorrect activity. For example, between Standing-Up and Sitting-Down. Between Walking-Upstairs and Walking-Downstairs

14 Data

All the data is present in 'UCI_HAR_dataset/' folder in present working directory. Feature names are present in 'UCI_HAR_dataset/features.txt'

Train Data 'UCI_HAR_dataset/train/X_train.txt' 'UCI_HAR_dataset/train/subject_train.txt'
'UCI_HAR_dataset/train/y_train.txt' Test Data 'UCI_HAR_dataset/test/X_test.txt'
'UCI_HAR_dataset/test/subject_test.txt' 'UCI_HAR_dataset/test/y_test.txt'

15 Data-Points Distribution

1.30 test-subjects data is randomly split to 70%(21) train and 30%(7) test data. 2.Each data-point corresponds one of the 6 Activities.

16 Plan of Action

We will apply classical Machine Learning models on these 561 sized domain expert engineered features. As we know that LSTM works well on time-series data, so we have decided that we will apply LSTM of Recurrent Neural Networks on 128 sized raw readings that we obtained from accelerometer and gyroscope signals.

```
In [ ]: # Importing Libraries
```

```
In [1]: import pandas as pd
import numpy as np
```

```
In [2]: # Activities are the class labels
# It is a 6 class classification
ACTIVITIES = {
    0: 'WALKING',
    1: 'WALKING_UPSTAIRS',
    2: 'WALKING_DOWNSTAIRS',
    3: 'SITTING',
    4: 'STANDING',
    5: 'LAYING',
}

# Utility function to print the confusion matrix
def confusion_matrix(Y_true, Y_pred):
    Y_true = pd.Series([ACTIVITIES[y] for y in np.argmax(Y_true, axis=1)])
    Y_pred = pd.Series([ACTIVITIES[y] for y in np.argmax(Y_pred, axis=1)])

    return pd.crosstab(Y_true, Y_pred, rownames=['True'], colnames=['Pred'])
```

16.0.1 Data

```
In [3]: # Data directory
```

```
DATADIR = 'UCI_HAR_Dataset'
```

```
In [4]: # Raw data signals
```

```
# Signals are from Accelerometer and Gyroscope
```

```
# The signals are in x,y,z directions
```

```
# Sensor signals are filtered to have only body acceleration
```

```

# excluding the acceleration due to gravity
# Triaxial acceleration from the accelerometer is total acceleration
SIGNALS = [
    "body_acc_x",
    "body_acc_y",
    "body_acc_z",
    "body_gyro_x",
    "body_gyro_y",
    "body_gyro_z",
    "total_acc_x",
    "total_acc_y",
    "total_acc_z"
]

```

```

In [5]: # Utility function to read the data from csv file
def _read_csv(filename):
    return pd.read_csv(filename, delim_whitespace=True, header=None)

# Utility function to load the load
def load_signals(subset):
    signals_data = []

    for signal in SIGNALS:
        filename = f'UCI_HAR_Dataset/{subset}/Inertial Signals/{signal}_{subset}.txt'
        signals_data.append(
            _read_csv(filename).as_matrix()
        )

    # Transpose is used to change the dimensionality of the output,
    # aggregating the signals by combination of sample/timestep.
    # Resultant shape is (7352 train/2947 test samples, 128 timesteps, 9 signals)
    return np.transpose(signals_data, (1, 2, 0))

```

```

In [6]: def load_y(subset):
        """
        The objective that we are trying to predict is a integer, from 1 to 6,
        that represents a human activity. We return a binary representation of
        every sample objective as a 6 bits vector using One Hot Encoding
        (https://pandas.pydata.org/pandas-docs/stable/generated/pandas.get\_dummies.html)
        """
        filename = f'UCI_HAR_Dataset/{subset}/y_{subset}.txt'
        y = _read_csv(filename)[0]

        return pd.get_dummies(y).as_matrix()

```

```

In [7]: def load_data():
        """
        Obtain the dataset from multiple files.

```

```
Returns: X_train, X_test, y_train, y_test
"""
```

```
X_train, X_test = load_signals('train'), load_signals('test')
y_train, y_test = load_y('train'), load_y('test')
```

```
return X_train, X_test, y_train, y_test
```

```
In [8]: # Importing tensorflow
np.random.seed(42)
import tensorflow as tf
tf.set_random_seed(42)
```

```
C:\Users\Saurabh\Anaconda3\lib\site-packages\h5py\__init__.py:36: FutureWarning: Conversion of
from ._conv import register_converters as _register_converters
```

```
In [9]: # Configuring a session
session_conf = tf.ConfigProto(
    intra_op_parallelism_threads=1,
    inter_op_parallelism_threads=1
)
```

```
In [10]: # Import Keras
from keras import backend as K
sess = tf.Session(graph=tf.get_default_graph(), config=session_conf)
K.set_session(sess)
```

Using TensorFlow backend.

```
In [11]: # Importing libraries
from keras.models import Sequential
from keras.layers import LSTM
from keras.layers.core import Dense, Dropout
```

```
In [30]: # Initializing parameters
epochs = 300
batch_size = 32
n_hidden = 64
```

```
In [31]: # Utility function to count the number of classes
def _count_classes(y):
    return len(set([tuple(category) for category in y]))
```

```
In [32]: # Loading the train and test data
X_train, X_test, Y_train, Y_test = load_data()
```

```
C:\Users\Saurabh\Anaconda3\lib\site-packages\ipykernel_launcher.py:12: FutureWarning: Method .:
if sys.path[0] == '':
```

```
In [33]: timesteps = len(X_train[0])
         input_dim = len(X_train[0][0])
         n_classes = _count_classes(Y_train)

         print(timesteps)
         print(input_dim)
         print(len(X_train))

128
9
7352
```

- Defining the Architecture of LSTM

```
In [34]: # Initiliazing the sequential model
         model = Sequential()
         # Configuring the parameters
         model.add(LSTM(n_hidden, input_shape=(timesteps, input_dim)))
         # Adding a dropout layer
         model.add(Dropout(0.5))
         # Adding a dense output layer with sigmoid activation
         model.add(Dense(n_classes, activation='sigmoid'))
         model.summary()
```

