## CS3223 AY23/24 SEM 2

Notation	Meaning
r	relational algebra expression
r	number of tuples in output of r
r	number of pages in output of r
b <sub>d</sub>	number of data records that can fit on a page
$b_i$	number of data entries that can fit on a page
F	average fanout of B <sup>+</sup> -tree index (i.e., number of pointers to child nodes)
h	height of B+-tree index (i.e., number of levels of internal nodes)
	$h = \lceil \log_F(\lceil \frac{  R  }{b_i} \rceil) \rceil$ if format-2 index on table $R$
В	number of available buffer pages

Data entry formats: 1. actual data record: 2. (k. RID) - fixed length (k. •): 3. (k. RID-list) - e.g. (k. {RID11, RID12})

### 04.1 SORTING

- clustered index → order of data entries ≈ data records
  - > 1 per relation: format 1 is always clustered

## External Merge Sort

- sorted run → sorted data records written to a file on disk
  - 1. create temporary file  $R_i$  for each B pages of R sorted 2. merge: use B-1 pages for input, 1 page for output
- total I/O =  $2N(\lceil \log_{B-1}(N_0) \rceil + 1)$
- 2N to create  $\lceil N/B \rceil$  sorted runs of B pages each
- merging sorted runs:  $2N \times \lceil \log_{B-1} N_0 \rceil$

#### optimisation with blocked I/O

- sequential I/O read/write in buffer blocks of b pages
- one block (b pages) for output, remaining blocks for input
  - number of runs merged per pass,  $F = \left| \frac{B}{L} \right| 1$
  - number of passes =  $\lceil \log_E(N_0) \rceil + 1$

## Sorting with B<sup>+</sup>-trees

- when sort key is a prefix of the index key of the B<sup>+</sup>-tree
- sequentially scan leaf pages of B<sup>+</sup>-tree
- for Format-2/3, use RID to retrieve data records

# **04.2 SELECTION:** $\sigma_n(R)$

- $\sigma_p(R)$  selects rows from relation R satisfying predicate p
- selectivity of an access path → number of index & data pages retrieved (more selective = fewer pages retrieved)
- covering index I for Q → if all attributes referenced in Q are part of the key of I (index-only plan: no RID lookup)

# Matching Predicates

- term  $\rightarrow$  of form R.A op c or  $R.A_i$  op  $R.A_i$
- conjunct → > 1 terms connected by ∨ (disjunctive: > 1)
- CNF predicate → one or more conjuncts connected by ∧



#### B<sup>+</sup>-tree matching predicates

• for index  $I = (K_1, K_2, \dots, K_n)$  and non-disjunctive CNF predicate p. I matches p if p is of the form

$$\underbrace{\left(K_{1}=c_{1}\right)\wedge\cdots\wedge\left(K_{i-1}=c_{i-1}\right)}_{\text{zero or more equality predicates}}\wedge\left(K_{i}\text{ op}_{i}\text{ }c_{i}\right),\ i\in\left[1,n\right]$$

 matching index: matching records are in contiguous pages Hash index matching predicates

• hash index I matches p if p is of form  $(K_1=c_1) \wedge (K_2=c_2) \wedge \cdots \wedge (K_n=C_n)$ 

# Primary/Covered Conjuncts

- **primary conjuncts**  $\rightarrow$  subset of conjuncts that I matches
- e.g.  $p = (A > 18) \land (A < 20) \land (W=65)$  for I = (A,W,H)• **covered conjuncts**  $\rightarrow$  attribute appears in the key of I

## primary conjuncts ⊆ covered conjuncts Cost of Evaluation

let p' = primary conjuncts of p,  $p_c$  = covered conjuncts of p

#### B<sup>+</sup>-tree index evaluation of p

- 1. navigate internal nodes to find first leaf page  $\begin{array}{l} {\rm cost_{internal}} = \lceil \log_F(\lceil \frac{||R||}{b_{d\,{\rm or}\,i}} \rceil) \rceil \quad {\rm for\ format-1/otherwise} \\ {\rm 2.\ \ scan\ leaf\ pages\ to\ access\ all\ qualifying\ data\ entries} \end{array}$
- $\cos t_{\text{leaf}} = \lceil \frac{||\sigma_{p'}(R)||}{b_{d \text{ of } i}} \rceil \quad \text{for format-1/otherwise}$  3. retrieve qualified data records via RID lookups
- $\mathsf{cost}_{\mathsf{RID}} = ||\sigma_{p_c}(R)||$  or 0 if I is covering or format-1
- · reduce cost with clustered data records (sort RIDs):  $\lceil \frac{||\sigma_{p_c}(R)||}{b_d} \rceil \le \mathsf{cost}_{RID} \le \min\{||\sigma_{p_c}(R)||, |R|\}$

