

A	G	C	C	T	A	T	G	C	A	T		
A	G	C	T	A	A	T	A	A	G	C	A	T

$\alpha(C, T)$

28

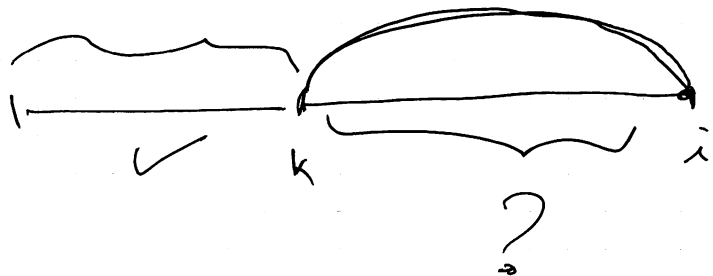
First (incorrect) try

① $M[i] = \text{size of the best matching for position } 1, 2, \dots, i \text{ in the string}$

② If i is not matched in opt.

$$M[i] = M[i-1]$$

If i is matched to $k < i-4$



X stack

Second (correct) try

① $M[i, j]$ = size of the best matching for positions $i, i+1, \dots, j$

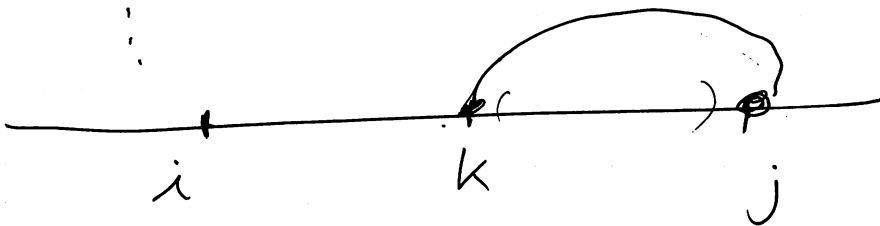
② If j is not matched

$$M[i, j] = M[i, j-1]$$

Else, j matched to $k : i \leq k \leq j-1$

$$M[i, j] = M[i, k-1] + M[k+1, j-1] + 1$$

$A[k] = 0$ and $A[j] = A$, or



③ # DP states = $\binom{n}{2} = O(n^2)$
each takes $O(n)$ time

total is $O(n^3)$
time

$$M[i, j] = \max \left(M[i, j-1], \max_{i \leq k < j-1} M[i, k-1] + M[k+1, j-1] \right)$$

$$M[i, j] = 0 \quad \text{if } j-i \leq 4$$

① $M[i, j]$ = best cost for
alignment of
 x_1, x_2, \dots, x_i
and
 y_1, y_2, \dots, y_j