Layer (type)	Output Shape	Param #
lstm_3 (LSTM)	(None, 64)	18944
dropout_3 (Dropout)	(None, 64)	0
dense_3 (Dense)	(None, 6)	390

Total params: 19,334
 Trainable params: 19,334
 Non-trainable params: 0

```
In [35]: # Compiling the model
         model.compile(loss='categorical_crossentropy',
                       optimizer='adam',
                       metrics=['accuracy'])
```

```
In [36]: # Training the model
         model.fit(X_train,
                   Y_train,
                   batch_size=batch_size,
```



```
validation_data=(X_test, Y_test),
epochs=epochs)
```

Train on 7352 samples, validate on 2947 samples

Epoch 1/300

7352/7352 [=====] - 24s 3ms/step - loss: 1.4284 - acc: 0.3644 - val_loss: 1.4284 - val_acc: 0.3644

Epoch 2/300

7352/7352 [=====] - 22s 3ms/step - loss: 1.3148 - acc: 0.3923 - val_loss: 1.3148 - val_acc: 0.3923

Epoch 3/300

7352/7352 [=====] - 24s 3ms/step - loss: 1.2377 - acc: 0.4463 - val_loss: 1.2377 - val_acc: 0.4463

Epoch 4/300

7352/7352 [=====] - 23s 3ms/step - loss: 1.1586 - acc: 0.4737 - val_loss: 1.1586 - val_acc: 0.4737

Epoch 5/300

7352/7352 [=====] - 22s 3ms/step - loss: 1.2517 - acc: 0.4286 - val_loss: 1.2517 - val_acc: 0.4286

Epoch 6/300

7352/7352 [=====] - 22s 3ms/step - loss: 1.1608 - acc: 0.5076 - val_loss: 1.1608 - val_acc: 0.5076

Epoch 7/300

7352/7352 [=====] - 22s 3ms/step - loss: 0.9851 - acc: 0.5613 - val_loss: 0.9851 - val_acc: 0.5613

Epoch 8/300

7352/7352 [=====] - 22s 3ms/step - loss: 0.9568 - acc: 0.5768 - val_loss: 0.9568 - val_acc: 0.5768

Epoch 9/300

7352/7352 [=====] - 22s 3ms/step - loss: 0.8428 - acc: 0.6217 - val_loss: 0.8428 - val_acc: 0.6217

Epoch 10/300

7352/7352 [=====] - 22s 3ms/step - loss: 0.7760 - acc: 0.6328 - val_loss: 0.7760 - val_acc: 0.6328

Epoch 11/300

7352/7352 [=====] - 22s 3ms/step - loss: 0.7391 - acc: 0.6506 - val_loss: 0.7391 - val_acc: 0.6506

Epoch 12/300

7352/7352 [=====] - 22s 3ms/step - loss: 0.7065 - acc: 0.6737 - val_loss: 0.7065 - val_acc: 0.6737

Epoch 13/300

7352/7352 [=====] - 23s 3ms/step - loss: 0.5739 - acc: 0.7421 - val_loss: 0.5739 - val_acc: 0.7421

Epoch 14/300

7352/7352 [=====] - 22s 3ms/step - loss: 0.5620 - acc: 0.7606 - val_loss: 0.5620 - val_acc: 0.7606

Epoch 15/300

7352/7352 [=====] - 22s 3ms/step - loss: 0.4878 - acc: 0.7818 - val_loss: 0.4878 - val_acc: 0.7818

Epoch 16/300

7352/7352 [=====] - 22s 3ms/step - loss: 0.6082 - acc: 0.7448 - val_loss: 0.6082 - val_acc: 0.7448

Epoch 17/300

7352/7352 [=====] - 22s 3ms/step - loss: 0.8085 - acc: 0.6663 - val_loss: 0.8085 - val_acc: 0.6663

Epoch 18/300

7352/7352 [=====] - 22s 3ms/step - loss: 0.5122 - acc: 0.7990 - val_loss: 0.5122 - val_acc: 0.7990

Epoch 19/300

7352/7352 [=====] - 22s 3ms/step - loss: 0.6121 - acc: 0.7682 - val_loss: 0.6121 - val_acc: 0.7682

Epoch 20/300

7352/7352 [=====] - 22s 3ms/step - loss: 0.5246 - acc: 0.8075 - val_loss: 0.5246 - val_acc: 0.8075

Epoch 21/300

7352/7352 [=====] - 22s 3ms/step - loss: 0.3587 - acc: 0.8811 - val_loss: 0.3587 - val_acc: 0.8811

Epoch 22/300

7352/7352 [=====] - 22s 3ms/step - loss: 0.4166 - acc: 0.8690 - val_loss: 0.4166 - val_acc: 0.8690

Epoch 23/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.3675 - acc: 0.8950 - val_loss: 0.4000
Epoch 24/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.5638 - acc: 0.7954 - val_loss: 0.4000
Epoch 25/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.3414 - acc: 0.8794 - val_loss: 0.4000
Epoch 26/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.2948 - acc: 0.9036 - val_loss: 0.4000
Epoch 27/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.2557 - acc: 0.9112 - val_loss: 0.4000
Epoch 28/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.2705 - acc: 0.9108 - val_loss: 0.4000
Epoch 29/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.2208 - acc: 0.9187 - val_loss: 0.4000
Epoch 30/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.2366 - acc: 0.9188 - val_loss: 0.4000
Epoch 31/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1712 - acc: 0.9377 - val_loss: 0.4000
Epoch 32/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1859 - acc: 0.9323 - val_loss: 0.4000
Epoch 33/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1516 - acc: 0.9415 - val_loss: 0.4000
Epoch 34/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.4006 - acc: 0.8566 - val_loss: 0.4000
Epoch 35/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.2925 - acc: 0.8991 - val_loss: 0.4000
Epoch 36/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1952 - acc: 0.9338 - val_loss: 0.4000
Epoch 37/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1562 - acc: 0.9423 - val_loss: 0.4000
Epoch 38/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.2587 - acc: 0.9127 - val_loss: 0.4000
Epoch 39/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1869 - acc: 0.9368 - val_loss: 0.4000
Epoch 40/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1435 - acc: 0.9457 - val_loss: 0.4000
Epoch 41/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1460 - acc: 0.9445 - val_loss: 0.4000
Epoch 42/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1453 - acc: 0.9460 - val_loss: 0.4000
Epoch 43/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1309 - acc: 0.9476 - val_loss: 0.4000
Epoch 44/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1829 - acc: 0.9339 - val_loss: 0.4000
Epoch 45/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1778 - acc: 0.9381 - val_loss: 0.4000
Epoch 46/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.2386 - acc: 0.9240 - val_loss: 0.4000

