

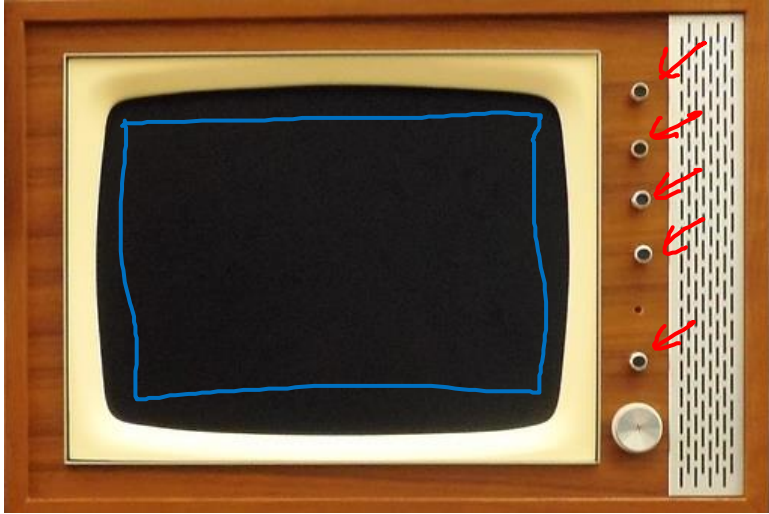


deeplearning.ai

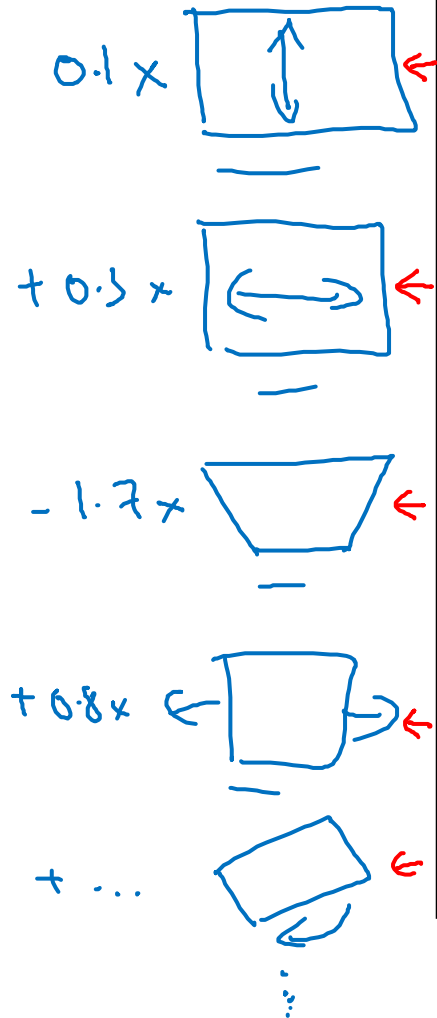
Introduction to ML strategy

Orthogonalization

TV tuning example



Orthogonalization



Car

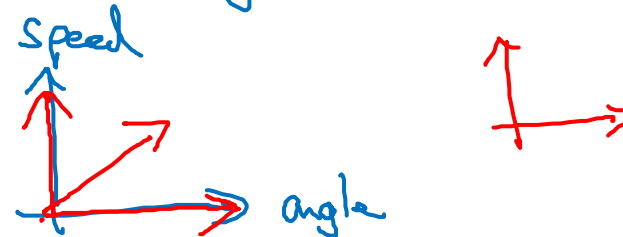


\rightarrow Steering

\rightarrow { Accelerator
Braking }

$$\rightarrow \frac{0.3 \times \text{angle} - 0.8 \text{ speed}}{}$$

$$\rightarrow 2 \times \text{angle} + 0.9 \text{ speed}$$



Chain of assumptions in ML

