

JEE MAIN | IIT JEE

ROTATION

(Part-3)

REVISION in 45 Min



Mohit Sir, IIT Kharagpur

PART 3 - Topics to covered

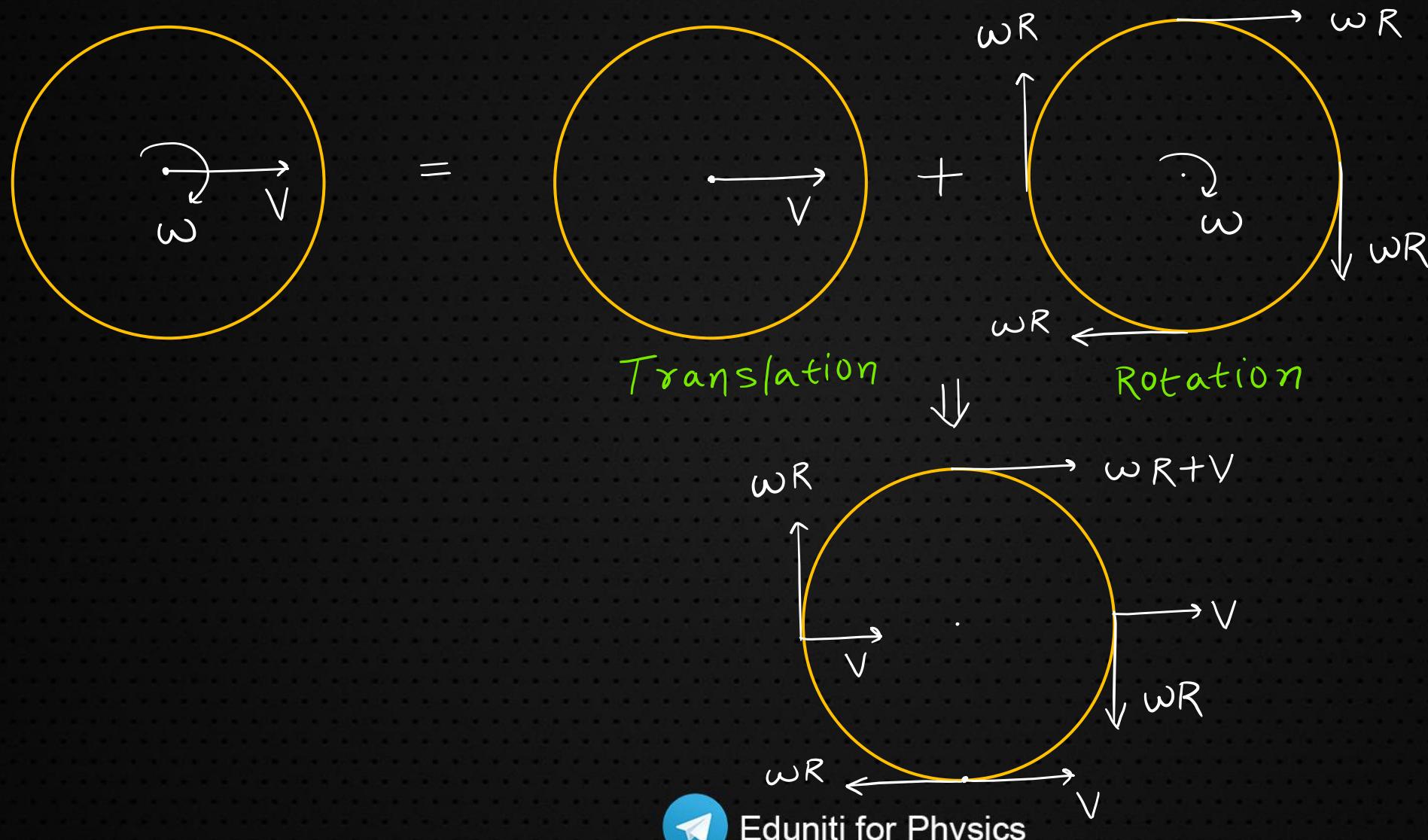
1. Velocity of a Point on Circumference (Trans + Rotational)
2. Acceleration of a Point of Circumference
3. Rolling Motion (*pure rolling & rolling with slipping*)
4. Question on Vel & acc of a circumference point
5. Total Kinetic Energy in Pure Rolling
6. External Force in Rolling (*numerical included*)
7. Question on Energy Conservation (*pure rolling on Inclined*)
8. Acceleration & Friction (*Rolling on Inclined Plane*)
9. Question on Acc & Friction
10. Toppling (*Question + toppling on Incline*)



