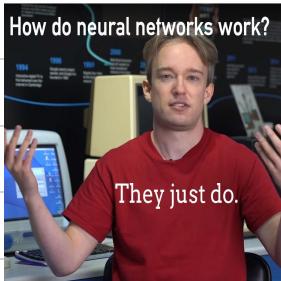
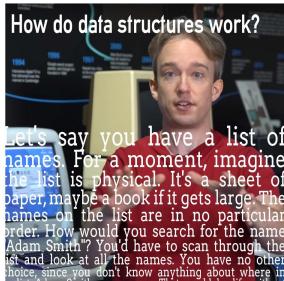


Asking programmers questions of increasing difficulty



DISCLOSE.TV

Facial Recognition Platform Misidentified
Dozens Of Politicians As Criminals

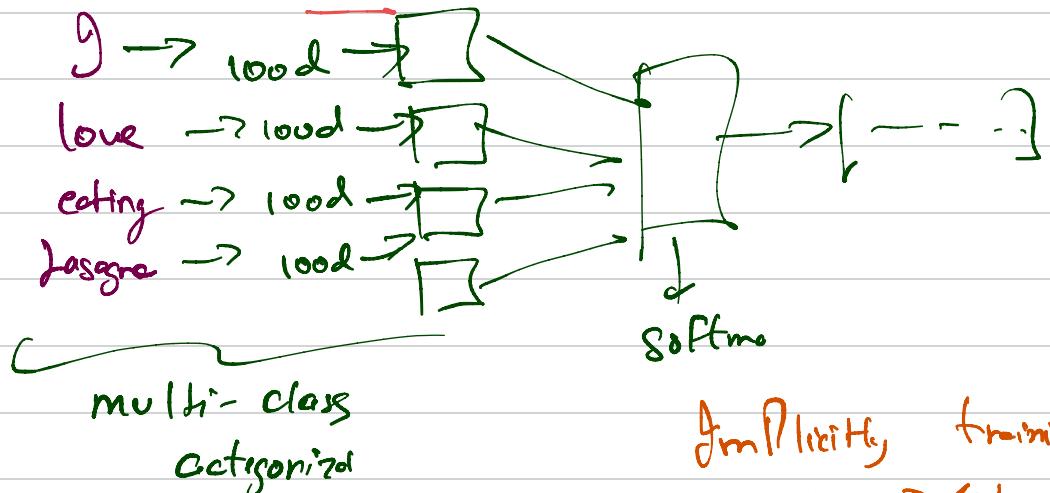


Agenda

1. RNN Architecture
2. Training a Many to One RNN model
3. Expanding training methods to other types of RNN
4. Code Implementation

MLP

① FFN- δP^2 with Word2Vec ✓ content
no Seq



- ① large no. of Para
② length → Padding
- U.V. efficient
- Inefficiency → 1st
2nd neuron

