

COMP2007/2907 - Algorithms

Course page: Blackboard and Ed

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Jessica McBroom Patrick Eades

Anton Jurisevic Shumin Kong

Gengxing Wang Hisham Husein

Mingshen Cai



Course book:

J. Kleinberg and E. Tardos Algorithm Design Addison-Wesley

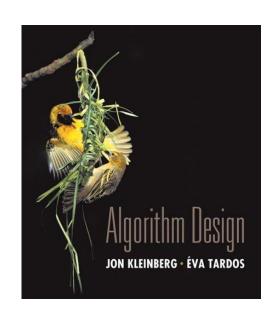
Outline:

12 lectures 5 assignments 10+1 quizzes Exam

Tutorials:

13 tutorials

Asymptotic Analysis
Running Time
Queue
Stack
Balanced Binary Tree







- This unit provides an introduction to the design and analysis of algorithms. Its main aims are
 - (i) learn how to develop algorithmic solutions to computational problem
 - (ii) develop understanding of algorithm efficiency.
- Assumes basic knowledge of discrete math
 - graphs
 - big O notation
 - proof techniques
 - and programming.



Assessment:

Quizzes 20% (average of best 8 out of 10) Each assignment 6% (5 assignments - total 30%) Exam 50% (minimum 40% required to pass)

Submissions:

Theory part - Blackboard (checked by Turnitin) Implementation - Ed

Collaboration:

General ideas - Yes!
Formulation and writing - No!
Read <u>Academic Dishonesty and Plagiarism.</u>





- > There will be 5 homework assignments
- The objective of these is to teach problem solving skills
- Each assignment represents 6% of your final mark. Late submissions will be penalized by 25% of the full marks per day.

```
For example, say you get 80% on your assignment: If submitted on time = 4.8

Late but within 24 hours = 4.8 * 0.75 = 3.6

Between 24 and 48 hours = 4.8 * 0.5 = 2.4

Between 48 and 72 hours = 4.8 * 0.25 = 1.2

More than 72 hours = 4.8 * 0 = 0
```





- The final will be 2.5 hours long. It will consist of 6 problems similar to those seen in the tutorials and assignments
- > The final will test your problem solving skills
- > There is a 40% exam barrier
- > The final exam represents 50% of your final mark
- Our advice is that you work hard on the assignments throughout the semester. It's the best preparation for the final.





- To get the most out of the tutorial, try to solve as many problems as you can before the tutorial. Your tutor is there to help you out if you get stuck, not to lecture.
- We will post solutions to tutorials (see Ed).



Preliminary schedule

- > Lecture 1 [Mon 31 July]: Introduction
- Lecture 2 [Mon 7 Aug]: Graphs
- > Lecture 3 [Mon 14 Aug]: Greedy algorithms
- Lecture 4 [Mon 21 Aug]: Divide & Conquer algorithms
- > Lecture 5 [Mon 28 Aug]: Sweepline algorithms
- > **Lecture 6** [Mon 4 Sep]: Dynamic programming: basic techniques
- > Lecture 7 [Mon 11 Sep]: Dynamic programming: interval scheduling and Bellman-Ford
- > Lecture 8 [Mon 18 Sep]: Network flows I: Theory

Mon 25 Sep: University break

Mon 2 Oct: Labour Day

- > Lecture 9 [Mon 9 Oct]: Network flows II: Applications
- > **Lecture 10** [Mon 16 Oct]: NP and intractability
- > Lecture 11 [Mon 23 Oct]: Coping with hardness
- > Lecture 12 [Mon 30 Oct]: Recap



Special Consideration (University policy)

- > If your performance on assessments is affected by illness or misadventure
- Follow proper bureaucratic procedures
 - Have professional practitioner sign special USyd form
 - Submit application for special consideration online, upload scans
 - Note you have only a quite short deadline for applying
 - http://sydney.edu.au/current_students/special_consideration/
- Also, notify coordinator by email as soon as anything begins to go wrong
- There is a similar process if you need special arrangements eg for religious observance, military service, representative sports



Academic dishonesty and plagiarism

- Please read the University policy on Academic Honesty carefully: http://sydney.edu.au/elearning/student/El/academic_honesty.shtml
- All cases of academic dishonesty and plagiarism will be investigated
- There is a new process and a centralized University system and database
- Three types of offenses:
 - Plagiarism when you copy from another student, website or other source. This
 includes copying the whole assignment or only a part of it.
 - Academic dishonesty when you make your work available to another student to copy (the whole assignment or a part of it). There are other examples of academic dishonesty.
 - Misconduct when you engage another person to complete your assignment (or a part of it), for payment or not. This is a very serious matter and the Policy requires that your case is forwarded to the University Registrar for investigation.





