

# Module 10: CS31003: Compilers

## Simple Code Generators

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# Module Objectives

## Module 10

Das

Objectives &  
Outline

Issues in Code  
Generation

Scheme A

Bubble Sort

Scheme B

Optimal Algorithm

Peephole

Optimizations

- Code Generation – Main Issues
- Samples of Generated Code
- Two Simple Code Generators
- Optimal Code Generation
  - Sethi-Ullman Algorithm
- Peephole Optimization

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Optimizations

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- 2 Issues in Code Generation
- 3 Scheme A
  - Bubble Sort
- 4 Scheme B
  - Optimal Algorithm
- 5 Peephole Optimizations

# Code Generation – Main Issues (1)

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Optimizations

- Transformation
  - Intermediate code  $\rightarrow$  m/c code (binary or assembly)
  - We assume that quads, CFG and ST are available
- Which instructions to generate?
  - For the quadruple  $A = A+1$ , we may generate:  
`Inc A`  
or  
`Load A, R1`  
`Add #1, R1`  
`Store R1, A`
  - One sequence is faster than the other
    - ▷ Cost implication

# Code Generation – Main Issues (2)

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Optimizations

- In which order?
  - Some orders may use fewer registers and/or may be faster
- Which registers to use?
  - Optimal assignment of registers to variables is difficult to achieve
- Optimize for memory, time or power?
- Is the code generator easily re-target-able to other machines?
  - Can the code generator be produced automatically from specifications of the machine?

# Samples of Generated Code

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Optimizations

- **B = A[i]**

```
Load  i, R1 // R1 = i
Mult  R1, 4, R1 // R1 = R1 * 4
// each element of array
// A is 4 bytes long
Load  A(R1), R2 // R2 = (A + R1)
Store R2, B // B = R2
```

- **X[j] = Y**

```
Load  Y, R1 // R1 = Y
Load  j, R2 // R2 = j
Mult  R2, 4, R2 // R2 = R2 * 4
Store R1, X(R2) // (X + R2) = R1
```

- **X = \*p**

```
Load  p, R1
Load  0(R1), R2 // R2 = (0 + R1)
Store R2, X
```

- **\*q = Y**

```
Load  Y, R1
Load  q, R2
Store R1, 0(R2) // (0 + R2) = R1
```

- **if X < Y goto L**

```
Load  X, R1
Load  Y, R2
Cmp   R1, R2
Bltz  L // Branch on less than 0
```

# A Simple Code Generator: Scheme A

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Optimizations

- Treat each quadruple as a *macro*
  - Example: The quad  $A := B + C$  will result in:  
Load B, R1    OR    Load B, R1  
Load C, R2  
Add R2, R1        Add C, R1  
Store R1, A        Store R1, A
  - Results in inefficient code
    - ▷ Repeated load/store of registers
  - Very simple to implement

# Sample Code Generation: Bubble Sort

## Three Address Code

- Three Address Code for Bubble Sort as generated by syntax directed translation

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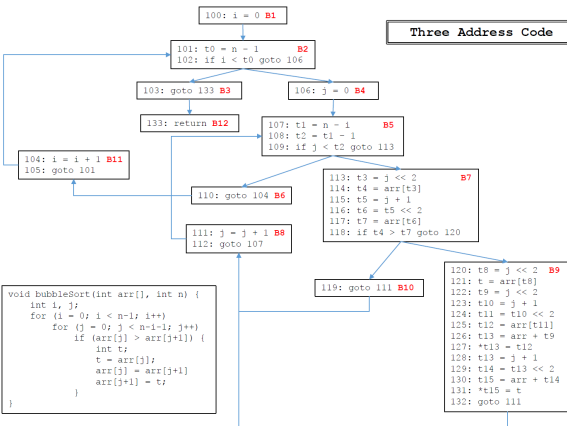
Optimal Algorithm