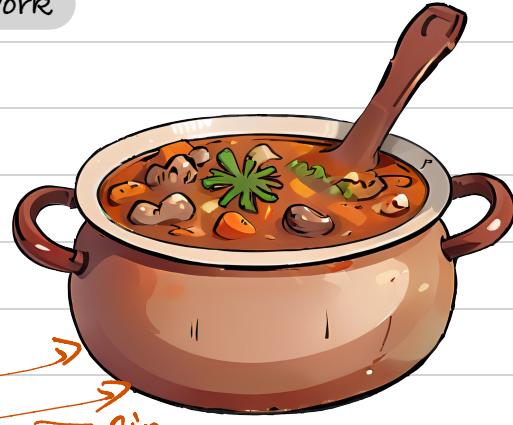


- ③ All words are present at once

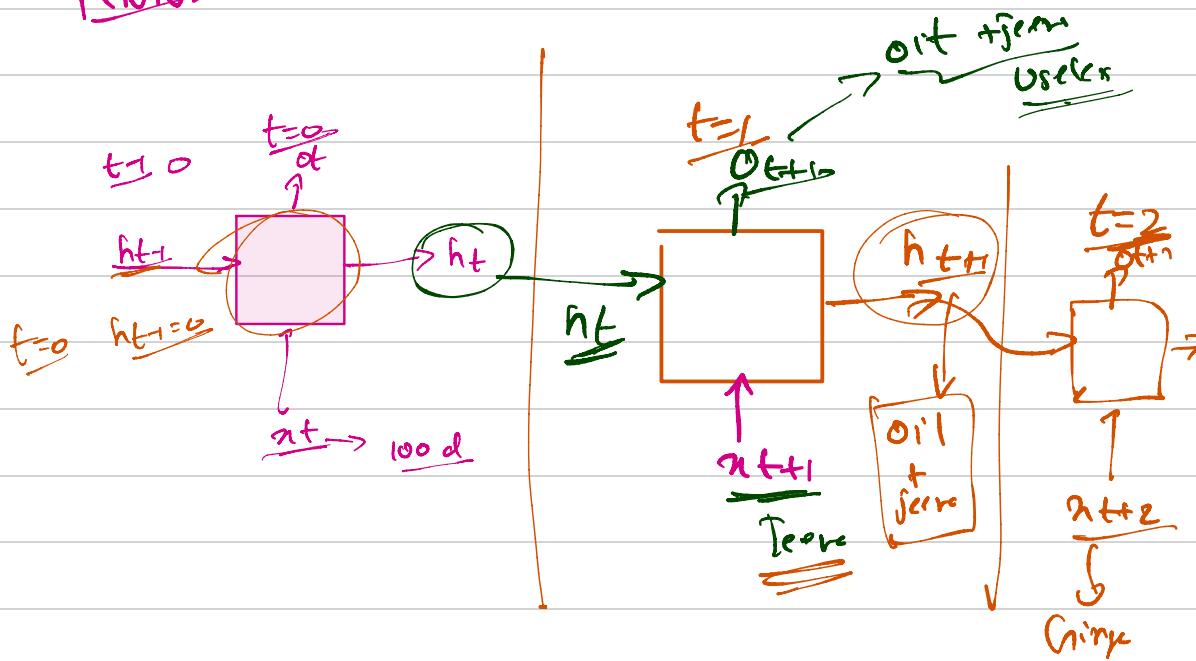
Recurrent Neural Network

Competition

10 Players \rightarrow One ingredient



RNN-

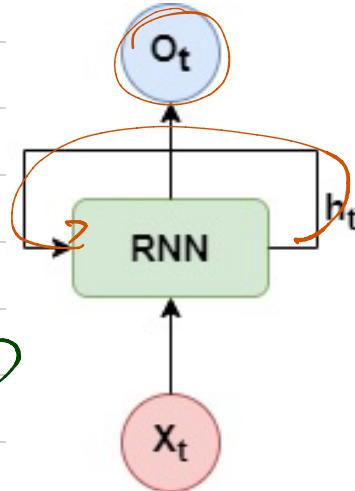


9 little cats

```

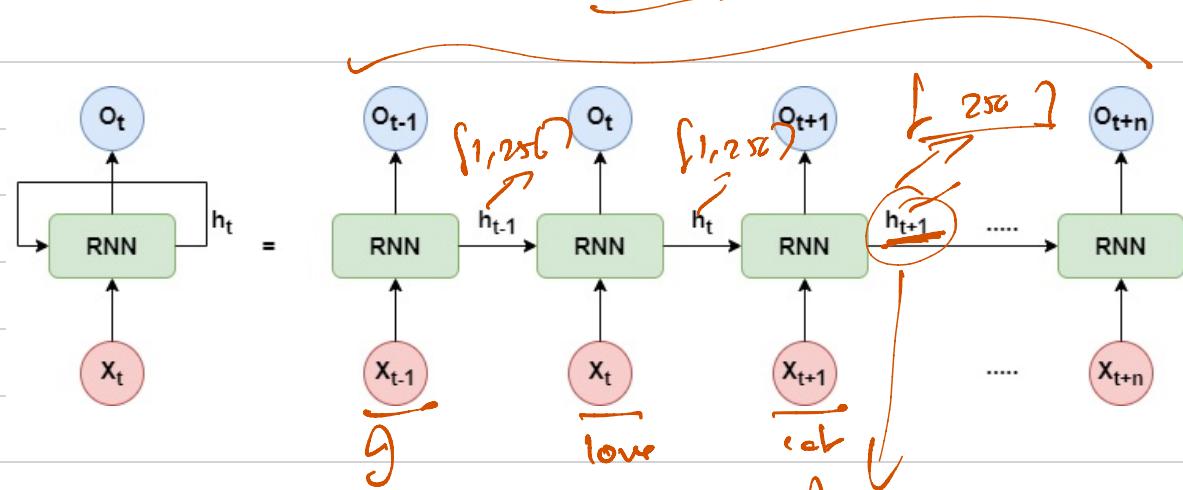
def minus(n)
    n = n - 1
    if n == 0:
        return 0
    else:
        return minus(n)

