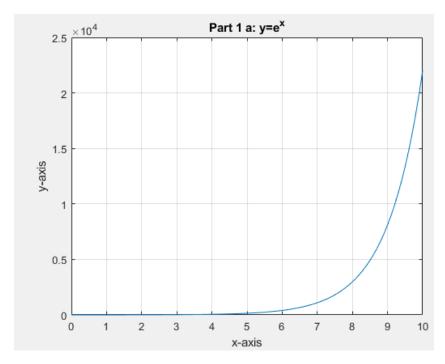
Part 1. Practice 'Basic Plotting Skills' Examples: Graphs – Gavin Binder

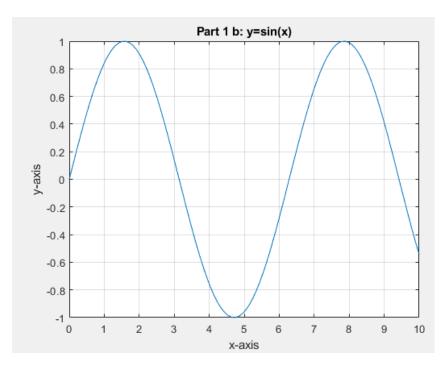
Part 1a.

```
x = linspace(0,10,100);
y = exp(x);
plot(x,y)
title("Part 1 a: y=e^x")
xlabel("x-axis")
ylabel("y-axis")
grid on
```



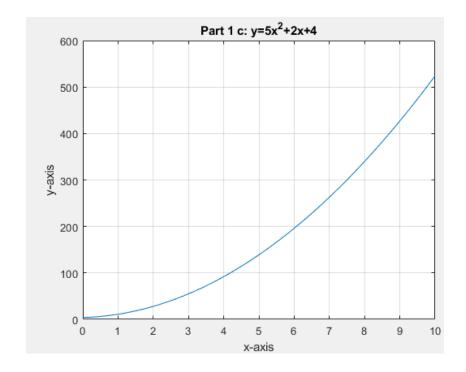
Part 1b.

```
x = linspace(0,10,100);
y = 5*x.^(2)+2*x+4;
plot(x,y)
title("Part 1 c: y=5x^2+2x+4")
xlabel("x-axis")
ylabel("y-axis")
grid on
```



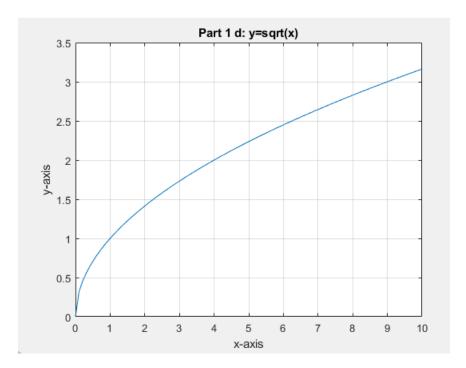
Part 1c.

```
x = linspace(0,10,100);
y = 5*x.^(2)+2*x+4;
plot(x,y)
title("Part 1 c: y=5x^2+2x+4")
xlabel("x-axis")
ylabel("y-axis")
grid on
```



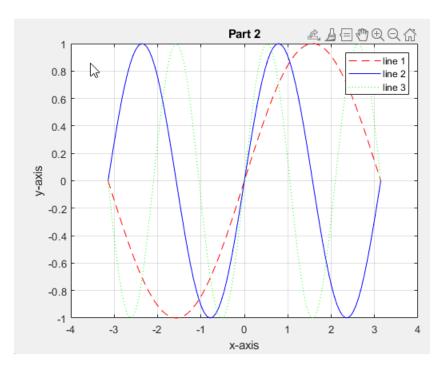
Part 1d.

```
x = linspace(0,10,100);
y = sqrt(x);
plot(x,y)
title("Part 1 d: y=sqrt(x)")
xlabel("x-axis")
ylabel("y-axis")
grid on
```



