## AI LAB 04

## Code:

```
def dfs(graph, start, goal):
   visited = []
   frontier = []
   stack = [[start, 0, [start]]] # [node, cost, path]
   optimal_path = []
   while stack:
       node, cost, path = stack.pop()
       if node not in visited:
          visited.append(node)
          frontier.append(node)
          if node == goal:
              if not optimal_path or cost < optimal_path[1]:</pre>
                 optimal_path = [path, cost]
          for neighbor in graph[node]:
              if neighbor not in visited:
                 stack.append([neighbor, cost+1, path+[neighbor]])
       print("Frontier:", frontier)
       print("Visited:", visited)
       print("----")
   print("Traversed path:", visited)
   print("Optimum path:", optimal_path[0])
   print("Path cost:", optimal_path[1])
   print("-----")
dfs(graph, '1', '4')
dfs(graph, '1', '10')
```

## **Output**

