Report: Deep AutoEncoder Based Recommender System

Overview

The goal of this assignment was to build a Deep AutoEncoder based recommender system using the MovieLens dataset. The system predicts user ratings for movies that have not been rated, enabling movie recommendations. This report outlines the implementation process, data preparation steps, model architecture, training procedure, and comments on the results obtained.

1. Data Preparation

1.1 Dataset Description

The MovieLens dataset consists of:

- 100,000 ratings from 943 users on 1,682 movies.
- Ratings are integers ranging from 1 to 5, with 0 indicating an unrated movie.

The data was cleaned to ensure each user rated at least 20 movies. The dataset includes:

- ratings.csv: User ratings for movies.
- movies.csv: Metadata for movies.

1.2 Data Splitting

The data was split into training and validation sets based on the timestamp column:

- **Training Set**: Ratings up to the 98th percentile of timestamps.
- Validation Set: Remaining ratings.

Key Steps:

- 1. Merging and Descriptive Analysis:
 - o ratings.csv was merged with movies.csv using movieId.
 - Summary statistics were printed to verify data distribution.
- 2. Data Filtering:

- Users in the validation set who were not present in the training set were removed.
- Movies not present in the training set were removed from the validation set.

Output:

Train Users: 595
Validation Users: 595
Train Movies: 9559
Validation Movies: 9559

The resulting data matrices were stored in train.csv and test.csv.

2. Model Architecture

2.1 AutoEncoder Structure

The AutoEncoder was implemented with the following architecture:

- Encoder:
 - o Input Layer: 9559 nodes (dimensionality of the movie-user matrix).
 - Hidden Layers: 512, 512, and 1024 nodes with ReLU activation.
- Decoder:
 - o Hidden Layers: 1024, 512, and 512 nodes with ReLU activation.
 - o Output Layer: 9559 nodes.

2.2 Loss Function

A custom Masked Mean Squared Error (MSE) loss function was used:

• The loss function only considers non-zero ratings (i.e., ratings provided by users) for error calculation.

3. Training Procedure

3.1 DataLoader Creation

 Custom TrainDataset and TestDataset classes were implemented to load user-movie rating matrices. Data was batched using DataLoader for efficient model training.

3.2 Training Loop

The training loop iterated for 40 epochs:

- Input data was passed through the encoder to generate compressed representations, then decoded back to reconstruct the original ratings.
- The optimizer used was Adam with a learning rate of 0.001.
- Loss was computed using the custom MSELoss_with_Mask function, and gradients were updated accordingly.

4. Results and Observations

4.1 Loss Reduction

The training loss decreased consistently over the 40 epochs:

- **Initial Loss** (Epoch 1): ~10.77
- Final Loss (Epoch 40): ~0.61

This indicates that the model effectively learned to minimize the reconstruction error.

4.2 Collected Results

- Training Data: Successfully split and filtered.
- Validation Data: Successfully split and filtered.
- User-Movie Rating Matrices: Constructed with 0.0 for missing ratings.
- **Training Performance**: The model converged well, showing consistent improvement in loss reduction across epochs.

4.3 Future Considerations

- **Parameter Tuning**: Further tuning of learning rates, hidden layers, and activation functions may yield improved performance.
- Data Scaling: Normalizing the ratings or using different loss functions could be explored.
- **Model Complexity**: Increasing the depth of the encoder/decoder or adding regularization may enhance generalization.

Conclusion

The Deep AutoEncoder-based recommender system was successfully implemented and trained using the MovieLens dataset. The model demonstrated a strong ability to minimize reconstruction error, achieving stable loss values. This approach can be further enhanced through additional fine-tuning and testing on larger datasets for real-world applications.