Epoch 47/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.2023 - acc: 0.9279 - val_loss: 0.2023
Epoch 48/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1627 - acc: 0.9467 - val_loss: 0.1627
Epoch 49/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1717 - acc: 0.9430 - val_loss: 0.1717
Epoch 50/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1299 - acc: 0.9520 - val_loss: 0.1299
Epoch 51/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1379 - acc: 0.9468 - val_loss: 0.1379
Epoch 52/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1245 - acc: 0.9482 - val_loss: 0.1245
Epoch 53/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1499 - acc: 0.9429 - val_loss: 0.1499
Epoch 54/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1514 - acc: 0.9408 - val_loss: 0.1514
Epoch 55/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.2301 - acc: 0.9230 - val_loss: 0.2301
Epoch 56/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1780 - acc: 0.9314 - val_loss: 0.1780
Epoch 57/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1400 - acc: 0.9484 - val_loss: 0.1400
Epoch 58/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.2840 - acc: 0.9112 - val_loss: 0.2840
Epoch 59/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1785 - acc: 0.9389 - val_loss: 0.1785
Epoch 60/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1423 - acc: 0.9491 - val_loss: 0.1423
Epoch 61/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1715 - acc: 0.9368 - val_loss: 0.1715
Epoch 62/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1732 - acc: 0.9410 - val_loss: 0.1732
Epoch 63/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1449 - acc: 0.9468 - val_loss: 0.1449
Epoch 64/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1437 - acc: 0.9476 - val_loss: 0.1437
Epoch 65/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1262 - acc: 0.9518 - val_loss: 0.1262
Epoch 66/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1207 - acc: 0.9532 - val_loss: 0.1207
Epoch 67/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1532 - acc: 0.9440 - val_loss: 0.1532
Epoch 68/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1256 - acc: 0.9493 - val_loss: 0.1256
Epoch 69/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1167 - acc: 0.9540 - val_loss: 0.1167
Epoch 70/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1373 - acc: 0.9471 - val_loss: 0.1373

```

Epoch 71/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1417 - acc: 0.9406 - val_loss: 0.1417
Epoch 72/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1263 - acc: 0.9441 - val_loss: 0.1263
Epoch 73/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1319 - acc: 0.9472 - val_loss: 0.1319
Epoch 74/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1806 - acc: 0.9400 - val_loss: 0.1806
Epoch 75/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1956 - acc: 0.9385 - val_loss: 0.1956
Epoch 76/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1451 - acc: 0.9455 - val_loss: 0.1451
Epoch 77/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1225 - acc: 0.9480 - val_loss: 0.1225
Epoch 78/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1197 - acc: 0.9501 - val_loss: 0.1197
Epoch 79/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1202 - acc: 0.9514 - val_loss: 0.1202
Epoch 80/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1661 - acc: 0.9387 - val_loss: 0.1661
Epoch 81/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1982 - acc: 0.9357 - val_loss: 0.1982
Epoch 82/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1338 - acc: 0.9509 - val_loss: 0.1338
Epoch 83/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1176 - acc: 0.9551 - val_loss: 0.1176
Epoch 84/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.2776 - acc: 0.9161 - val_loss: 0.2776
Epoch 85/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1763 - acc: 0.9359 - val_loss: 0.1763
Epoch 86/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1629 - acc: 0.9347 - val_loss: 0.1629
Epoch 87/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1494 - acc: 0.9400 - val_loss: 0.1494
Epoch 88/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1376 - acc: 0.9463 - val_loss: 0.1376
Epoch 89/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1353 - acc: 0.9456 - val_loss: 0.1353
Epoch 90/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1405 - acc: 0.9465 - val_loss: 0.1405
Epoch 91/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1277 - acc: 0.9490 - val_loss: 0.1277
Epoch 92/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1315 - acc: 0.9467 - val_loss: 0.1315
Epoch 93/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1290 - acc: 0.9470 - val_loss: 0.1290
