W1

March 27, 2020

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Worksheet 1 Introduction to linear algebra by Prof J.Morlier February 2020 #import Base.print matrix #import Pkg: Pkg.add("SymPy")
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#import Base.print_matrix #import Pkg; Pkg.add("SymPy")
[157]: using LinearAlgebra, SparseArrays, SuiteSparse, Random
       using SymPy
       import Base.print_matrix
[156]: versioninfo()
      Julia Version 1.3.1
      Commit 2d5741174c (2019-12-30 21:36 UTC)
      Platform Info:
         OS: macOS (x86_64-apple-darwin18.6.0)
         CPU: Intel(R) Core(TM) i5-8259U CPU @ 2.30GHz
         WORD_SIZE: 64
         LIBM: libopenlibm
         LLVM: libLLVM-6.0.1 (ORCJIT, skylake)
      A 2x2 Recap
 [83]: entries = @syms a b c d real=true
 [83]: (a, b, c, d)
 [84]: M = [a b; c d]
 [84]:
                                                \left[\begin{array}{cc} a & b \\ c & d \end{array}\right]
 [85]: dM= det(M)
 [85]:
                                                ad - bc
      How can I invert a 3x3 matrix ?
 [86]: entries = @syms a b c d e f g h i real=true
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[86]: (a, b, c, d, e, f, g, h, i)
[87]: A = reshape([entries...],(3,3))
[87]:
                                                          \left[\begin{array}{ccc} a & d & g \\ b & e & h \\ c & f & i \end{array}\right]
[88]: detA = det(A) |> simplify
[88]:
                                              aei - afh - bdi + bfq + cdh - ceq
       on the SVD of matrix A of size 2 \times 3
[89]: A=[4 \ 11 \ 14; \ 8 \ 7 \ -2]; \text{ show}(A)
       [4 11 14; 8 7 -2]
       Construct B = A^T A
[90]: B=transpose(A)*A; show(B)
        [80 100 40; 100 170 140; 40 140 200]
       #Check; # B=[80 100 40; 100 170 140; 40 140 200];
[91]: lambda = symbols("lambda", real=true)
[91]:
                                                                  \lambda
[92]: C=B-lambda*[1 0 0; 0 1 0; 0 0 1]
[92]:
                                                  \begin{bmatrix} 80 - \lambda & 100 & 40 \\ 100 & 170 - \lambda & 140 \\ 40 & 140 & 200 - \lambda \end{bmatrix}
[93]: dC=det(C)
[93]:
                                     31200\lambda + (80 - \lambda)(170 - \lambda)(200 - \lambda) - 2720000
[94]: simplify(dC)
[94]:
                                                    \lambda \left( -\lambda^2 + 450\lambda - 32400 \right)
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[95]: eqn = -lambda^3 + 450*lambda^2 -32400*lambda
 [95]:
                                       -\lambda^3 + 450\lambda^2 - 32400\lambda
 [96]: real_roots(eqn)
 [96]:
 [97]: solve(eqn)
 [97]:
 [98]: factor(-lambda^3 + 450*lambda^2 -32400*lambda,lambda)
 [98]:
                                       -\lambda (\lambda - 360) (\lambda - 90)
 [99]: #recap
       #A=[4 11 14; 8 7 -2];
[100]: A = [4 11 14; 8 7 -2];
      https://docs.julialang.org/en/v1/stdlib/LinearAlgebra/#LinearAlgebra.svd
[101]: U,S,V = svd(A)
[101]: SVD{Float64,Float64,Array{Float64,2}}
       U factor:
       2×2 Array{Float64,2}:
        -0.948683 -0.316228
        -0.316228 0.948683
       singular values:
       2-element Array{Float64,1}:
        18.973665961010283
         9.486832980505136
       Vt factor:
       2×3 Array{Float64,2}:
        -0.333333 -0.666667 -0.666667
```

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[131]: function fullsvd(A)
          U,s,V = svd(A, full = true) # compute svd
          \Sigma = zeros(size(A))
                                    # container for \Sigma
          for i=1:length(s)
             \Sigma[i,i] = s[i]
                                   # place singular values in \Sigma
                                  # a practical sud would never store all these zeros
          display(U); display(\Sigma); display(V) # display the answer
          return (U, \Sigma, V)
                                     # return the answer
      end
[131]: fullsvd (generic function with 1 method)
     https://github.com/mitmath/1806/blob/master/summaries.md
[132]: function rankrsvd(A)
          U,s,V = svd(A, full = true) # compute svd
          r = sum(s.>1e-8)
                                    # rank = how many positive?
          U = U[:,1:r]
          \Sigma = Diagonal(s[1:r]) # Diagonal matrix of singular values
          V = V[:,1:r]
          display(V); display(\Sigma); display(V) # display the answer
                                       # return the answer
          return(U,\Sigma,V)
      end
[132]: rankrsvd (generic function with 1 method)
[135]: U,S,V = fullsvd(A) #matlab notation
     2×2 Array{Float64,2}:
      -0.948683 -0.316228
                 0.948683
      -0.316228
     2×3 Array{Float64,2}:
      18.9737 0.0
                       0.0
       0.0
               9.48683 0.0
     3×3 Adjoint{Float64,Array{Float64,2}}:
      -0.666667
                  0.333333 0.666667
      -0.666667 -0.666667 -0.333333
[135]: ([-0.9486832980505135 -0.3162277660168378; -0.3162277660168378
      0.9486832980505138], [18.973665961010283 0.0 0.0; 0.0 9.486832980505136 0.0],
      [-0.333333333333333 0.66666666666666 -0.6666666666666 ; -0.66666666666666
      -0.3333333333333333])
```

```
[136]: print_matrix(stdout, U);
       -0.9486832980505135 -0.3162277660168378
       -0.3162277660168378
                            0.9486832980505138
[137]: print_matrix(stdout,S);
       18.973665961010283 0.0
                                             0.0
        0.0
                          9.486832980505136
                                             0.0
[138]: print_matrix(stdout, V);
       -0.3333333333333333
                            -0.6666666666666
                            0.3333333333333333
                                                 0.6666666666666
       -0.66666666666666
                           -0.6666666666666671
                                               -0.3333333333333333
      Need to check that (B - \lambda_i I)v_i = 0
[139]: #check for lambda_1
       360*V[:,1]
[139]: 3-element Array{Float64,1}:
       -119.9999999999996
       -239.9999999999994
       -239.9999999999994
[140]: alpha=360
[140]: 360
[141]: (B)*V[:,1]
[141]: 3-element Array{Float64,1}:
       -119.9999999999997
       -239.9999999999994
       -239.9999999999994
[142]: #check done
      Pseudo inverse and linear system
[143]: b=[1;2]
[143]: 2-element Array{Int64,1}:
       1
       2
[144]: rang_A=rank(A)
```