- The penalties are severe and include:
 - 1) a permanent record of academic dishonesty, plagiarism and misconduct in the University database and on your student file
 - 2) mark deduction, ranging from 0 for the assignment to Fail for the course
 - 3) expulsion from the University and cancelling of your student visa
- Do not confuse legitimate co-operation and cheating! You can discuss the assignment with another student, this is a legitimate collaboration, but you cannot complete the assignment together everyone must write their own code or report, unless the assignment is group work.
- When there is copying between students, note that both students are penalised – the student who copies and the student who makes his/her work available for copying





- We will use the similarity detection software TurnItIn and MOSS to compare your assignments with these of other students (current and previous) and the Internet
 - Turnitin is for text documents: http://www.turnitin.com/en_us/higher-education
 - MOSS is for programming code: https://theory.stanford.edu/~aiken/moss/
- These tools are extremely good!
 - e.g. MOSS cannot be fooled by changing the names of the variables or changing the order of the conditions in if-else statements
- Examples of plagiarism in programming code:
 - http://www.upenn.edu/academicintegrity/ai_computercode.html





- Plagiarism and any form of academic dishonesty will be dealt with, and the penalties are severe
- We use plagiarism detection systems such as MOSS that are extremely good. If you cheat, the chances you will be caught are very high.
- If someone asks you to see or copy your assignment, or to complete the
 assignment instead of them, just say: I can't do this we can both be thrown
 out of the University. I will not risk my future by doing this.

Be smart and don't risk your future by engaging in plagiarism and academic dishonesty!





- > There are a wide range of support services available for students
- > Please make contact, and get help
- > You are not required to tell anyone else about this



DISABILITY SERVICES

Do you have a disability?

- You may not think of yourself as having a 'disability' but the definition under the Disability Discrimination Act is broad and includes temporary or chronic medical conditions, physical or sensory disabilities, psychological conditions and learning disabilities.
- The types of disabilities we see include:
- anxiety, arthritis, asthma, asperger's disorder, ADHD, bipolar disorder, broken bones, cancer, cerebral palsy, chronic fatigue syndrome, crohn's disease, cystic fibrosis, depression, diabetes, dyslexia, epilepsy, hearing impairment, learning disability, mobility impairment, multiple sclerosis, post traumatic stress, schizophrenia, vision impairment, and much more.
- Students needing assistance must register with Disability Services —
- http://sydney.edu.au/study/academic-support/disability-support.html





- Learning support
 - http://sydney.edu.au/study/academic-support/learning-support.html
- International students
 - http://sydney.edu.au/study/academic-support/support-for-internationalstudents.html
- Aboriginal and Torres Strait Islanders
 - http://sydney.edu.au/study/academic-support/aboriginal-and-torres-strait-islander-support.html
- Student organization (can represent you in academic appeals etc)
 - http://srcusyd.net.au/ or http://www.supra.net.au/
- Please make contact, and get help
- You are not required to tell anyone else about this



- Metacognition
 - Pay attention to the learning outcomes in CUSP
 - Self-check that you are achieving each one
 - Think how each assessment task relates to these
- Time management
 - Watch the due dates
 - Start work early, submit early
- Networking and community-formation
 - Make friends and discuss ideas with them
 - Know your tutor and lecturer
- Enjoy the learning!

COMP2007/2907: Algorithms

Algorithms then, and now





What's in an algorithm?

- Algorithms can have huge impact
- For example -

A report to the White House from 2010 includes the following.

- Professor Martin Grotschel
 - A benchmark production planning model solved using linear programming would have taken 82 years to solve in 1988, using the computers and the linear programming algorithms of the day.
 - Fifteen years later, in 2003, this same model could be solved in roughly 1 minute, an improvement by a factor of roughly 43 million!

