# Part 1. Practice 'Matrix Manipulation Skills' examples: Matrices – Gavin Binder

# Part 1 MATLAB code

```
a 📙 [12, 17, 3, 6]
b = [5, 8, 3;
   1, 2, 3;
    2, 4, 6]
c = [22;
    17;
    4]
x1 = a(2)
x2 = b(:,3)
x3 = b(3,:)
x4 = diag(b)
x5 = [a(:,1:3);
   b(:,:)]
x6 = [22 5 1 2; 17 8 2 4; 4 3 3 6; 12 17 3 6]
x7 = b(8)
x8 = reshape(b,[],1)
```

# Prerequisite:

```
a =

12 17 3 6

b =

5 8 3
1 2 3
2 4 6

c =

22
17
4
```

## Part 1. #1 Answer

```
x1 =
```

17

# Part 1. #2 Answer

x2 =

3

3 6

# Part 1. #3 Answer

x3 =

2 4 6

# Part 1. #4 Answer

x4 =

5

2 6

# Part 1. #5 Answer

x5 =

12 17 3 5 8 3 1 2 3 2 4 6

# Part 1. #6 Answer

x6 =

22 5 1 2 17 8 2 4 4 3 3 6 12 17 3 6

### Part 1. #7 Answer

x7 =

3

# Part 1. #8 Answer

6

# Part 2. Practice 'Matrix Manipulation 2 Skills' examples: Matrices\_2 – Gavin Binder

# Part 2ia Code and Answer

```
A = [12, 4;

3, -5]

B = [2, 12;

0, 0]

A * B

B * A

A = 12 4

3 -5

B = 2 12

0 0

ans = 24 144

6 36

ans = 60 -52
```

0 0

# Part 2ib Code and Answer

```
A=[1,3,5;
      2,4,6]
  B=[-2,4;
      3,8;
      12,-2]
  A*B
  B*A
A =
   12
       -2
ans =
   67
       18
  80
      28
ans =
      10 14
41 63
   6
  19
       28
           48
```

# Part 2ii1 Code and Answer

Related documentation

```
A=[2,5;
       2,9;
        6,5]
   B=[2,5;
       2,9
        6,5]
   A*B
   B*A
   %can't be multiplied%
A =
     2
          5
     2
           5
     2
Error using _*
Incorrect dimensions for matrix multiplication. Check that the
number of columns in the first matrix matches the number of
rows in the second \mathtt{matrix.}\ \mathtt{To}\ \mathtt{perform}\ \mathtt{elementwise}
multiplication, use '.*'.
Error in Part2ii1 (line 7)
```

# Part 2ii2 Code and Answer

# Part 2ii3 Code and Answer

```
A=[5,1,9;
      7,2,2]
   B=[8,5;
      4,2;
      8,9]
   A<mark>*</mark>B
   B*A
  %can be multiplied
A =
   5 1 9
7 2 2
B =
   8 5
ans =
 116 108
80 57
ans =
  75 18 82
34 8 40
103 26 90
```

### Part 2ii4 Code and Answer

```
A=[1,9,8;
         8,4,7;
         2,5,3]
   B<u>=</u>[7;
         1;
         5]
   A*B
   B*A
   %can't be multiplied
    56
    95
    34
Error using _*
Incorrect dimensions for matrix multiplication. Check that the
number of columns in the first matrix matches the number of
rows in the second \mathtt{matrix.}\ \mathtt{To}\ \mathtt{perform}\ \mathtt{elementwise}
multiplication, use '.*'.
Error in \underline{Part2ii4} (\underline{line 8})
Related documentation
```

# Part 2iiia Typed and Answer

Determinant of A = (-1)(2)-(3)(4)=-2-12=-14

## Part 2iiib Code and Answer

```
A = [-1 3; 4 2]
det(A)

A =

-1 3
4 2

ans =

-14
```

# Part 3. Practice 'Systems of Linear Equations' examples: Systems of equations - Gavin Binder

# Part 3ia Code and Answer

```
A = [-2 1; 1 1];

B = [3; 10];

X = inx(A)*B

X = A\B

x =

2.3333

7.6667

X =

2.3333

7.6667
```

