Water Surface Garbage Collector System

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1 Introduction

In this fastest growing world, we are forgetting the nature and degrading it in several ways. For specific plastic is non bio degradable object that is thrown in the aquatic ecosystem, that is leading to degradation of marine habitat and also affecting human life. The main focus is to enhance the life of aquatic species.

2 Market Research

- 40 percent of world's water is polluted and unsafe for drinking
- 30 percent of people is dependent on water bodies for their occupations.
- Each year around 14 billion pounds of plastics are dumped into the water bodies.
- Untreated waste is dumped into water around 1.2 trillion gallons every year.
- 47 percent people will suffer to find drinking water by 2050.

3 Hardware Requirements

- pipe * 4
- Bearings *4
- Net
- Lithium Ion Battery (11.6V, 4 Amp)
- Power Bank (5V)
- USB Camera
- Raspberry Pi
- Nodemcu Esp8266
- Motor 60 RPM * 2
- Motor 100 RPM * 2
- Motor Driver * 2
- Sun Board

- Servo Motor(SG-90) * 2
- Servo Motor(MG-995)

4 Software Requirements

• Arduino IDE

5 Implementation

In this system, there are three phases –

- 1. Detection of Waste For the detection of waste, the camera is installed in the system so that user can easily monitor the location of waste. The output screen is built in the remote controller that is used to control the system in every possible direction.
- 2. Extraction of Waste The detected waste is then carried to the system by using conveyor belt fixed with the net that will segregate the waste and water.
- 3. Collection of waste The extracted waste is then travelled to the external net that is added at the back of the system, so that there is no effect of the weight on the system.

6 Diagram

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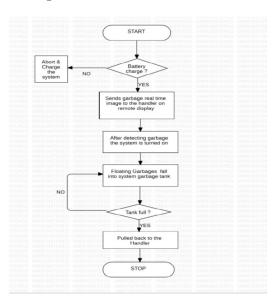


Figure 1: Flow Chart

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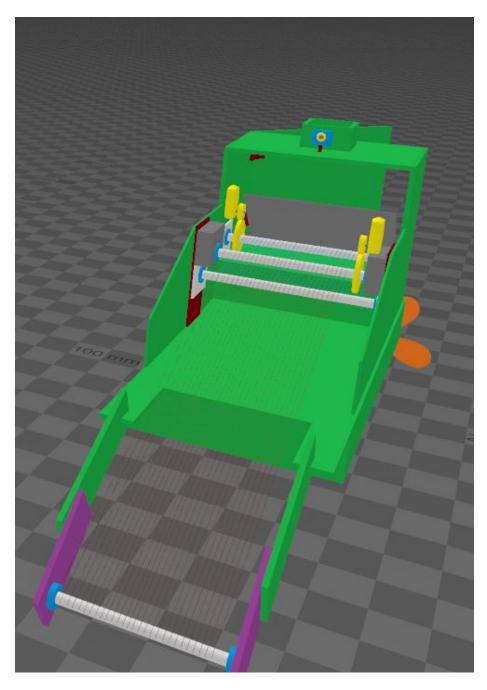


Figure 2: Model

7 Feasiblity Study