# A Supplementary Material

## A.1 Relaxation on Local Polytope

The relaxation of (1) over the *local polytope* is given by:

$$\begin{split} & \underset{\mu}{\min} & \sum_{u \in V} \sum_{i \in L} \mu_u(i) c(u,i) + \sum_{e = (u,v)} \sum_{i,j} \mu_e(ij) \theta_{(u,v)}(i,j) \\ & \text{s.t.} & \sum_{i} \mu_u(i) = 1, & \forall i \in L. \\ & \sum_{j} \mu_e(ij) = \mu_u(i), & \forall e = (u,v) \in E, i \in L. \\ & \sum_{i} \mu_e(ij) = \mu_v(j), & \forall e = (u,v) \in E, j \in L. \\ & \mu_u(i) \geq 0, & \forall u \in V, \ i \in L. \\ & \mu_e(ij) \geq 0, & \forall e \in E, \ i,j \in L. \end{split}$$

For a Ferromagnetic Potts Model, the objective becomes:

$$\min_{\mu} \sum_{u \in V} \sum_{i \in L} \mu_u(i) c(u, i) + \sum_{e = (u, v)} w(u, v) \sum_{i, j} \mu_e(ij) \mathbb{1}(i \neq j)$$

Fix the values  $\mu_u(i)$ . We want to minimize

$$\sum_{e=(u,v)} w(u,v) \sum_{i,j} \mu_e(ij) \mathbb{1}(i \neq j)$$

subject to the constraints

$$\sum_{j} \mu_{e}(ij) = \mu_{u}(i), \qquad \forall e = (u, v) \in E, i \in L.$$

$$\sum_{i} \mu_{e}(ij) = \mu_{v}(j), \qquad \forall e = (u, v) \in E, j \in L.$$

$$\mu_{e}(ij) \geq 0, \qquad \forall e \in E, i, j \in L.$$

Because  $w(u, v) \geq 0$  and  $\mu_e(ij) \geq 0$ , we want to put as much mass on  $\mu_e(ii)$  as possible without violating a constraint, since those terms do not appear in the objective. To that end, we set  $\mu_e(ii) = \min(\mu_u(i), \mu_v(i))$ . Then using the first constraint, the objective becomes:

$$\sum_{e=(u,v)} w(u,v) \sum_{i} \mu_{u}(i) - \min(\mu_{u}(i), \mu_{v}(i))$$

$$= \sum_{e=(u,v)} w(u,v) \left( 1 - \frac{1}{2} \sum_{i} \mu_{u}(i) + \mu_{v}(i) + \sum_{i} |\mu_{u}(i) - \mu_{v}(i)| \right)$$

$$= \sum_{e=(u,v)} w(u,v) \sum_{i} |\mu_{u}(i) - \mu_{v}(i)|$$

$$= \sum_{e=(u,v)} w(u,v) \frac{|\mu_{u} - \mu_{v}|}{2},$$

where we use multiple times that  $\sum_{i} \mu_{u}(i) = 1$ . The LP objective is thus:

$$\min_{\mu} \sum_{u \in V} \sum_{i \in L} \mu_u(i) c(u, i) + \sum_{e = (u, v)} w(u, v) \frac{|\mu_u - \mu_v|}{2}$$

Identifying  $\mu_u$  with  $\bar{u}$  and  $\mu_v$  with  $\bar{v}$ , we obtain the LP (3).

#### A.2 Proof of Lemma 1

Proof. This argument is similar to the one in Angelidakis et al. (2017). First, we verify the last two conditions in Lemma 1. Let  $\alpha = \frac{2}{k\theta} = \frac{5}{3}$  and  $\beta = k\theta = \frac{6}{5}$ . The algorithm clearly returns a feasible solution (i.e. a valid labeling). Consider any two vertices u and v, and let  $\Delta = d(u,v)$ . There are two cases: j(u) = j(v) and  $j(u) \neq j(v)$ . In the first case, let j = j(u) = j(v). We have  $P(u) \neq P(v)$  exactly when  $r \in (\min(\bar{u}_i, \bar{v}_i), \max(\bar{u}_i, \bar{v}_i))]$  and  $i \neq j$ . r is uniformly distributed in  $(0, \theta)$ , so the probability of this occurring is

$$\mathbb{P}[P(u) \neq P(v)] = \frac{1}{k} \sum_{i:i \neq j} \frac{|\bar{u}_i - \bar{v}_i|}{\theta} \le \frac{2}{k\theta} d(u, v) = \alpha \Delta.$$

