Gavin Vasandani

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Education

Imperial College London, Master of Engineering, Computer Engineering

Oct 2021 - Jun 2025

- Combined degree in Department of Electrical Engineering and Department of Computing.
- Achieved First-Class Honours (equivalent to 4.0 GPA) in 1st and 2nd year.
- Relevant Modules: Discrete Math, Instruction Architectures and Compilers, System Performance Engineering

Professional & Research Experience

AMD (Advanced Micro Devices) Inc., Software and Hardware Engineering Intern

Jun 2023 - Sept 2023

- Intern in the Platform IP team within AMD's Adaptive and Embedded Computing Group.
- *Project 1*: Created SystemVerilog and C++ testbenches to verify CMS Subsystem IP, responsible for monitoring AMD Xilinx's Alveo acceleration card performance.
- Verified IP on 5 major simulators (XSim, VSA, Riviera) and committed on Vivado 2023.2.
- *Project 2*: Developed a 16-bit CRC, an error-detecting program, on C++ to implement on the CMS Subsystem.
- *Project 3:* Developed and deployed a script to generate randomized hardware configuration files from a YAML parameter file for the CMS Subsystem, accelerating time to reach complete functional coverage.

Provise Cybersecurity Firm, Software Engineering Intern

Jun 2022 – Oct 2022

- *Project 1:* Built inhouse tools using Bash to automate build processes. Summarized status of builds and created pipeline to notify engineers involved.
- *Project 2:* Created custom memory allocator and profiler in C++ to analyze suspicious memory changes due to malware.
- Tools helped evaluate cybersecurity threats for major telecom, banking, and energy firms.

Jane Street IN FOCUS, Software Engineering Track

Apr 2022 - May 2022

- Project 1: Learned functional programming using OCaml and developed backend for a snake game.
- *Project 2:* Created a trading bot in C++ that exploits discrepancies in the price of an ADR pair. Determined ADR's fair value through moving average. Achieved 6th in Jane Street's Electronic Trading Competition.

Institute of Photonic Sciences, Quantum Computing and Engineering, Student Research Intern

Jun 2019 – Aug 2019

- Selected as a student researcher from the Middle East for the Barcelona International Youth Science Competition.
- *Project 1:* Conducted an experiment to validate the BB84 quantum key distribution protocol. Directed a laser through polarizers with confidential orientations shared only between the sender and receiver and created a decryption program in C to decrypt the incoming light signals.

NASA Wallops Flight Center, Satellite Projects, Student Research Intern

Jun 2018 – Sept 2018

- $\bullet \ Synthesized \ a \ nitrogen-doped \ double-walled \ carbon \ nanotube \ epoxy \ resin \ for \ radiation \ shielding \ in \ manned \ spaceflight.$
- Project was selected by Cubes in Space & NASA and launched on their RB-4 research satellite from NASA Wallops Flight Center, Virginia, USA to higher Earth Orbit.

Projects

RISC-V Processor (SystemVerilog, C++)

• Designed a RISC-V processor with its complete instruction set architecture and improved processor efficiency by implementing 5-stage pipelining and 2-way associative cache with LRU replacement.

C90 to RISCV Assembly Compiler (C, Assembly)

- Developed C90 to RISCV compiler with support for arrays, recursion, and floating-point arithmetic.
- Improved memory allocation with static memory analysis and added a stack simulator for RISC-V memory emulation.
- Created scripts for automated testing and an AST visualizer for debugging.
- Passed 90% of testcases.

C++ Trading Platform (C++, Asio, Bash)

- Developed a multi-client, server trading platform using Asio Networking Library with custom memory management.
- Created and hosted price-time priority orderbook with pro-rata matching.
- Simulated market liquidity by creating market maker bots to provide buy and sell orders.

<u>Self-balancing 2-Wheeled Autonomous Rover</u> (C, JavaScript w/ Node.js)

- Developed multithreaded C++ program on ESP32 dual-core microcontroller to retrieve sensor data and predict motor movement in parallel.
- Implemented software interrupts and ISR's for immediate motor movements in response to sensor readings, enabling real-time self-balancing.
- Developed a 'mission control' web app using Node.js and hosted on AWS with real-time updating of rover movements.

Programming Languages

Advanced in C++, SystemVerilog, Bash, MATLAB, Swift. Intermediate in OCaml, Python, SQL.

Tools: GDB, Valgrind, Cppcheck, Viper

Technologies: Git, Docker, Perforce, JIRA, Confluence, Swarm, AWS