```



\downarrow
 RNN
 Recurrent
 $f^{(n)}$
 $\left. \begin{array}{c} f^{(n)} \\ f^{(n)} \end{array} \right\}$

unrolling



Includes inform.

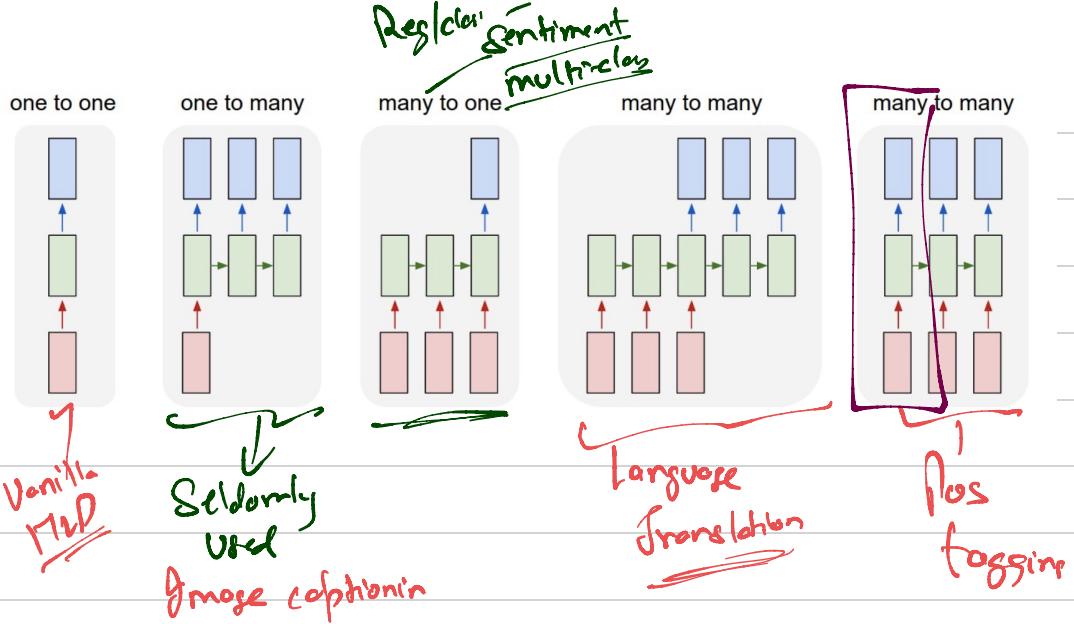
From previous

→ Any Sequential data

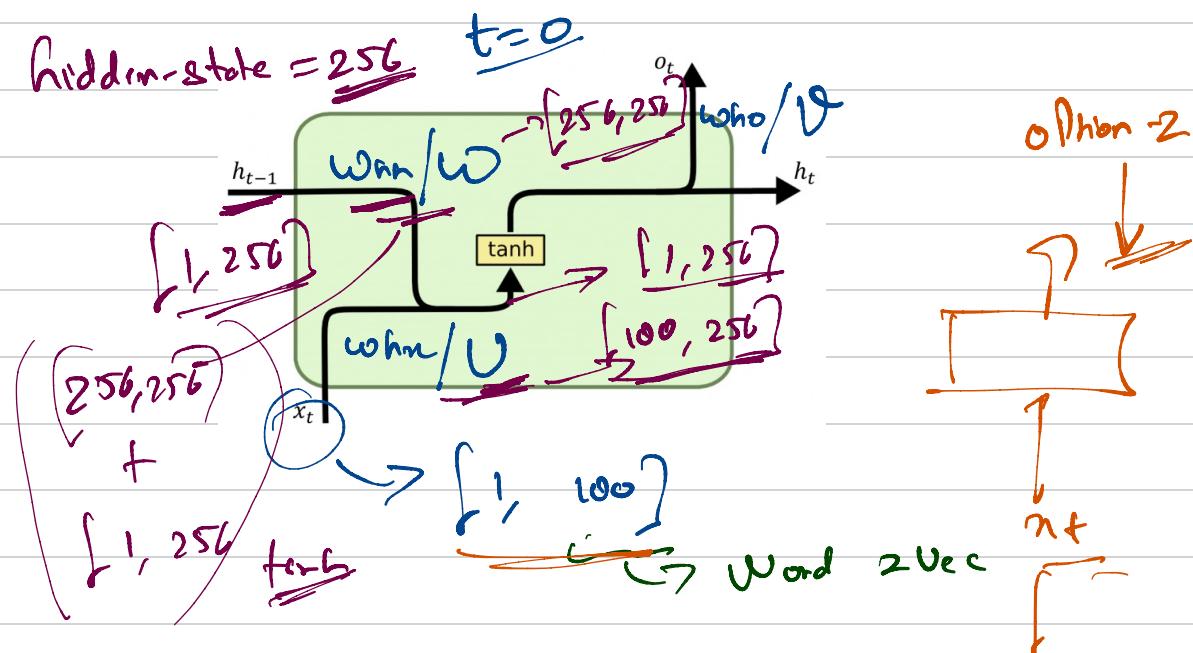
Time-series. E.g. Stock market time series