Epoch 94/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1273 - acc: 0.9502 - val_loss: 0.1273

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Epoch 95/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1315 - acc: 0.9468 - val_loss: 0.1315
Epoch 96/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.2131 - acc: 0.9305 - val_loss: 0.2131
Epoch 97/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1738 - acc: 0.9395 - val_loss: 0.1738
Epoch 98/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1344 - acc: 0.9512 - val_loss: 0.1344
Epoch 99/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1254 - acc: 0.9525 - val_loss: 0.1254
Epoch 100/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1246 - acc: 0.9517 - val_loss: 0.1246
Epoch 101/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1217 - acc: 0.9528 - val_loss: 0.1217
Epoch 102/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1160 - acc: 0.9535 - val_loss: 0.1160
Epoch 103/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1241 - acc: 0.9493 - val_loss: 0.1241
Epoch 104/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1266 - acc: 0.9464 - val_loss: 0.1266
Epoch 105/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1156 - acc: 0.9548 - val_loss: 0.1156
Epoch 106/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1168 - acc: 0.9533 - val_loss: 0.1168
Epoch 107/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1134 - acc: 0.9563 - val_loss: 0.1134
Epoch 108/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1260 - acc: 0.9538 - val_loss: 0.1260
Epoch 109/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1281 - acc: 0.9513 - val_loss: 0.1281
Epoch 110/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1240 - acc: 0.9523 - val_loss: 0.1240
Epoch 111/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1355 - acc: 0.9508 - val_loss: 0.1355
Epoch 112/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1168 - acc: 0.9544 - val_loss: 0.1168
Epoch 113/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1221 - acc: 0.9528 - val_loss: 0.1221
Epoch 114/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1194 - acc: 0.9551 - val_loss: 0.1194
Epoch 115/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1147 - acc: 0.9570 - val_loss: 0.1147
Epoch 116/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1139 - acc: 0.9554 - val_loss: 0.1139
Epoch 117/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1105 - acc: 0.9548 - val_loss: 0.1105
Epoch 118/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1476 - acc: 0.9427 - val_loss: 0.1476

Epoch 119/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1338 - acc: 0.9421 - val_loss: 0.1338

Epoch 120/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1197 - acc: 0.9505 - val_loss: 0.1197

Epoch 121/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1667 - acc: 0.9380 - val_loss: 0.1667

Epoch 122/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1307 - acc: 0.9463 - val_loss: 0.1307

Epoch 123/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1149 - acc: 0.9516 - val_loss: 0.1149

Epoch 124/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1127 - acc: 0.9512 - val_loss: 0.1127

Epoch 125/300
7352/7352 [=====] - 22s 3ms/step - loss: 0.1130 - acc: 0.9529 - val_loss: 0.1130

Epoch 126/300
7352/7352 [=====] - 1253s 170ms/step - loss: 0.1120 - acc: 0.9557 - val_loss: 0.1120

Epoch 127/300
7352/7352 [=====] - 43s 6ms/step - loss: 0.1275 - acc: 0.9495 - val_loss: 0.1275

Epoch 128/300
7352/7352 [=====] - 26s 4ms/step - loss: 0.1185 - acc: 0.9506 - val_loss: 0.1185

Epoch 129/300
7352/7352 [=====] - 39s 5ms/step - loss: 0.1074 - acc: 0.9547 - val_loss: 0.1074

Epoch 130/300
7352/7352 [=====] - 40s 5ms/step - loss: 0.1272 - acc: 0.9484 - val_loss: 0.1272

Epoch 131/300
7352/7352 [=====] - 40s 5ms/step - loss: 0.1192 - acc: 0.9499 - val_loss: 0.1192

Epoch 132/300
7352/7352 [=====] - 40s 5ms/step - loss: 0.1190 - acc: 0.9538 - val_loss: 0.1190

Epoch 133/300
7352/7352 [=====] - 38s 5ms/step - loss: 0.1170 - acc: 0.9504 - val_loss: 0.1170

Epoch 134/300
7352/7352 [=====] - 42s 6ms/step - loss: 0.1171 - acc: 0.9529 - val_loss: 0.1171

Epoch 135/300
7352/7352 [=====] - 43s 6ms/step - loss: 0.1133 - acc: 0.9533 - val_loss: 0.1133

Epoch 136/300
7352/7352 [=====] - 42s 6ms/step - loss: 0.1079 - acc: 0.9524 - val_loss: 0.1079

Epoch 137/300
7352/7352 [=====] - 43s 6ms/step - loss: 0.1284 - acc: 0.9490 - val_loss: 0.1284

Epoch 138/300
7352/7352 [=====] - 43s 6ms/step - loss: 0.1229 - acc: 0.9531 - val_loss: 0.1229

Epoch 139/300
7352/7352 [=====] - 43s 6ms/step - loss: 0.1146 - acc: 0.9544 - val_loss: 0.1146

