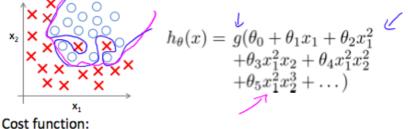
## **Regularized Logistic Regression**

We can regularize logistic regression in a similar way that we regularize linear regression. As a result, we can avoid overfitting. The following image shows how the regularized function, displayed by the pink line, is less likely to overfit than the non-regularized function represented by the blue line:

## Regularized logistic regression.



$$J(\theta) = -\left[\frac{1}{m} \sum_{i=1}^{m} y^{(i)} \log h_{\theta}(x^{(i)}) + (1 - y^{(i)}) \log(1 - h_{\theta}(x^{(i)}))\right]$$

$$+ \frac{\lambda}{2m} \int_{\mathbb{R}^{n}}^{\mathbb{R}^{n}} \Theta_{j}^{2}$$

## **Cost Function**

Recall that our cost function for logistic regression was:

$$J( heta) = -rac{1}{m} \sum_{i=1}^m [y^{(i)} \; \log(h_ heta(x^{(i)})) + (1-y^{(i)}) \; \log(1-h_ heta(x^{(i)}))]$$

We can regularize this equation by adding a term to the end:

$$J( heta) = -rac{1}{m} \sum_{i=1}^m [y^{(i)} \; \log(h_ heta(x^{(i)})) + (1-y^{(i)}) \; \log(1-h_ heta(x^{(i)}))] + rac{\lambda}{2m} \sum_{j=1}^n heta_j^2$$

The second sum,  $\sum_{j=1}^{n} \theta_j^2$  means to explicitly exclude the bias term,  $\theta_0$ . I.e. the  $\theta$  vector is indexed from 0 to n (holding n+1 values,  $\theta_0$  through  $\theta_n$ ), and this sum explicitly skips  $\theta_0$ , by running from 1 to n, skipping 0. Thus, when computing the equation, we should continuously update the two following equations:

## **Gradient descent**

Repeat { 
$$\Rightarrow \quad \theta_0 := \theta_0 - \alpha \frac{1}{m} \sum_{i=1}^m (h_\theta(x^{(i)}) - y^{(i)}) x_0^{(i)}$$
 