#### hash index evaluation of p

- format-1: cost to retrieve data records  $\geq \lceil \frac{||\sigma_{p'}(R)||}{b_d} \rceil$  format-2: cost to retrieve data entries  $\geq \lceil \frac{||\sigma_{p'}(R)||}{b_c} \rceil$
- cost to retrieve data records = 0 if I is a covering index,

# **05.1 PROJECTION** $\pi_{A_1,\ldots,A_m}(R)$

- $\pi_L(R)$  eliminates duplicates,  $\pi_L^*(R)$  preserves duplicates
- can **index scan** if index contains the attributes as a prefix

# Sort-based approach

 $||\sigma_{p_c}(R)||$  otherwise

#### cost analysis

- 1. extract attributes:  $|R| \operatorname{scan} + |\pi_I^*(R)|$  output temp result
- 2. sort records:  $2|\pi_{I}^{*}(R)|(\log_{m}(\bar{N}_{0})+1)$
- 3. remove duplicates:  $|\pi_L^*(R)|$  to scan records

#### optimised sort-based approach

- 1. create sorted runs with projected attributes only
- 2. merge sorted runs and remove duplicates
- if  $B > \sqrt{|\pi_I^*(R)|}$ , same I/O cost as hash-based approach
  - $N_0 = \lfloor \frac{|R|}{B} \rfloor \approx \sqrt{|\pi_L^*(R)|}$  initial sorted runs  $\log_{B-1}(N_0) \approx 1$  merge passes

# Hash-based approach

- 1. **partitioning phase**: hash each tuple  $t \in R$  to some  $R_i$ 
  - one buffer for input, (B-1) buffers for output
  - for each t: project attributes to form t', hash h(t') to one output buffer, flush output buffer to disk when full
- 2. **duplicate elimination** from each  $\pi_{\tau}^*(R_i)$ 
  - for each  $R_i$ : initialise in-mem hash table, hash each  $t \in R_i$  to bucket  $B_i$  with  $h' \neq h$ , insert if  $t \notin B_i$
  - · write tuples in hash table to results
- I/O cost (no partition overflow):  $|R| + 2|\pi_I^*(R)|$ 
  - partitioning cost:  $|R| + |\pi_T^*(R)|$
- duplicate elimination cost:  $|\pi_I^*(R)|$ · partition overflow: recursively apply partitioning

• to avoid, B > size of hash table for  $R_i = \frac{|\pi_L^*(R)|}{B-1} \times f$ • approximately  $B > \sqrt{f \times |\pi_L^*(R)|}$ 

# **05.2 JOIN** $R\bowtie_{\theta} S$

R =outer relation (smaller relation); S =inner relation

- ! for format-2 index. add cost of retrieving record
- tuple-based nested loop join:  $|R| + ||R|| \times |S|$
- page-based nested loop join:  $|R| + |R| \times |S|$
- block nested loop join:  $|R| + (\lceil \frac{|R|}{R-2} \rceil \times |S|)$ ,
  - 1 page output, 1 page input, (B-2) pages to read R
  - for each (B-2) pages of R: for each  $P_S$  of S: check
- index nested loop join: for joining  $R.A_i = S.B_i$

$$|R| + ||R|| \times \left(\log_F\left(\lceil \frac{||S||}{b_d} \rceil\right) + \lceil \frac{||S||}{b_d ||\pi_{B_j}(S)||} \rceil + c\right)$$