Note that we used  $u_i \leq \varepsilon < \theta$  for  $i \neq j$  and for all u. Now consider the case where  $j(u) \neq j(v)$ . Here  $d(u,v) \geq d(e_{j(u)},e_{j(v)}) - d(u,e_{j(u)}) - d(v,e_{j(v)})$  by the triangle inequality  $(e_i$  is the ith standard basis vector in  $\mathbb{R}^k$ ). So  $d(u,v) \geq 1 - 2\varepsilon \geq 1 - 2/30$  for  $k \geq 3$ . So  $d(u,v) \geq 14/15$ , and  $\alpha = 5/3$  so  $\alpha\Delta > 1$  and the bound trivially applies.

Next we verify the "co-appoximation" condition. First consider the case where j(u)=j(v)=j. Then  $d(u,v)\leq d(u,e_j)+d(e_j,v)\leq 2\varepsilon\leq 1/15$ . As we showed,  $\mathbb{P}[P(u)\neq P(v)]\leq \alpha\Delta$ . So  $\mathbb{P}[P(u)=P(v)]\geq 1-\alpha\Delta\geq \beta^{-1}(1-\Delta)$ , where the last inequality is because  $\frac{1-\beta^{-1}}{\alpha-\beta^{-1}}=\frac{1/6}{5/3-5/6}=\frac{1}{5}\geq \Delta$ . Now assume  $j(u)\neq j(v)$ . Note that if  $\bar{u}_i\geq r$  and  $\bar{v}_i\geq r$ , u and v are both added to  $P_i$ . So

$$\mathbb{P}[P(u) = P(v)] \ge \mathbb{P}[u_i \ge r, v_i \ge r]$$

$$= \frac{1}{k} \sum_{i=1}^k \frac{\min(\bar{u}_i, \bar{v}_i)}{\theta}.$$

Here we used that for all i,  $\min(\bar{u}_i, \bar{v}_i) \leq \varepsilon < \theta$  since  $j(u) \neq j(v)$ . Then

$$\mathbb{P}[P(u) = P(v)] \ge \frac{1}{k} \sum_{i=1}^{k} \frac{\bar{u}_i + \bar{v}_i - |\bar{u}_i - \bar{v}_i|}{2\theta}$$
$$= \frac{1}{k\theta} (1 - d(u, v)) = \beta^{-1} (1 - d(u, v)).$$

The approximation conditions hold.

Finally, we check the first two conditions of Lemma 1. First consider  $\mathbb{P}[P(u) = i, i \neq j(u)]$ . This can only occur when i is selected and u is assigned to  $P_i$ . So

$$\mathbb{P}[P(u) = i, i \neq j(u)] = \frac{1}{k} \mathbb{P}[\bar{u}_i \geq r] = \frac{1}{k} \frac{\bar{u}_i}{\theta} = \frac{5}{6} \bar{u}_i.$$

Now we compute  $\mathbb{P}[P(u) \neq j(u)]$ . A vertex u clearly can only be assigned a label  $i \neq j(u)$  if such an i is selected and u is assigned to it; namely,

$$\mathbb{P}[P(u) \neq j(u)] = \frac{1}{k} \sum_{i:i \neq j(u)} \frac{\bar{u}_i}{\theta} = \frac{1}{k\theta} (1 - \bar{u}_{j(u)})$$
$$= \frac{5}{6} (1 - \bar{u}_{j(u)}).$$

This concludes the proof.

#### A.3 Full Proof of Theorem 1

Here we reproduce the proof of Theorem 1 in more detail.

**Theorem.** On a (2,1)-stable instance of UNIFORM METRIC LABELING with optimal integer solution g, the LP relaxation (3) is tight.

*Proof.* Assume for a contradiction that the optimal LP solution  $\{\bar{u}^{LP}\}$  of (3) is fractional. To construct a stability-violating labeling, we will run Algorithm 2 on a fractional labeling  $\{\bar{u}\}$  constructed from  $\{\bar{u}^{LP}\}$  and the optimal integer solution g. We then use Lemma 1 to show that in expectation, the output of  $\mathcal{R}(\{\bar{u}\})$  must be better than the optimal integer solution in a particular (2,1)-perturbation, which contradicts (2,1)-stability.