Chapter	Formulae_Concept VIDEO LINK		
Unit & Dimensions	https://youtu.be/wdd-wlZF4Hk	Electrostatics	https://youtu.be/3stXbGRMcrk
Errors and Vectors	https://youtu.be/pVoN045dV8I	Capacitors	https://youtu.be/EXEiickNUKY
Vernier Calliper	https://youtu.be/gYd2PtmZ0mw	Current Electricity	https://youtu.be/gm8FUfjrX18
Screw Gauge	https://youtu.be/U4NNxFaFliE	Moving Charges and Magnetic Effect of Current	https://youtu.be/ULD2Ok1CGJk
Kinematics_Motion in 1d	https://youtu.be/4_Zo5WhMf7w	Earth's Magnetism	https://youtu.be/a4CT5uVwAK4
Kinematics_Motion in 2d	https://youtu.be/7JIR8gNRQIs	Magnetic Properties	https://youtu.be/63 cwdYXNIYE
Laws of Motion	https://youtu.be/Rn1bLst7eGk	EMI	https://youtu.be/puVavm_GFRM
Friction	https://youtu.be/kjrXoE-kDI8	Alternating Current	https://youtu.be/74dTY-pzM_o
Work Energy Power	https://youtu.be/KnFymKHIkT0	Ray Optics	https://youtu.be/BhnyTWzIIBA
Circular Motion	https://youtu.be/ads35RKD618	Wave Optics Part 1_Interference	https://youtu.be/LG5nIE8XTel
Centre of Mass	https://youtu.be/3f0u4L-lyyw	Wave Optics Part 2_Diffraction_Polarization	https://youtu.be/ymMyyJGGqnY
Cons of Momentum & Collision	https://youtu.be/O6j1mLp06XI	Optical Instruments	https://youtu.be/OQssbDH0A4I
Rotational Motion – Part 1	https://youtu.be/0Hni1DRdfAQ	Electromagnetic Waves	https://youtu.be/bcVXgEkyQZY
Rotational Motion – Part 2	https://youtu.be/rAj2huLVaEk	Semiconductors_Basics + Zener Diode	https://youtu.be/_A2JomQ7-50
Gravitation	https://youtu.be/gSXxjk89I_c	Semiconductors_Transistors	https://youtu.be/psDwl84Nzb0
Properties of Solids	https://youtu.be/RFKx9B9yo3M	Semiconductors_Logic Gates	https://youtu.be/pZdQAzLbFT0
Fluids Statics (Part 1)	https://youtu.be/Y717vQpUEJQ	Communication Systems	https://youtu.be/8NgMqK9X79Y
Fluid Dynamics (Part 2)	https://youtu.be/V8xUWWK2oT0	Modern Physics_Part 1_Atomic Physics	https://youtu.be/9VKUnE3mpHk
Fluid Properties (Part 3)	https://youtu.be/Rlb7ofNG09I	Modern Physics_Part 2_Photoelectric Effect	https://youtu.be/24oTQp84jrk
Simple Harmonic Motion	https://youtu.be/OYjjyPlzddE	Modern Physics_Part 3_Dual Nature of Light	https://youtu.be/0zoR_saMAQY
Thermal Properties	https://youtu.be/PyNboHgtYzM	Modern Physics_Part 4_Radioactivity	https://youtu.be/AdX3YBhQyog
Heat Transfer	https://youtu.be/XO1tvFhla0I	Modern Physics_Part 5_Nuclear Physics	https://youtu.be/VDWqVahGixc
KTG	https://youtu.be/iz_kf1jRDRw	Modern Physics_Part 6_X Rays	https://youtu.be/dSHXdzX7NX0
Thermodynamics	https://youtu.be/fB7pfJ77za8		
Wave Motion -Organ Pipes and Resonance Tube	https://youtu.be/9-BxOaamnwg		
Wave Motion - Doppler's Effect			



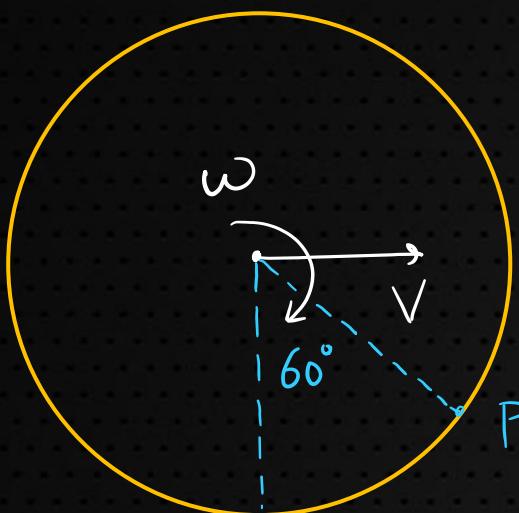
1. Velocity of Point on Circumference (Trans + Rotational)