Part 2. 'More plots with special format': Graphs – Gavin Binder

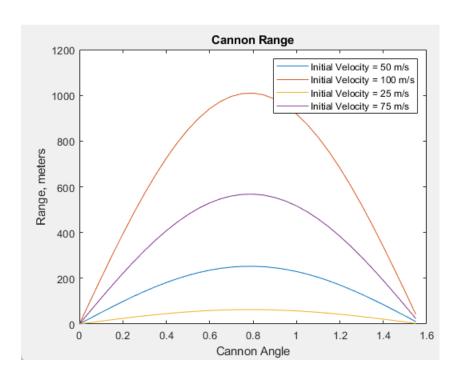
```
x=linspace(-pi,pi,100);
y1=sin(x);
y2=sin(2*x);
y3=sin(3*x);
plot(x,y1,'--r',x,y2,'-b',x,y3,':g')
title("Part 2")
xlabel("x-axis")
ylabel("y-axis")
grid on
legend('line 1', 'line 2', 'line 3')
text(2,100,'y1 = red, y2 = blue, y3 = green')
```

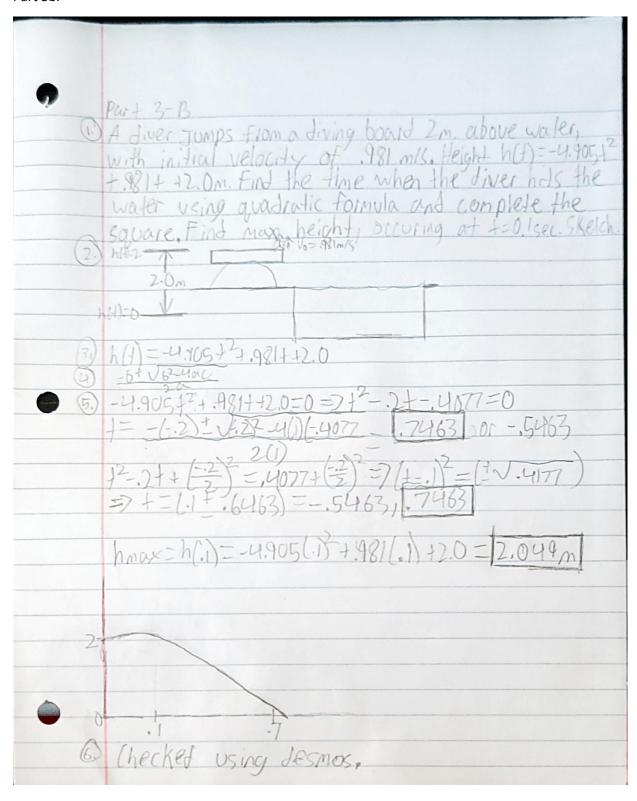


Part 3. Intro to STEM application' Problem – Projectile motion – Gavin Binder

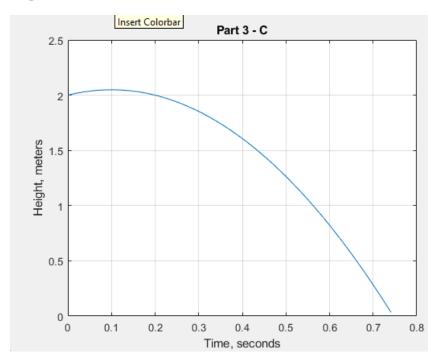
Part 3a.

```
% Define constants
g= 9.9;
v1=50;
v2=100;
v3=25;
v4=75;
% Define angle vector
angle=0:0.05:pi/2;
% Calculate range
R1=v1^2/g*sin(2*angle);
R2=v2^2/g*sin(2*angle);
R3=v3^2/g*sin(2*angle);
R4=v4^2/g*sin(2*angle);
% Plot results
plot(angle,R1,angle,R2,angle,R3,angle,R4)
title('Cannon Range')
xlabel('Cannon Angle')
ylabel('Range, meters')
legend('Initial Velocity = 50 m/s','Initial Velocity = 100 m/s', ...
    'Initial Velocity = 25 m/s', 'Initial Velocity = 75 m/s')
```

