

# Algorithms and Complexity

## NP-completeness

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We have seen a number of reductions in the last few lectures:

- Maximum matching  $\rightarrow$  Maximum flow
- Minimum cut  $\rightarrow$  Maximum flow
- Open-pit mining  $\rightarrow$  Minimum cut
- Maximum number of disjoint paths  $\rightarrow$  Maximum flow

In all these cases we reduced  $X$  to  $Y$ , where

- $X$  = new problem
- $Y$  = problem we already knew how to solve

Reducing  $X$  to  $Y$  is, in a sense, equivalent to saying

If “ $Y$  is easy” then “ $X$  is easy”

# Reductions are double-edged swords

Reducing  $X$  to  $Y$  also gives us the following statement:

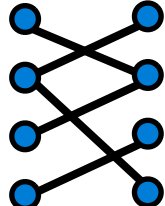
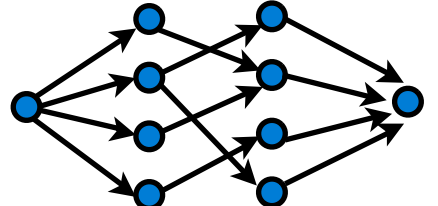
If “ $X$  is hard” then “ $Y$  is hard”

Our proof techniques do not allow to show unequivocally that a certain problem is “hard”, but certain problems are widely believed to be “hard”. Reductions allow us to transfer this belief.

Reducing  $X$  to  $Y$  gives us the following statement:

If “we believe that  $X$  is hard” then “we believe that  $Y$  is hard”

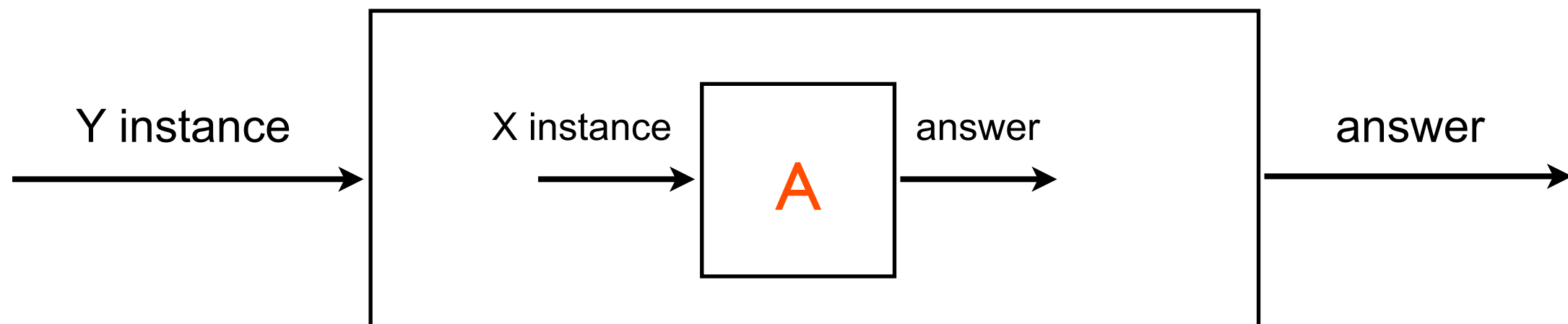
# Reduction in action

Problem	Perfect Matching	Maximum flow
Instance		
Question	Does the graph have a PM?	Is there a flow with value $n/2$ ?
Proof	Yes instance No instance	Yes instance No instance

# Polynomial-time reduction

Def. : Let  $X$  and  $Y$  be two computational problems and  $A$  be a black box routine for solving  $X$ . Suppose  $Y$  can be solved in a polynomial number of computational steps plus a polynomial number of calls to  $A$ . Then we say that  $Y$  is polynomial-time reducible to  $X$ , and we write

$$Y \leq_P X$$



# Properties of poly-time reductions

Suppose  $Y \leq_P X$ . If  $X$  can be solved in polynomial time,  
then  $Y$  can be solved in polynomial time too

Suppose  $Y \leq_P X$ . If  $Y$  cannot be solved in polynomial time,  
then  $X$  cannot be solved in polynomial time either

Reductions are transitive: If  $Z \leq_P Y$  and  $Y \leq_P X$  then  $Z \leq_P X$

# Example of a reduction

Let  $G=(V,E)$  be an undirected graph. We say  $S$  subset of  $V$  is

- a vertex cover if every  $(u,v)$  in  $E$  has an endpoint in  $S$  ( $u$  in  $S$  or  $v$  in  $S$ )
- an independent set if every  $(u,v)$  in  $E$  has at most one an endpoint in  $S$   
( $u$  not in  $S$  or  $v$  not in  $S$ )

The vertex cover problem is the following:

- Input: graph  $G$  and a number  $k$
- Question: Does  $G$  have a vertex cover of size at most  $k$ ?