... continued

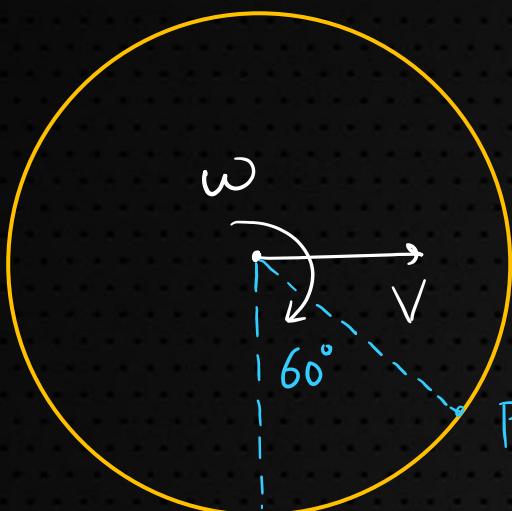
$$V = 5 \text{ m/s}, \omega = 2.5 \text{ rad/s}, R = 2 \text{ m}. \text{ Find } V_P ?$$

Ex 1.

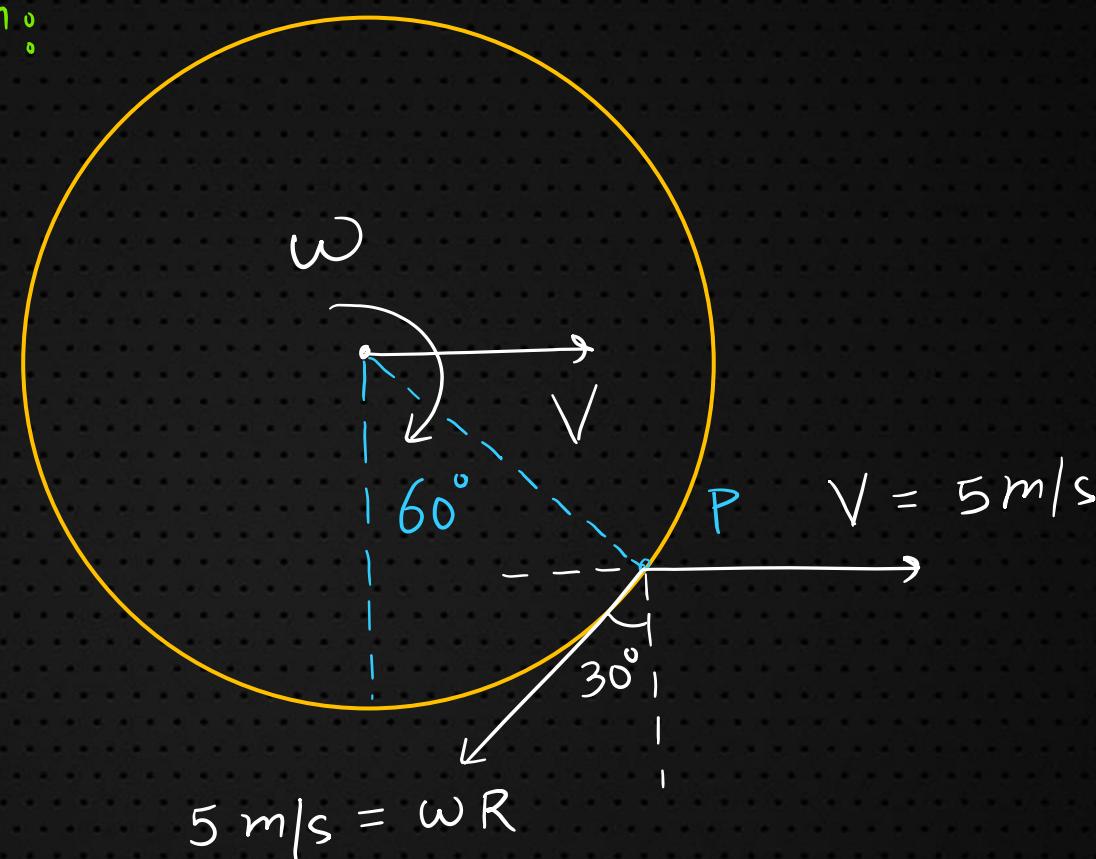


... continued $V = 5 \text{ m/s}, \omega = 2.5 \text{ rad/s}, R = 2 \text{ m}. \text{ Find } V_p ?$

Ex 1.



