

4 Build an Artificial Neural Network by implementing the Backpropagation algorithm and test the same using appropriate dataset.

```
from math import exp
from random import seed
from random import random
```

```
def initialize_networks (n-inputs, n-hidden, n-outputs):
    network = list()
    hidden_layer = [{'weights': [random() for i in range
                                   (n-inputs+1)]} for i in range(n-hidden)]
    network.append(hidden_layer)
    output_layer = [{'weights': [random() for i in range
                                   (n-hidden + 1)]} for i in range(n-outputs)]
    network.append(output_layer)
    return network
```

```
def activate(weights, inputs):
    activation = weights[-1]
    for i in range(len(weights)-1):
        activation += weight[i]*inputs[i]
    return activation
```

```
def transfer(activation):
    return 1.0 / (1.0 + exp(-activation))
```

```
def forward_propagate(network, now):  
    inputs = now  
    for layer in network:  
        new_inputs = []  
        for neuron in layer:  
            activation = activate(neuron['weights'], inputs)  
            neuron['outputs'] = transfer(activation)  
            new_inputs.append(neuron['outputs'])  
        inputs = new_inputs  
    return inputs.
```

```
def transfer_derivative(output):  
    return output * (1.0 - output)
```

```
def backward_propagate_error(network, expected):  
    for i in reversed(range(len(network))):  
        layer = network[i]  
        errors = list()  
        if i == len(network) - 1:  
            for j in range(len(layer)):  
                error = 0.0  
                for neuron in network[i+1]:  
                    error += (network['weights'][i][j] *  
                             neuron['delta'])  
                errors.append(error)  
        else:  
            for j in range(len(layer)):  
                neuron = layer[j]  
                errors.append(expected[j] - neuron['output'])
```



```
for j in range(len(layer)):
    neuron = layer[i]
    neuron['data'] = errors[j] * transfer-derivate
                                (neuron['output'])
```

```
def update_weights(network, row, l_rate):
    for i in range(len(network)):
        inputs = row[-1]
        if i != 0:
            inputs = [neuron['output'] for neuron in
                      network[i-1]]
        for neuron in network[i]:
            for j in range(len(inputs)):
                neuron['weights'][j] += l_rate *
                    neuron['delta'] * inputs[j]
            neuron['weights'][-1] += l_rate * neuron['delta']
```

```
def train_network(network, train, l_rate, n_epoch, n_outputs):
    for epoch in range(n_epoch):
        sum_error = 0
        for row in train:
            outputs = forward_propagate(network, row)
            expected = [0 for i in range(n_outputs)]
            expected[row[-1]] = 1
            sum_error += sum([(expected[i] - outputs[i])
                              ** 2 for i in range(len(expected))])
            back_propagate_error(network, expected)
        update_weights(network, row, l_rate)
```

```
print('> epoch = %d , rate = %.3f , error = %.3f
      % (epoch, rate, sum_error))
```

```
seed(1)
```

```
dataset = [
```

```
[2.7810836 , 2.550537003, 0],
```

```
[1.465489372 , 2.362125076, 0],
```

```
[3.396561688 , 4.400293529, 0],
```

```
[1.38807019 , 1.850220317, 0],
```

```
[3.06407232 , 3.005305973, 0],
```

```
[7.627531214 , 2.759262235, 0],
```

```
[5.332441248 , 2.088626775, 1],
```

```
[6.922596716 , 1.77106367, 1],
```

```
[8.675418651 , -0.242068655, 1],
```

```
[7.673756466 , 3.508563011, 1]]
```

```
n_inputs = len(dataset[0]) - 1
```

```
n_outputs = len(set([row[-1] for row in dataset]))
```

```
network = initialize_networks(n_inputs, 2, n_outputs)
```

```
train_network(network, dataset, 0.5, 20, n_outputs)
```

```
for layer in network:
```

```
    print(layer)
```


output :-

| | | |
|---------------|-------------------|---------------|
| >epoch = 0 , | lr rate = 0.500 , | error = 6.350 |
| >epoch = 1 , | lr rate = 0.500 , | error = 5.531 |
| >epoch = 2 , | lr rate = 0.500 , | error = 5.221 |
| >epoch = 3 , | lr rate = 0.500 , | error = 4.951 |
| >epoch = 4 , | lr rate = 0.500 , | error = 4.519 |
| >epoch = 5 , | lr rate = 0.500 , | error = 4.173 |
| >epoch = 6 , | lr rate = 0.500 , | error = 3.835 |
| >epoch = 7 , | lr rate = 0.500 , | error = 3.506 |
| >epoch = 8 , | lr rate = 0.500 , | error = 3.192 |
| >epoch = 9 , | lr rate = 0.500 , | error = 2.892 |
| >epoch = 10 , | lr rate = 0.500 , | error = 2.626 |
| >epoch = 11 , | lr rate = 0.500 , | error = 2.377 |
| >epoch = 12 , | lr rate = 0.500 , | error = 2.153 |
| >epoch = 13 , | lr rate = 0.500 , | error = 1.953 |
| >epoch = 14 , | lr rate = 0.500 , | error = 1.774 |
| >epoch = 15 , | lr rate = 0.500 , | error = 1.614 |
| >epoch = 16 , | lr rate = 0.500 , | error = 1.472 |
| >epoch = 17 , | lr rate = 0.500 , | error = 1.346 |
| >epoch = 18 , | lr rate = 0.500 , | error = 1.233 |
| >epoch = 19 , | lr rate = 0.500 , | error = 1.132 |

[{'weights': [-1.4688375095432327, 1.850887325439514, 1.80858178629550297], 'output': 0.02998030560442685, 'delta': -0.0059546604162323625}],

{'weights': [0.37711098142462157, -0.0625909894552989, 0.27651237026422716], 'outputs': 0.945622000211323, 'delta': 0.0026279652850863837}]

[{'weights': [2.515394649397849, -0.3391927502445985, -0.967456542639275], 'output': 0.23648794202357587, 'delta': -0.042700592783648587}, {'weights': [-2.5584149848484263, 1.0036422106209202, 0.42383086467582715], 'output': 0.7790535202438367, 'delta': 0.03803132596437354}]