MA1521

AY20/21 Sem 1 by jovyntls

01. FUNCTIONS & LIMITS

Rules of Limits

- 1. $\lim_{x \to a} (f \pm g)(x) = L \pm L'$
- $2. \lim_{x \to a} (fg)(x) = LL'$
- 3. $\lim_{x \to a} \frac{f}{g}(x) = \frac{L}{L'}$, provided $L' \neq 0$
- 4. $\lim_{x \to \infty} kf(x) = kL$ for any real number k.

02. DIFFERENTIATION

extreme values:

- f'(x) = 0
- f'(x) does not exist
- \bullet end points of the domain of f

parametric differentiaton: $\frac{d^2y}{dx^2}=\frac{d}{dx}(\frac{dy}{dx})=\frac{\frac{d}{dt}(\frac{dy}{dx})}{\frac{dx}{dx}}$

Differentiation Techniques

f(x)	f'(x)		
$\tan x$	$\sec^2 x$		
$\csc x$	$-\csc x \cot x$		
$\sec x$	$\sec x \tan x$		
$\cot x$	$-\csc^2 x$		
$a^{f(x)}$	$\ln a \cdot f'(x) a^{f(x)}$		
$\log_a f(x)$	$\log_a e \cdot \frac{f'(x)}{f(x)}$		
$\sin^{-1} f(x)$	$\frac{f'(x)}{\sqrt{1-[f(x)]^2}}, f(x) < 1$		
$\cos^{-1} f(x)$	$-\frac{f'(x)}{\sqrt{1-[f(x)]^2}}, f(x) < 1$		
	$\frac{f'(x)}{1+[f(x)]^2}$		
$\cot^{-1} f(x)$	$-rac{f'(x)}{1+[f(x)]^2}$		
$\sec^{-1} f(x)$	$\frac{f'(x)}{ f(x) \sqrt{[f(x)]^2 - 1}}$		
$\csc^{-1} f(x)$	$-\frac{f'(x)}{ f(x) \sqrt{[f(x)]^2-1}}$		

L'Hopital's Rule

$$\lim_{x \to x_0} \frac{f(x)}{g(x)} = \lim_{x \to x_0} \frac{f'(x)}{g'(x)}$$

- for indeterminate forms $(\frac{0}{0} \text{ or } \frac{\infty}{\infty})$, cannot directly substitute
- for other forms: convert to $(\frac{0}{0} \text{ or } \frac{\infty}{\infty})$ then apply L'Hopital's
- for exponents: use \ln , then sub into $e^{f(x)}$

03. INTEGRATION

Integration Techniques

f(x)	$\int f(x)$
$\tan x$	$\ln(\sec x)$, $ x < \frac{\pi}{2}$
$\cot x$	$\ln(\sin x),_{0} < x < \pi$
$\csc x$	$-\ln(\csc x + \cot x), 0 < x < \pi$
$\sec x$	$\ln(\sec x + \tan x), x < \frac{\pi}{2}$
$\frac{1}{x^2+a^2}$	$\frac{1}{a} \tan^{-1}(\frac{x}{a})$
$\frac{1}{\sqrt{a^2-x^2}}$	$\sin^{-1}\left(\frac{x}{a}\right)$, $ x < a$
$\frac{1}{x^2 - a^2}$	$\frac{1}{2a}\ln\left(\frac{x-a}{x+a}\right), x > a$
$\frac{1}{a^2 - x^2}$	$\frac{1}{2a}\ln(\frac{x+a}{x-a}), x < a$
a^x	$\frac{a^x}{\ln a}$

$$\frac{d}{dx} \int_{a}^{x} f(t)dt = f(x)$$

- indefinite integral the integral of the function without any limits
- antiderivative any function whose derivative will be the same as the original function

substitution: $\int_a^b f(g(x))g'(x)dx = \int_{g(a)}^{g(b)} f(u)du$ by parts: $\int uv' dx = uv - \int u'v dx$

Volume of Revolution

about x-axis:

- (with hollow area) $V = \pi \int_a^b [f(x)]^2 [g(x)]^2 dx$
- (about line y = k) $V = \pi \int_a^b [f(x) k]^2 dx$

04. SERIES

Geometric Series

sum (divergent)	
$a(1-r^n)$	
1 - r	

sum (convergent)

Power Series

power series about x=0

$$\sum_{n=0}^{\infty} c_n x^n = c_0 + c_1 x + c_2 x^2 + \dots$$

power series about x = a (a is the centre of the power series)

$$\sum_{n=0}^{\infty} c_n x^n = c_0 + c_1(x-a) + c_2(x-a)^2 + \dots$$

Taylor series

$$\sum_{k=0}^{\infty} \frac{f^k(a)}{k!} (x-a)^k$$

 $f(x) = \sum_{n=0}^{\infty} \frac{f^n(0)}{n!} x^n$

Taylor polynomial of f at a:

$$P_n(x) = \sum_{k=0}^{n} \frac{f^k(a)}{k!} (x-a)^k$$

Radius of Convergence

power series converges where $\lim_{n\to\infty} \left| \frac{u_{n+1}}{u_n} \right| < 1$

converge at	R	$\lim_{n \to \infty} \left \frac{u_{n+1}}{u_n} \right $
x = a	0	∞
(x-h,x+h)	$h, \frac{1}{N}$	$N \cdot x-a $
all x	∞	0

MacLaurin Series

$$\begin{aligned} & \text{For } -\infty < x < \infty \\ & \sin x = \sum_{n=0}^{\infty} \frac{(-1)^n x^{2n+1}}{(2n+1)!} \\ & \cos x = \sum_{n=0}^{\infty} \frac{(-1)^n x^{2n}}{(2n)!} \\ & e^x = \sum_{n=0}^{\infty} \frac{x^n}{n!} \\ & \text{For } -1 < x < 1 \end{aligned}$$

$$\frac{1}{1-x} = \sum_{n=0}^{\infty} x^{n}$$

$$\frac{1}{1+x} = \sum_{n=0}^{\infty} (-1)^{n} x^{n}$$

$$\frac{1}{1+x^{2}} = \sum_{n=0}^{\infty} (-1)^{n} x^{2n}$$

$$\ln(1+x) = \sum_{n=1}^{\infty} \frac{(-1)^{n-1} x^{n}}{n}$$

$$\tan^{-1} x = \sum_{n=0}^{\infty} \frac{(-1)^{n}}{2n+1} x^{2n+1}$$

$$\frac{1}{(1+x)^{2}} = \sum_{n=1}^{\infty} (-1)^{n-1} n x^{n-1}$$

$$\frac{1}{(1-x)^{2}} = \sum_{n=1}^{\infty} n x^{n-1}$$

$$\frac{1}{(1-x)^{3}} = \frac{1}{2} \sum_{n=2}^{\infty} n(n-1) x^{n-2}$$

$$(1+x)^{k} = \sum_{n=0}^{\infty} {k \choose n} x^{n}$$

$$= 1 + kx + \frac{k(k-1)}{2!} x^{2} + \dots$$

Differentiation/Integration

For
$$f(x) = \sum_{n=0}^{\infty} c_n (x-a)^n$$
 and $a-h < x < a+h$, differentiation of power series:

$$f'(x) = \sum_{n=0}^{\infty} nc_n (x-a)^{n-1}$$

$$\int f(x)dx = \sum_{n=0}^{\infty} c_n \frac{(x-1)^{n+1}}{n+1} + c$$

if $R = \infty$, f(x) can be integrated to $\int_0^1 f(x)dx$

05. VECTORS

unit vector,
$$\hat{m p}=rac{m p}{|m p|}$$



 $p = \frac{\mu a + \lambda b}{\lambda + \mu}$

midpoint theorem

Dot product

$$egin{aligned} oldsymbol{a} \cdot oldsymbol{b} &= |oldsymbol{a}||oldsymbol{b}||\cos heta \ inom{a_1}{a_2} &\cdot inom{b_1}{b_2} &= a_1b_1 + a_2b_2 + a_3b_3 \ a \perp oldsymbol{b} \Rightarrow oldsymbol{a} \cdot oldsymbol{b} &= 0 \ a \parallel oldsymbol{b} \Rightarrow oldsymbol{a} \cdot oldsymbol{b} &= 0 \ a \parallel oldsymbol{b} \Rightarrow oldsymbol{a} \cdot oldsymbol{b} &= |oldsymbol{a}||oldsymbol{b}| \ a \cdot oldsymbol{b} > 0 : oldsymbol{a} \text{ is acute} \ a \parallel oldsymbol{b} \Rightarrow oldsymbol{a} \cdot oldsymbol{b} &= |oldsymbol{a}||oldsymbol{b}| \ a \cdot oldsymbol{b} > 0 : oldsymbol{a} \text{ is acute} \ a \cdot oldsymbol{b} < 0 : oldsymbol{a} \text{ is obtuse} \end{aligned}$$