Epoch 140/300
7352/7352 [=====] - 41s 6ms/step - loss: 0.1213 - acc: 0.9514 - val_loss: 0.1213

Epoch 141/300
7352/7352 [=====] - 42s 6ms/step - loss: 0.1169 - acc: 0.9557 - val_loss: 0.1169

Epoch 142/300
7352/7352 [=====] - 35s 5ms/step - loss: 0.1123 - acc: 0.9581 - val_loss: 0.1123

Epoch 143/300
7352/7352 [=====] - 38s 5ms/step - loss: 0.1184 - acc: 0.9513 - val_loss: 0.1242
Epoch 144/300
7352/7352 [=====] - 34s 5ms/step - loss: 0.1242 - acc: 0.9461 - val_loss: 0.1242
Epoch 145/300
7352/7352 [=====] - 40s 5ms/step - loss: 0.1088 - acc: 0.9529 - val_loss: 0.1242
Epoch 146/300
7352/7352 [=====] - 44s 6ms/step - loss: 0.1202 - acc: 0.9502 - val_loss: 0.1242
Epoch 147/300
7352/7352 [=====] - 36s 5ms/step - loss: 0.1097 - acc: 0.9581 - val_loss: 0.1242
Epoch 148/300
7352/7352 [=====] - 33s 4ms/step - loss: 0.1061 - acc: 0.9576 - val_loss: 0.1242
Epoch 149/300
7352/7352 [=====] - 33s 4ms/step - loss: 0.1094 - acc: 0.9555 - val_loss: 0.1242
Epoch 150/300
7352/7352 [=====] - 34s 5ms/step - loss: 0.1082 - acc: 0.9566 - val_loss: 0.1242
Epoch 151/300
7352/7352 [=====] - 34s 5ms/step - loss: 0.1025 - acc: 0.9592 - val_loss: 0.1242
Epoch 152/300
7352/7352 [=====] - 36s 5ms/step - loss: 0.1123 - acc: 0.9538 - val_loss: 0.1242
Epoch 153/300
7352/7352 [=====] - 45s 6ms/step - loss: 0.1685 - acc: 0.9403 - val_loss: 0.1242
Epoch 154/300
7352/7352 [=====] - 42s 6ms/step - loss: 0.1104 - acc: 0.9525 - val_loss: 0.1242
Epoch 155/300
7352/7352 [=====] - 38s 5ms/step - loss: 0.1115 - acc: 0.9553 - val_loss: 0.1242
Epoch 156/300
7352/7352 [=====] - 33s 5ms/step - loss: 0.1192 - acc: 0.9527 - val_loss: 0.1242
Epoch 157/300
7352/7352 [=====] - 33s 4ms/step - loss: 0.1104 - acc: 0.9597 - val_loss: 0.1242
Epoch 158/300
7352/7352 [=====] - 40s 6ms/step - loss: 0.1098 - acc: 0.9574 - val_loss: 0.1242
Epoch 159/300
7352/7352 [=====] - 35s 5ms/step - loss: 0.1059 - acc: 0.9597 - val_loss: 0.1242
Epoch 160/300
7352/7352 [=====] - 34s 5ms/step - loss: 0.1320 - acc: 0.9453 - val_loss: 0.1242
Epoch 161/300
7352/7352 [=====] - 34s 5ms/step - loss: 0.1115 - acc: 0.9499 - val_loss: 0.1242
Epoch 162/300
7352/7352 [=====] - 35s 5ms/step - loss: 0.1088 - acc: 0.9548 - val_loss: 0.1242
Epoch 163/300
7352/7352 [=====] - 33s 5ms/step - loss: 0.1092 - acc: 0.9536 - val_loss: 0.1242
Epoch 164/300
7352/7352 [=====] - 42s 6ms/step - loss: 0.1108 - acc: 0.9533 - val_loss: 0.1242
Epoch 165/300
7352/7352 [=====] - 39s 5ms/step - loss: 0.1346 - acc: 0.9416 - val_loss: 0.1242
Epoch 166/300
7352/7352 [=====] - 39s 5ms/step - loss: 0.1300 - acc: 0.9486 - val_loss: 0.1242

Epoch 167/300
7352/7352 [=====] - 41s 6ms/step - loss: 0.1103 - acc: 0.9582 - val_loss: 0.1103
Epoch 168/300
7352/7352 [=====] - 38s 5ms/step - loss: 0.1086 - acc: 0.9563 - val_loss: 0.1086
Epoch 169/300
7352/7352 [=====] - 39s 5ms/step - loss: 0.1089 - acc: 0.9576 - val_loss: 0.1089
Epoch 170/300
7352/7352 [=====] - 39s 5ms/step - loss: 0.1183 - acc: 0.9574 - val_loss: 0.1183
Epoch 171/300
7352/7352 [=====] - 39s 5ms/step - loss: 0.1005 - acc: 0.9574 - val_loss: 0.1005
Epoch 172/300
7352/7352 [=====] - 40s 5ms/step - loss: 0.1005 - acc: 0.9578 - val_loss: 0.1005
Epoch 173/300
7352/7352 [=====] - 40s 5ms/step - loss: 0.1092 - acc: 0.9588 - val_loss: 0.1092
Epoch 174/300
7352/7352 [=====] - 38s 5ms/step - loss: 0.1034 - acc: 0.9597 - val_loss: 0.1034
Epoch 175/300
7352/7352 [=====] - 40s 5ms/step - loss: 0.1028 - acc: 0.9561 - val_loss: 0.1028
Epoch 176/300
7352/7352 [=====] - 38s 5ms/step - loss: 0.1072 - acc: 0.9561 - val_loss: 0.1072
Epoch 177/300
7352/7352 [=====] - 38s 5ms/step - loss: 0.1093 - acc: 0.9557 - val_loss: 0.1093
Epoch 178/300
7352/7352 [=====] - 38s 5ms/step - loss: 0.1101 - acc: 0.9555 - val_loss: 0.1101
Epoch 179/300
7352/7352 [=====] - 38s 5ms/step - loss: 0.1004 - acc: 0.9573 - val_loss: 0.1004
Epoch 180/300
7352/7352 [=====] - 38s 5ms/step - loss: 0.1120 - acc: 0.9547 - val_loss: 0.1120
Epoch 181/300
7352/7352 [=====] - 34s 5ms/step - loss: 0.1104 - acc: 0.9510 - val_loss: 0.1104
Epoch 182/300
7352/7352 [=====] - 33s 5ms/step - loss: 0.1223 - acc: 0.9531 - val_loss: 0.1223
Epoch 183/300
7352/7352 [=====] - 33s 4ms/step - loss: 0.1390 - acc: 0.9354 - val_loss: 0.1390
Epoch 184/300
7352/7352 [=====] - 33s 5ms/step - loss: 0.1504 - acc: 0.9373 - val_loss: 0.1504
Epoch 185/300
7352/7352 [=====] - 33s 5ms/step - loss: 0.1139 - acc: 0.9502 - val_loss: 0.1139
Epoch 186/300
7352/7352 [=====] - 32s 4ms/step - loss: 0.1104 - acc: 0.9514 - val_loss: 0.1104
Epoch 187/300
7352/7352 [=====] - 33s 4ms/step - loss: 0.1100 - acc: 0.9524 - val_loss: 0.1100
Epoch 188/300
7352/7352 [=====] - 33s 5ms/step - loss: 0.1043 - acc: 0.9528 - val_loss: 0.1043