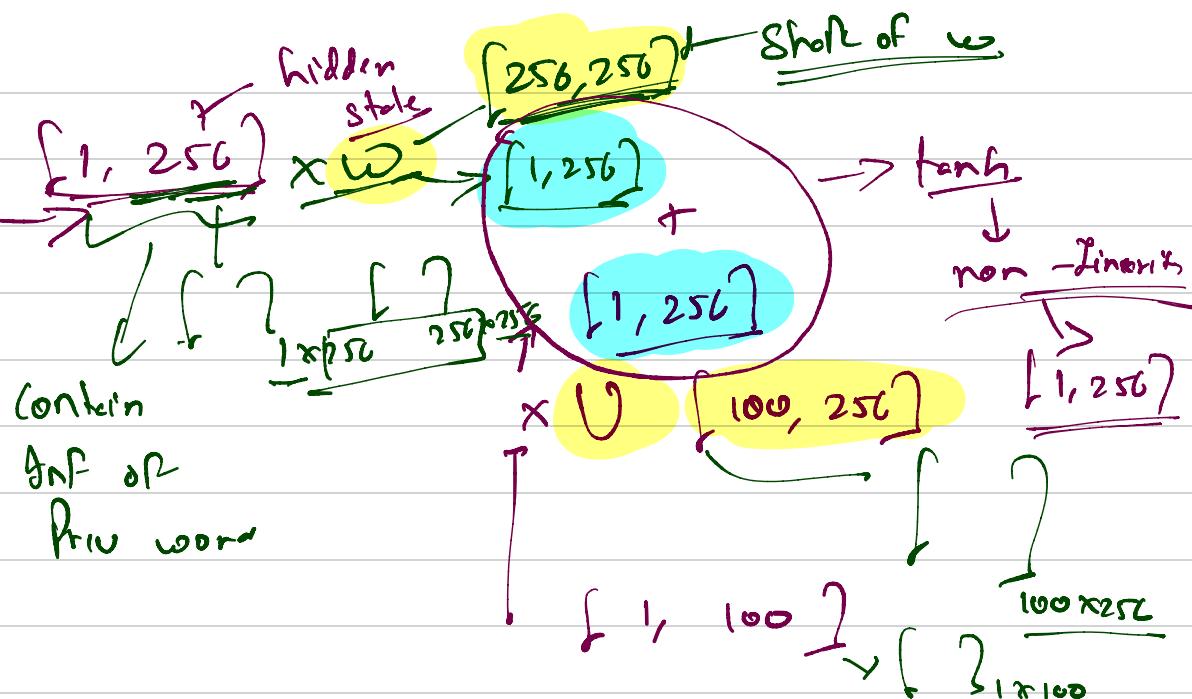
① Signal e.g. audio / speech

② Text / Video



→ How RNN works internally





S - close

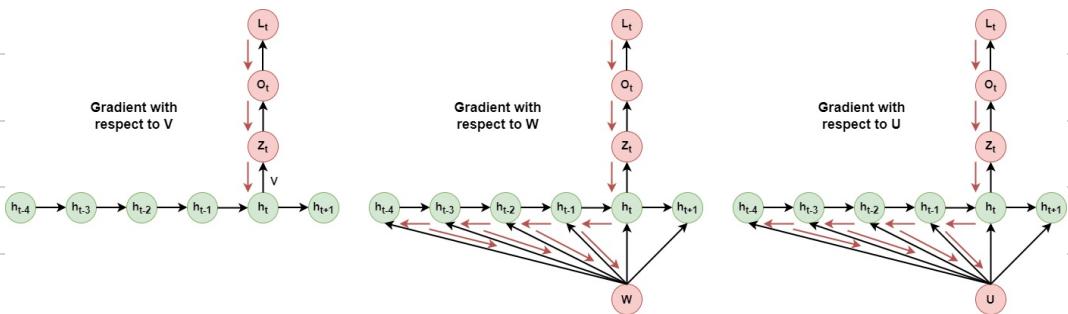
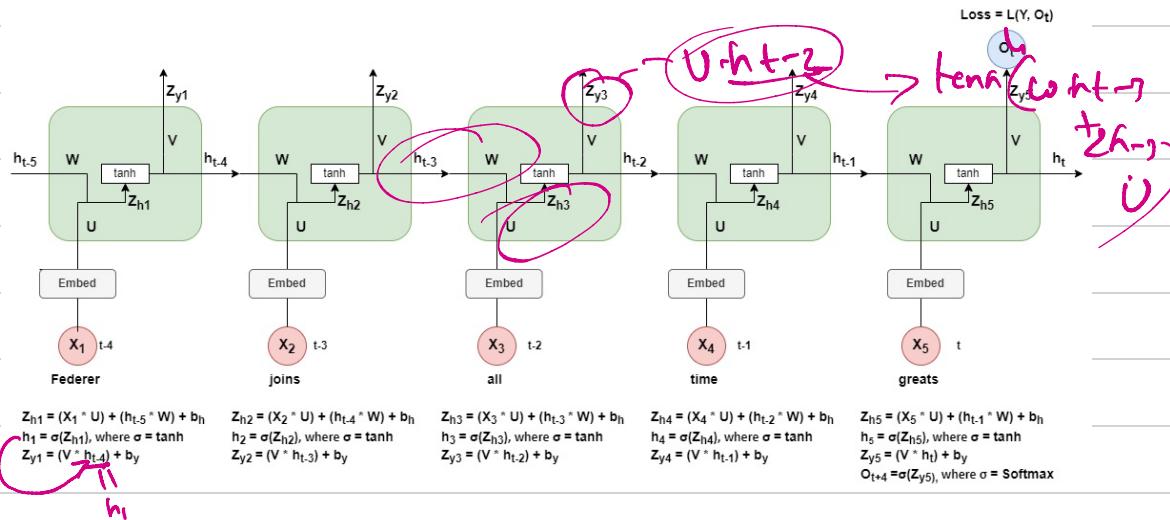


ht \propto Amount of information you want to share across timesteps

lose only w.r.t. last time

ht & how much model memorize

LET'S TRAIN RNN



forget t

$$\frac{\partial \mathbf{h}_t}{\partial \mathbf{W}} = \frac{\partial \mathbf{h}_t}{\partial \mathbf{W}} + \frac{\partial \mathbf{h}_t}{\partial \mathbf{h}_{t-1}} * \boxed{\frac{\partial \mathbf{h}_{t-1}}{\partial \mathbf{W}}}$$