③ # DP states = $n m$
Each takes = $O(1)$ time

total time = $O(n m)$ time

② If i unmatched in OPT

$$M[i, j] = M[i-1, j] + \delta$$

If j unmatched in OPT

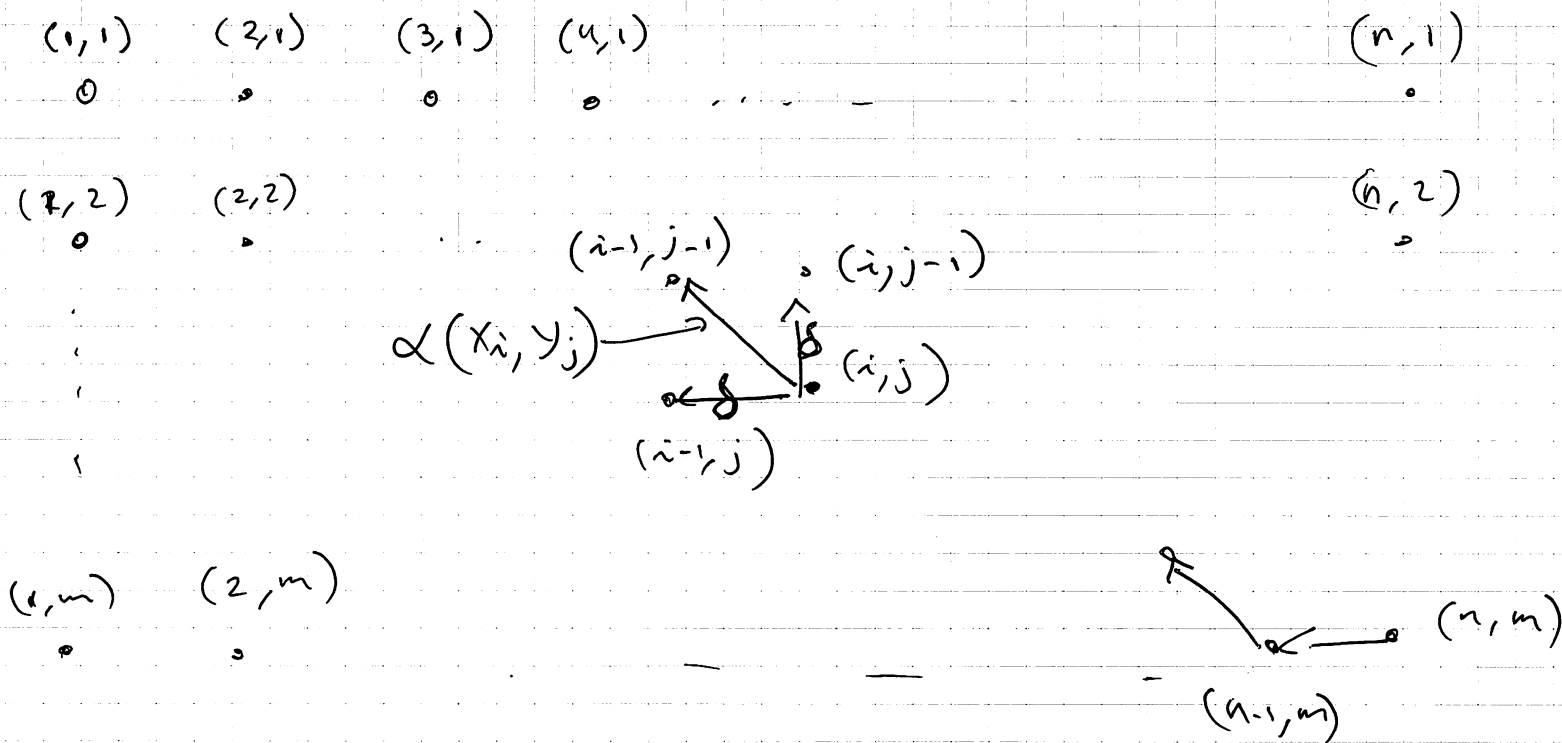
$$M[i, j] = M[i, j-1] + \delta$$

Else $x_i \text{ --- } y_j$

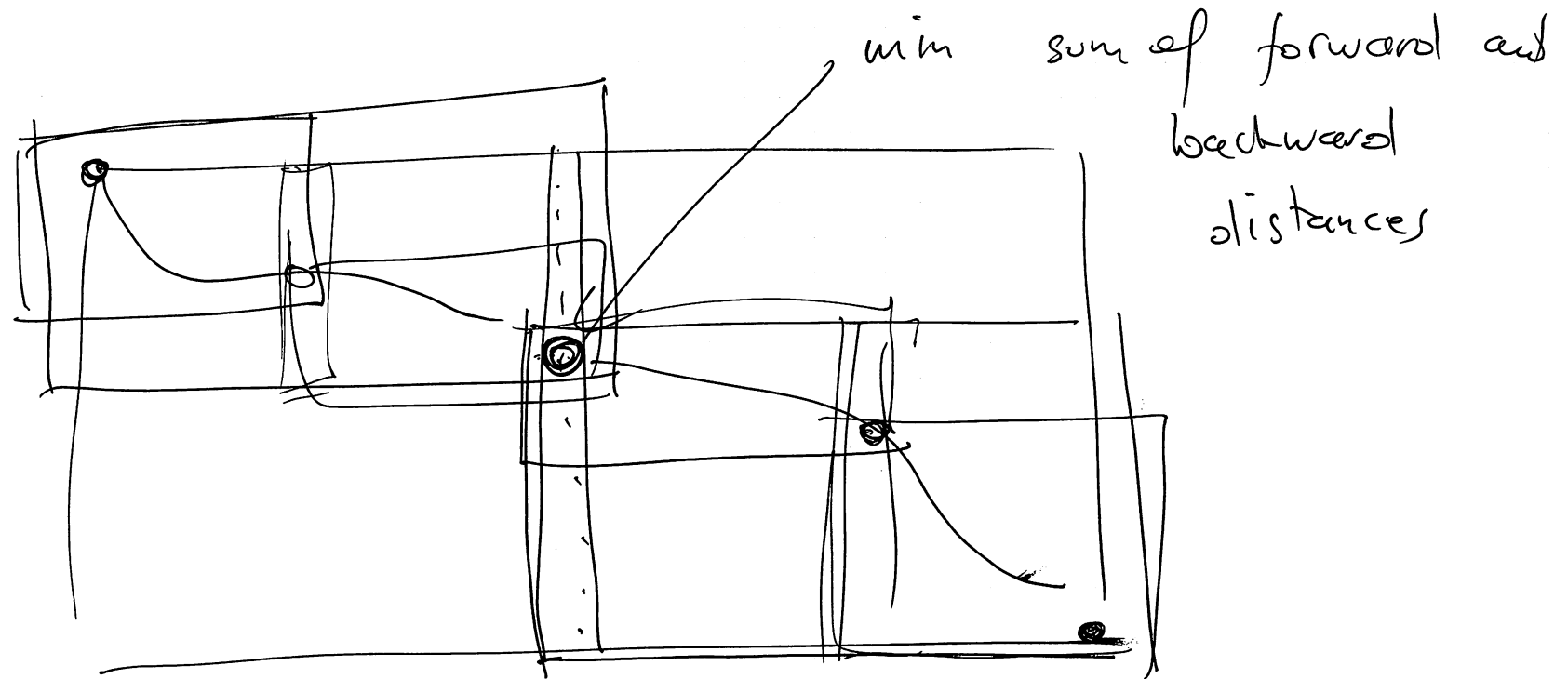
$$M[i, j] = M[i-1, j-1] + \alpha(x_i, y_j)$$