The independent set problem is the following:

- Input: graph  $G$  and a number  $t$
- Question: Does  $G$  have an independent set of size at least  $t$ ?

Def.: A Boolean formula  $\phi$  is defined on variables  $x_1, x_2, \dots$  in  $\{0, 1\}$

$$\phi = ( (x_1 \wedge x_2) \vee (\neg x_3 \wedge x_2) ) \wedge (\neg x_2 \vee x_1)$$

Def.: A truth assignment is  $v: X \rightarrow \{F, T\}$ , is said to satisfy  $\phi$  if the formula evaluates to  $T$

Def.: A conjunctive normal form (**CNF**) formula is the conjunction of disjunctions of literals (a variable or its negation)

$$\phi = (x_1 \vee x_2) \wedge (\neg x_3 \vee x_2 \vee x_1) \wedge (\neg x_2 \vee x_1)$$

Def.: A **k-CNF** formula is **CNF** and has **k** literals per disjunction



Input:

- A **k-CNF** formula  $\phi$

Question:

- Is there a satisfying assignment for  $\phi$

What do we know about this problem?

- **2-SAT** can be solved in polynomial time
- **3-SAT** is thought to be a “hard” problem

Today we will see that **3-SAT**  $\leq_P$  **IS**. If we believe that **3-SAT** is hard, this indicates that **IS** is a “hard” problem as well.

For technical reasons, we will deal with problems that involve answering a yes/no question. These are called *decision* problems

A decision problem is simply a partition of instances into “yes instances” and “no instances”

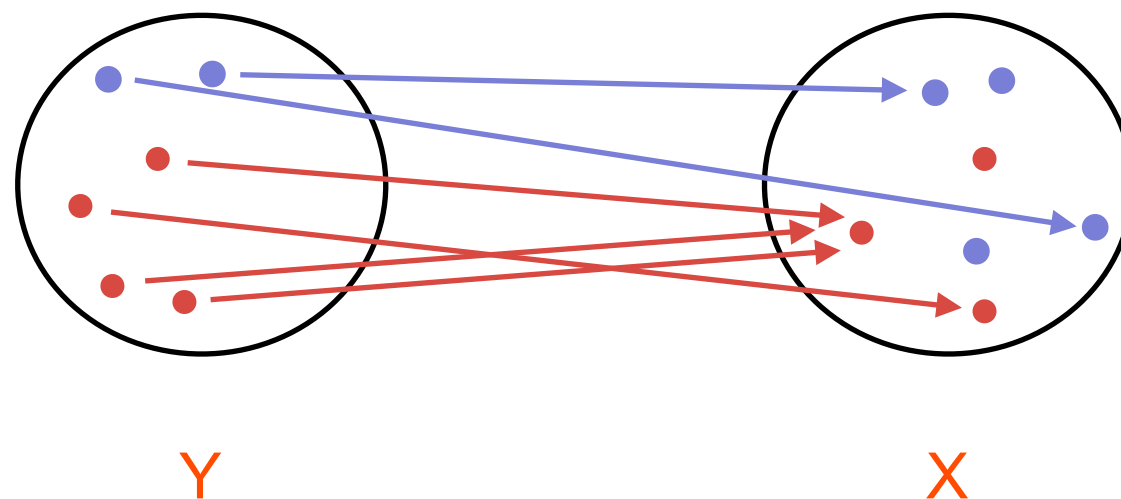
Examples:

- $\{ (G,k) : G \text{ has a vertex cover of size } k \}$
- $\{ (G, c, s, t, T) : (G,c) \text{ has an } s\text{-}t \text{ flow of value } T \}$
- $\{ \text{board} : \text{there is a domino tiling of board} \}$
- $\{ (n, t) : t \text{ is the number of binary search trees on } n \text{ keys} \}$

# Reduction template

When trying to show  $Y \leq_P X$  we define a mapping from instances of problem  $Y$  to instances of problem  $X$  such that:

- the mapping can be computed in polynomial time
- “yes instances” of problem  $Y$  map to “yes instances” of problem  $X$
- “no instances” of problem  $Y$  map to “no instances” of problem  $X$



- yes instance
- no instance

# Complexity classes (informal defs)

Problems are classified according to their complexity.

Def.: **P** are those problems that admit a polynomial time algorithm

Def.: **NP** are those problems that admit a polynomial time algorithm for *verifying* “yes instances”

Obs.: All problems in **P** belong to **NP** as well.