[Extreme case, but even the average factor is very high.]



What's in an algorithm?

- In 2003 there were examples of problems that we can solve 43 million times faster than in 1988
 - This is because of better hardware and better algorithms



What's in an algorithm?

- In 1988
 - Intel 386 and 386SX
 - About 275,000 transistors
 - clock speeds of 16MHz, 20MHz, 25MHz, and 33MHz
 - MSDOS 4.0 and windows 2.0
 - VGA

- In 2003
 - Pentium M
 - About 140 million transistors
 - Up to 2.2 GHz
 - AMD Athlon 64
 - Windows XP





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Observation:

- Hardware: 1,000 times improvement
- Algorithms: 43,000 times improvement

Efficient algorithms



- Efficient algorithms produce results within available resource limits
- In practice
 - Low polynomial time algorithms behave well
 - Exponential running times are infeasible except for very small instances, or carefully designed algorithms
- Performance depends on many obvious factors
 - Hardware
 - Software
 - Algorithm
 - Implementation of the algorithm
- This unit: Algorithms



Efficient algorithms

- Efficient algorithms "do the job" the way you want them to...
 - Do you need the exact solution?
 - Are you dealing with some special case and not with a general problem?
 - Is it ok if you miss the right solution sometimes?





Complex, highly sophisticated algorithms can greatly improve performance

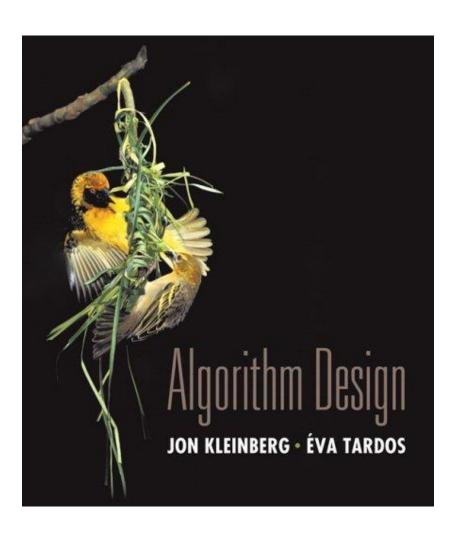
but...

 Reasonably good algorithmic solutions that avoid simple, or "lazy" mistakes, can have a much bigger impact! List of topics

Greedy algorithms
Divide and conquer
Sweepline
Dynamic programming
Network flows
Mincut theorems
Approximation
Optimization problems





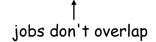


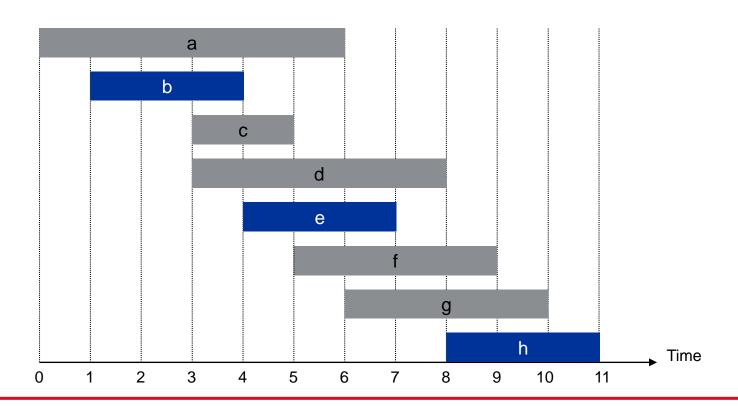
Introduction:
Some Representative
Problems



Four Representative Problems: Interval Scheduling

- > Input. Set of jobs with start times and finish times.
- Goal. Find maximum cardinality subset of mutually compatible jobs.