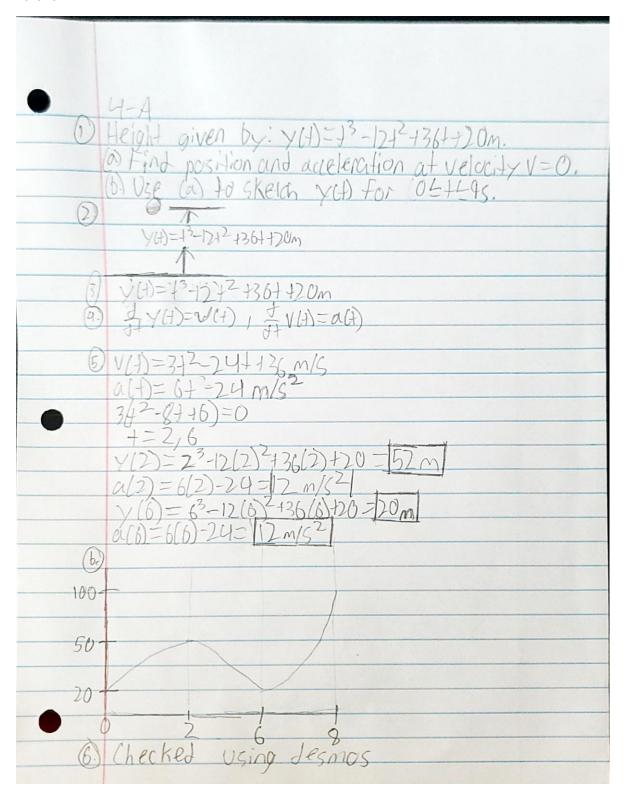




```
a=1;
b=-0.2;
c=-0.4007;
val_1=(-(b)+sqrt(b.^2-4*a*c))/2*a
val_2=(-(b)-sqrt(b.^2-4*a*c))/2*a
t=linspace(0,val_1,100);
h=-4.905*t.^2+0.981*t+2.0;
x=0.1;
h_max=-4.905*x.^2+0.981*x+2.0
plot(t,h)
title('Part 3 - C')
xlabel('Time, seconds')
ylabel('Height, meters')
grid on
```

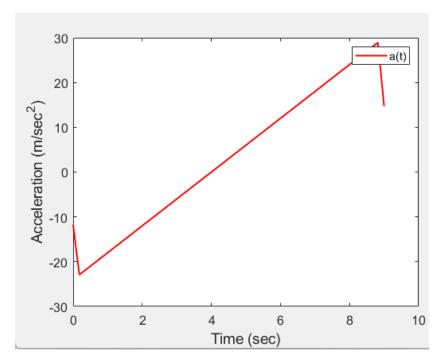


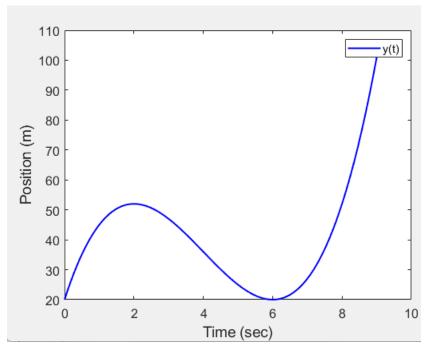
Part 4. Intro to STEM application' Problem – electrical circuits – Gavin Binder Part 4a.

