#### **WEEKLY REPORT and MEETING AGENDA**

Report #: 9 Project Name:		Open Source Lidar	
Date: 3.31.2022	Prepared by:	Yile Chen	

### Agenda for the weekly meeting

- 1. Distribute hardware
- 2. Start working on tasks with hardware.

## Accomplishments during this period

- 1. Created CDR and Presentation
- 2. Presented the CDR Presentation
- 3. Discussed possible contingency plans due to supply chain delays.
- 4. Received the majority of parts and have begun working on creating a physical system.

### Plans for next period

- 1. Setup software for commercial lidar to get Bag data.
- 2. Flash code onto ST MCU through orange pi. Set up ROS for multiple machines after connecting orange PI to wifi to view hector Slam results through laptop.
- 3. Setup the motor and make it spin properly
- 4. Setup encoder proto-board circuit to help correct motor speed.
- 5. Print the base for holding the lidar and the overhang to hold the motor.
- 6. Divide photodiode and laser into separate PCB boards.
- 7. Create a clear testing procedure.

### Project management status

- 1. Schedule and milestones Integrating the entire system for the next couple weeks.
- 2. Teamwork Both teams are meeting for major work session on Saturday at Zach
- 3. Purchases Still awaiting the PCB, yet most of the other parts have arrived.

# Minutes from previous meeting

<ol> <li>Finished CDR documentations.</li> <li>Waiting for PCB and the mirror.</li> <li>Potentially flash the Discovery STM.</li> <li>Created dependencies of the features in the firmware.</li> </ol>		
	2. 3.	Waiting for PCB and the mirror. Potentially flash the Discovery STM.