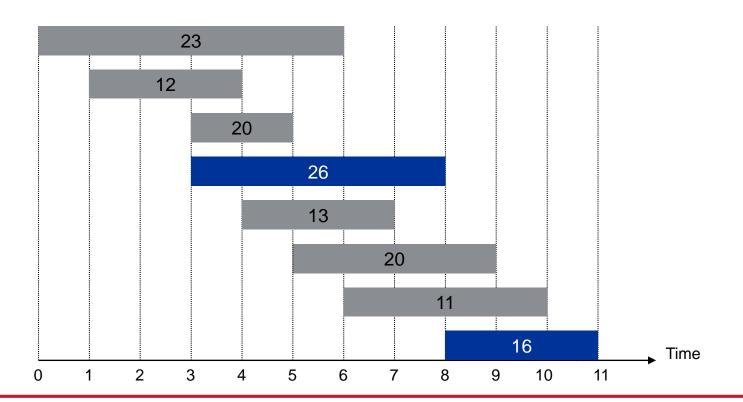






Weighted Interval Scheduling

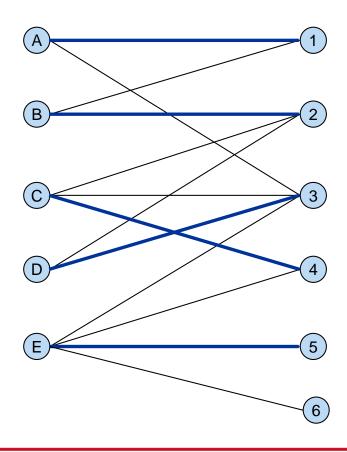
- > Input. Set of jobs with start times, finish times, and weights.
- Goal. Find maximum weight subset of mutually compatible jobs.







- > Input. Bipartite graph.
- > Goal. Find maximum cardinality matching.

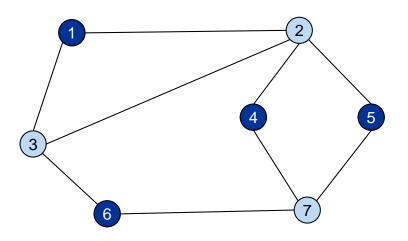






- > Input. Graph.
- > Goal. Find maximum cardinality independent set.

subset of nodes such that no two joined by an edge

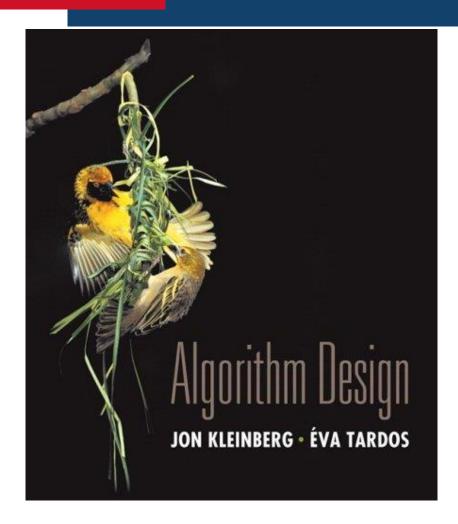




Four Representative Problems

- > Interval scheduling: O(n log n) time greedy algorithm.
- > Weighted interval scheduling: O(n log n) dynamic programming algorithm.
- Bipartite matching: O(n³) maxflow based algorithm.
- Independent set: NP-complete.





Algorithm Analysis & Data Structures

Polynomial-Time



- > Brute force. For many non-trivial problems, there is a natural brute force search algorithm that checks every possible solution.
 - Typically takes 2^N time or worse for inputs of size N.
 - Unacceptable in practice.
- Desirable scaling property. When the input size doubles, the algorithm should only slow down by some constant factor C.

There exists constants c > 0 and d > 0 such that on every input of size N, its running time is bounded by c N^d steps.

> Definition: An algorithm is poly-time if the above scaling property holds.





- Worst case running time. Obtain bound on largest possible running time of algorithm on input of a given size N.
 - Generally captures efficiency in practice.
 - Draconian view, but hard to find effective alternative.

- Average case running time. Obtain bound on running time of algorithm on random input as a function of input size N.
 - Hard (or impossible) to accurately model real instances by random distributions.
 - Algorithm tuned for a certain distribution may perform poorly on other inputs.



Worst-Case Polynomial-Time

- > Definition: An algorithm is efficient if its running time is polynomial.
- Justification: It really works in practice!
 - In practice, the poly-time algorithms that people develop almost always have low constants and low exponents.
 - Breaking through the exponential barrier of brute force typically exposes some crucial structure of the problem.
- > Exceptions.
 - Some poly-time algorithms do have high constants and/or exponents, and are useless in practice.
 - Some exponential-time (or worse) algorithms are widely used because the worst-case instances seem to be rare.