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[144]: 2
[145]: #Non inversible == square matrix
       # 1/A
       # inv(A)
       #Least square possible using pinv
       pinv(A)
[145]: 3×2 Array{Float64,2}:
        -0.00555556
                      0.0722222
         0.022222
                      0.044444
        0.0555556
                   -0.0555556
[146]: xstar=pinv(A)*b
[146]: 3-element Array{Float64,1}:
        0.1388888888888888
        0.11111111111111109
        -0.05555555555555
[147]: #check 1
[148]: pseudoA1=V*pinv(S)*U'
[148]: 3×2 Array{Float64,2}:
        -0.00555556
                    0.0722222
        0.022222
                      0.044444
        0.0555556 -0.0555556
[152]: xstar1=pseudoA1*b
[152]: 3-element Array{Float64,1}:
        0.13888888888888888
        0.1111111111111109
        -0.05555555555555684
[153]: St=Sn[1:2,1:2]
[153]: 2×2 Array{Float64,2}:
        18.9737 0.0
        0.0
                 9.48683
[154]: pseudoA2=V*[inv(St'*St)*St'; 0 0 ]*U'
[154]: 3×2 Array{Float64,2}:
        -0.00555556
                      0.0722222
```

0.0222222 0.0444444 0.0555556 -0.0555556

[155]: xstar2=pseudoA2*b

[155]: 3-element Array{Float64,1}:

0.13888888888888888

0.11111111111111109

-0.0555555555555684