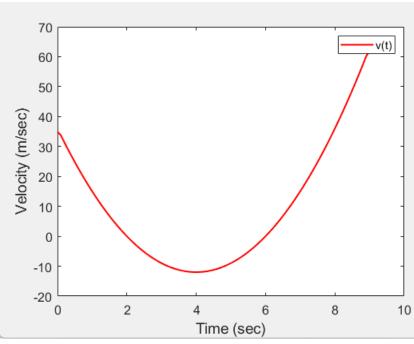


```
Part 4b.
```

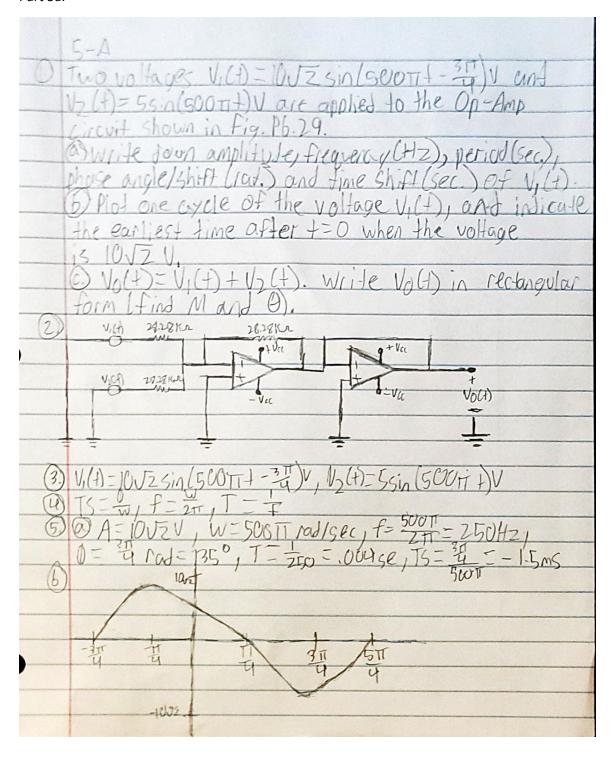
```
clear
clear
close all
t = linspace(0,9,100);
y = t.^3-12*t.^2+36*t+20;
figure
plot(t,y,'b','linewidth',1.5)
set(gca,'fontsize',12)
xlabel('Time (sec)','fontsize',14)
ylabel('Position (m)','FontSize',14)
legend('y(t)')
dy_dt=gradient(y,t);
plot(t,dy_dt,'r','linewidth',1.5)
set(gca,'fontsize',12)
xlabel('Time (sec)','fontsize',14)
ylabel('Velocity (m/sec)','FontSize',14)
legend('v(t)')
dv_dt=gradient(dy_dt,t);
figure
plot(t,dv_dt,'r','linewidth',1.5)
set(gca,'fontsize',12)
xlabel('Time (sec)','fontsize',14)
ylabel('Acceleration (m/sec^2)', 'FontSize',14)
legend('a(t)')
```

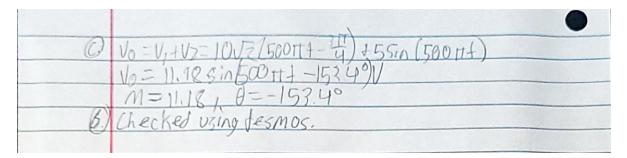






Part 5. Intro to STEM application' Problem – electrical circuits – Gavin Binder Part 5a.

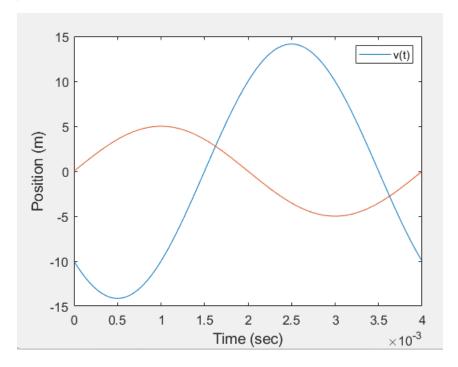




Part 5b.

```
clear
clear
close all
t = linspace(0,0.004,100);
v1 = 10*sqrt(2)*sin(500*pi*t-3*pi/4);
v2 = 5*sin(500*pi*t);

figure
plot(t,v1,t,v2)
set(gca,'fontsize',12)
xlabel('Time (sec)','FontSize',14)
ylabel('Position (m)','FontSize',14)
legend('v(t)')
```



Part 6. Reflection on new P3F group 'collaboration' activities

Part 6a

The group consists of myself, Ryan Thompson, and Francisco Ribas. Communication happened mainly through Discord messages, and everything went very smoothly in terms of collaboration. For the presentation, I did the formatting, introduction, and conclusion. Ryan did the calculations and Frankie did the problem statement and MATLAB code. For Mini Project 4, we mostly just helped with the MATLAB portions, helping each other if when we need it.

Part 6b

- Graph manipulation, as MATLAB allows for many different options in terms of formatting and changing graphs to suite your needs.
- Image processing and computer visions, as you can use MATLAB to analyze images and build algorithms.