Unix grep



Table 2.1 The running times (rounded up) of different algorithms on inputs of increasing size, for a processor performing a million high-level instructions per second. In cases where the running time exceeds 10²⁵ years, we simply record the algorithm as taking a very long time.

	n	$n \log_2 n$	n^2	n^3	1.5 ⁿ	2 ⁿ	n!
n = 10	< 1 sec	< 1 sec	< 1 sec	< 1 sec	< 1 sec	< 1 sec	4 sec
n = 30	< 1 sec	< 1 sec	< 1 sec	< 1 sec	< 1 sec	18 min	10^{25} years
n = 50	< 1 sec	< 1 sec	< 1 sec	< 1 sec	11 min	36 years	very long
n = 100	< 1 sec	< 1 sec	< 1 sec	1 sec	12,892 years	10 ¹⁷ years	very long
n = 1,000	< 1 sec	< 1 sec	1 sec	18 min	very long	very long	very long
n = 10,000	< 1 sec	< 1 sec	2 min	12 days	very long	very long	very long
n = 100,000	< 1 sec	2 sec	3 hours	32 years	very long	very long	very long
n = 1,000,000	1 sec	20 sec	12 days	31,710 years	very long	very long	very long



Asymptotic Order of Growth

- Upper bounds. T(n) is O(f(n)) if there exist constants c > 0 and $n_0 \ge 0$ such that for all $n \ge n_0$ we have T(n) $\le c \cdot f(n)$.
- Lower bounds. T(n) is $\Omega(f(n))$ if there exist constants c > 0 and $n_0 \ge 0$ such that for all $n \ge n_0$ we have $T(n) \ge c \cdot f(n)$.
- Tight bounds. T(n) is $\Theta(f(n))$ if T(n) is both O(f(n)) and $\Omega(f(n))$.
- Ex: $T(n) = 32n^2 + 17n + 32$.
 - T(n) is O(n²), O(n³), Ω (n²), Ω (n), and Θ (n²).
 - T(n) is not O(n), $\Omega(n^3)$, $\Theta(n)$, or $\Theta(n^3)$.



- > Slight abuse of notation. T(n) = O(f(n)).
 - Asymmetric:
 - $f(n) = 5n^3$; $g(n) = 3n^3$
 - $f(n) = O(n^3) = g(n)$
 - but $f(n) \neq g(n)$.
 - Better notation: $T(n) \in O(f(n))$.
- Meaningless statement. Any comparison-based sorting algorithm requires at least O(n log n) comparisons.
 - Statement doesn't "type-check."
 - Use Ω for lower bounds.



> Transitivity

- If f = O(g) and g = O(h) then f = O(h).
- If $f = \Omega(g)$ and $g = \Omega(h)$ then $f = \Omega(h)$.
- If $f = \Theta(g)$ and $g = \Theta(h)$ then $f = \Theta(h)$.

> Additivity

- If f = O(h) and g = O(h) then f + g = O(h).
- If $f = \Omega(h)$ and $g = \Omega(h)$ then $f + g = \Omega(h)$.
- If $f = \Theta(h)$ and g = O(h) then $f + g = \Theta(h)$.

Asymptotic Bounds for Some Common Functions

- > Polynomials. $a_0 + a_1 n + ... + a_d n^d$ is $\Theta(n^d)$ if $a_d > 0$.
- Polynomial time. Running time is O(nd) for some constant d independent of the input size n.
- > Logarithms. $O(\log_a n) = O(\log_b n)$ for any constants a, b > 0.
- > Logarithms. For every x > 0, log $n = O(n^x)$.

log grows slower than every polynomial

> Exponentials. For every r > 1 and every d > 0, $n^d = O(r^n)$.

every exponential grows faster than every polynomial





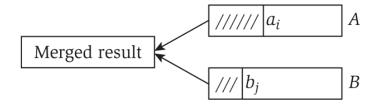
- Linear time. Running time is at most a constant factor times the size of the input.
- Computing the maximum. Compute maximum of n numbers $a_1, ..., a_n$.

```
    \text{max} \leftarrow a_1 \\
    \text{for } i = 2 \text{ to n} \\
    \{ \\
    \text{if } (a_i > \text{max}) \\
    \text{max} \leftarrow a_i \\
    \}
```