The most central problem in computer science is to determine whether **P = NP** or whether **P  $\subset$  NP**

# Polynomial-time algorithms

Def.: Let  $X$  be a computational problem. An algorithm  $A$  *efficiently solves*  $X$  if

- $A$  is polynomial time algorithm that takes one input  $s$  (an instance of  $X$ )
- for every  $s$  of  $X$  we have:  $s$  is “yes instance” if and only if  $A(s)$  returns “yes”

Def.:  $P$  are those problems that admit a polynomial time algorithm

Example:

- $X$  = “Given an undirected bipartite graph, does it have a perfect matching?”
- $X$  in  $P$  by the reduction to max flow + Ford-Fulkerson

Def.: Let  $X$  be a computational problem. An algorithm  $A$  is an *efficient verifier* for  $X$  if

- $A$  is a polynomial time algorithm that takes two inputs  $s$  (an instance of  $X$ ) and  $t$  (a certificate)
- There is a polynomial function  $p$  such that for every instance  $s$  of  $X$  we have,  $s$  is a “yes instance” if and only if there is a certificate  $t$  such that  $|t| < p(|s|)$  and  $A(s,t)$  returns “yes”

Def.:  $NP$  are those problems that admit a polynomial time verifier

Example:

- $X$  = “Given a general undirected graph, does it have a perfect matching?”
- $X$  in  $NP$  because given the matching the property is trivial to check!

# NP-complete problems

Def.: A problem  $X$  is **NP-hard** if every problem in **NP** is polynomial-time reducible to  $X$ ; that is, if  $Y \leq_P X$  for all  $Y$  in **NP**.

Def.: A problem  $X$  is **NP-complete** if it belongs to **NP** and is NP-hard; that is, if  $X$  in **NP** and  $Y \leq_P X$  for all  $Y$  in **NP**.

Cook and Levin independently showed that such problems exist

Thm.

3-SAT is NP-complete

Consider the independent set problem:

- it belongs to NP because it is easy to verify a “yes instance”
- we know that  $3\text{-SAT} \leq_P \text{IS}$  and that  $\leq_P$  is transitive therefore IS is NP-hard

Thm.

Independent set is NP-complete



Let  $G=(V, E)$  be an undirected graph

A  $k$ -coloring of  $G$  is a function  $\varphi : V \rightarrow \{1, \dots, k\}$

A coloring  $\varphi$  is feasible if there are no monochromatic edges

Input:

- An undirected graph  $G$

Question:

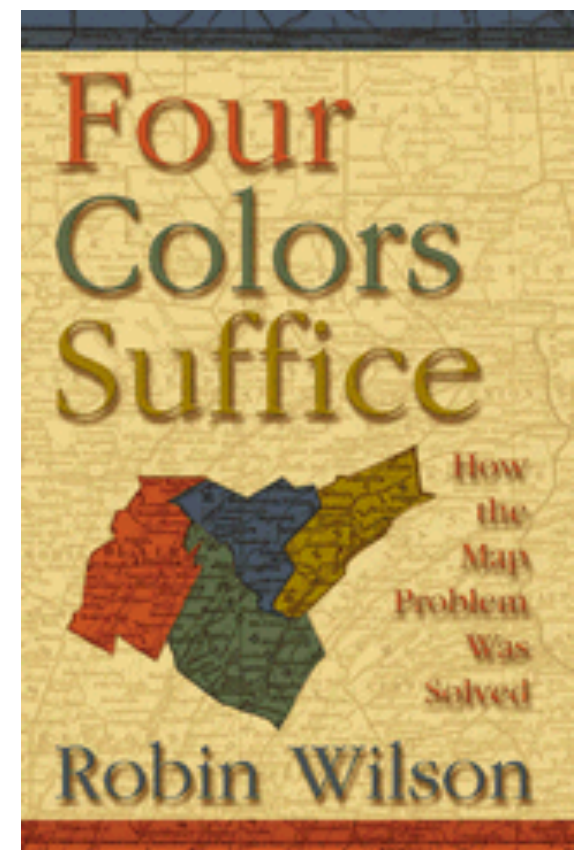
- Does  $G$  admit a feasible  $k$ -coloring?

Originally studied as a subproblem in map drawing, graph coloring has many applications.

What do we know about this problem?

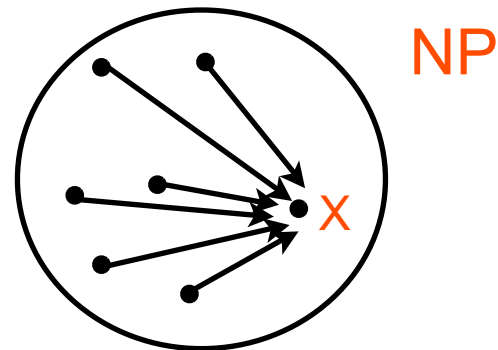
- graph 2-coloring is “easy”
- graph 3-coloring is NP-hard even for planar graphs
- every planar graph admits a feasible 4-coloring

Today we'll show that 3-coloring is NP-hard in general graphs



# Template of NP-completeness proof

Suppose we want to show that **X** is NP-complete.



what we want

Then we need to:

1. First, argue that **X** belongs in **NP**
2. Pick a known **NP**-complete problem **Y**
3. Finally, argue that  $Y \leq_P X$