Soln:

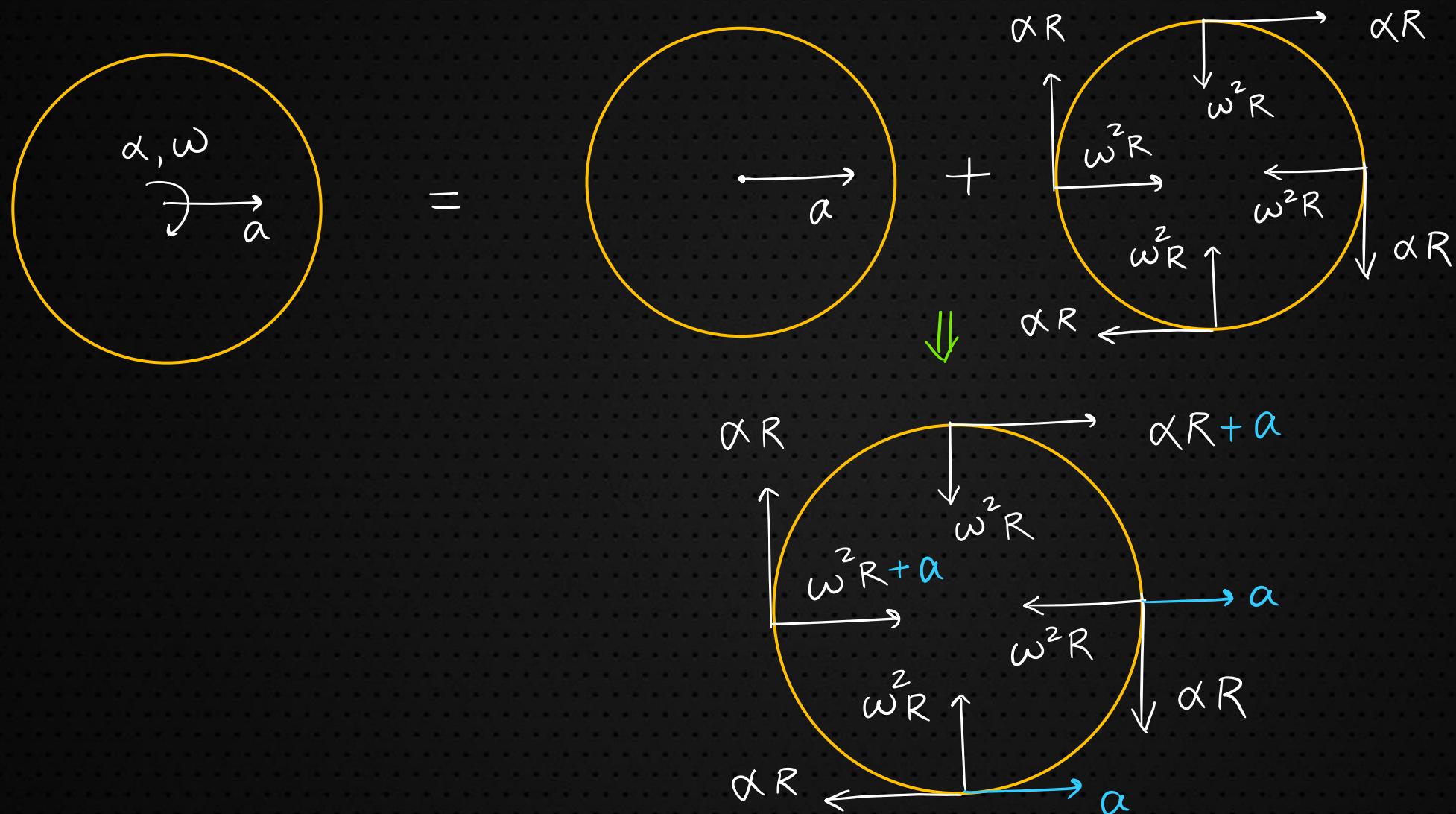


$$5 \text{ m/s} = \omega R$$

$$V_p = \sqrt{5^2 + 5^2 + 2.5^2 \underbrace{\cos 120^\circ}_{-\frac{1}{2}}} = \boxed{5 \text{ m/s}}$$