Merge. Combine two sorted lists A = a₁,a₂,...,a_n with B = b₁,b₂,...,b_n into one sorted list.



```
\label{eq:continuous} \begin{split} &i=1,\ j=1\\ &\text{while (both lists are nonempty) } \{\\ &\quad \text{if } (a_i \leq b_j) \text{ then append } a_i \text{ to output list and increment i }\\ &\quad \text{else append } b_j \text{ to output list and increment j}\\ &\}\\ &\quad \text{append remainder of nonempty list to output list} \end{split}
```





- O(n log n) time. Arises in divide-and-conquer algorithms.
- > Sorting. Mergesort and heapsort are sorting algorithms that perform O(n log n) comparisons.
- Largest empty interval. Given n time-stamps x_1 , ..., x_n on which copies of a file arrive at a server, what is largest interval of time when no copies of the file arrive?
- O(n log n) solution. Sort the time-stamps. Scan the sorted list in order, identifying the maximum gap between successive time-stamps.





- > Quadratic time. Enumerate all pairs of elements.
- > Closest pair of points. Given a list of n points in the plane $(x_1, y_1), ..., (x_n, y_n)$, find the pair that is closest.
- \rightarrow O(n²) solution. Try all pairs of points.

```
 \begin{aligned} & \min \leftarrow (\mathbf{x}_1 - \mathbf{x}_2)^2 + (\mathbf{y}_1 - \mathbf{y}_2)^2 & \longleftarrow & \text{don't need to} \\ & \text{for i = 1 to n } \{ & & \text{take square roots} \\ & \text{for j = i+1 to n } \{ & & \text{d} \leftarrow (\mathbf{x}_i - \mathbf{x}_j)^2 + (\mathbf{y}_i - \mathbf{y}_j)^2 \\ & \text{if (d < min)} & & \longleftarrow & \text{see chapter 5} \\ & & \text{} \} \end{aligned}
```





- > Cubic time. Enumerate all triples of elements.
- > Set disjointness. Given n sets S_1 , ..., S_n each of which is a subset of 1, 2, ..., n, is there some pair of these which are disjoint?
- > O(n³) solution. For each pairs of sets, determine if they are disjoint.

```
foreach set S<sub>i</sub> {
   foreach other set S<sub>j</sub> {
     foreach element p of S<sub>i</sub> {
        determine whether p also belongs to S<sub>j</sub>
     }
     if (no element of S<sub>i</sub> belongs to S<sub>j</sub>)
        report that S<sub>i</sub> and S<sub>j</sub> are disjoint
   }
}
```



Polynomial Time: O(nk) Time

- Independent set of size k. Given a graph, are there k nodes such that no two are joined by an edge?
- > O(nk) solution. Enumerate all subsets of k nodes.

```
foreach subset S of k nodes {
   check whether S in an independent set
   if (S is an independent set)
      report S is an independent set
   }
}
```

- Check whether S is an independent set = $O(k^2)$.

- Number of k element subsets = $\binom{n}{k} = \frac{n(n-1)(n-2)\cdots(n-k+1)}{k(k-1)(k-2)\cdots(2)(1)} \le \frac{n^k}{k!}$

- $O(k^2 n^k / k!) = O(n^k)$.





- Independent set. Given a graph, what is maximum size of an independent set?
- > O(n² 2ⁿ) solution. Enumerate all subsets.

```
S* ← ф
foreach subset S of nodes {
   check whether S in an independent set
   if (S is largest independent set seen so far)
      update S* ← S
   }
}
```



Summary: Algorithm analysis

- You must learn the asymptotic order of growth. It is fundamental when measuring the performance of an algorithm.
 - O-notation
 - Ω -notation
 - ⊕-notation
- Transitivity and additivity



Basic dynamic data structures

Assumed knowledge:

- Linked lists
- Queues
- Stacks
- Balanced binary trees





- > Programs manipulate data
- Data should be organized so manipulations will be efficient
 - Search (e.g. Finding a word/file/web page)
- Good programs are powered by good data structures
- > Naïve choices are often much less efficient than clever choices
- Data structures are existing tools that can help you
 - guide your design, and
 - save you time (avoid re-inventing the wheel)