Epoch 189/300
7352/7352 [=====] - 37s 5ms/step - loss: 0.1056 - acc: 0.9540 - val_loss: 0.1056
Epoch 190/300
7352/7352 [=====] - 41s 6ms/step - loss: 0.1038 - acc: 0.9535 - val_loss: 0.1038

Epoch 191/300
7352/7352 [=====] - 40s 5ms/step - loss: 0.1106 - acc: 0.9566 - val_loss: 0.1106
Epoch 192/300
7352/7352 [=====] - 40s 5ms/step - loss: 0.0998 - acc: 0.9584 - val_loss: 0.1106
Epoch 193/300
7352/7352 [=====] - 40s 5ms/step - loss: 0.0995 - acc: 0.9591 - val_loss: 0.1106
Epoch 194/300
7352/7352 [=====] - 39s 5ms/step - loss: 0.0993 - acc: 0.9600 - val_loss: 0.1106
Epoch 195/300
7352/7352 [=====] - 39s 5ms/step - loss: 0.0953 - acc: 0.9596 - val_loss: 0.1106
Epoch 196/300
7352/7352 [=====] - 40s 5ms/step - loss: 0.1004 - acc: 0.9588 - val_loss: 0.1106
Epoch 197/300
7352/7352 [=====] - 39s 5ms/step - loss: 0.1170 - acc: 0.9572 - val_loss: 0.1106
Epoch 198/300
7352/7352 [=====] - 40s 5ms/step - loss: 0.1590 - acc: 0.9431 - val_loss: 0.1106
Epoch 199/300
7352/7352 [=====] - 44s 6ms/step - loss: 0.1601 - acc: 0.9457 - val_loss: 0.1106
Epoch 200/300
7352/7352 [=====] - 41s 6ms/step - loss: 0.1212 - acc: 0.9551 - val_loss: 0.1106
Epoch 201/300
7352/7352 [=====] - 41s 6ms/step - loss: 0.1406 - acc: 0.9517 - val_loss: 0.1106
Epoch 202/300
7352/7352 [=====] - 42s 6ms/step - loss: 0.1190 - acc: 0.9570 - val_loss: 0.1106
Epoch 203/300
7352/7352 [=====] - 40s 5ms/step - loss: 0.1104 - acc: 0.9582 - val_loss: 0.1106
Epoch 204/300
7352/7352 [=====] - 34s 5ms/step - loss: 0.1087 - acc: 0.9580 - val_loss: 0.1106
Epoch 205/300
7352/7352 [=====] - 34s 5ms/step - loss: 0.1143 - acc: 0.9529 - val_loss: 0.1106
Epoch 206/300
7352/7352 [=====] - 37s 5ms/step - loss: 0.1066 - acc: 0.9578 - val_loss: 0.1106
Epoch 207/300
7352/7352 [=====] - 39s 5ms/step - loss: 0.1061 - acc: 0.9572 - val_loss: 0.1106
Epoch 208/300
7352/7352 [=====] - 40s 5ms/step - loss: 0.1048 - acc: 0.9588 - val_loss: 0.1106
Epoch 209/300
7352/7352 [=====] - 42s 6ms/step - loss: 0.1412 - acc: 0.9523 - val_loss: 0.1106
Epoch 210/300
7352/7352 [=====] - 40s 5ms/step - loss: 0.1328 - acc: 0.9517 - val_loss: 0.1106
Epoch 211/300
7352/7352 [=====] - 36s 5ms/step - loss: 0.1099 - acc: 0.9567 - val_loss: 0.1106
Epoch 212/300
7352/7352 [=====] - 42s 6ms/step - loss: 0.1221 - acc: 0.9512 - val_loss: 0.1106
Epoch 213/300
7352/7352 [=====] - 35s 5ms/step - loss: 0.1106 - acc: 0.9563 - val_loss: 0.1106
Epoch 214/300
7352/7352 [=====] - 41s 6ms/step - loss: 0.1044 - acc: 0.9558 - val_loss: 0.1106

Epoch 215/300
7352/7352 [=====] - 41s 6ms/step - loss: 0.1018 - acc: 0.9577 - val_loss: 0.1018
Epoch 216/300
7352/7352 [=====] - 41s 6ms/step - loss: 0.1019 - acc: 0.9566 - val_loss: 0.1019
Epoch 217/300
7352/7352 [=====] - 41s 6ms/step - loss: 0.1106 - acc: 0.9529 - val_loss: 0.1106
Epoch 218/300
7352/7352 [=====] - 41s 6ms/step - loss: 0.1015 - acc: 0.9589 - val_loss: 0.1015
Epoch 219/300
7352/7352 [=====] - 41s 6ms/step - loss: 0.1036 - acc: 0.9589 - val_loss: 0.1036
Epoch 220/300
7352/7352 [=====] - 37s 5ms/step - loss: 0.0998 - acc: 0.9595 - val_loss: 0.0998
Epoch 221/300
7352/7352 [=====] - 41s 6ms/step - loss: 0.1021 - acc: 0.9577 - val_loss: 0.1021
Epoch 222/300
7352/7352 [=====] - 38s 5ms/step - loss: 0.1232 - acc: 0.9478 - val_loss: 0.1232
Epoch 223/300
7352/7352 [=====] - 40s 5ms/step - loss: 0.1313 - acc: 0.9422 - val_loss: 0.1313
Epoch 224/300
7352/7352 [=====] - 41s 6ms/step - loss: 0.1422 - acc: 0.9404 - val_loss: 0.1422
Epoch 225/300
7352/7352 [=====] - 40s 6ms/step - loss: 0.1183 - acc: 0.9465 - val_loss: 0.1183
Epoch 226/300
7352/7352 [=====] - 41s 6ms/step - loss: 0.1113 - acc: 0.9495 - val_loss: 0.1113
Epoch 227/300
7352/7352 [=====] - 40s 5ms/step - loss: 0.1080 - acc: 0.9542 - val_loss: 0.1080
Epoch 228/300
7352/7352 [=====] - 39s 5ms/step - loss: 0.1227 - acc: 0.9482 - val_loss: 0.1227
Epoch 229/300
7352/7352 [=====] - 39s 5ms/step - loss: 0.1321 - acc: 0.9415 - val_loss: 0.1321
Epoch 230/300
7352/7352 [=====] - 40s 5ms/step - loss: 0.1082 - acc: 0.9520 - val_loss: 0.1082
Epoch 231/300
7352/7352 [=====] - 40s 5ms/step - loss: 0.1069 - acc: 0.9565 - val_loss: 0.1069
Epoch 232/300
7352/7352 [=====] - 41s 6ms/step - loss: 0.1031 - acc: 0.9573 - val_loss: 0.1031
Epoch 233/300
7352/7352 [=====] - 39s 5ms/step - loss: 0.1065 - acc: 0.9540 - val_loss: 0.1065
Epoch 234/300
7352/7352 [=====] - 40s 6ms/step - loss: 0.1051 - acc: 0.9558 - val_loss: 0.1051
Epoch 235/300
7352/7352 [=====] - 41s 6ms/step - loss: 0.1076 - acc: 0.9543 - val_loss: 0.1076
Epoch 236/300
7352/7352 [=====] - 40s 5ms/step - loss: 0.1107 - acc: 0.9567 - val_loss: 0.1107
Epoch 237/300
7352/7352 [=====] - 40s 5ms/step - loss: 0.1041 - acc: 0.9589 - val_loss: 0.1041