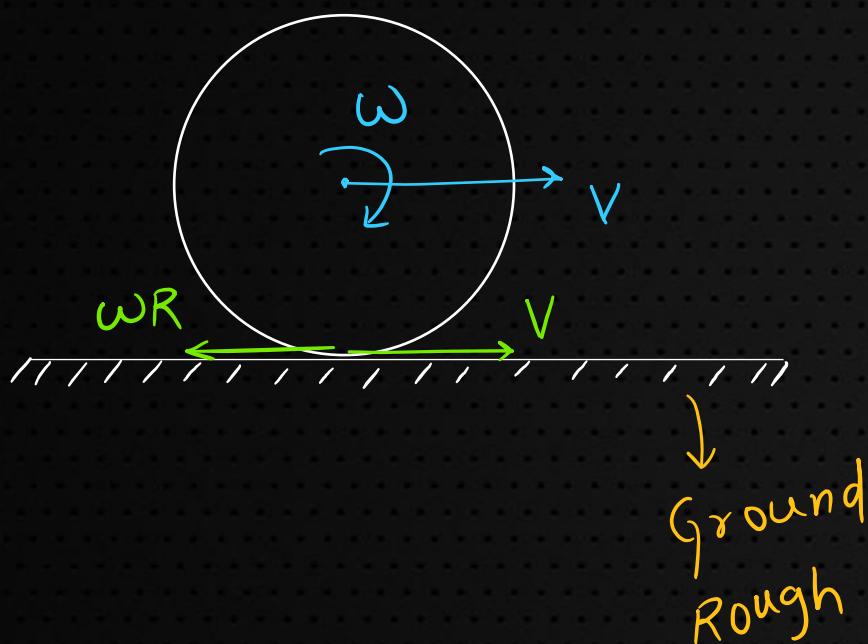


2. Acceleration of Point on circumference



3. Rolling Motion

(a) Pure rolling : No relative motion of Pt. of Contact or Pt. of contacts have same Velocity.



$$\therefore V_{\text{Ground}} = 0 \Rightarrow V - \omega R = 0 \quad \therefore V = \omega R$$

$$(i) V = \omega R \quad (\because a = \alpha R)$$

(ii) NO friction force acting

(b) Rolling with slipping : $V \neq \omega R$

↳ If $V > \omega R \Rightarrow f_K$ acts backward

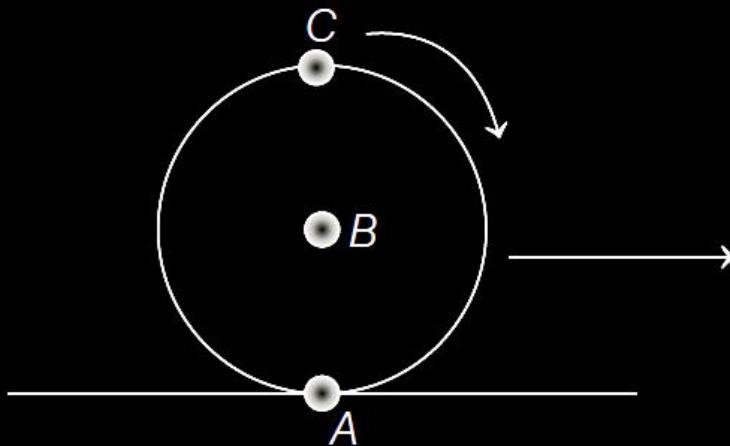
↳ If $\omega R > V \Rightarrow f_K$ acts forward

NOTE : f_K until Pure rolling starts



4. Question on Velocity & Acceleration in Pure Rolling

Ex 2. A sphere is rolling without slipping on a fixed horizontal plane surface.



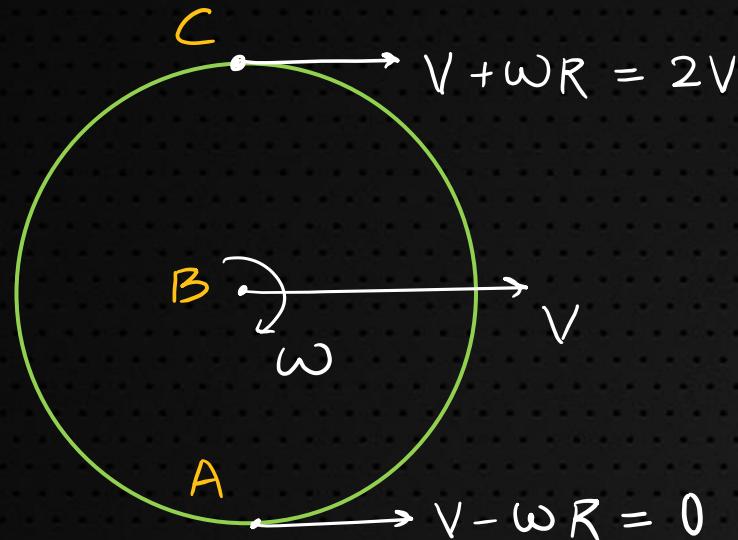
In the figure, A is the point of contact. B is the centre of the sphere and C is its topmost point. Then, (2009)