# Part 3ib Code and Answer

```
A = [5 3 -1; 3 2 1; 4 -1 3]

B = [10; 4; 12]

x = iny(A)*B

X = A\B

A =

5 3 -1
3 2 1
4 -1 3

B =

10
4 12

x =

3.1613
-2.2581
-0.9677

X =

3.1613
-2.2581
-0.9677
```

### Part 3ii

```
A = [3 4 2 -1 1 7 1; 2 -2 3 -4 5 2 8; 1 2 3 1 2 4 6; 5 10 4 3 9 -2 1; 3 2 -2 -4 -5 -6 7; -2 9 1 3 -3 5 1; 1 -2 -8 4 2 4 5]

B = [42; 32; 12; -5; 10; 18; 17]

tic

x = inv(A)*B

toc

tic

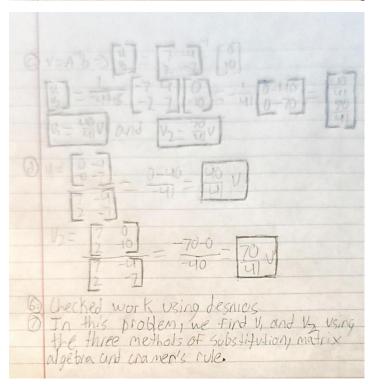
X = A\B

toc
```

Elapsed time is 0.000281 seconds.

Part 4. Intro to STEM application' Problem – electrical circuits – Gavin Binder Part 4a.

ANGLE
O An analysis of the circuit shoup in Fig. P7.7
yields the following system of aguations
1-4U+7V=0 (7.96)
24-74, 410-0 (197)
of find I and Us using the substitution method.
(5) write the system of equations (7.96) and (7.91) in
the matrix form AV = b, where V = 1/2
Perform all computations by hard and slow all
Steps.
A) Find U, and V2 using Clamer's rule.
20 By By Rh
201 101 101
VI RIBA RA VICTION
Q (7.96) and (2.97)
(1) AV=6 ) V= (V2)
(5) D71 = 4N2 2(472-7V2+10=0
V1=4V2 8 V2-7U2 =-10
100 P 10
V= 4(4) - 16 or 976 V2 = 30 or 1.707 V
6 7-4 VI - 0
2 -7 1/2 = -10



### Part 4b

### Code

### Test 1

```
Input the value of R1: 5
Input the value of R2: 5
Input the value of R3: 5
Input the value of R4: 5
Input the value of R5: 5
Input the value of voltage: 0
```

#### I =

0

0

0

#### Test 2

```
Input the value of R1: 2
Input the value of R2: 4
Input the value of R3: 6
Input the value of R4: 8
Input the value of R5: 10
Input the value of voltage: 10
```

### I =

1.6935

0.9677

0.8065

#### Part 4c Code and Answer

```
coef = [7, -4;
      2, -7]
  result = [0; -10]
  v = inv(coef)*result
  V = coef\result
coef =
     7 -4
          -7
result =
     0
   -10
v =
    0.9756
    1.7073
v =
    0.9756
    1.7073
```

### Part 4d Code and Answer

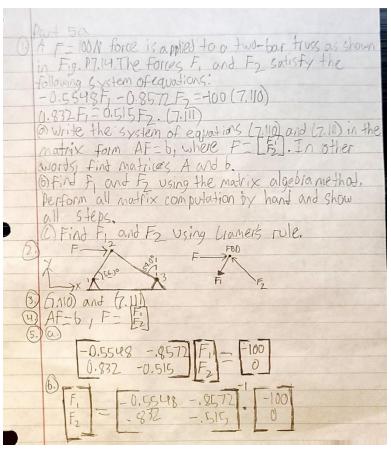
```
Input the value of R1: 2
Input the value of R2: 4
Input the value of R3: 6
Input the value of R4: 8
Input the value of R5: 10
Input the value of voltage: 10
```

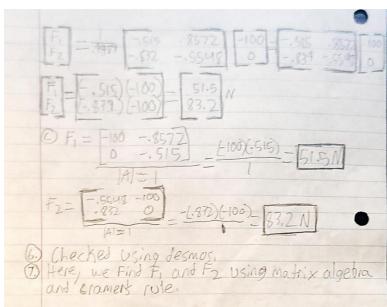
I =

- 1.6935
- 0.9677
- 0.8065

Part 5. Intro to STEM application' Problem – mechanical systems

Part 5a.