Peephole

Optimizations

```

100*: i = 0
101*: t0 = n - 1
102: if i < t0 goto 106
103*: goto 133
104*: i = i + 1
105: goto 101
106*: j = 0
107*: t1 = n - i
108: t2 = t1 - 1
109: if j < t2 goto 113
110*: goto 104
111*: j = j + 1
112: goto 107
113*: t3 = j << 2
114: t4 = arr[t3]
115: t5 = j + 1
116: t6 = t5 << 2
117: t7 = arr[t6]
118: if t4 > t7 goto 120
119*: goto 111
120*: t8 = j << 2
121: t = arr[t8]
122: t9 = j << 2
123: t10 = j + 1
124: t11 = t10 << 2
125: t12 = arr[t11]
126: t13 = arr + t9
127: *t13 = t12
128: t13 = j + 1
129: t14 = t13 << 2
130: t15 = arr + t14
131: *t15 = t
132: goto 111
133*: return
    
```

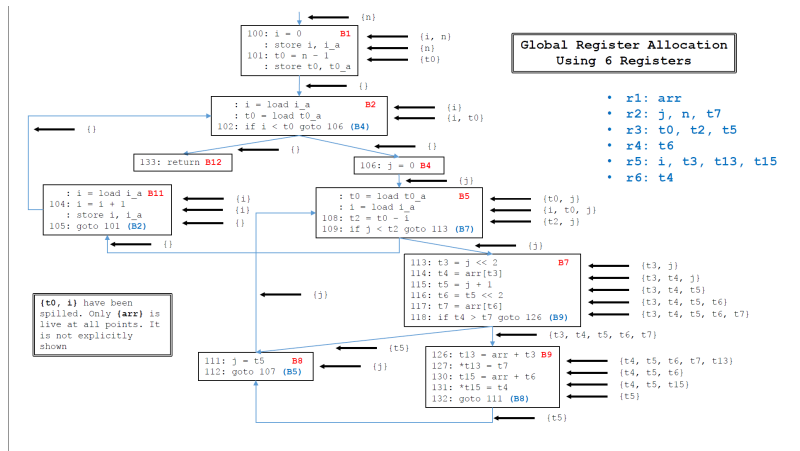




# Sample Code Generation: Bubble Sort

## Liveness after LCSE, GCSE Optimization

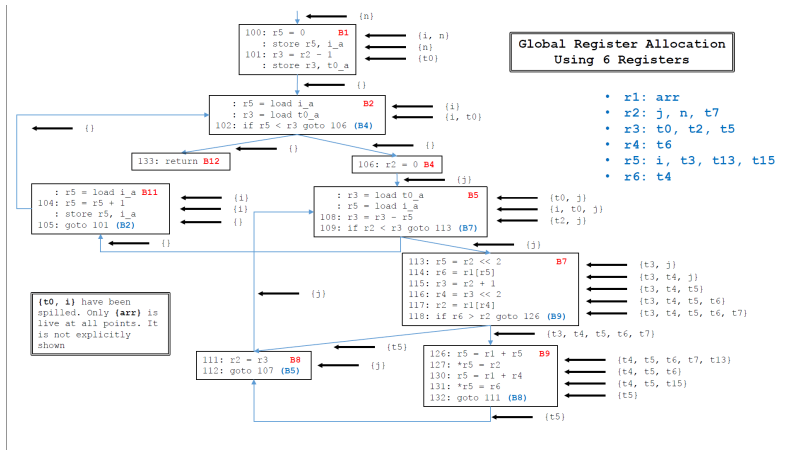
- Three Address Code Optimized by peephole, LCSE by VN and GCSE by DFA. Finally, live variables are computed by DFA



# Sample Code Generation: Bubble Sort

## Global Register Allocation

- Registers are allocated globally using graph coloring based on the liveness information
- Variables are replaced by respective registers



# Sample Code Generation: Bubble Sort

## Linearized and Optimized Target Code

- The CFG is linearized and further optimized to get the final target code

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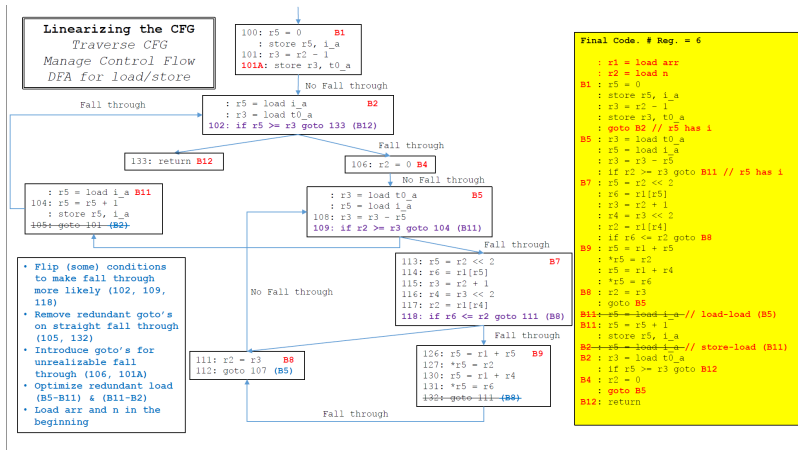
Scheme A