#### sort-merge join

- sort R & S:  $2|R|(\log_m(N_R) + 1) + 2|S|(\log_m(N_S) + 1)$ • merge cost: |R| + |S| (worst case  $|R| + |R| \times |S|$ )
- optimised sort-merge join
- merge sorted runs until B > N(R, i) + N(S, j); then join
- 3(|R| + |S|) = 2 + 1 (for initial sorted runs + merging) • if  $B > \sqrt{2|S|}$ , one pass to merge initial sorted runs
- Grace hash ioin

for build relation R and probe relation S,

- 1. **partition** R and S into k partitions each, k = B 1
- $\pi_A(R_i) \cap \pi_B(S_i) = \emptyset \quad \forall R_i, S_i, i \neq j$
- $R = R_1 \cup R_2 \cup \cdots \cup R_k$ ,  $t \in R_i \iff h(t.A) = i$
- 2. **probing phase**: hash  $r \in R_i$  with h'(r,A) to table T;  $\forall s \in S_i, r \in \text{bucket } h'(s.B)$ : output (r, s) if match
- $R \bowtie_{R,A=S,B} S = (R_1 \bowtie S_1) \cup \cdots \cup (R_k \bowtie S_k)$
- partition overflow if R<sub>i</sub> cannot fit in memory: recurse
- I/O cost: #Partition Phases  $\times$  2(|R| + |S|) + |R| + |S|•  $B>\frac{f imes|R|}{B-1}+2$  (input & output buffer)  $pprox B>\sqrt{f imes|R|}$
- during probing, B > size of each partition +2

# adapting join algorithms

- multiple equality-join conditions:  $(R.A=S.A) \land (R.B=S.B)$ 
  - index nested loop join: use index on some/all join attribs
- · sort-merge join: sort on combination of attributes • inequality-join conditions: (R.A < S.A)
- index nested loop join: requires B<sup>+</sup>-tree index
- · not applicable: sort-merge join, hash-based joins
- set operations
  - intersection:  $R(A,B) \cap S(A,B) = \pi_{R,A,R,B}(R \bowtie_p S)$
- cross product:  $R \times S = R \bowtie_{true} S$
- union/difference: duplicate elimination/slightly modified

## 06. QUERY EVALUATION

- aggregation: maintain running information while table scan
- · index scan if there is a covering index for the query · group-by: sort/hash to group by attributes then aggregate
- if group-by attributes are a B+tree prefix, just aggregate materialised evaluation
- · evaluates bottom-up; materialise intermediate results to
- x incurs I/O 
  √ simple implementation 
  √ less memory pipelined evaluation (top-down, demand-driven)

- interleaved execution of operators pass output directly to parent operator - can switch execution to where it is needed
- · blocking operator: can't produce output until all input tuples received (grace hash & sort-merge join, external mergesort)

### hybrid: pipelined evaluation + partial materialisation

· materialise if repeatedly scanned (e.g. nested loop join)

guery: > 1 logical plans: implemented by > 1 physical plans query plan trees

- linear > 1 operand per join operation is a base relation (else bushv)
- **left-deep** every right join operand is a base relation query optimisation
- binary operators (⋈, ×) are commutative & associative
- push selection and projection to operands first DP query plan enumeration: use all optimal sub-plans to build overall plan (single-relation  $\Rightarrow$  two-relation  $\Rightarrow \dots$ )

## System R Optimiser

- · enumerate only left-deep query plans; avoid cross-product query plans; consider early selections and projections
- DP + sort order  $o_i$  of query plan output:  $optPlan(S_i, o_i)$

#### cost estimation

- estimation assumptions
- 1. uniformity of distribn of attr values
- 2. independence for distribn of values in different attrs
- 3. inclusion for  $R \bowtie_{R,A=S,B} S$ , if  $||\pi_A(R)|| \le ||\pi_B(S)||$ , then  $\pi_A(R) \subseteq \pi_B(S)$  $\Rightarrow$  every R tuple joins with some S tuple
- size estimation for query  $q = \sigma_p(e), \quad p = t_1 \wedge \cdots \wedge t_n$ 
  - selectivity factor → fraction of tuples satisfying term
    - aka reduction factor,  $rf(t_i) = \frac{||\sigma_t(e)||}{||\Gamma_i||}$
  - $||q|| \approx ||e|| \times \prod_{i=1}^{n} rf(t_i)$
  - join selectivity estimation:
  - $rf(R.A = S.B) \approx \frac{1}{\max\{||\pi_A(R)||, ||\pi_B(S)||\}}$
  - given  $\pi_A(R) \leq \pi_B(S)$ :  $||Q|| = ||R|| \times \frac{||S||}{\pi_B(S)}$
- histogram estimation
  - equiwidth → ≈equal number of values per bucket
  - **equidepth**  $\rightarrow \approx$  equal number of *tuples* per bucket
- with MCV: keep a k/v pair of value/#tuples 07. TRANSACTION MANAGEMENT
- to ensure ACID properties of transactions →
- 1. atomicity either all or none of the actions happen 2. consistency - if each txn is consistent, and the DB starts consistent, then the DB ends up consistent
- 3. isolation execution of one txn is isolated from other
- 4. durability if txn commits, its effects persist
- view equivalent → same reads-from and final write
- view serialisable → view equiv to some serial schedule conflict → at least 1 write + different txns + same object
- conflict equivalent → all pairs of conflicting actions are ordered in the same way
- conflict serialisable → conflict equivalent to a serial sched

- 1. acyclic conflict serialisability graph (node: committed txn, edge: precedes and conflicts with any action)
- 2. conflict serialisable ⇒ view serialisable
- 3. view serialisable + no blind writes ⇒ conflict serialisable
  - blind write → did not read before write

anomalies arise due to conflicting actions

- · dirty read due to WR conflicts
- unrepeatable read due to RW conflict  $(R_1, W_2, R_1)$
- lost update due to WW conflict
- · phantom read re-executing a query on a search condition gives different results (prevent by predicate/index locking)

#### recovery

- cascading abort  $\rightarrow$  if  $T_1$  reads from  $T_2$ ,  $T_1$  must abort when  $T_2$  aborts (for correctness)
- **recoverable**  $\rightarrow$  if T reads from T', then T commits after
  - · guarantees that committed txns will not be aborted
- cascadeless  $\rightarrow$  whenever  $T_i$  reads from  $T_i$ ,  $Commit_i$ must precede this action
- all values read are produced by a committed transaction
- before-images: log before action & restore (must be strict)
- **strict**  $\rightarrow$  for every  $W_i(O)$  in S, O is not read/written by another txn until  $T_i$  either aborts or commits
- strict schedule ⇒ cascadeless ⇒ recoverable

# 08. CONCURRENCY CONTROL

# **Lock-based Concurrency Control**

# 2PL (Two Phase Locking)

- · may release locks any time
- · once a txn releases a lock, it cannot request any more locks
- growing/shrinking phase: before/after releasing 1<sup>st</sup>
- · prevents all anomalies, including phantom read

#### Strict 2PL

- Strict 2PL → txn must hold locks until it commits/aborts
- 2PL ⇒ conflict serialisable
- strict 2PL ⇒ strict & conflict serialisable

## **Lock Management**

### deadlocks

- deadlock detection: waits-for graph (WFG)
  - · nodes represent active txns
  - edge  $T_i \to T_j$  if  $T_i$  is waiting for  $T_j$  to release a lock
  - WFG has a cycle ⇒ deadlock
    - abort one transaction and its edges from WFG
- deadlock prevention: older = higher priority
  - wait-die policy → lower-priority aborts instead of
    - · less aggressive; younger txns may keep aborting
  - wound-wait policy → (preemptive) higher- aborts
    - · preemptive can abort another txn

Prevention Policy	revention Policy $   T_i$ has higher priority			
Wait-die	$T_i$ waits for $T_j$	T <sub>i</sub> aborts		
Wound-wait	$T_j$ aborts	$T_i$ waits for $T_j$		

· restarted txn uses original timestamp to avoid starvation

#### lock conversion

- increases concurrency; only in the growing phase
- lock upgrade,  $UG_i(A)$ : allowed if no other txn is holding a shared lock on A and  $T_i$  has not yet released any lock
  - · ensures serialisable schedule
- lock downgrade.  $DG_i(A)$ : allowed if  $T_i$  has not modified A and has not released any lock

#### **ANSI SQL Isolation Levels**

	Dirty	Unrepeatable	Phantom
Isolation Level	Read	Read	Read
READ UNCOMMITTED	possible	possible	possible
READ COMMITTED	not possible	possible	possible
REPEATABLE READ	not possible	not possible	possible
SERIALIZABLE	not possible	not possible	not possible