- (a) $\mathbf{v}_C - \mathbf{v}_A = 2(\mathbf{v}_B - \mathbf{v}_C)$
- (b) $\mathbf{v}_C - \mathbf{v}_B = \mathbf{v}_B - \mathbf{v}_A$
- (c) $|\mathbf{v}_C - \mathbf{v}_A| = 2|\mathbf{v}_B - \mathbf{v}_C|$
- (d) $|\mathbf{v}_C - \mathbf{v}_A| = 4|\mathbf{v}_B|$



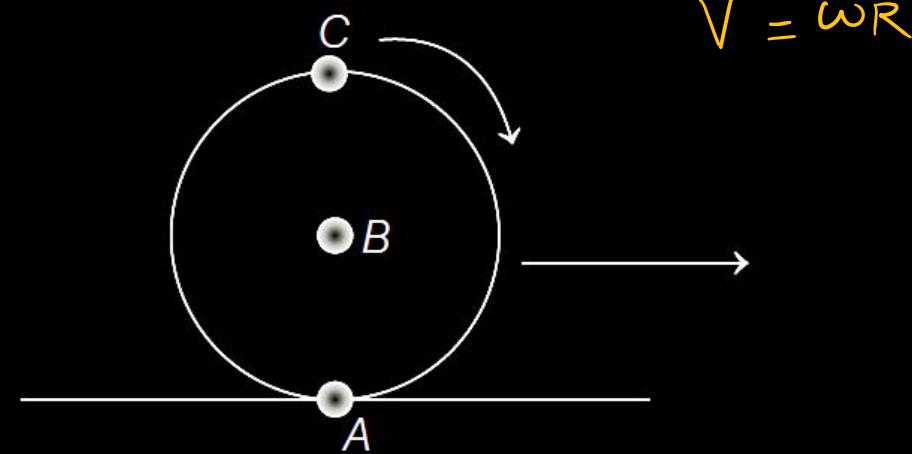
4. Question on Velocity & Acceleration in Pure Rolling

Soln:



Ex 2.

A sphere is rolling without slipping on a fixed horizontal plane surface.



$$V = \omega R$$

In the figure, A is the point of contact. B is the centre of the sphere and C is its topmost point. Then, (2009)

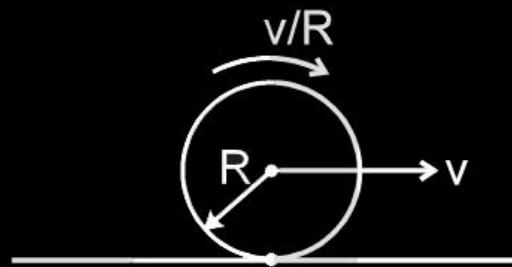
- (a) $\mathbf{v}_C - \mathbf{v}_A = 2(\mathbf{v}_B - \mathbf{v}_C)$
- (b) $\mathbf{v}_C - \mathbf{v}_B = \mathbf{v}_B - \mathbf{v}_A$
- (c) $|\mathbf{v}_C - \mathbf{v}_A| = 2|\mathbf{v}_B - \mathbf{v}_C|$
- (d) $|\mathbf{v}_C - \mathbf{v}_A| = 4|\mathbf{v}_B|$



... continued

Ex 3.

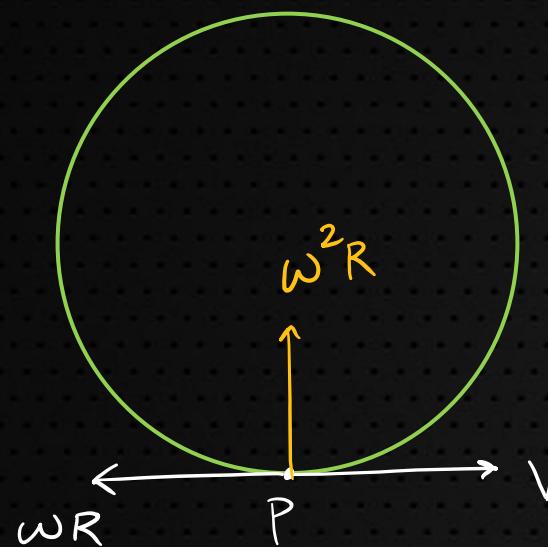
A disc is performing pure rolling on a smooth stationary surface with constant angular velocity as shown in figure. At any instant, for the lower most point of the disc



- (a) Velocity is v , acceleration is zero
- (b) Velocity is zero, acceleration is zero
- (c) velocity is v , acceleration is $\frac{v^2}{R}$.
- (d) velocity is zero, acceleration is $\frac{v^2}{R}$



... continued
Sol:



$$v_p = 0$$

$$\begin{aligned} a_p &= \omega^2 R \\ &= \frac{v^2}{R} \end{aligned}$$

Ex 3.