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# A Simple Code Generator: Scheme B

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Optimizations

- Track values in registers and reuse them
  - If any operand is already in a register, take advantage of it
  - Register Descriptors
    - ▷ Tracks **<register, variable name>** pairs
    - ▷ A single register can contain values of multiple names, if they are all copies
  - Address Descriptors
    - ▷ Tracks **<variable name, location>** pairs
    - ▷ A single name may have its value in multiple locations, such as, memory, register, and stack



# A Simple Code Generator: Scheme B

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Optimizations

- Leave computed result in a register as long as possible
- Store only at the end of a basic block or when that register is needed for another computation
  - On exit from a basic block, store only **live variables** which are not in their memory locations already (use address descriptors to determine the latter)
  - If liveness information is not known, assume that all variables are live at all times

# Example

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Optimizations

$A := B + C$

- If B and C are in registers R1 and R2, then generate
  - `ADD R2, R1` (cost = 1, result in R1)
    - ▷ legal only if B is not live after the statement
- If R1 contains B, but C is in memory
  - `ADD C, R1` (cost = 2, result in R1)
    - or
  - `LOAD C, R2`  
`ADD R2, R1` (cost = 3, result in R1)
    - ▷ legal only if B is not live after the statement
    - ▷ attractive if the value of C is subsequently used (it can be taken from R2)

# Next Use Information

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Optimizations

- Next use info is used in code generation and register allocation
- Next use of **A** in quad **i** is **j** if  
Quad **i** : **A** = ... (assignment to **A**)  
     $\Downarrow$  (control flows from **i** to **j** with no assignments to **A**)  
Quad **j** : = **A op B** (usage of **A**)
- In computing next use, we assume that on exit from the basic block
  - All temporaries are considered non-live
  - All programmer defined variables (and non-temps) are live
- Each procedure/function call is assumed to start a basic block
- Next use is computed on a backward scan on the quads in a basic block, starting from the end
- Next use information is stored in the symbol table

# Example of computing Next Use

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Optimizations

3	$T1 := 4 * I$	$T1: (nlv, lu\ 0, nu\ 5), I: (lv, lu\ 3, nu\ 10)$
4	$T2 := \text{addr}(A) - 4$	$T2: (nlv, lu\ 0, nu\ 5), A: (lv, lu\ 4, nnu)$
5	$T3 := T2[T1]$	$T3: (nlv, lu\ 0, nu\ 8), T2: (nlv, lu\ 5, nnu),$ $T1: (nlv, lu\ 5, nu\ 7)$
6	$T4 := \text{addr}(B) - 4$	$T4: (nlv, lu\ 0, nu\ 7), B: (lv, lu\ 6, nnu)$
7	$T5 := T4[T1]$	$T5: (nlv, lu\ 0, nu\ 8), T4: (nlv, lu\ 7, nnu),$ $T1: (nlv, lu\ 7, nnu)$
8	$T6 := T3 * T5$	$T6: (nlv, lu\ 0, nu\ 9), T3: (nlv, lu\ 8, nnu),$ $T5: (nlv, lu\ 8, nnu)$
9	$PROD := PROD + T6$	$PROD: (lv, lu\ 9, nnu), T6: (nlv, lu\ 9, nnu)$
10	$I := I + 1$	$I: (lv, lu\ 10, nu\ 11)$
11	if $I = 20$ goto 3	$I: (lv, lu\ 11, nnu)$

nlv: not live lv: live lu: last use nu: next use nnu: no next use lu 0: no last use



