Al LAB 6 – 9557-Gaurav Mishra – Batch B

Implementation of AO* algorithm

Code:

```
import random
# Define the initial state of the block world
initial state = ['A', 'B', 'C', 'D']
# Define the goal state of the block world
goal_state = ['D', 'C', 'B', 'A']
# Define a function to calculate the heuristic (number of misplaced blocks)
def heuristic(state):
  return sum([1 for i, j in zip(state, goal state) if i != j])
# Define a function to generate neighboring states (move a block to the top)
def generate_neighbors(state):
  neighbors = []
  for i in range(len(state)):
    for j in range(i+1, len(state)):
       neighbor = state[:i] + [state[j]] + state[i:j] + state[j+1:]
       neighbors.append(neighbor)
  return neighbors
```

Define the Hill Climbing algorithm

```
def hill climbing(initial state, goal state):
  current_state = initial_state
  while True:
    current_heuristic = heuristic(current_state)
    neighbors = generate_neighbors(current_state)
    best_neighbor = min(neighbors, key=lambda neighbor:
heuristic(neighbor))
    if heuristic(best_neighbor) >= current_heuristic:
      return current_state
    current_state = best_neighbor
# Run the Hill Climbing algorithm
final_state = hill_climbing(initial_state, goal_state)
# Print the result
print("Initial State:", initial_state)
print("Final State:", final_state)
```

OUTPUT:

