

Gaussian Mixture Model (GMM) - standard construction

A linear superposition of K-Gaussians

 μ_k : mean

 σ_k : covariance

$$p(\mathbf{x}_i) = \sum_{k=1}^{K} \underbrace{\pi_k}_{p(k)} \underbrace{\mathcal{N}(\mathbf{x}_i | \mu_k, \sigma_k)}_{p(\mathbf{x}_i | k)}, i = 1, ..., N$$

is called a **Gaussian mixture (GM)**. The mixture coefficient π_k satisfies

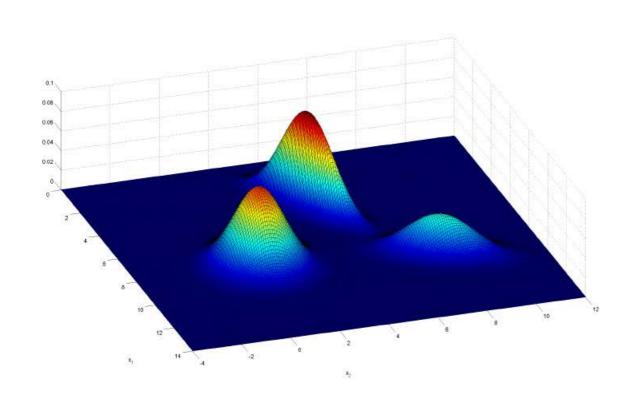
$$\sum_{k=1}^{K} \pi_k = 1, \qquad 0 \le \pi_k \le 1$$

Interpretation: The density $p(\mathbf{x}|k) = \mathcal{N}(\mathbf{x}|\mu_k, \sigma_k)$ is the probability of \mathbf{x} , given that component k was chosen. The probability of choosing component k is given by the prior probability p(k).



For example, consider the following GMM:

$$p(x) = \underbrace{0.3}_{\pi_1} \mathcal{N}\left(x \mid \underbrace{\begin{pmatrix} 4 \\ 4.5 \end{pmatrix}}_{\mu_1}, \underbrace{\begin{pmatrix} 1.2 & 0.6 \\ 0.6 & 0.5 \end{pmatrix}}_{\Sigma_1}\right) + \underbrace{0.5}_{\pi_2} \mathcal{N}\left(x \mid \underbrace{\begin{pmatrix} 8 \\ 1 \end{pmatrix}}_{\mu_2}, \underbrace{\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}}_{\Sigma_2}\right) + \underbrace{0.2}_{\pi_3} \mathcal{N}\left(x \mid \underbrace{\begin{pmatrix} 9 \\ 8 \end{pmatrix}}_{\mu_3}, \underbrace{\begin{pmatrix} 0.6 & 0.5 \\ 0.5 & 1.5 \end{pmatrix}}_{\Sigma_3}\right)$$



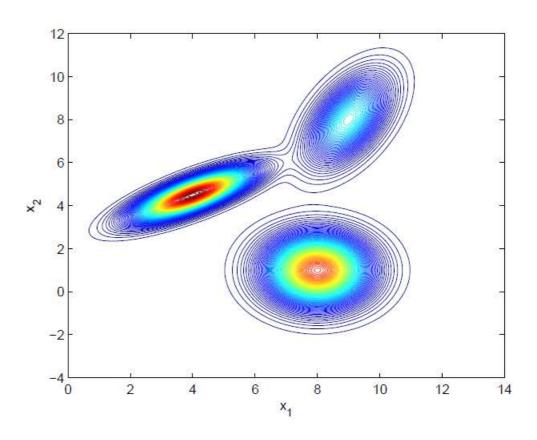


Figure: Probability density function.

Figure: Contour plot.



The form of the GM distribution is governed by the parameters π , μ and σ . One way to get them is by **maximum likelihood**.

Given N observations $\{x_n\}_{n=1}^N$, the log-likelihood function is

$$\ln p(X; \pi_{1:K}, \mu_{1:K}, \sigma_{1:K}) = \sum_{n=1}^{N} \ln \left(\sum_{k=1}^{K} \pi_k \mathcal{N}(\mathbf{x}_n | \mu_k, \sigma_k) \right)$$

There is **no closed-form solution** available (due to the sum inside the logarithm).

This problem can be separated into two simple problems using the *expectation-maximization (EM)* algorithm.



Conditions to be satisfied at a maximum of the likelihood function

$$\frac{\mathrm{d}}{\mathrm{d}\mu_k} \left[\ln p(\mathbf{x}|\pi, \mu, \sigma) \right] = 0 \quad \to \quad 0 = -\sum_{n=1}^N \underbrace{\frac{\pi_k \mathcal{N}(\mathbf{x}_n | \mu_k, \sigma_k)}{\sum_j \pi_j \mathcal{N}(\mathbf{x}_n | \mu_j, \sigma_j)}}_{\gamma(z_{nk})} \sigma_k(\mathbf{x}_n - \mu_k)$$

which gives
$$\rightarrow \mu_k = \frac{1}{N_k} \sum_{n=1}^N \gamma(z_{nk}) \mathbf{x}_n$$

$$\frac{\mathrm{d}}{\mathrm{d}\sigma_k} \left[\ln p(\mathbf{x}|\pi, \mu, \sigma) \right] = 0 \quad \to \quad \sigma_k = \frac{1}{N_k} \sum_{n=1}^N \gamma(z_{nk}) \left(\mathbf{x}_n - \mu_k \right) \left(\mathbf{x}_n - \mu_k \right)^T$$

Maximize $\ln p(\mathbf{x}|\pi,\mu,\sigma)$ with respect to π_k (using Lagrange multipliers) gives

$$\pi_k = \frac{N_k}{N}$$
, where $N_k = \sum_{n=1}^N \gamma(z_{nk})$

Algorithm 1 EM for Gaussian mixtures

- 1: Initialize $\mu_k^1, \sigma_k^1, \pi_k^1$ and set i = 1.
- 2: while not converged do
- 3: Compute $\gamma(z_{nk})$. \triangleright Expectation step 4: Compute $\mu_k^{i+1}; \pi_k^{i+1}; N_k; \sigma_k^{i+1}$. \triangleright Maximization step
- 5: $i \leftarrow i + 1$.
- 6: end while

$$\gamma(z_{nk}) = \frac{\pi_k^i \mathcal{N}(\mathbf{x}_n | \mu_k^i, \sigma_k^i)}{\sum_{j=1}^K \pi_j^i \mathcal{N}(\mathbf{x}_n | \mu_j^i, \sigma_j^i)}, n = 1, ..., N; k = 1, ..., K$$

$$\mu_k^{i+1} = \frac{1}{N_k} \sum_{n=1}^{N} \gamma(z_{nk}) \mathbf{x}_n,$$

$$\pi_k^{i+1} = \frac{N_k}{N}, \quad N_k = \sum_{n=1}^N \gamma(z_{nk}),$$

$$\sigma_k^{i+1} = \frac{1}{N_k} \sum_{n=1}^{N} \gamma(z_{nk}) \left(\mathbf{x}_n - \mu_k^{i+1} \right) \left(\mathbf{x}_n - \mu_k^{i+1} \right)^T.$$