# Scheme B – Algorithm

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Optimizations

- We deal with one basic block at a time
- We assume that there is no global register allocation
- For each quad  $A := B \text{ op } C$  do the following
  - Find a location  $L$  to perform  $B \text{ op } C$ 
    - ▷ Usually a register returned by  $\text{GETREG}()$  (could be a mem loc)
  - Where is  $B$ ?
    - ▷  $B'$ , found using address descriptor for  $B$
    - ▷ Prefer register for  $B'$ , if it is available in memory and register
    - ▷ Generate  $\text{Load } B', L$  (if  $B'$  is not in  $L$ )
  - Where is  $C$ ?
    - ▷  $C'$ , found using address descriptor for  $C$
    - ▷ Generate  $\text{op } C', L$
  - Update descriptors for  $L$  and  $A$
  - If  $B/C$  have no next uses, update descriptors to reflect this information

# Function *GETREG()*

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Finds L for computing  $A := B \text{ op } C$

- [1] If B is in a register (say R), R holds no other names, and
  - B has no next use, and B is not live after the block, then return R
- [2] Failing (1), return an empty register, if available
- [3] Failing (2)
  - If A has a next use in the block, OR  
if B op C needs a register (e.g., op is an indexing operator)
    - Use a heuristic to find an occupied register R
      - a register whose contents are referenced farthest in future, or
      - the number of next uses is smallest etc.
    - Spill it by generating an instruction, *MOV R, mem*
      - mem is the memory location for the variable in R
      - That variable is not already in mem
    - Update Register and Address descriptors
- [4] If A is not used in the block, or no suitable register can be found
  - Return a memory location for L

# Example

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Optimizations

- T, U, and V are temporaries – not live at the end of the block
- W is a non-temporary – live at the end of the block, 2 registers
- Using two registers R0 and R1

Statements	Code Generated	Register Descriptor	Address Descriptor
T := A * B	Load A, R0 Mult B, R0	R0 contains T	T in R0
U := A + C	Load A, R1 Add C, R1	R0 contains T R1 contains U	T in R0 U in R1
V := T - U	Sub R1, R0	R0 contains V R1 contains U	U in R1 V in R0
W := V * U	Mult R1, R0	R0 contains W	W in R0
	Store R0, W		W in memory (restored)

# Optimal Code Generation: The Sethi-Ullman Algorithm

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Optimizations

- Generates the shortest sequence of instructions
  - Provably optimal algorithm (w.r.t. length of the sequence)
- Suitable for expression trees (basic block level)
- Machine model
  - All computations are carried out in registers
  - Instructions are of the form  $op\ R_s,\ R_t$  or  $op\ M_s,\ R_t$
- *Always computes the left subtree into a register and reuses it immediately*
- Two phases
  - Labelling phase
  - Code generation phase

# The Labelling Algorithm

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Optimizations

- Label each node of the tree with an integer:
  - Consider binary trees
  - Fewest no. of registers required to evaluate the tree with no intermediate stores to memory

- For leaf nodes
  - if  $n$  is the leftmost child of its parent then

$$\text{label}(n) := 1 \text{ else } \text{label}(n) := 0$$

- For internal nodes

$$\begin{aligned} \text{label}(n) &= \max(l_1, l_2), \text{ if } l_1 \neq l_2 \\ &= l_1 + 1, \text{ if } l_1 = l_2 \end{aligned}$$



# Labelling – Example

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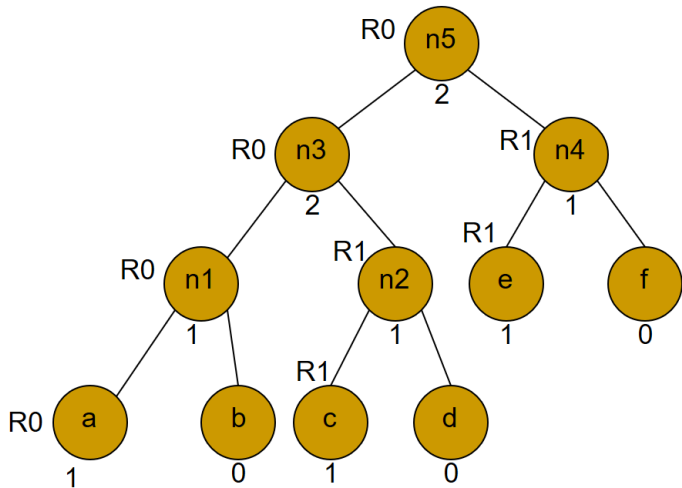
Bubble Sort