The Queue data structure

- The Queue data structure stores arbitrary objects
- Insertions and deletions follow the first-in first-out (FIFO) scheme
- Insertions are at the rear of the queue and removals are at the front of the queue
- Main queue operations:
 - enqueue (object): inserts an element at the end of the queue
 - object dequeue(): removes and returns the element at the front of the queue

- Auxiliary queue operations:
 - object front(): returns the element at the front without removing it
 - integer size(): returns the number of elements stored
 - boolean (isEmpty(): indicates whether no elements are stored



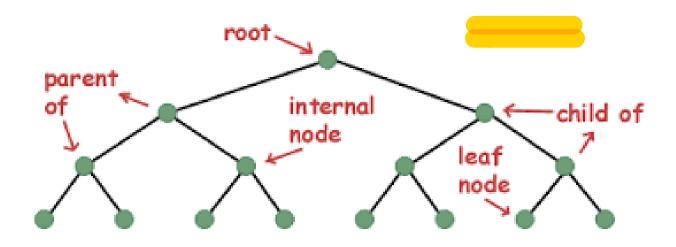


- The Stack data structure stores arbitrary objects
- Insertions and deletions follow the last-in first-out (LIFO) scheme
- Think of a spring-loaded plate dispenser
- Main stack operations:
 - push(object): inserts an element
 - object pop(): removes and returns the last inserted element

- Auxiliary stack operations:
 - object top(): returns the last inserted element without removing it
 - integer size(): returns the number of elements stored
 - boolean <u>isEmpty()</u>: indicates whether no elements are stored





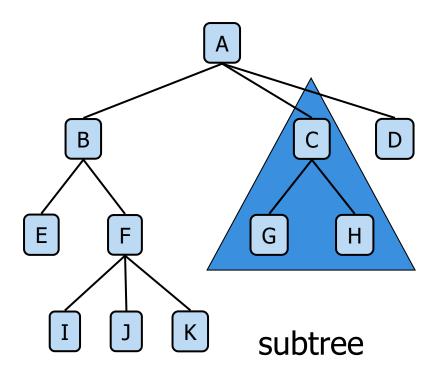




Tree Terminology

- Root: node without parent (A)
- Internal node: node with at least one child (A, B, C, F)
- External node (a.k.a. leaf): node without children (E, I, J, K, G, H, D)
- Ancestors of a node: parent, grandparent, grand-grandparent, etc.
- Depth of a node: number of ancestors
- Height of a tree: maximum depth of any node (3)
- Descendant of a node: child, grandchild, grand-grandchild, etc.

Subtree: tree consisting of a node and its descendants







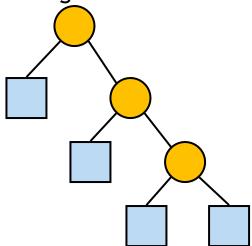
Notation

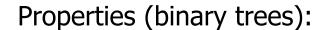
n number of nodes

e number of external nodes

i number of internal nodes

h height





$$e = i + 1$$

$$n = 2e - 1$$

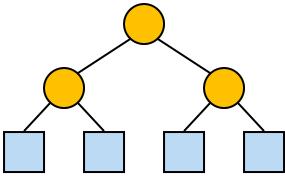
■
$$h \leq i$$

■
$$h \le (n-1)/2$$

•
$$e \leq 2^h$$

■
$$h \ge \log_2 e$$

■
$$h \ge \log_2 (n + 1) - 1$$





Running Times for AVL Trees

Self balancing binary search tree

- find is O(log n)
 - height of tree is O(log n), no restructures needed
- insert is O(log n)
 - initial find is O(log n)
 - Restructuring up the tree, maintaining heights is O(log n)
- remove is O(log n)
 - initial find is O(log n)
 - Restructuring up the tree, maintaining heights is O(log n)



Summary data structures

- Queues
 - Enqueue, dequeue, first and size operations in O(1) time.
- > Stacks
 - Push, pop, top and size operations in O(1) time
- Balanced binary trees (e.g. AVL trees)
 - Insert, delete and find operations in O(log n) time