## Style Swap - Assignment 3

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## 1 Configurations

- $\bullet\,$  Batch Size 128
- Width, Height, Channels 64, 64, 3
- Epochs 5
- Device Cuda
- Learning Rate 2e-4
- $\bullet$  Momentum 0.5
- Features (Generator and Discriminator) 64

## 2 Architecture

- Load the dataset, and transform and resize it to (64, 64), convert it into a tensor, and Normalise the data with mean of 0.5 and standard deviation of 0.5.
- Leaky ReLU 0.2
- Noise Dimension 100
- Create the model for the Generator and Discriminator as mentioned in the paper
- Initialize them with random weights from a random distribution having mean 0 and std 0.02.
- Optimizer Adam, for both the Generator and Discriminator
- $\bullet \ \operatorname{Loss} \ \operatorname{Function} \ \text{-} \ \operatorname{\mathbf{BCEWithLogitsLoss}}$

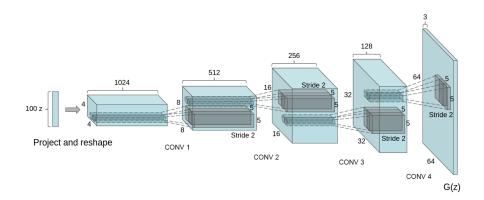


Figure 1: DCGAN

Figure 2: Generator Model

```
Discriminator(
   (disc): Sequential(
    (0): Sequential(
    (0): Sequential(
        (0): Sequential(
        (0): Sequential(
        (0): Conv2d(3, 64, kernel_size=(4, 4), stride=(2, 2), padding=(1, 1), bias=False)
        (1): BatchNorm2d(64, eps=1e=05, momentum=0.1, affine=True, track_running_stats=True)
        (2): LeakyReLU(negative_slope=0.2)
        (1): Sequential(
        (0): Conv2d(64, 128, kernel_size=(4, 4), stride=(2, 2), padding=(1, 1), bias=False)
        (1): BatchNorm2d(128, eps=1e=05, momentum=0.1, affine=True, track_running_stats=True)
        (2): LeakyReLU(negative_slope=0.2)
        (2): Sequential(
        (0): Conv2d(128, 256, kernel_size=(4, 4), stride=(2, 2), padding=(1, 1), bias=False)
        (1): BatchNorm2d(256, eps=1e=05, momentum=0.1, affine=True, track_running_stats=True)
        (2): LeakyReLU(negative_slope=0.2)
        (1): BatchNorm2d(512, eps=1e=05, momentum=0.1, affine=True, track_running_stats=True)
        (2): LeakyReLU(negative_slope=0.2)
        (4): Conv2d(512, 1, kernel_size=(4, 4), stride=(2, 2))
        (4): Conv2d(512, 1, kernel_size=(4, 4), stride=(2, 2))
}
```

Figure 3: Discriminator Model