Scheme B

Optimal Algorithm

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Optimizations



# Code Generation Phase: Procedure GENCODE(n)

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Optimizations

- RSTACK – stack of registers,  $R0, \dots, R(r-1)$
- TSTACK – stack of temporaries,  $T0, T1, \dots$
- A call to Gencode(n) generates code to evaluate a tree  $T$ , rooted at node  $n$ , into the register  $\text{top}(\text{RSTACK})$ , and
  - the rest of RSTACK remains in the same state as the one before the call
- A swap of the top two registers of RSTACK is needed at some points in the algorithm to ensure that **a node is evaluated into the same register as its left child**

# The Code Generation Algorithm (Cases 0-1-2)

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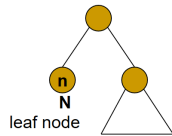
Optimal Algorithm

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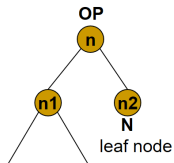
Optimizations

```

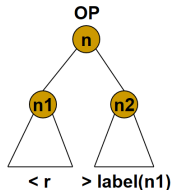
Procedure gencode(n);
{ /* case 0 */
  if
    n is a leaf representing operand N
    and is the leftmost child of its parent
  then
    print(Load N, top(RSTACK))
  /* case 1 */
  else if
    n is an interior node with operator
    OP, left child n1, and right child n2
  then
    if label(n2) == 0 then {
      let N be the operand for n2;
      gencode(n1);
      print(OP N, top(RSTACK));
    }
  /* case 2 */
  else if ((1 <= label(n1) < label(n2))
    and (label(n1) < r))
  then {
    swap(RSTACK); gencode(n2);
    R := pop(RSTACK); gencode(n1);
    /* R holds the result of n2 */
    print(OP R, top(RSTACK));
    push (RSTACK, R);
    swap(RSTACK);
    /* The swap() function ensures that a
    node is evaluated into the same
    register as its left child */
  }
}
  
```



Case 0



Case 1



Case 2



# The Code Generation Algorithm (Cases 3-4)

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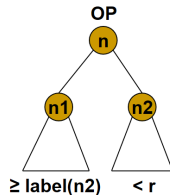
Optimal Algorithm

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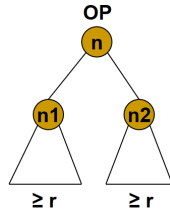
Optimizations

```

/* case 3 */
else if ((l1 <= label(n2) <= label(n1))
        and (label(n2) < r))
then {
    gencode(n1);
    R := pop(RSTACK); gencode(n2);
    /* R holds the result of n1 */
    print(OP top(RSTACK), R);
    push (RSTACK,R);
}
/* case 4, both labels are > r */
else {
    gencode(n2); T:= pop(TSTACK);
    print(LOAD top(RSTACK), T);
    gencode(n1);
    print(OP T, top(RSTACK));
    push(TSTACK, T);
}
}
    
```



Case 3



Case 4

# Code Generation Phase – Examples

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No. of registers =  $r = 2$

```

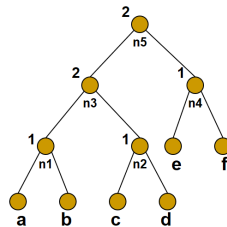
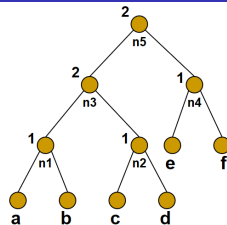
n5 -> n3 (case 3)
-> n1 -> a (case 3)
-> Load a, R0, op_n1 b, R0
-> n2 -> c      -> Load c, R1
                  -> op_n2 d, R1
                  -> op_n3 R1, R0
-> n4 -> e      -> Load e, R1
                  -> op_n4 f, R1
-> op_n5 R1, R0
  
```

No. of registers =  $r = 1$ .

