



JOINT INSTITUTE
交大密西根学院

VV 285
MID 2 Review

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Content



- **The Second Derivative**

- **Extrema of Potential Functions**

The Second Derivative



2.5.1. Definition. Let X, V be finite-dimensional normed vector spaces and $\Omega \subset X$ an open set. A function $f: \Omega \rightarrow V$ is said to be **twice differentiable at $x \in \Omega$** if

- ▶ f is differentiable in an open ball $B_\varepsilon(x)$ around x and
- ▶ the function $Df: B_\varepsilon(x) \rightarrow \mathcal{L}(X, V)$ is differentiable at x .

We say that f is twice differentiable on Ω if f is twice differentiable at every $x \in \Omega$.

Actually, the second derivative is a map:

$$D(Df) =: D^2f: \Omega \rightarrow \mathcal{L}(X, \mathcal{L}(X, V)).$$

And is found by:

$$Df|_{x+h} = Df|_x + D^2f|_x h + o(h) \quad \text{as } h \rightarrow 0.$$

Example



- Calculate the second, third and forth derivatives of the map,
- $\Phi : \text{Mat}(n \times n; \mathbb{R}) \rightarrow \text{Mat}(n \times n; \mathbb{R}), \Phi(A) = A^3$

$$D\Phi|_A = AHA + AAH + HAA$$

$$D^2\Phi|_A(H, J) = JHA + AHJ + AJH + JAH + AHJ + AJH$$

$$D^3\Phi|_A(H, J, K) = JHK + KHJ + KJH + JKH + KHJ + KJH$$

$$D^4\Phi|_A = 0$$

The Hessian



The Hessian. For a differentiable potential function $f : \mathbb{R}^n \rightarrow \mathbb{R}$.
The derivative is given by the Jacobian:

$$Df|_x = \begin{pmatrix} \frac{\partial f}{\partial x_1} \Big|_x & \cdots & \frac{\partial f}{\partial x_n} \Big|_x \end{pmatrix}, \quad Df|_x \in \mathcal{L}(\mathbb{R}^n, \mathbb{R})$$

and the second derivative is found by **Hessian** where

$$\text{Hess } f(x) = D(\nabla f)|_x = \begin{pmatrix} \frac{\partial^2 f}{\partial x_1 \partial x_1} \Big|_x & \frac{\partial^2 f}{\partial x_2 \partial x_1} \Big|_x & \cdots & \frac{\partial^2 f}{\partial x_n \partial x_1} \Big|_x \\ \vdots & \vdots & & \vdots \\ \frac{\partial^2 f}{\partial x_1 \partial x_n} \Big|_x & \frac{\partial^2 f}{\partial x_2 \partial x_n} \Big|_x & \cdots & \frac{\partial^2 f}{\partial x_n \partial x_n} \Big|_x \end{pmatrix}$$

$$D^2 f|_x h = \text{Hess } f(x)h$$

Bilinear Maps



Note that the expression $\langle \text{Hess } f(x)h, \tilde{h} \rangle$ is linear in both h and \tilde{h} ; hence we can also regard the second derivative as a **bilinear map**

$$D^2f|_x: \mathbb{R}^n \times \mathbb{R}^n \rightarrow \mathbb{R}, \quad (h, \tilde{h}) \mapsto \langle \text{Hess } f(x)h, \tilde{h} \rangle.$$

2.5.3. Definition. Let X, V be finite-dimensional normed vector spaces. The set of multilinear maps from X to V is denoted by

$$\mathcal{L}^{(n)}(X, V) := \left\{ L: X \times \cdots \times X \rightarrow V : L \text{ linear in each component} \right\}.$$

In the special case $V = \mathbb{R}$ an element of $\mathcal{L}^{(n)}(X, V)$ is called a **multilinear form**.

Bilinear form in \mathbb{R}^n



- Every linear map $L \in (\mathbb{R}^n)^*$ has the form $L = \langle z, \cdot \rangle$ for some $z \in \mathbb{R}^n$.
- Interpret an element $A \in L(\mathbb{R}^n, L(\mathbb{R}^n, \mathbb{R}))$ as a linear map, $A: y \rightarrow L_y := \langle z_y, \cdot \rangle$, $z_y = A(y)$.
- A is actually a matrix $A: y \rightarrow z_y$.
- For every $y \in \mathbb{R}^n$ we obtain a linear map $\langle Ay, \cdot \rangle \in L(\mathbb{R}^n, \mathbb{R})$.
- Then $L_y x = \langle Ay, x \rangle = L(x, y)$.