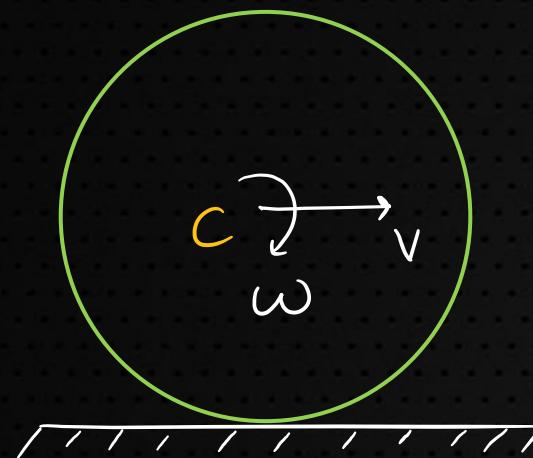
A disc is performing pure rolling on a smooth stationary surface with constant angular velocity as shown in figure. At any instant, for the lower most point of the disc



- (a) Velocity is v , acceleration is zero
- (b) Velocity is zero, acceleration is zero
- (c) velocity is v , acceleration is $\frac{v^2}{R}$.
- (d) velocity is zero, acceleration is $\frac{v^2}{R}$



5. KE in Pure Rolling ($V = \omega R$)



$$I_C = k m R^2$$

\hookrightarrow 1 if Ring or Hollow Cylinder

$\frac{1}{2}$ if Disc or Solid Cylinder

$\frac{2}{3}$ if Hollow Sphere

$\frac{2}{5}$ if Solid Sphere

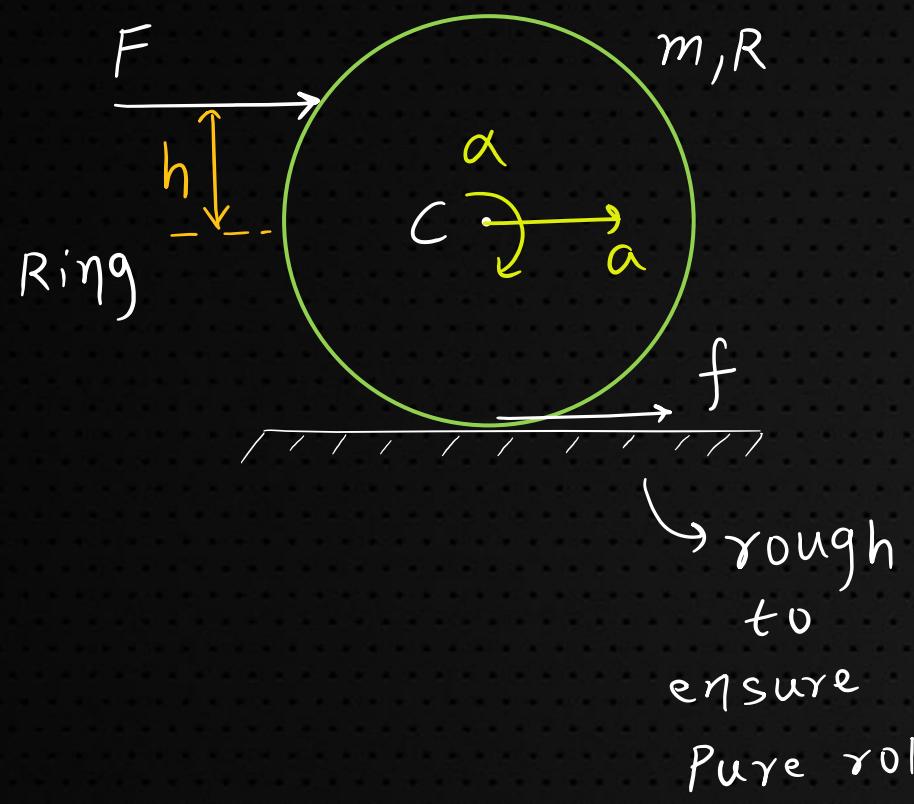
$$KE = K_T + K_R = \frac{1}{2} m V^2 + \frac{1}{2} \cdot k m R^2 \cdot \left(\frac{V}{R}\right)^2$$

$$\therefore \boxed{KE = \frac{1}{2} m V^2 (1 + k)}$$



6. External Force in Rolling

NOTE: (i) \therefore Pure rolling $\Rightarrow f$ is static
(ii) Pt. of contact is at instantaneous rest $\Rightarrow w_f = 0$



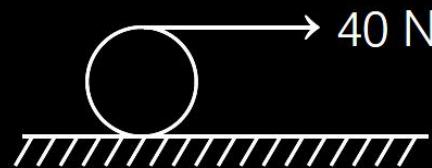
$$F + f = ma \quad \text{--- (1)}$$

$$Fh - fR = mR^2 \cdot \alpha \quad \left\{ \alpha = \frac{a}{R} \right\}$$

$$\Rightarrow Fh - fR = mR^2 \cdot \frac{a}{R} \quad \text{--- (2)}$$

Solve (1) & (2) to get
a and f.