$$\frac{\partial \mathbf{h}_{t-1}}{\partial \mathbf{W}} = \frac{\partial \mathbf{h}_{t-1}}{\partial \mathbf{W}} + \boxed{\frac{\partial \mathbf{h}_{t-1}}{\partial \mathbf{h}_{t-2}} * \boxed{\frac{\partial \mathbf{h}_{t-2}}{\partial \mathbf{W}}}}$$

$$\frac{\partial \mathbf{h}_{t-2}}{\partial \mathbf{W}} = \frac{\partial \mathbf{h}_{t-2}}{\partial \mathbf{W}} + \frac{\partial \mathbf{h}_{t-2}}{\partial \mathbf{h}_{t-3}} * \boxed{\frac{\partial \mathbf{h}_{t-3}}{\partial \mathbf{W}}}$$

$$\frac{\partial \mathbf{h}_{t-3}}{\partial \mathbf{W}} = \frac{\partial \mathbf{h}_{t-3}}{\partial \mathbf{W}} + \frac{\partial \mathbf{h}_{t-3}}{\partial \mathbf{h}_{t-4}} * \frac{\partial \mathbf{h}_{t-4}}{\partial \mathbf{W}}$$

$$\frac{\partial \mathbf{h}_{t-4}}{\partial \mathbf{W}} = \frac{\partial \mathbf{h}_{t-4}}{\partial \mathbf{W}} + \frac{\partial \mathbf{h}_{t-4}}{\partial \mathbf{h}_{t-5}} * \frac{\partial \mathbf{h}_{t-5}}{\partial \mathbf{W}}$$

... ...

$$\frac{\partial \mathbf{h}_{t-5}}{\partial \mathbf{W}} =$$

$$\frac{\partial L}{\partial \mathbf{w}} = \frac{\partial L}{\partial \mathbf{h}_t} \frac{\partial \mathbf{h}_t}{\partial \mathbf{w}} + \frac{\partial L}{\partial \mathbf{h}_{t-1}}$$

$$\frac{\partial L}{\partial \mathbf{w}} \times \frac{\partial \mathbf{h}_t}{\partial \mathbf{w}}$$

$$\frac{\partial L}{\partial \mathbf{w}} \times \frac{\partial \mathbf{h}_{t-1}}{\partial \mathbf{w}}$$

$$\frac{\partial L}{\partial \mathbf{w}} = \frac{\partial L}{\partial \mathbf{h}_t} \times \frac{\partial \mathbf{h}_t}{\partial \mathbf{w}} + \frac{\partial L}{\partial \mathbf{h}_{t-1}} \times \frac{\partial \mathbf{h}_{t-1}}{\partial \mathbf{w}}$$

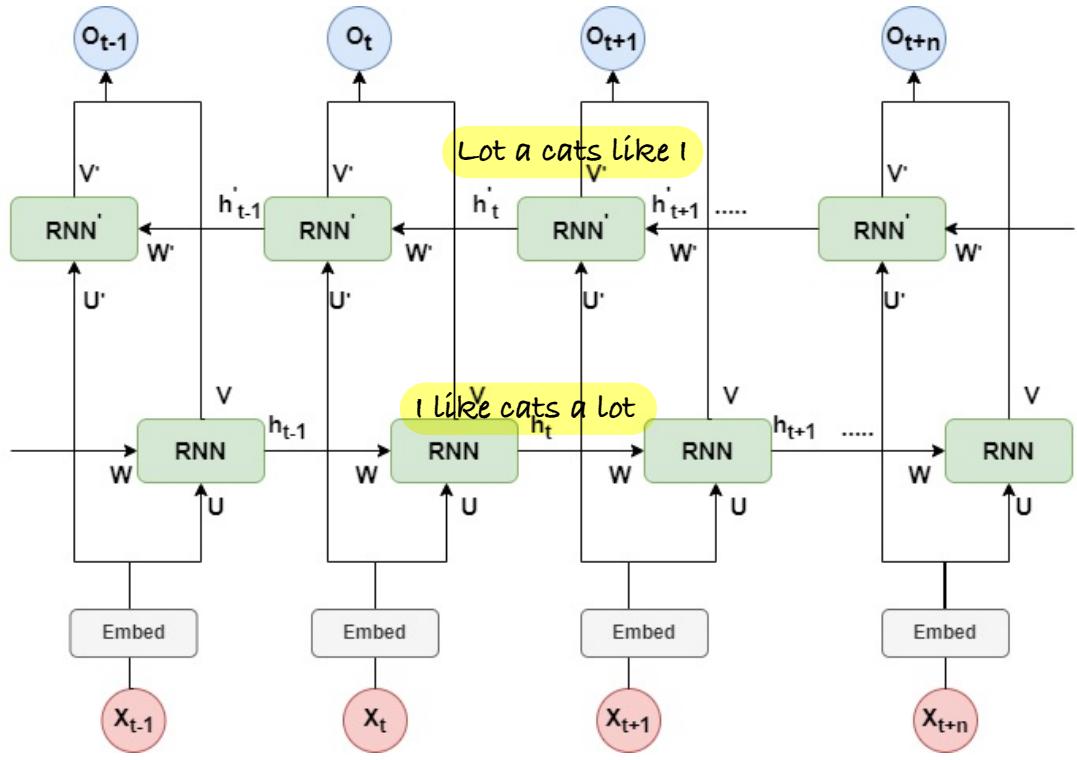
$$\frac{\partial L}{\partial h_{t+5}} \times \frac{\partial h_{t+5}}{\partial w}$$