#### Part 5b.

### Test 1 Code and Answer

```
theta1=45
  theta2=45
  f1x=0
  f1y=-1000
  A=[-\cos d(\text{theta1}), \cos d(\text{theta2}), 0, 0, 0, 0]
      -sind(theta1),-sind(theta2),0,0,0,0
      cosd(theta1),0,1,1,0,0
      sind(theta1),0,0,0,1,0
      0,-cosd(theta2),-1,0,0,0
      0,sind(theta2),0,0,0,1]
  B = [f1x, -f1y, 0, 0, 0, 0]'
  x=(A\setminus B)'
thetal =
   45
theta2 =
   45
flx =
  0
fly =
     -1000
A =
  -0.7071 0.7071 0 0 0 0 0 -0.7071 -0.7071 0 0 0
                                              0
                                       0
                                               0
  в =
      1000
        0
         0
-707.1068 -707.1068 500.0000 0 500.0000 500.0000
```

### Test 2 Code and Answer

```
theta1=30
         theta2=60
         f1x=1000
         f1y=0
         A=[-\cos d(\text{theta1}), \cos d(\text{theta2}), 0, 0, 0, 0]
                        -sind(theta1),-sind(theta2),0,0,0,0
                        cosd(theta1),0,1,1,0,0
                        sind(theta1),0,0,0,1,0
                        0,-cosd(theta2),-1,0,0,0
                        0,sind(theta2),0,0,0,1]
         B=[f1x,-f1y,0,0,0,0]'
         x=inv(A)*B
        x=A\B
fly =
              0
A =

        -0.8660
        0.5000
        0
        0
        0
        0

        -0.5000
        -0.8660
        0
        0
        0
        0
        0

        0.8660
        0
        1.0000
        1.0000
        0
        0
        0
        0

        0.5000
        0
        0
        0
        0
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        0
        0</t
B =
                       1000
                               0
                               0
                               0
x =
      1.0e+03 *
       -0.8660
       0.5000
       -0.2500
          1.0000
         0.4330
       -0.4330
       1.0e+03 *
      -0.8660
        0.5000
       -0.2500
          1.0000
         0.4330
        -0.4330
```

# Part 5c. Code and Answer

```
coef = [-0.5548, -0.8572;
    0.832, -0.515]
  result 💂 [-100; 0]
  f = inv(coef)*result
  F = coef\result
coef =
  -0.5548 -0.8572
   0.8320 -0.5150
result =
 -100
    0
f =
  51.5561
  83.2906
F =
  51.5561
```

83.2906

#### Part 5d Code and Answer

```
theta1=59.0
      theta2=56.3
      f1x=0
      f1y=-100
      A=[-\cos d(\text{theta1}), \cos d(\text{theta2}), 0, 0, 0, 0]
              -sind(theta1),-sind(theta2),0,0,0,0
              cosd(theta1),0,1,1,0,0
              sind(theta1),0,0,0,1,0
              0,-cosd(theta2),-1,0,0,0
              0,sind(theta2),0,0,0,1]
      B=[f1x,-f1y,0,0,0,0]
      F=(A\B)'
thetal =
      59
theta2 =
   56.3000
flx =
fly =
 -100
A =

        -0.5150
        0.5548
        0
        0
        0
        0

        -0.8572
        -0.8320
        0
        0
        0
        0

        0.5150
        0
        1.0000
        1.0000
        0
        0

        0.8572
        0
        0
        0
        1.0000
        0

        0
        -0.5548
        -1.0000
        0
        0
        0

        0
        0.8320
        0
        0
        0
        1.0000

B =
        0
     100
         0
         0
F =
   -61.3710 -56.9680 31.6084 -0.0000 52.6052 47.3948
```

### Part 6. Reflection on P3F group 'collaboration' activities – Gavin Binder

- A. My group included Jeffrey Hsu and Phoenix Martin. Other than some help with MATLAB code, there where no other points of assistance.
- B. MATLAB could be very useful in calculating derivates, including finding maxima and minima values. You could also do integration in MATLAB, likely making complicated problems much easier. —Gavin Binder
  - MATLAB could be a useful STEM tool because it can do all sorts of calculations which may be necessary for the field. Projects that would normally take time to write out and calculate by hand can be finished and replicated by MATLAB should one take the time to set up code for it. -Phoenix Martin