Epoch 238/300
7352/7352 [=====] - 40s 5ms/step - loss: 0.1127 - acc: 0.9548 - val_loss: 0.1127

Epoch 239/300
7352/7352 [=====] - 40s 5ms/step - loss: 0.1108 - acc: 0.9577 - val_loss: 0.1108
Epoch 240/300
7352/7352 [=====] - 40s 5ms/step - loss: 0.1044 - acc: 0.9584 - val_loss: 0.1044
Epoch 241/300
7352/7352 [=====] - 39s 5ms/step - loss: 0.1019 - acc: 0.9593 - val_loss: 0.1019
Epoch 242/300
7352/7352 [=====] - 40s 5ms/step - loss: 0.0995 - acc: 0.9580 - val_loss: 0.0995
Epoch 243/300
7352/7352 [=====] - 40s 5ms/step - loss: 0.1423 - acc: 0.9482 - val_loss: 0.1423
Epoch 244/300
7352/7352 [=====] - 40s 5ms/step - loss: 0.1149 - acc: 0.9525 - val_loss: 0.1149
Epoch 245/300
7352/7352 [=====] - 40s 5ms/step - loss: 0.1112 - acc: 0.9521 - val_loss: 0.1112
Epoch 246/300
7352/7352 [=====] - 41s 6ms/step - loss: 0.1070 - acc: 0.9562 - val_loss: 0.1070
Epoch 247/300
7352/7352 [=====] - 40s 5ms/step - loss: 0.1038 - acc: 0.9554 - val_loss: 0.1038
Epoch 248/300
7352/7352 [=====] - 40s 5ms/step - loss: 0.1011 - acc: 0.9569 - val_loss: 0.1011
Epoch 249/300
7352/7352 [=====] - 41s 6ms/step - loss: 0.0997 - acc: 0.9592 - val_loss: 0.0997
Epoch 250/300
7352/7352 [=====] - 41s 6ms/step - loss: 0.0953 - acc: 0.9595 - val_loss: 0.0953
Epoch 251/300
7352/7352 [=====] - 41s 6ms/step - loss: 0.0965 - acc: 0.9599 - val_loss: 0.0965
Epoch 252/300
7352/7352 [=====] - 39s 5ms/step - loss: 0.1134 - acc: 0.9539 - val_loss: 0.1134
Epoch 253/300
7352/7352 [=====] - 40s 5ms/step - loss: 0.1013 - acc: 0.9581 - val_loss: 0.1013
Epoch 254/300
7352/7352 [=====] - 40s 5ms/step - loss: 0.0947 - acc: 0.9606 - val_loss: 0.0947
Epoch 255/300
7352/7352 [=====] - 39s 5ms/step - loss: 0.0995 - acc: 0.9589 - val_loss: 0.0995
Epoch 256/300
7352/7352 [=====] - 40s 5ms/step - loss: 0.0969 - acc: 0.9591 - val_loss: 0.0969
Epoch 257/300
7352/7352 [=====] - 40s 5ms/step - loss: 0.0946 - acc: 0.9585 - val_loss: 0.0946
Epoch 258/300
7352/7352 [=====] - 40s 5ms/step - loss: 0.1006 - acc: 0.9569 - val_loss: 0.1006
Epoch 259/300
7352/7352 [=====] - 40s 5ms/step - loss: 0.1617 - acc: 0.9434 - val_loss: 0.1617
Epoch 260/300
7352/7352 [=====] - 40s 5ms/step - loss: 0.1136 - acc: 0.9527 - val_loss: 0.1136
Epoch 261/300
7352/7352 [=====] - 40s 5ms/step - loss: 0.1338 - acc: 0.9509 - val_loss: 0.1338
Epoch 262/300
7352/7352 [=====] - 39s 5ms/step - loss: 0.1070 - acc: 0.9569 - val_loss: 0.1070

Epoch 263/300
7352/7352 [=====] - 39s 5ms/step - loss: 0.1031 - acc: 0.9559 - val_loss: 0.1031
Epoch 264/300
7352/7352 [=====] - 40s 5ms/step - loss: 0.0982 - acc: 0.9573 - val_loss: 0.1031
Epoch 265/300
7352/7352 [=====] - 39s 5ms/step - loss: 0.0991 - acc: 0.9578 - val_loss: 0.1031
Epoch 266/300
7352/7352 [=====] - 40s 5ms/step - loss: 0.1367 - acc: 0.9411 - val_loss: 0.1031
Epoch 267/300
7352/7352 [=====] - 40s 6ms/step - loss: 0.1390 - acc: 0.9418 - val_loss: 0.1031
Epoch 268/300
7352/7352 [=====] - 34s 5ms/step - loss: 0.1270 - acc: 0.9441 - val_loss: 0.1031
Epoch 269/300
7352/7352 [=====] - 32s 4ms/step - loss: 0.1168 - acc: 0.9453 - val_loss: 0.1031
Epoch 270/300
7352/7352 [=====] - 33s 4ms/step - loss: 0.1128 - acc: 0.9487 - val_loss: 0.1031
Epoch 271/300
7352/7352 [=====] - 32s 4ms/step - loss: 0.1107 - acc: 0.9527 - val_loss: 0.1031
Epoch 272/300
7352/7352 [=====] - 32s 4ms/step - loss: 0.1079 - acc: 0.9512 - val_loss: 0.1031
Epoch 273/300
7352/7352 [=====] - 32s 4ms/step - loss: 0.1077 - acc: 0.9517 - val_loss: 0.1031
Epoch 274/300
7352/7352 [=====] - 34s 5ms/step - loss: 0.1112 - acc: 0.9548 - val_loss: 0.1031
Epoch 275/300
7352/7352 [=====] - 39s 5ms/step - loss: 0.1090 - acc: 0.9529 - val_loss: 0.1031
Epoch 276/300
7352/7352 [=====] - 39s 5ms/step - loss: 0.1058 - acc: 0.9544 - val_loss: 0.1031
Epoch 277/300
7352/7352 [=====] - 34s 5ms/step - loss: 0.1123 - acc: 0.9528 - val_loss: 0.1031
Epoch 278/300
7352/7352 [=====] - 33s 5ms/step - loss: 0.1090 - acc: 0.9550 - val_loss: 0.1031
Epoch 279/300
7352/7352 [=====] - 36s 5ms/step - loss: 0.1832 - acc: 0.9363 - val_loss: 0.1031
Epoch 280/300
7352/7352 [=====] - 37s 5ms/step - loss: 0.1165 - acc: 0.9506 - val_loss: 0.1031
Epoch 281/300
7352/7352 [=====] - 35s 5ms/step - loss: 0.1097 - acc: 0.9525 - val_loss: 0.1031
Epoch 282/300
7352/7352 [=====] - 34s 5ms/step - loss: 0.1055 - acc: 0.9539 - val_loss: 0.1031
Epoch 283/300
7352/7352 [=====] - 36s 5ms/step - loss: 0.1048 - acc: 0.9558 - val_loss: 0.1031
Epoch 284/300
7352/7352 [=====] - 36s 5ms/step - loss: 0.1137 - acc: 0.9538 - val_loss: 0.1031
Epoch 285/300
7352/7352 [=====] - 36s 5ms/step - loss: 0.1051 - acc: 0.9569 - val_loss: 0.1031
Epoch 286/300
7352/7352 [=====] - 35s 5ms/step - loss: 0.1029 - acc: 0.9585 - val_loss: 0.1031