Cross product

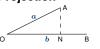
$$\mathbf{a} \times \mathbf{b} = |\mathbf{a}| |\mathbf{b}| \sin \theta \hat{\mathbf{n}}$$

$$\begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} \cdot \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix} = \begin{pmatrix} a_2b_3 - 1_3b_2 \\ -(a_1b_3 - a_3b_1) \\ a_1b_2 - a_2b_1 \end{pmatrix}$$

$$\mathbf{a} \perp \mathbf{b} \Rightarrow \mathbf{a} \times \mathbf{b} = |\mathbf{a}| |\mathbf{b}| \qquad \mathbf{a} \times \mathbf{b} = -(\mathbf{b} \times \mathbf{a})$$

$$\mathbf{a} \parallel \mathbf{b} \Rightarrow \mathbf{a} \times \mathbf{b} = 0 \qquad \lambda \mathbf{a} \times \mu \mathbf{b} = \lambda \mu (\mathbf{a} \times \mathbf{b})$$

Projection



$$egin{aligned} ullet |\overrightarrow{ON}| = |a \cdot \hat{b}| = rac{|a \cdot b|}{|b|} \ ullet \overrightarrow{ON} = (a \cdot \hat{b})\hat{b} = rac{|a \cdot b|}{|b|^2} \end{aligned}$$

Planes

Equation of a Plane

n is a perpendicular to the plane; A is a point on the plane.

- parametric: $r = a + \lambda b + \mu c$
- scalar product: $r \cdot n = a \cdot n$
- standard form: $\mathbf{r} \cdot \hat{\mathbf{n}} = d$
- cartesian: ax + by + cz = p

Length of projection of \boldsymbol{a} on $\boldsymbol{n}=|\boldsymbol{a}\cdot\hat{\boldsymbol{n}}|=\perp$ from O to π

Distance from a point to a plane

Shortest distance from a point $S(x_0, y_0, z_0)$ to a plane $\Pi : ax + by + c = d$ is given by: $|ax_0+by_0+cz_0-d|$ $\sqrt{a^2+b^2+c^2}$

06. PARTIAL DIFFERENTIATION

Partial Derivatives

For f(x, y),

first-order parțial derivatives:

$$f_x = rac{d}{dx} f(x,y)$$
 $f_y = rac{d}{dy} f(x,y)$ second-order partial derivatives:

$$f_{xx} = (f_x)_x = \frac{d}{dx} f_x$$

$$f_{yy} = (f_y)_y = \frac{d}{dy} f_y$$

$$f_{xy} = (f_x)_y = \frac{d}{dx} f_x$$

$$f_{yx} = (f_y)_x = \frac{d}{dx} f_y$$

Chain Rule

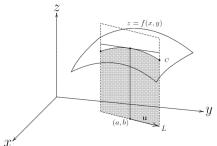
$$\begin{aligned} & \text{For } z(t) = f(x(t), y(t)), \\ & \frac{dz}{dt} = \frac{\partial z}{\partial x} \frac{dx}{dt} + \frac{\partial z}{\partial y} \frac{dy}{dt} \\ & \text{For } z(s,t) = f\left(x(s,t), y(s,t)\right), \\ & \frac{\partial z}{\partial t} = \frac{\partial z}{\partial x} \frac{\partial x}{\partial t} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial t} \\ & \frac{\partial z}{\partial s} = \frac{\partial z}{\partial x} \frac{\partial x}{\partial s} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial s} \end{aligned}$$

Directional Derivatives

The directional derivative of f at (a,b) in the direction of unit vector $\hat{\pmb{u}}=u_1\pmb{i}+u_2\pmb{j}$ is

$$D_u f(a,b) = f_x(a,b) \cdot u_1 + f_y(a,b) \cdot u_2$$

$$\vdots$$



• **geometric meaning**: $D_u f(a,b)$ is the gradient of the tangent at (a,b) to curve C on a surface z=f(x,y)• rate of change of f(x,y) at (a,b) in the direction of u

Gradient Vector

The **gradient** at
$$f(x, y)$$
 is the vector
$$\nabla f = f_x \mathbf{i} + f_y \mathbf{j}$$
$$D_u f(a, b) = \nabla f(a, b) \cdot \hat{\mathbf{u}}$$
$$= |\nabla f(a, b)| \cos \theta$$

