

Fundamental Analysis and Algebra

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Lecture 1: Introduction to Isometries

Thu 12 sep 2023 01:59

1 Geometry

Definition 1. Felix Klien's geometry is a set S , called a space on which a group G operates. The study of properties invariant under the operations of G is called geometry.

1.1 Geometries v. Groups

| Space | Tranf. grps | Geometry | Invariants | Linear groups |
|------------------|-------------------|----------------|--------------|--------------------------------|
| \mathbb{R}^n | isometries | euclidean g | distance | $O_n\mathbb{R}$ |
| \mathbb{R}^n | similarities | Similaritiy g. | angle | $\mathbb{R}_{>0}O_n\mathbb{R}$ |
| \mathbb{R}^n | collineations | affine g. | parallelism | $GL_n(\mathbb{R})$ |
| $\mathbb{R}^n P$ | projective transf | Projective g. | collinearity | $PGL_{n+1}(\mathbb{R})$ |

and many more... but these are the only ones we will talk about.

Definition 2. A transformation on \mathbb{R}^n is a bijection from \mathbb{R}^n to \mathbb{R}^n . We will denote by $\mathcal{B}(\mathbb{R}^n)$ the set of all transformations on \mathbb{R}^n .

Definition 3. A transformation on the euclidean plane is called a plane transformation.

- A linear isomorphism is a transformation but a linear map may not.
- The identity map $1 : \mathbb{R}^n \rightarrow \mathbb{R}^n$ is a transformation.
- Fix \mathbf{a} . The map $T_{\mathbf{b}} : \mathbb{R}^n \rightarrow \mathbb{R}^n$, is called a translation. and a translation is a transformation. A more geometric way to view a transformation is as follows: The map takes a point P to the point P' such that the vector $\overrightarrow{PP'} = \mathbf{b}$. We denote a translation that takes $P \rightarrow P'$ by $\tau_{PP'} := T_{\mathbf{b}}$

Notation. The map

$$T_{A\mathbf{b}} : \mathbb{R}^n \rightarrow \mathbb{R}^n, \mathbf{v} \mapsto A\mathbf{x} + \mathbf{b}.$$

Lecture 2

Thu 12 sep 2023 19:44