Schwarz's Theorem



2.5.5. Schwarz's Theorem. Let X, V be normed vector spaces and $\Omega \subset X$ an open set. Let $f \in C^2(\Omega, V)$. Then $D^2f|_x \in \mathcal{L}^{(2)}(X \times X, V)$ is symmetric for all $x \in \Omega$, i.e.,

$$D^2f(u, v) = D^2f(v, u), \quad \text{for all } u, v \in X.$$

- This implies that if f is **twice continuously differentiable**, the Hessian of f at x is symmetric.

$$\frac{\partial^2 f}{\partial x_i \partial x_j} = \frac{\partial^2 f}{\partial x_j \partial x_i}.$$

In other words, if f is twice continuously differentiable, the order of differentiation in the second-order partial derivatives does not matter.

Schwarz's Theorem



- Note: The Schwarz's theorem will hold if all the second-order partial derivatives **are continuous**.
- It will break if the function fails to differentiable partial derivative.
- Example:

$$f(x,y) = \begin{cases} \frac{xy(x^2-y^2)}{x^2+y^2} & \text{for } (x,y) \neq (0,0) \\ 0 & \text{for } (x,y) = (0,0) \end{cases}$$

- Since the second partial derivative is **not continuous** at $(0,0)$
- Try to see that it is not symmetric

Schwarz's Theorem



- Try to see that it is not symmetric
- $f(x,y) = \begin{cases} \frac{xy(x^2-y^2)}{x^2+y^2}, & \text{for } (x,y) \neq (0,0) \\ 0 & \text{for } (x,y) = (0,0) \end{cases}$

- Try to calculate

$$\frac{\partial^2}{\partial x \partial y} f|_{(0,0)}$$

$$\frac{\partial^2}{\partial y \partial x} f|_{(0,0)}$$

Exercise 1-1



- Find the first and second derivatives of the following functions:
 - 1. $f : \text{Mat}(n \times n; \mathbb{R}) \rightarrow \mathbb{R}$, $f(A) = \text{tr}(A^2)$
 - 2. $g : \text{Mat}(n \times n; \mathbb{R}) \rightarrow \mathbb{R}$, $f(A) = (\text{tr} A)^2$

Exercise 1-2



- Find the second derivative of the determinant of an invertible matrix A.

Det: $\text{Mat}(n \times n; \mathbb{R}) \rightarrow \mathbb{R}$

The Frenet–Serret formulas (in \mathbf{R}^3)



$$\frac{d\mathbf{T}}{ds} = \kappa \mathbf{N},$$

$$\frac{d\mathbf{N}}{ds} = -\kappa \mathbf{T} + \tau \mathbf{B},$$

$$\frac{d\mathbf{B}}{ds} = -\tau \mathbf{N},$$

$$T(t) = \frac{\gamma'(t)}{\|\gamma'(t)\|}$$

$$N(t) = \frac{(T \circ \gamma)'(t)}{\|(T \circ \gamma)'(t)\|}$$

$$B(t) = T \times N$$

$$\kappa = \frac{\|\gamma'(t) \times \gamma''(t)\|}{\|\gamma'(t)\|^3}$$

$$\tau = \frac{\det(\gamma'(t), \gamma''(t), \gamma'''(t))}{\|\gamma'(t) \times \gamma''(t)\|^2}$$

Content



- **The Second Derivative**

- **Extrema of Potential Functions**

Quadratic Approximation of Potential Functions



2.6.1. Lemma. Let $\Omega \subset \mathbb{R}^n$ be an open set and $f \in C^2(\Omega, \mathbb{R})$. Then for any $h \in \mathbb{R}^n$ small enough that $x + h \in \Omega$,

$$f(x + h) = f(x) + \langle \nabla f(x), h \rangle + \int_0^1 (1 - t) \langle \text{Hess } f(x + th)h, h \rangle dt. \quad (2.6.2)$$

2.6.2. Corollary. Let $\Omega \subset \mathbb{R}^n$ be an open set and $f \in C^2(\Omega, \mathbb{R})$. Then, as $h \rightarrow 0$,

$$f(x + h) = f(x) + \langle \nabla f(x), h \rangle + \frac{1}{2} \langle \text{Hess } f(x)h, h \rangle + o(h^2). \quad (2.6.3)$$

Quadratic Form



2.6.3. Definition. Let $A \in \text{Mat}(n \times n, \mathbb{R})$. Then the ***quadratic form induced by A*** is defined as the map

$$Q_A := \langle \cdot, A(\cdot) \rangle, \quad x \mapsto \langle x, Ax \rangle = \sum_{j,k=1}^n a_{jk}x_jx_k, \quad x \in \mathbb{R}^n.$$

Clearly, $Q_A(\lambda x) = \lambda^2 Q_A(x)$ for any $\lambda \in \mathbb{R}$. Note also that Q_A is continuous, because it is a polynomial in x_1, \dots, x_n .