- f increases most rapidly in the direction $\nabla f(a,b)$
- f decreases most rapidly in the direction $-\nabla f(a,b)$
- largest possible value of $D_u f(a,b) = |\nabla f(a,b)|$ • occurs in the same direction as $f_x(a,b) i + f_y(a,b) j$

Physical Meaning

Suppose a point p moves a small distance Δt along a unit vector $\hat{\boldsymbol{u}}$ to a new point \boldsymbol{q} .



increment in f, $\Delta f \approx D_u f(\boldsymbol{p})(\Delta t)$

Maximum & Minimum Values

f(x,y) has a **local maximum** at (a,b) if $f(x,y) \leq f(a,b)$ for all points (x,y) near (a,b).

f(x,y) has a **local minimum** at (a,b) if $f(x,y) \ge f(a,b)$ for all points (x,y) near (a,b).

Critical Points

- $f_x(a,b)$ or $f_y(a,b)$ does not exist; OR
- $f_x(a,b) = 0$ and $f_y(a,b) = 0$

Saddle Points

- $f_x(a,b) = 0, f_y(a,b) = 0$
- · neither a local minimum nor a local maximum

Second Derivative Test

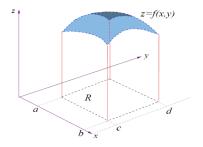
07. DOUBLE INTEGRALS

Let ΔA_i be the area of R_i and (x_i,y_i) be a point on R_i . Let f(x,y) be a function of two variables. The **double** integral of f over R is

$$\iint_{R} f(x,y)dA = \lim_{n \to \infty} \sum_{i=1}^{n} f(x_{i}, y_{i}) \Delta A_{i}$$

Geometric Meaning

 $\iint_R f(x,y) dA$ is the volume under hte surface z=f(x,y) and above the xy-plane over the region R.



Properties of Double Integrals

- 1. $\iint_{R} (f(x,y) + g(x,y)) dA$ $= \iint_{R} f(x,y) dA + \iint_{R} g(x,y) dA$
- $=\iint_R f(x,y)dA+\iint_R g(x,y)dA$ 2. $\iint_R cf(x,y)dA=c\iint_R f(x,y)dA, \text{ where } c \text{ is a constant}$
- 3. If $f(x,y) \geq g(x,y)$ for all $(x,y) \in \mathbb{R}$, then $\iint_{\mathbb{R}} f(x,y) dA \geq \iint_{\mathbb{R}} g(x,y) dA$
- 4. If $R = R1 \cup R2$, R1 and R2 do not overlap, then $\iint_R f(x,y) dA = \iint_{R1} f(x,y) dA + \iint_{R2} f(x,y) dA$
- 5. The area of R,

 $A(R) = \iint_{R} dA = \iint_{R} 1 dA$

6. If $m \le f(x,y) \le M$ for all $(x,y) \in R$, then $mA(R) \le \iint_R f(x,y) dA \le MA(R)$

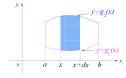
Rectangular Regions

For a rectangular region R in the xy-plane, $a \le x \le b, \quad c \le y \le d$

$$\begin{aligned} d & \leq x \leq b, \quad c \leq y \leq d \\ & \iint_R f(x,y) dA = \int_c^d \left[\int_a^b f(x,y) dx \right] dy \\ & = \int_a^b \left[\int_c^d f(x,y) dy \right] dx \\ & \text{If } f(x,y) = g(x) h(y), \text{ then } \\ & \iint_R g(x) h(y) dA = \left(\int_a^b g(x) dx \right) \left(\int_a^d h(y) dy \right) \end{aligned}$$

General Regions

Type A



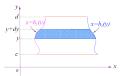
lower/upper bounds: $g_1(x) \le y \le g_2(x)$

left/right bounds: $a \le x \le b$

The region R is given by

$$\iint_{R} f(x,y)dA = \int_{a}^{b} \left[\int_{g_{1}(x)}^{g_{2}(x)} f(x,y)dy \right] dx$$

Type B

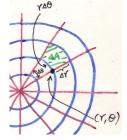


 $\begin{array}{c} \text{lower/upper bounds:} \\ c \leq y \leq d \end{array}$

left/right bounds: $h_1(y) \le x \le h_2(y)$

The region R is given by $\iint_R f(x,y)dA = \int_c^d \Big[\int_{h_1(y)}^{h_2(y)} f(x,y)dx \Big] dy$