```

Epoch 287/300
7352/7352 [=====] - 35s 5ms/step - loss: 0.0993 - acc: 0.9584 - val_loss: 0.0993
Epoch 288/300
7352/7352 [=====] - 34s 5ms/step - loss: 0.0944 - acc: 0.9603 - val_loss: 0.0944
Epoch 289/300
7352/7352 [=====] - 42s 6ms/step - loss: 0.0933 - acc: 0.9581 - val_loss: 0.0933
Epoch 290/300
7352/7352 [=====] - 36s 5ms/step - loss: 0.0993 - acc: 0.9574 - val_loss: 0.0993
Epoch 291/300
7352/7352 [=====] - 35s 5ms/step - loss: 0.0943 - acc: 0.9585 - val_loss: 0.0943
Epoch 292/300
7352/7352 [=====] - 34s 5ms/step - loss: 0.0960 - acc: 0.9593 - val_loss: 0.0960
Epoch 293/300
7352/7352 [=====] - 34s 5ms/step - loss: 0.0958 - acc: 0.9597 - val_loss: 0.0958
Epoch 294/300
7352/7352 [=====] - 33s 5ms/step - loss: 0.0945 - acc: 0.9576 - val_loss: 0.0945
Epoch 295/300
7352/7352 [=====] - 34s 5ms/step - loss: 0.1000 - acc: 0.9573 - val_loss: 0.1000
Epoch 296/300
7352/7352 [=====] - 32s 4ms/step - loss: 0.1204 - acc: 0.9567 - val_loss: 0.1204
Epoch 297/300
7352/7352 [=====] - 33s 4ms/step - loss: 0.0881 - acc: 0.9604 - val_loss: 0.0881
Epoch 298/300
7352/7352 [=====] - 34s 5ms/step - loss: 0.0848 - acc: 0.9618 - val_loss: 0.0848
Epoch 299/300
7352/7352 [=====] - 33s 5ms/step - loss: 0.0939 - acc: 0.9603 - val_loss: 0.0939
Epoch 300/300
7352/7352 [=====] - 32s 4ms/step - loss: 0.0990 - acc: 0.9582 - val_loss: 0.0990

```

Out[36]: <keras.callbacks.History at 0x1f1cd453860>

```

In [37]: # Confusion Matrix
print(confusion_matrix(Y_test, model.predict(X_test)))

```

Pred \ True	LAYING	SITTING	STANDING	WALKING	WALKING_DOWNSTAIRS	WALKING_UPSTAIRS
LAYING	537	0	0	0	0	0
SITTING	0	378	113	0	0	0
STANDING	0	59	473	0	0	0
WALKING	0	0	0	496	0	0
WALKING_DOWNSTAIRS	0	1	0	12	399	0
WALKING_UPSTAIRS	0	2	1	3	0	0

Pred \ True	WALKING_UPSTAIRS
LAYING	0
SITTING	0

STANDING	0
WALKING	0
WALKING_DOWNSTAIRS	8
WALKING_UPSTAIRS	465

```
In [38]: score = model.evaluate(X_test, Y_test)
```

```
2947/2947 [=====] - 3s 897us/step
```

```
In [39]: score
```

```
Out[39]: [0.21770981482614904, 0.9324737020699015]
```

- With a simple 2 layer architecture we got 93.24% accuracy and a loss of 0.21
- We can further improve the performance with Hyperparameter tuning

17 Conclusion :

1. Here we saw that by using two layered LSTM, we got an accuracy of 93.24% with a loss of 0.21%. Deep Learning helps us to build models even when we don't have domain expert engineered features. 2. LSTM model can give good results by doing more hyperparameter tuning. 3. In this case study for better accuracy I had checked different epochs with different parameters.