Assume $\alpha(z, z) = 0$

$$\Rightarrow \begin{cases} M[0, j] = \delta j & M[i, 0] = \delta i \\ M[i, j] = \min \left(\begin{aligned} &M[i-1, j] + \delta, \\ &M[i, j-1] + \delta, \\ &M[i-1, j-1] + \alpha(x_i, y_j) \end{aligned} \right) \end{cases}$$



\Rightarrow compute $M[n, m]$ in $O(nm)$ time
 $O(m)$ space



⇒ linear space

⇒ $O(nm)$ time

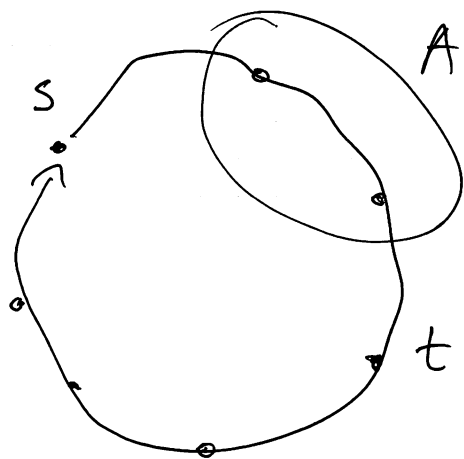
What's the trivial algorithm for TSP?

pre compute distances ~~$O(k^2)$~~ $\text{dist}(x_i, x_j)$ $\forall x_i, x_j \in X$

go over all permutations of X

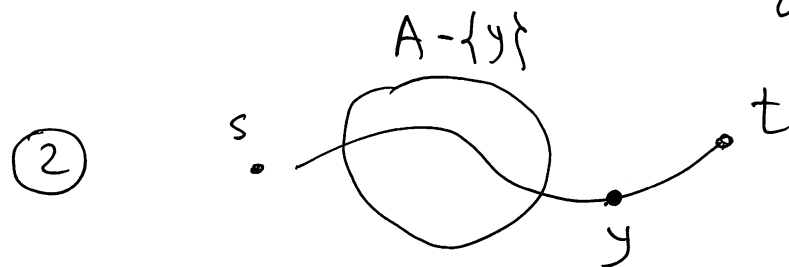
keep the one minimizing objective

\Rightarrow Time complexity: $O(k! k)$ time



$A \subseteq X$

① $M[A, t] = \text{cost of going from } s \text{ to } t \text{ through cities in } A$



②

$$M[A, t] = M[A - \{y\}, y] + \text{dist}(y, t)$$

$$\Rightarrow \begin{cases} M[A, t] = \min_{y \in A} (M[A - \{y\}, y] + \text{dist}(y, t)) \\ M[\emptyset, t] = \text{dist}(s, t) \end{cases}$$

③ Time complexity

DP states = 2^k k

each takes = $O(k)$ time

$$\Rightarrow O(2^k k^2)$$

total time