$$\Rightarrow \quad \theta_j := \theta_j - \alpha \underbrace{\left[ \frac{1}{m} \sum_{i=1}^m (h_\theta(x^{(i)}) - y^{(i)}) x_j^{(i)} + \frac{\lambda}{m} \odot_j \right]}_{(j = \mathbf{X}, 1, 2, 3, \dots, n)}$$
 } 
$$\underbrace{\left[ \frac{\lambda}{\lambda \Theta_j} \underbrace{\mathcal{I}(\Theta)}_{j = \mathbf{X}, 1, 2, 3, \dots, n} \right]}_{h_{\Theta}(\mathbf{x})^*} \underbrace{\left[ \frac{\lambda}{\lambda \Theta_j} \underbrace{\mathcal{I}(\Theta)}_{j = \mathbf{X}, 1, 2, 3, \dots, n} \right]}_{h_{\Theta}(\mathbf{x})^*} \underbrace{\left[ \frac{\lambda}{\lambda \Theta_j} \underbrace{\mathcal{I}(\Theta)}_{j = \mathbf{X}, 1, 2, 3, \dots, n} \right]}_{h_{\Theta}(\mathbf{x})^*} \underbrace{\left[ \frac{\lambda}{\lambda \Theta_j} \underbrace{\mathcal{I}(\Theta)}_{j = \mathbf{X}, 1, 2, 3, \dots, n} \right]}_{h_{\Theta}(\mathbf{x})^*} \underbrace{\left[ \frac{\lambda}{\lambda \Theta_j} \underbrace{\mathcal{I}(\Theta)}_{j = \mathbf{X}, 1, 2, 3, \dots, n} \right]}_{h_{\Theta}(\mathbf{x})^*} \underbrace{\left[ \frac{\lambda}{\lambda \Theta_j} \underbrace{\mathcal{I}(\Theta)}_{j = \mathbf{X}, 1, 2, 3, \dots, n} \right]}_{h_{\Theta}(\mathbf{x})^*} \underbrace{\left[ \frac{\lambda}{\lambda \Theta_j} \underbrace{\mathcal{I}(\Theta)}_{j = \mathbf{X}, 1, 2, 3, \dots, n} \right]}_{h_{\Theta}(\mathbf{x})^*} \underbrace{\left[ \frac{\lambda}{\lambda \Theta_j} \underbrace{\mathcal{I}(\Theta)}_{j = \mathbf{X}, 1, 2, 3, \dots, n} \right]}_{h_{\Theta}(\mathbf{x})^*} \underbrace{\left[ \frac{\lambda}{\lambda \Theta_j} \underbrace{\mathcal{I}(\Theta)}_{j = \mathbf{X}, 1, 2, 3, \dots, n} \right]}_{h_{\Theta}(\mathbf{x})^*} \underbrace{\left[ \frac{\lambda}{\lambda \Theta_j} \underbrace{\mathcal{I}(\Theta)}_{j = \mathbf{X}, 1, 2, 3, \dots, n} \right]}_{h_{\Theta}(\mathbf{x})^*} \underbrace{\left[ \frac{\lambda}{\lambda \Theta_j} \underbrace{\mathcal{I}(\Theta)}_{j = \mathbf{X}, 1, 2, 3, \dots, n} \right]}_{h_{\Theta}(\mathbf{x})^*} \underbrace{\left[ \frac{\lambda}{\lambda \Theta_j} \underbrace{\mathcal{I}(\Theta)}_{j = \mathbf{X}, 1, 2, 3, \dots, n} \right]}_{h_{\Theta}(\mathbf{x})^*} \underbrace{\left[ \frac{\lambda}{\lambda \Theta_j} \underbrace{\mathcal{I}(\Theta)}_{j = \mathbf{X}, 1, 2, 3, \dots, n} \right]}_{h_{\Theta}(\mathbf{x})^*} \underbrace{\left[ \frac{\lambda}{\lambda \Theta_j} \underbrace{\mathcal{I}(\Theta)}_{j = \mathbf{X}, 1, 2, 3, \dots, n} \right]}_{h_{\Theta}(\mathbf{x})^*} \underbrace{\left[ \frac{\lambda}{\lambda \Theta_j} \underbrace{\mathcal{I}(\Theta)}_{j = \mathbf{X}, 1, 2, 3, \dots, n} \right]}_{h_{\Theta}(\mathbf{x})^*} \underbrace{\left[ \frac{\lambda}{\lambda \Theta_j} \underbrace{\mathcal{I}(\Theta)}_{j = \mathbf{X}, 1, 2, 3, \dots, n} \right]}_{h_{\Theta}(\mathbf{x})^*} \underbrace{\left[ \frac{\lambda}{\lambda \Theta_j} \underbrace{\mathcal{I}(\Theta)}_{j = \mathbf{X}, 1, 2, 3, \dots, n} \right]}_{h_{\Theta}(\mathbf{x})^*} \underbrace{\left[ \frac{\lambda}{\lambda \Theta_j} \underbrace{\mathcal{I}(\Theta)}_{j = \mathbf{X}, 1, 2, 3, \dots, n} \right]}_{h_{\Theta}(\mathbf{x})^*} \underbrace{\left[ \frac{\lambda}{\lambda \Theta_j} \underbrace{\mathcal{I}(\Theta)}_{j = \mathbf{X}, 1, 2, 3, \dots, n} \right]}_{h_{\Theta}(\mathbf{x})^*} \underbrace{\left[ \frac{\lambda}{\lambda \Theta_j} \underbrace{\mathcal{I}(\Theta)}_{j = \mathbf{X}, 1, 2, 3, \dots, n} \right]}_{h_{\Theta}(\mathbf{x})^*} \underbrace{\left[ \frac{\lambda}{\lambda \Theta_j} \underbrace{\mathcal{I}(\Theta)}_{j = \mathbf{X}, 1, 2, 3, \dots, n} \right]}_{h_{\Theta}(\mathbf{x})^*} \underbrace{\left[ \frac{\lambda}{\lambda \Theta_j} \underbrace{\mathcal{I}(\Theta)}_{j = \mathbf{X}, 1, 2, 3, \dots, n} \right]}_{h_{\Theta}(\mathbf{x})^*} \underbrace{\left[ \frac{\lambda}{\lambda \Theta_j} \underbrace{\mathcal{I}(\Theta)}_{j = \mathbf{X}, 1, 2, 3, \dots, n} \right]}_{h_{\Theta}(\mathbf{x})^*} \underbrace{\left[ \frac{\lambda}{\lambda \Theta_j} \underbrace{\mathcal{I}(\Theta)}_{j = \mathbf{X}, 1, 2, 3, \dots, n} \right]}_{h_{\Theta}(\mathbf{x})^*} \underbrace{\left[ \frac{\lambda}{\lambda \Theta_j} \underbrace{\mathcal{I}(\Theta)}_{j = \mathbf{X}, 1, 2, 3, \dots, n}$$