

Manifolds: (there are) or (there exist)

Topological space: \exists so many that mathematicians cannot even classify them

For space-time physics, we may focus on topological spaces (M, \mathcal{O}) that can be charted, analogously to how the surface of the Earth is charted in an atlas.

1. Topological manifolds

Def. A top. space (M, \mathcal{O}) is called a d -dimensional topological manifold if

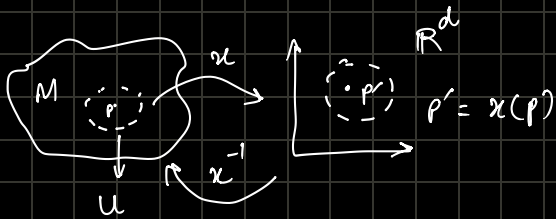
$$\forall p \in M: \exists \underset{\substack{U \\ p}}{U} \in \mathcal{O}: \exists \chi: U \rightarrow \chi(U) \subseteq \mathbb{R}^d$$

such that (i) χ is invertible

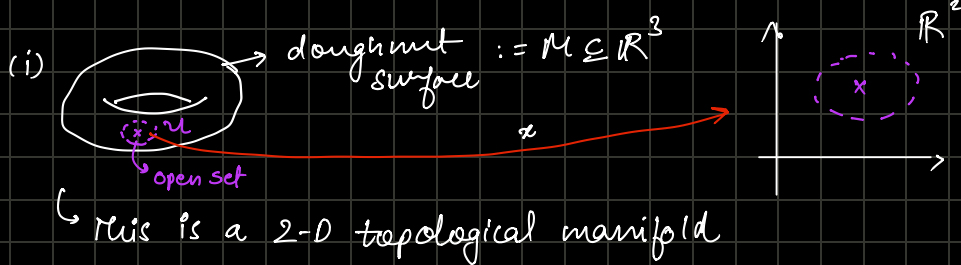
$$\chi^{-1}: \chi(U) \rightarrow U$$

(ii) χ is continuous

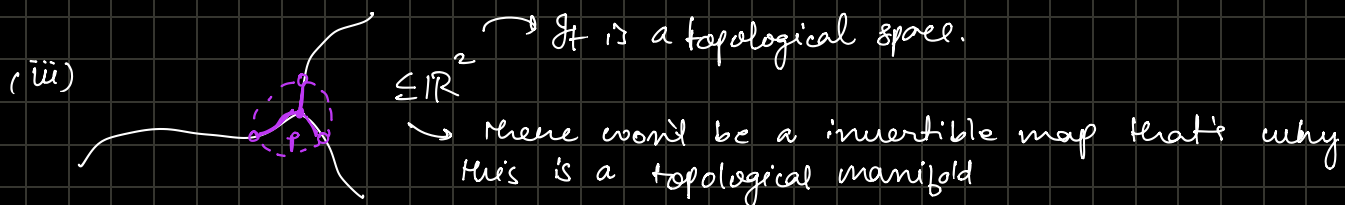
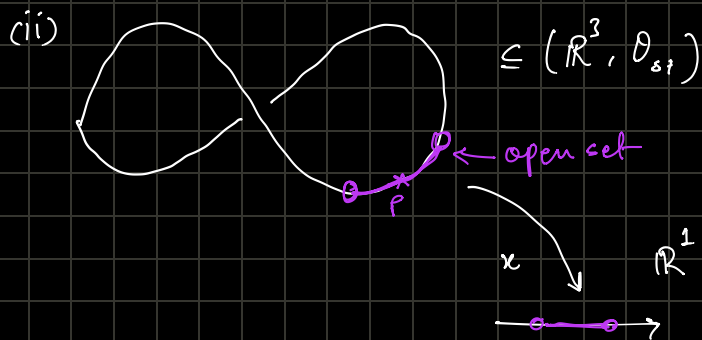
(iii) χ^{-1} is continuous



Examples:



Terminology: (U, χ) called a chart of (M, \mathcal{O})



Terminology: $\mathcal{A} = \{ (U_\alpha, x_\alpha) \mid \alpha \in A \}$ an atlas of (M, θ) if $M = \bigcup_{\alpha \in A} U_\alpha$

$x: U \rightarrow x(U) \subseteq \mathbb{R}^d = \mathbb{R} \times \mathbb{R} \times \dots \times \mathbb{R}$ (d numbers in order)

↪ chart map $\therefore x(p) = (x^1(p), \dots, x^d(p))$

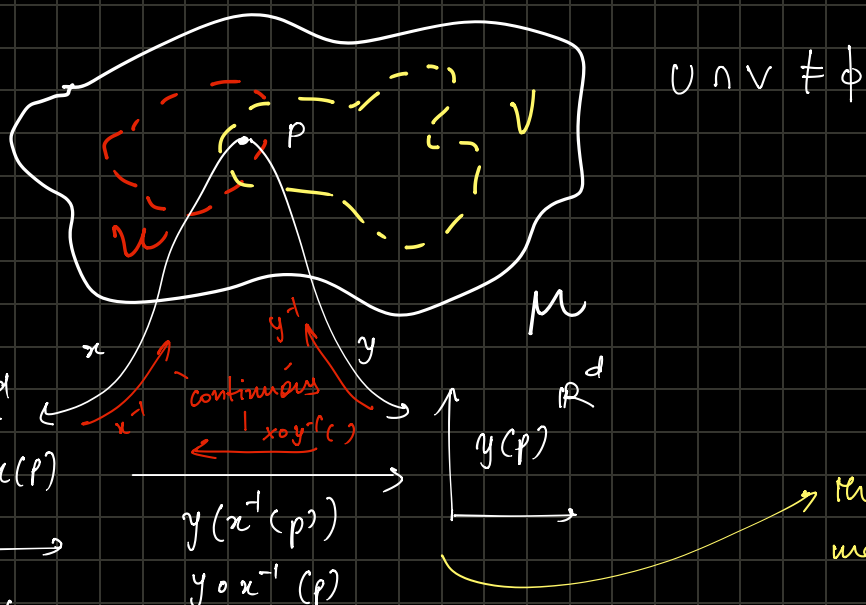
$\therefore x^i: U \rightarrow \mathbb{R}$ (mapping each point) = Component maps or the coordinate maps.

• $p \in U$ then $x^1(p)$ is the first coordinate of point p w.r.t to chosen chart (U, x)

$x^2(p)$ is the 2nd coordinate of p .

3. Chart transition maps

Imagine two charts with overlapping regions

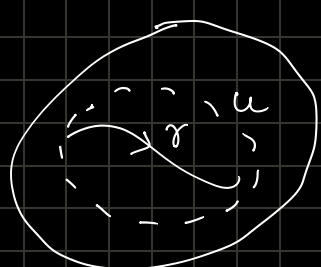


↪ this is called the chart transition map.

↳ Obviously we can do that for the full chart $U \neq V$.

4. Manifold Philosophy:

Often it is desired to define perspectives of real world object by judging suitable coordinates not on the real world object but on the chart representation of that object -



$$\mathbb{R} \xrightarrow{f} U \xrightarrow{x} x(U) \subseteq \mathbb{R}^d$$

$x \circ f$

But it may be ill defined, so we need to make sure that properties don't change if we change the chart