Here we choose rst first so that lst can be computed into R0 later (case 4)

```

n5 -> n4 -> e -> Load e, R0
                  -> op_n4 f, R0
-> Load R0, T0 {release R0}
-> n3 -> n2 -> c      -> Load c, R0
                  -> op_n2 d, R0
                  -> Load R0, T1 {release R0}
                  -> n1 -> a      -> Load a, R0
                  -> op_n1 b, R0
                  -> op_n3 T1, R0 {release T1}
-> op_n5 T0, R0 {release T0}
  
```



# Peephole Optimizations

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Optimizations

- Simple but effective local optimization
- Usually carried out on machine code, but intermediate code can also benefit from it
- Examines a sliding window of code (peephole), and replaces it by a shorter or faster sequence, if possible
- Each improvement provides opportunities for additional improvements
- Therefore, repeated passes over code are needed



# Peephole Optimizations

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Optimizations

- Some well known peephole optimizations
  - eliminating redundant instructions
  - eliminating unreachable code
  - eliminating jumps over jumps
  - algebraic simplifications
  - strength reduction
  - use of machine idioms

# Elimination of Redundant Loads and Stores

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Optimizations

### Basic block B

Load X, R0  
{no modifications  
to X or R0 here}  
Store R0, X

Store instruction  
can be deleted

### Basic block B

Load X, R0  
{no modifications  
to X or R0 here}  
Load X, R0

Second Load instr  
can be deleted

### Basic block B

Store R0, X  
{no modifications  
to X or R0 here}  
Load X, R0

Load instruction  
can be deleted

### Basic block B

Store R0, X  
{no modifications  
to X or R0 here}  
Store R0, X

Second Store instr  
can be deleted

# Eliminating Unreachable Code

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Optimizations

- An unlabeled instruction immediately following an unconditional jump may be removed
  - May be produced due to debugging code introduced during development
  - Or due to updates to programs (changes for fixing bugs) without considering the whole program segment

# Eliminating Unreachable Code

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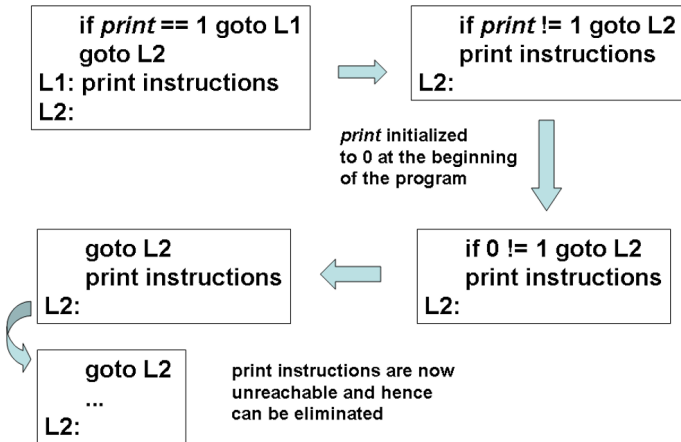
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# Flow-of-Control Optimizations

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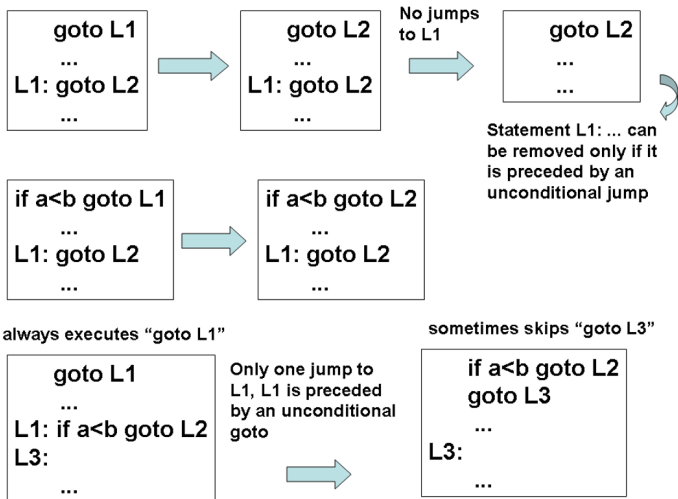
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# Reduction in Strength and Use of Machine Idioms

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Optimizations

- $x^2$  is cheaper to implement as  $x * x$ , than as a call to an exponentiation routine
- For integers,  $x * 2^3$  is cheaper to implement as  $x \ll 3$  ( $x$  left-shifted by 3 bits)
- For integers,  $x / 2^2$  is cheaper to implement as  $x \gg 2$  ( $x$  right-shifted by 2 bits)

# Reduction in Strength and Use of Machine Idioms

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Optimizations

- Floating point division by a constant can be approximated as multiplication by a constant
- Auto-increment and auto-decrement addressing modes can be used wherever possible
  - Subsume INCREMENT and DECREMENT operations (respectively)
- Multiply and add is a more complicated pattern to detect