Let  $\{\bar{u}^g\}$  be the solution to (3) corresponding to g, and define the following  $\varepsilon$ -close solution  $\{\bar{u}\}$ : for every u and every i, set  $\bar{u}_i = (1 - \varepsilon)\bar{u}_i^g + \varepsilon\bar{u}_i^{LP}$ . Note that  $\{\bar{u}\}$  is fractional and j(u) = g(u) for all u.

Recall that  $E_g$  is the set of edges cut by the optimal solution g. Define the following (2,1)-perturbation w' of the weights w:

$$w'(u,v) = \begin{cases} w(u,v) & (u,v) \in E_g\\ \frac{1}{2}w(u,v) & (u,v) \in E \setminus E_g. \end{cases}$$

We refer to the objective with modified weights w' as Q' (that is, Q' is the objective in the instance with weights w' and costs c).

Now let  $h = \mathcal{R}(\{\bar{u}\})$ . To compare g and h, we will compute  $\mathbb{E}[Q'(g) - Q'(h)]$ , where the expectation is over the randomness of the rounding algorithm. By definition,

$$\mathbb{E}[Q'(g) - Q'(h)] = \mathbb{E}[Q'(g) - Q'(h)|h = g] \Pr(h = g) + \mathbb{E}[Q'(g) - Q'(h)|h \neq g] \Pr(h \neq g).$$

The first term of the sum above is clearly zero. Further, as  $\{\bar{u}\}$  is fractional, the guarantees in Lemma 1 imply that  $\Pr(h \neq g) > 0$ . By (2,1)-stability of the instance, any labeling  $h \neq g$  must satisfy Q'(h) > Q'(g). So stability and fractionality of the LP imply  $\mathbb{E}[Q'(g) - Q'(h)] < 0$ .

If we compute  $\mathbb{E}[Q'(g) - Q'(h)]$  and simplify using Lemma 1 and the definition of w' (see the appendix for a full derivation), we obtain:

Taking the expectation, we obtain:

$$\mathbb{E}[Q'(g) - Q'(h)] = \sum_{u \in V} c(u, g(u)) \Pr(h(u) \neq g(u))$$

$$+ \sum_{(u,v) \in E_g} w'(u,v) \Pr((u,v) \text{ not cut})$$

$$- \sum_{u \in V} \sum_{i \neq g(u)} c(u,i) \Pr(h(u) = i)$$

$$- \sum_{(u,v) \in E \setminus E_g} w'(u,v) \Pr((u,v) \text{ cut}).$$

Applying Lemma 1 with j(u) = g(u),

$$\mathbb{E}[Q'(g) - Q'(h)] \ge \frac{5}{6} \left( \sum_{u \in V} c(u, g(u)) (1 - \bar{u}_{g(u)}) + \sum_{(u,v) \in E_g} w'(u,v) (1 - d(u,v)) - \sum_{u \in V} \sum_{i \ne g(u)} c(u,i) \bar{u}_i - \sum_{(u,v) \in E \setminus E_g} 2w'(u,v) d(u,v) \right)$$

Using the definition of w',

$$\mathbb{E}[Q'(g) - Q'(h)] \ge \frac{5}{6} \left( \sum_{u \in V} c(u, g(u)) + \sum_{(u,v) \in E_g} w(u,v) - \sum_{u \in V} \sum_{i \in L} c(u,i) \bar{u}_i - \sum_{(u,v) \in E} w(u,v) d(u,v) \right)$$

The first two terms are simply Q(g), and the last two are the objective  $Q(\{\bar{u}\})$  of the LP solution  $\bar{u}$ . Since  $\bar{u} = (1 - \varepsilon)\bar{u}^g + \varepsilon \bar{u}^{LP}$  and  $Q(\{\bar{u}^{LP}\}) \leq Q(\{\bar{u}^g\})$ , the convexity of the LP objective implies  $Q(\{\bar{u}\}) \leq Q(\{\bar{u}^g\}) = Q(g)$ . So  $\mathbb{E}[Q'(g) - Q'(h)] \geq 0$ . But stability of the instance and fractionality of the LP solution implied  $\mathbb{E}[Q'(g) - Q'(h)] < 0$ .