Code:

```
@author: ahmed-notebook
import pandas as pd
import numpy as np
import torch
import torch.nn as nn
from torch.utils.data import Dataset, DataLoader
import matplotlib.pyplot as plt
class TrainDataset(Dataset):
       self.data = pd.read csv(train file)
       self.transform = transform
       return len(self.data)
   def __getitem__(self, ind):
       user vector = self.data.iloc[ind].values.astype(np.float32)
       user vector = torch.FloatTensor(user vector) # Convert directly
   def init (self, test file, transform=None):
```

```
self.data = pd.read csv(test file)
      self.transform = transform
      return len(self.data)
   def getitem (self, ind):
      user vector = self.data.iloc[ind].values.astype(np.float32)
      user vector = torch.FloatTensor(user vector) # Convert directly
      return user vector
def prepare train validation movielens step1():
   rat = pd.read csv('/content/ratings.csv')
   mov = pd.read csv('/content/movies.csv')
   df combined = pd.merge(rat, mov, on='movieId')
   print(rat.describe())
   ts = rat['timestamp'].quantile(0.98)
   train ratings = pd.DataFrame(columns=['userId', 'movieId', 'rating'])
   validation ratings = pd.DataFrame(columns=['userId', 'movieId',
   for i in range(len(rat)):
      if rat['timestamp'].iloc[i] <= ts:</pre>
          train ratings = pd.concat([train ratings,
pd.DataFrame([{'userId': rat['userId'].iloc[i], 'movieId':
validation ratings = pd.concat([validation ratings,
pd.DataFrame([{'userId': rat['userId'].iloc[i], 'movieId':
validation ratings = pd.concat([validation ratings,
pd.DataFrame([{'userId': rat['userId'].iloc[i], 'movieId':
if i % 10000 == 0:
          print(i, "Completed")
   print(len(train ratings))
   print(len(validation ratings))
```

```
train users = train ratings['userId'].unique()
   users not in train set = []
   for i in range(1, 611):
       if i not in train users:
           users_not_in_train_set.append(i)
   for i in users not in train set:
       validation ratings =
validation ratings[validation ratings['userId'] != i]
   validation ratings.reset index(drop=True)
   print(len(train ratings['movieId'].unique()))
   print(len(validation ratings['movieId'].unique()))
   validation movies = validation ratings['movieId'].unique()
   train movies = train ratings['movieId'].unique()
   movies not in train set = []
   for i in validation movies:
       if i not in train movies:
           movies not in train set.append(i)
   for i in movies not in train set:
       validation ratings =
validation ratings[validation ratings['movieId'] != i]
   validation ratings.reset index(drop=True)
   print('Train Users: ', train ratings['userId'].nunique())
   print('Validation Users: ', validation ratings['userId'].nunique())
   print('Train Movies: ', train ratings['movieId'].nunique())
   print('Validation Movies: ', validation ratings['movieId'].nunique())
   train ratings.to csv("/content/train ratings.csv")
   validation ratings.to csv("/content/validation ratings.csv")
def prepare traintest movielens step2():
   tr ratings = pd.read csv('/content/train ratings.csv')
   val ratings = pd.read csv('/content/validation ratings.csv')
```

```
train dataset = tr ratings.pivot table(index='userId',
columns='movieId', values='rating')
   train dataset.fillna(0, inplace=True)
   print(train dataset.head(10))
   test dataset = val ratings.pivot table(index='userId',
columns='movieId', values='rating')
   test dataset.fillna(0, inplace=True)
   print(test dataset.head(10))
   train dataset.to csv('/content/train.csv')
   test dataset.to csv('/content/test.csv')
def get traintestloaders():
   train dat = TrainDataset('/content/train.csv')
   test dat = TestDataset('/content/test.csv')
   train loader = DataLoader(dataset=train dat, batch size=128,
shuffle=True, num workers=1)
   test loader = DataLoader(dataset=test dat, batch size=128,
shuffle=True, num workers=1)
   def init (self):
       super(MSELoss with Mask, self). init ()
   def forward(self, inputs, targets):
       mask = (targets != 0).float()
       number ratings = torch.max(torch.sum(mask),
torch.tensor(1.0).cuda())
       error = torch.sum(mask * (targets - inputs) ** 2)
       loss = error / number ratings
class AutoEncoder(nn.Module):
   def init (self, encoder layers sizes, activation='ReLU'):
       super(AutoEncoder, self). init ()
       self.encoder = nn.Sequential(
            nn.Linear(encoder layers sizes[0], encoder layers sizes[1]),
```

```
nn.ReLU(),
            nn.Linear(encoder layers sizes[1], encoder layers sizes[2]),
            nn.ReLU(),
            nn.Linear(encoder layers sizes[2], encoder layers sizes[3]),
            nn.ReLU()
       self.decoder = nn.Sequential(
            nn.Linear(encoder layers sizes[3], encoder layers sizes[2]),
            nn.ReLU(),
            nn.Linear(encoder layers sizes[2], encoder layers sizes[1]),
           nn.ReLU(),
           nn.Linear(encoder layers sizes[1], encoder layers sizes[0])
   def forward(self, x):
       encoded = self.encoder(x)
       decoded = self.decoder(encoded)
       return decoded
import torch.optim as optim
def train(model, criterion, optimizer, train loader, test loader,
num epochs=50):
   model.train()
   for epoch in range(num epochs):
        train loss = 0.0
       for data in train loader:
            inputs = data.cuda()
            optimizer.zero grad()
           outputs = model(inputs)
            loss = criterion(outputs, inputs)
            loss.backward()
           optimizer.step()
            train loss += loss.item()
       print(f'Epoch {epoch+1}, Loss: {train loss/len(train loader)}')
def main():
```

```
prepare_train_validation_movielens_step1()
    prepare_traintest_movielens_step2()
    train_loader, test_loader = get_traintestloaders()
    encoder_layers_sizes = [9559, 512, 512, 1024]
    model = AutoEncoder(encoder_layers_sizes)
    model = model.cuda()
    criterion = MSELoss_with_Mask().cuda()
    optimizer = optim.Adam(model.parameters(), lr=0.001)
    train(model, criterion, optimizer, train_loader, test_loader, 40)

if __name__ == '__main__':
    main()
```

Output:

Please refer to the Python notebook file.