$P \rightarrow \underline{2G_1} -- f_K$

Back-Propagation through time



Before I went to bed, I turned off the ___, it was very loud and I
Needed to fall asleep.



Bidirectional RNN processes sequences in both forward and backward directions.

$$z = \begin{bmatrix} 0.1 & 0.2 & 0.3 \end{bmatrix}$$

$$\text{softmax} =$$

$$\begin{bmatrix} 0.1 \\ 0.2 \\ 0.3 \end{bmatrix}$$

$$\frac{e^{0.1}}{e^{0.1} + e^{0.2} + e^{0.3}} / \frac{e^{0.2}}{e^{0.1} + e^{0.2} + e^{0.3}} / \frac{e^{0.3}}{e^{0.1} + e^{0.2} + e^{0.3}}$$

$$h_t \rightarrow (\omega \times h_{t-1} + U_{m-}) \cdot 1 + e^{-2}$$

$$h_{t-1} \quad \{ \quad \omega \times h_{t-2} + \dots$$

$$h_{t-2} \quad \{ \quad \omega \times h_{t-3} \dots$$

$\frac{\partial}{\partial \omega}$

$$\frac{\partial L}{\partial \omega} =$$

Last
time step

$$\frac{\partial L}{\partial \omega} \times \frac{\partial h_t}{\partial \omega} + \frac{\partial L}{\partial \omega} \times \frac{\partial h_{t-1}}{\partial \omega} + \frac{\partial L}{\partial \omega} \times \frac{\partial h_{t-2}}{\partial \omega}$$

$$\frac{\partial h_t}{\partial \omega} = \frac{\partial h_t}{\partial W} + \frac{\partial h_t}{\partial h_{t-1}} * \frac{\partial h_{t-1}}{\partial \omega}$$

$$\frac{\partial h_{t-1}}{\partial \omega} = \frac{\partial h_{t-1}}{\partial W} + \frac{\partial h_{t-1}}{\partial h_{t-2}} * \frac{\partial h_{t-2}}{\partial \omega}$$

$$\frac{\partial h_{t-2}}{\partial \omega} = \frac{\partial h_{t-2}}{\partial W} + \frac{\partial h_{t-2}}{\partial h_{t-3}} * \frac{\partial h_{t-3}}{\partial \omega}$$

$$\frac{\partial h_{t-3}}{\partial \omega} = \frac{\partial h_{t-3}}{\partial W} + \frac{\partial h_{t-3}}{\partial h_{t-4}} * \frac{\partial h_{t-4}}{\partial \omega}$$

$$\frac{\partial h_{t-4}}{\partial \omega} = \frac{\partial h_{t-4}}{\partial W} + \frac{\partial h_{t-4}}{\partial h_{t-5}} * \frac{\partial h_{t-5}}{\partial \omega}$$

$$\frac{\partial L}{\partial \omega} \times \frac{\partial h_t}{\partial \omega} \times \frac{\partial h_{t-1}}{\partial \omega}$$

U

Since all together