### A.4 Generating Counterexamples

The following procedure can be used to find  $(\beta, \gamma)$ -stable instances.

- 1. Given a fixed number of nodes n and labels k, randomly generate a graph G as follows:
  - (a) Connect any two nodes (u, v) with an edge with probability connectProb.
  - (b) When connecting two nodes, choose the edge weight w(u, v) uniformly at random from  $\mathbb{Z} \cap [0, \mathtt{weightMax}]$ .
- 2. For each node u, choose an index i uniformly at random from  $\{1 \dots k\}$ . Draw c(u,i) uniformly at random from  $\mathbb{Z} \cap [0, \mathsf{costMax}]$ . Set c(u,j) = 0 for  $j \neq i$ .
- 3. Find the optimal solution g to the instance (G, w, c, L).
- 4. Let  $E_g$  be the set of edges cut by g, and consider the following adversarial perturbation w' of w:

$$w'(u,v) = \begin{cases} \frac{1}{\beta}w(u,v) & (u,v) \in E \setminus E_g\\ \gamma w(u,v) & (u,v) \in E_g \end{cases}$$

Let Q' be the objective with these modified weights.

5. Enumerate the  $k^n-1$  possible labelings not equal to g. If any of them have  $Q'(h) \leq Q'(g)$ , return to step 1. Otherwise, print V, E, w, c.

Following this procedure, we can also enforce additional properties of the instance in step 5 before printing it out. For instance, we can enforce that the LP must be fractional on the instance, or that  $\alpha$ -expansion must not find the optimal solution. If these additional conditions fail to hold, we return to step 1.

The examples in Section 6 were found with connectProb = 0.5, weightMax = 4, costMax = 20, and then modified for simplicity. Steps 3-5 were repeated for each modification to ensure the resulting instances satisfied the correct stability conditions. In Section 6,  $\beta=1$  and  $\gamma=2$ ; in Section 6,  $\beta=2$  and  $\gamma=1$ .

The following lemma proves that steps 3-5 are sufficient to verify stability.

**Lemma A.1.** Let  $w^*$  be an arbitrary  $(\beta, \gamma)$ -perturbation of the weights w, and let w' be the adversarial perturbation for the optimal solution g. Then for any labeling h,  $Q^*(h) \leq Q^*(g)$  implies  $Q'(h) \leq Q'(g)$ . In other words, if a labeling h violates stability in any perturbation, it violates stability in the adversarial perturbation w'.

Proof. We show that  $Q^*(g) - Q^*(h) \leq Q'(g) - Q'(h)$ . Let  $V_{\Delta} = \{u \in V \mid g(u) \neq h(u)\}$ . Recall that  $E_g$  and  $E_h$  are the sets of edges cut by g and h, respectively. We compute

$$\begin{split} Q'(g) - Q'(h) &= \sum_{u \in V_{\Delta}} c(u, g(u)) + \sum_{(u, v) \in E_g \setminus E_h} w'(u, v) \\ &- \sum_{u \in V_{\Delta}} c(u, h(u)) - \sum_{(u, v) \in E_h \setminus E_g} w'(u, v). \end{split}$$

Using the definition of w',

$$Q'(g) - Q'(h) = \sum_{u \in V_{\Delta}} c(u, g(u)) + \sum_{(u,v) \in E_g \setminus E_h} \gamma w(u,v)$$
$$- \sum_{u \in V_{\Delta}} c(u, h(u)) - \sum_{(u,v) \in E_h \setminus E_g} \frac{w(u,v)}{\beta}.$$

Since  $w^*$  is a valid  $(\beta, \gamma)$ -perturbation,  $\frac{1}{\beta}w(u, v) \leq w^*(u, v) \leq \gamma w(u, v)$ . Then since all the c's and w's are nonnegative,

$$Q'(g) - Q'(h) \ge \sum_{u \in V_{\Delta}} c(u, g(u)) + \sum_{(u,v) \in E_g \setminus E_h} w^*(u,v)$$
$$- \sum_{u \in V_{\Delta}} c(u, h(u)) - \sum_{(u,v) \in E_h \setminus E_g} w^*(u,v)$$
$$= Q^*(g) - Q^*(h).$$