Quadratic Form



2.6.4. Definition. A quadratic form Q_A induced by a matrix $A \in \text{Mat}(n \times n, \mathbb{R})$ is called

- ▶ **positive definite** if $Q_A(x) > 0$ for all $x \neq 0$,
- ▶ **negative definite** if $Q_A(x) < 0$ for all $x \neq 0$,
- ▶ **indefinite** if $Q_A(x_0) > 0$ for some $x_0 \in \mathbb{R}^n$ and $Q_A(y_0) < 0$ for some $y_0 \in \mathbb{R}^n$.

A matrix A is said to be negative definite / positive definite / indefinite if the induced quadratic form Q_A has the corresponding property.

Criteria for Definiteness



2.6.7. Lemma. Let $A \in \text{Mat}(2 \times 2, \mathbb{R})$ be symmetric, i.e.,

$$A = \begin{pmatrix} a & b \\ b & c \end{pmatrix}.$$

Let $\Delta = \det A$. Then

- (i) A positive definite $\Leftrightarrow a > 0$ and $\Delta > 0$
- (ii) A negative definite $\Leftrightarrow a < 0$ and $\Delta > 0$
- (iii) A indefinite $\Leftrightarrow \Delta < 0$

2.6.8. Lemma. The matrix $A \in \text{Mat}(n \times n, \mathbb{R})$ is

$$\text{positive definite} \quad \Leftrightarrow \quad \exists_{\alpha > 0} \forall_{x \in \mathbb{R}^n} Q_A(x) \geq \alpha \|x\|^2$$

$$\text{negative definite} \quad \Leftrightarrow \quad \exists_{\alpha > 0} \forall_{x \in \mathbb{R}^n} Q_A(x) \leq -\alpha \|x\|^2$$

Extrema of Real Functions



2.6.10. Definition. Let $\Omega \subset \mathbb{R}^n$ and $f: \Omega \rightarrow \mathbb{R}$.

- (i) f is said to have a **local maximum** at $\xi \in \Omega$ if there exists a $\delta > 0$ such that

$$x \in \Omega \cap B_\delta(\xi) \quad \Rightarrow \quad f(x) \leq f(\xi).$$

- (ii) f is said to have a **strict local maximum** at $\xi \in \Omega$ if there exists a $\delta > 0$ such that

$$x \in \Omega \cap B_\delta(\xi) \setminus \{\xi\} \quad \Rightarrow \quad f(x) < f(\xi).$$

Extrema of Real Function



2.6.11. Theorem. Let $\Omega \subset \mathbb{R}^n$, $f: \Omega \rightarrow \mathbb{R}$ and $\xi \in \text{int } \Omega$. Assume that all partial derivatives of f exist at ξ and that f has a local extremum (maximum or minimum) in ξ . Then

$$\nabla f(\xi) = 0.$$

If f is differentiable in ξ , this implies $Df|_{\xi} = 0$.

2.6.12. Theorem. Let $\Omega \subset \mathbb{R}^n$ be open, $f \in C^2(\Omega)$ and $\xi \in \Omega$. Let $\nabla f(\xi) = 0$ (i.e., $Df|_{\xi} = 0$).

- (i) If $\text{Hess } f|_{\xi}$ is positive definite, f has a strict local minimum at ξ .
- (ii) If $\text{Hess } f|_{\xi}$ is negative definite, f has a strict local maximum at ξ .
- (iii) If $\text{Hess } f|_{\xi}$ is indefinite, f has no extremum at ξ .

Extrema of Real Functions



2.6.13. Corollary. Let $\Omega \subset \mathbb{R}^2$ be open, $f \in C^2(\Omega)$ and $\xi \in \Omega$ with $\nabla f(\xi) = 0$. Set

$$\Delta := \det \text{Hess } f|_{\xi} = \frac{\partial^2 f}{\partial x_1^2} \Big|_{\xi} \frac{\partial^2 f}{\partial x_2^2} \Big|_{\xi} - \left(\frac{\partial^2 f}{\partial x_1 \partial x_2} \Big|_{\xi} \right)^2$$

Then $f(\xi)$ is

- ▶ a local minimum if $\frac{\partial^2 f}{\partial x_1^2} \Big|_{\xi} > 0$ and $\Delta > 0$,
- ▶ a local maximum if $\frac{\partial^2 f}{\partial x_1^2} \Big|_{\xi} < 0$ and $\Delta > 0$,
- ▶ no extremum if $\Delta < 0$.

Note that if $\Delta = 0$, Corollary 2.6.13 yields no information.

Finding Extrema



In searching for extrema of functions $f \in C^2(\Omega, \mathbb{R})$, we follow a four-step process:

1. Check for critical points $\xi \in \text{int } \Omega$, i.e., those where $Df|_{\xi} = 0$.
2. Use Theorem 2.6.12 or Corollary 2.6.13 to check which of the critical points is an extremum.
3. Check the boundary $\partial\Omega$ separately for local extrema.
4. Identify the global extrema. Any finite global extremum must also be a local extremum, so it will be included among those found above.

Reference



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Thank You

Have fun in Mid 2!