	Isolation	Write	Read	Predicate	
Degree	level	Locks	Locks	Locking	
0	Read Uncommitted	long duration	none	none	
1	Read Committed	long duration	short duration	none	
2	Repeatable Read	long duration	long duration	none	
3	Serializable	long duration	long duration	yes	

- short-duration lock → can be released before commit/abort
- long-duration lock → held until txn commits/aborts

### **Locking Granularity**

*I*-lock (intention)

- (coarsest/most granular) database > relation > page >
- multi-granular lock → can request different granularity • if T holds lock mode M on data granule D, then Timplicitly holds M on data granules finer than D
- before acquiring any S-/X-lock on G, must acquire I-locks on granules coarser than G in a top-down manner
- can be shared with other I-locks

Lock compatability matrix

 $\bullet$  × limited concurrency: S-lock is incompatible with I-lock

#### IS- and IX-lock (intention shared/exclusive)

- acquire locks top-down, release locks bottom-up
  - · to obtain S or IS lock: must hold IS or IX lock on parent
  - to obtain X or IX lock: must hold IX lock on parent

Look compatability matrix				Lock compatability matrix						
Lock	Lock Held				Lock	Lock Held				
Requested	-	IS	IX	S	Х	Requested	-	1	S	х
IS	V	V	<b>√</b>	V	×	1	П ,	,		×
IX	V	V	V	×	×	'	<b>V</b> .	<b>√</b>		
S	V	V	×	V	×	5	√	×	√	×
X	1	×	×	×	×	X	$   \sqrt{ }$	×	×	×

# 09. MULTIVERSION CONCURRENCY CONTROL (MVCC)

- · maintain multiple versions of each object
- $W_i(O)$  creates new version,  $R_i(O)$  reads some version
- ✓ read-only txns not blocked by update txns ✓ update txns not blocked by read-only txns √ read-only txns never aborted
- **multi-version** schedule  $\rightarrow$  read can return *any* version
- **mono-version**  $\rightarrow$  always reads most recent version
- multi-version view equivalent,  $S \equiv_{mv} S' \rightarrow$  same set of read-from relationships:
- $R_i(x_i) \in S \iff R_i(x_i) \in S'$ • final write doesn't matter (concept in monoversion only)

- mono-version schedule that is multi-version view equivalent mono-version view serialisable ⇒ MVSS
- VSS  $\subseteq$  MVSS; VSS  $\Rightarrow$  MVSS; MVSS  $\not\Rightarrow$  VSS

multi-version view serialisable (MVSS) → exists a serial

### Snapshot Isolation

- each txn T sees a snapshot of the DB comprising updates by transactions that committed before T starts
- concurrent txns → overlap, defined by start(T)/commit(T)
- protocol: O<sub>i</sub> is more recent if commit(T<sub>i</sub>) is later
  - $W_i(O)$  creates version i of O
- $R_i(O)$  reads either its latest  $W_i(O)$  or the latest version of O created by a txn that committed before
- concurrent update property: if multiple concurrent txn update the same object, only 1 commits (ensure serialisable)
  - FCW (first committer wins): commit ← no committed concurrent txn on updated object
  - FUW (first updater wins): acquire X-lock to update
    - T proceeds iff all concurrent T' (previously holding the X-lock) aborts and O has not been updated by any concurrent txn. / else abort T
- garbage collection: if not read by any (active/future) txn
  - delete  $O_i$  if there exists a newer  $O_i$  (commit( $T_i$ ) < commit $(T_i)$ ) such that for every active txn  $T_k$  that started after commit( $T_i$ ), we have commit( $T_i$ ) <  $start(T_k)$
- performance: √ similar to READ\_COMMITTED but without lost update or unrepeatable read anomalies
- x ≠ serialisability (some non-serialisable executions)
  - $\bullet$  write skew anomaly:  ${\scriptstyle R_1(x_0),R_2(y_0),W_1(y_1),W_2(x_2)}$
- read-only txn anomaly:  $T_3 \xrightarrow{rw} T_2 \xrightarrow{rw} T_1 \xrightarrow{wr} T_3$ x does not guarantee serialisability

