# Algorithms and Complexity

Dynamic programming

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### A counting problem

How many way are there to go up a staircase with n steps when you can go up one or two steps at a time?

#### Let F(n) be this number. Then

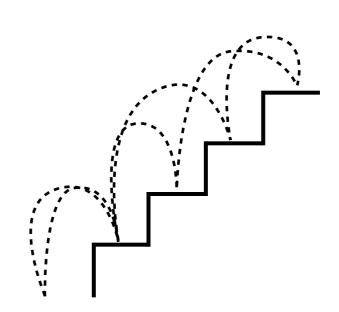
$$-F(0) = I$$

$$-F(1) = 1$$

$$-F(2) = 2$$

$$-F(3) = 3$$

$$-F(4) = 5$$



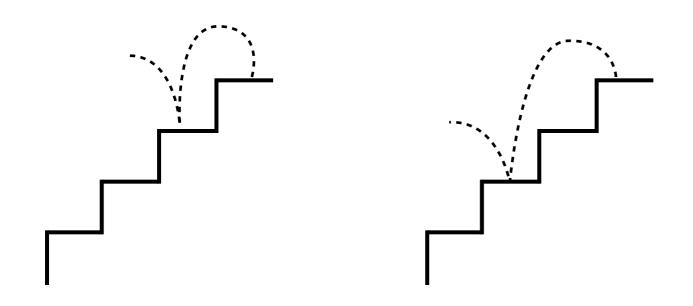
#### What's the pattern?



#### A counting problem

#### To see the pattern, condition on the last move

- There are F(n-1) ways of ending with a 1-step move
- There are F(n-2) ways of ending with a 2-step move



$$F(n) = F(n-1) + F(n-2)$$
 for  $n > 1$ 



## Time complexity

Let T(n) be the running time of our algorithm then

$$T(n) = T(n-1) + T(n-2) + O(1)$$
 for  $n > 1$ 

which is at least  $\Omega(2^{n/2})$ 

What can be done to speed up the algorithm?

Reuse computation!



### Iterative algorithm

```
def fib(n):

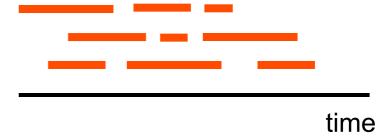
    M = array of length n + 1
    M[0] = 1
    M[1] = 1
    for i in range(2, n+1):
        M[i] = M[i-1] + M[i-2]
    return M[n]
```



## Weighted Interval Scheduling

#### Motivation:

- Users submitting requests to use some common resource (e.g., a classroom)
- Each request has a time window where the resource is needed
- Users cannot share the resource
- Users have priority



#### Input:

- Set of weighted intervals  $\{l_1, l_2, ..., l_n\}$  where  $l_i = (s(i), f(i))$  and  $w_i > 0$ 

#### Task:

- Find a maximum weight subset of intervals that do not intersect

### The structure of optimum

Assume intervals are sorted so that  $f_1 \le f_2 \le \cdots \le f_n$ 

Let OPT(i) be an optimal solution for intervals {1, ..., i}

Obs I: If interval  $n \notin OPT(n)$  then OPT(n) = OPT(n-1)

Obs 2: If interval  $n \in OPT(n)$  then  $OPT(n) = \{n\} \cup OPT(p(n))$ , where p(i) is the largest index such that  $f_{p(i)} \leq s_i$ 

Let M(i) be the value of the optimal solution then

$$M(i) = max \{ M(i-1), w(i) + M(p(i)) \}$$
 for  $i > 0$ 



# Recursive algorithm

```
def MWIS(intervals,w):
  def helper(i):
    if i == 0:
      return 0
    return max(helper(i-1),
               w[i] + helper(p[i])
  sort intervals in increasing f-value
  compute p-values for each interval
  return helper(n)
```



## Time complexity

Let T(n) be the running time of the algorithm. In the instance below p(i) = i - 2 for each i > 2 so

$$T(n) \ge T(n-1) + T(n-2) + O(1)$$

which be already saw is exponential!

time



#### Iterative algorithm

```
def MWIS(intervals,w):

    n = len(intervals)
    sort intervals in increasing f-value
    compute p-values for each interval

    M = array of length n + 1
    M[0] = 0
    for i in range(1, n+1):
        M[i] = max(M[i-1], w[i] + M[p[i]])
    return M[n]
```



## Time complexity

Sorting the intervals takes O(n log n) time

Computing the p-values can be done in O(n log n) time

There are n-2 iterations each taking O(1), so computing M takes O(n) time

Overall the algorithm runs in O(n log n) time



## What about finding the solution?

```
def MWIS(intervals,w):
  def helper(i):
    if i == 0:
      return []
    if M[i] == M[i-1]:
      return helper(i-1)
    else:
      return helper(p[i]) + [i]
  sort intervals in increasing f-value
  compute p-values for each interval
  compute M-values
  return helper(n)
```



### Longest increasing subsequence

#### Input:

- Unsorted array A with n numbers

#### Task:

- Find longest sequence  $i_1 < i_2 < \cdots < i_k$  such that  $A[i_1] < A[i_2] < \cdots < A[i_k]$ 





#### Motivation:

- You need to design an investment portfolio for yourself
- There are n investment options, each having associated a profit and cost.
- Investment decision are binary decision (all or nothing)
- Given your budget, find the best investment option

#### Input:

- Set of pairs  $(w_1, v_1)$ ,  $(w_2, v_2)$ , ...,  $(w_n, v_n)$  and knapsack capacity W

#### Task:

- Find  $S \subseteq \{1, ..., n\}$  maximizing v(S) subject to  $w(S) \leq W$ 



## Recap: Dynamic programming (DP)

#### DP algorithms have three distinctive ingredients

- A big subproblem is broken up into smaller subproblems
- The solution of a subproblem can be expressed recursively
- There is an ordering of the subproblems from "small" to "large" such that to solve a subproblem we only need the solution to "smaller" subproblems

Correctness depends on the correctness of the recurrence

Time complexity is usually dominated by
# of DP states \* time it takes to fill one state