Polar Coordinates



 $x = r \cos \theta$ $y = r \sin \theta$ $dxdy \Rightarrow rdrd\theta$

$$\Delta A \approx (r\Delta\theta)(\Delta r)$$
$$= r\Delta r\Delta\theta$$
$$dA = rdrd\theta$$

The region R is given by $R: a \leq r \leq b, \ \alpha \leq \theta \leq \beta$ $\iint_{R} f(x,y) dA = \int_{0}^{\beta} \int_{0}^{b} f(r\cos\theta, r\sin\theta) r \ dr d\theta$

Applications

Volume

Suppose D is a solid under the surface of z=f(x,y) over a plane region R $\text{Volume of } D=\iint_{\mathbb{R}}f(x,y)dA$

Surface Area

For area S of that portion of the surface z=f(x,y) that projects onto R, $S=\iint_{B}\sqrt{(\frac{\partial z}{\partial x})^{2}+(\frac{\partial z}{\partial y})^{2}+1}dA$

08. ORDINARY DIFFERENTIAL EQUATIONS

- general solution: solution containing arbitrary constants
- particular solution: gives specific values to arbitrary constants
- \bullet the general solution of the n-th order DE will have n arbitrary constants

Separable Equations

A first-order DE is **separable** if it can be written in the form M(x) - N(y)y' = 0 or M(x)dx = N(y)dy

Reductions to Separable Form

form	change of variable
$y' = g(\frac{y}{x})$	$ set v = \frac{y}{x} \\ \Rightarrow y' = v + xv' $
y' = f(ax + by + c) $\Rightarrow y' = \frac{ax + by + c}{\alpha x + \beta y + \gamma}$	set v = ax + by
y' + P(x)y = Q(x)	$R = e^{\int P dx}$ $\Rightarrow y = \frac{1}{R} \int RQ dx$
$y' + P(x)y = Q(x)y^n$	$\begin{array}{l} \operatorname{set} z = y^{1-n} \\ \Rightarrow y' = \frac{y^n}{1-n} z' \\ R = e^{\int P dx} \\ \Rightarrow y = \frac{1}{R} \int RQ dx \end{array}$

Population models

N - number; B - birth rate; t - time

$$N = \frac{ \underset{N_{t=\infty}}{\text{Logistic Model}}}{1 + (\frac{N_{t=\infty}}{N_{t=0}} - 1)e^{-Bt}}$$

Malthus Model $N(t) = N_0 e^{kt}$

Common Scenarios

uranium decays into thorium

amount of uranium,
$$U(t) = U_0 e^{-k_U t}$$

$$\frac{dU}{dt} = -k_U U$$
 amount of thorium,
$$T(t) = \frac{k_U U_0}{k_T - k_U} (e^{-k_U t} - e^{-k_T t})$$

$$\frac{dT}{dt} = k_U U - k_T T$$
 decay rate constant,
$$k = \frac{\ln 2}{t_{1/2}}$$
 ratio of thorium to uranium,
$$\frac{T}{U} = \frac{k_U}{k_T - k_U} (1 - e^{-(k_T - k_U)t})$$

Radioactive Decay

$Q(t) = Q_0 e^{-kt}$ $k = \frac{\ln 2}{t_{1/2}}$

Cooling/Heating

$$\frac{dT}{dt} = k(T - T_{env})$$

$$\frac{1}{T - T_{env}} dT = kdt$$

Falling objects (N2L)

$$m\frac{dv}{dt} = mg - bv^{2}$$

$$\text{Let } k = \sqrt{\frac{mg}{b}}$$

$$\Rightarrow \frac{1}{v^{2} - k^{2}} dv = -\frac{b}{m} dt$$

Resistance = bv^2

Resistive medium

Resistance =
$$kv$$
 $m\frac{dv}{dt} = mg - kv$ $v' + \frac{k}{m}v = g$ (linear)

Concentration of salt in liquid

Let R = rate of flow (in and out), Q = total amount of salt, V = total volume, C_{in} = concentration of inflow

Rate of flow,
$$\frac{dQ}{dt} = RC_{in} - \frac{R}{V}Q$$
 $\Rightarrow Q' + \frac{R}{V}Q = RC_{in}$