#### Serialisable Snapshot Isolation (SSI)

- ensures MVSS
- detect  $T_i \xrightarrow{rw} T_i \xrightarrow{rw} T_k$  and abort one of  $T_i, T_i, T_k$ 
  - · keeps track of rw dependencies; possible false

#### transactional dependencies: ww, wr, rw

- immediate successor → no W(x) commits betw commits
- dependency serialisation graph, DSG
  - · nodes: (committed) transactions
  - edges: transactional dependencies, e.g.  $T_i \xrightarrow{wr} T_i$ • --→/→ for concurrent/non-concurrent
- ullet if S is a SI schedule that is not MVSS, then
- there is at least one cycle in DSG(S)
- for each cycle in DSG(S),  $\exists T_i, T_j, T_k$  such that •  $T_i \xrightarrow{rw} T_i \xrightarrow{rw} T_k$  exists
- $T_i$  and  $T_k$  may be same txn (eg. write-skew anomaly)

## 10. CRASH RECOVERY

- recovery manager guarantees atomicity and durability
- · undo: preserve atomicity (remove effects of aborts) redo: durability (re-install effects of commits)
- steal policy → can write dirty page to disk before commit force policy → must write all dirty pages to disk at commit

- No-force undo & no redo undo & redo No-steal no undo & no redo no undo & redo
- · no-steal: may run out of buffer pages
  - · force: incur random

### **ARIES Recovery Algorithm**

- steal; no-force; assumes strict 2PL for concurrency control
- transaction table (TT) 1 entry for each active txn (txn ID, last LSN, C/U status)
- dirty page table (DPT) (pageID, recLSN) = earliest LR that dirtied page
- log records: (type, txn ID, prevLSN, undoNextLSN)
- write-ahead logging (WAL) protocol → do not flush uncommitted update to DB until log record containing before-image is flushed to log (abort)
- force-at-commit protocol → do not commit txn until the after-images of all its updated records are in stable storage
- (! redoable) = update LR and compensation LR
- · All types of log records must have type, txnID, prevLSN

#### implementing restart

- 1. analysis phase TT (active txns) & DPT (superset of dirty)
- 1.1. initialise TT & DPT (retrieve ECPLR from BCPLR)
- 1.2. for each r in log file in forward direction/chronological
  - if end LR, remove T from TT; continue
  - if redoable LR for P and P not in DPT:
  - create P's entry in DPT with recLSN=r.LSN
  - add or update entry for T in TT: lastLSN = r.LSN • if commit LR: update status=C
- 2. **redo phase** restore DB to state at time of crash
- 2.1. start from redoLSN = smallest recLSN in DPT 2.2. scan in forward direction for all redoable LR
  - i. if not redoable or NOT optimisation cond: continue
  - ii. if P.pageLSN < r.LSN: (r has not been installed)
    - reapply logged action in r to P
    - update P.pageLSN = r.LSN
  - iii. (optimisation) else: recLSN ≤ r.LSN ≤ P.pageLSN
    - update P in DPT: recLSN=P.pageLSN+1
- 2.3. create end LR for all status=C in TT: remove entry optimisation cond: (P ∉ DPT) or (DPT P.recLSN >
  - update of r has already been applied to P
- 3. **undo phase** abort **loser** txns (active at crash) in *reverse*
- 3.1. initialise L = set of lastLSN (status=U) from TT
- update-L-and-TT(LSN) := if LSN is not null, add to L; else create end LR for T and remove T from TT
- 3.2. while  $L \neq \emptyset$ :
  - i. r = largest lastLSN in L; delete r from L
  - ii. if *r* is *update LR* for T on P:
  - create  $CLR r_2$  with  $r_2$ .undoNextLSN=r.prevLSN
  - update TT: T.lastLSN=r<sub>2</sub>.LSN
  - create DPT entry for P with recLSN= $r_2$ .LSN if P not in DPT
  - undo logged action and update P.pageLSN= $r_2$ .LSN
  - update-L-and-TT(r.prevLSN)
  - iii. else if r is CLR: update-L-and-TT(r.undoNextLSN)
- iv. else r is abort LR: update-L-and-TT(r.prevLSN)