Ex 4. A string is wound around a hollow cylinder of mass 5 kg and radius 0.5 m. If the string is now pulled with a horizontal force of 40 N and the cylinder is rolling without slipping on a horizontal surface (see figure), then the angular acceleration of the cylinder will be (Neglect the mass and thickness of the string)

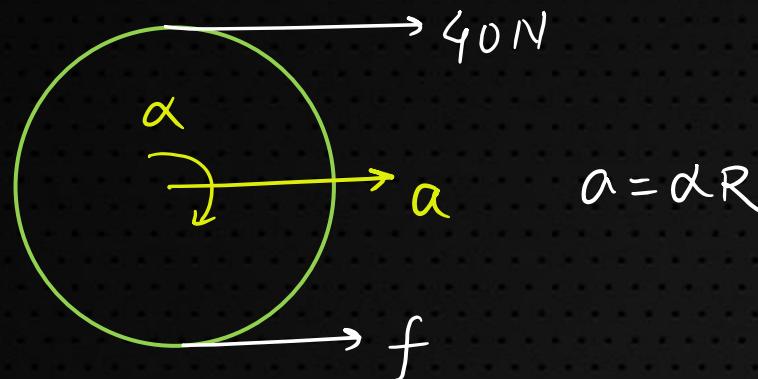


(2019 Main, 11 Jan II)

- (a) 10 rad/ s^2
- (b) 16 rad/ s^2
- (c) 20 rad/ s^2
- (d) 12 rad/ s^2

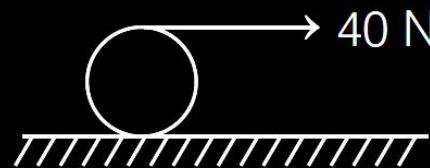


... continued
soⁿ:



$$40 + f = ma \quad \text{--- (1)}$$

- Ex 4. A string is wound around a hollow cylinder of mass 5 kg and radius 0.5 m. If the string is now pulled with a horizontal force of 40 N and the cylinder is rolling without slipping on a horizontal surface (see figure), then the angular acceleration of the cylinder will be (Neglect the mass and thickness of the string)



(2019 Main, 11 Jan II)

- (a) 10 rad/ s^2
- (b) 16 rad/ s^2
- (c) 20 rad/ s^2
- (d) 12 rad/ s^2

$$40R - fR = mR^2 \cdot \alpha \Rightarrow 40 - f = mR\alpha \quad \text{--- (2)}$$

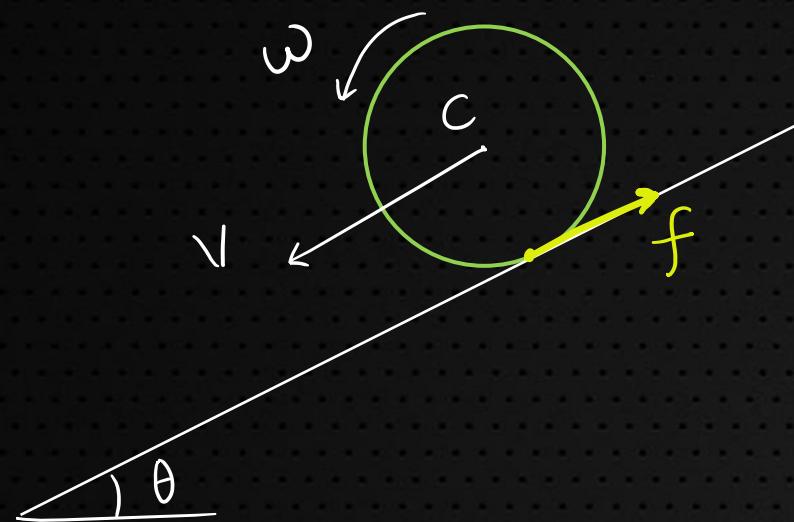
$$(1) + (2) : 80 = m(a + \alpha R) \Rightarrow \frac{80}{2mR} = \alpha$$

$$\therefore \alpha = \frac{80}{2 \times 5 \times 0.5} = \boxed{16 \text{ rad/s}^2}$$



7. Questions on Energy Conservation (pure rolling on Inclined)

$$\hookrightarrow v = \omega R \quad \& \quad a = \alpha R$$



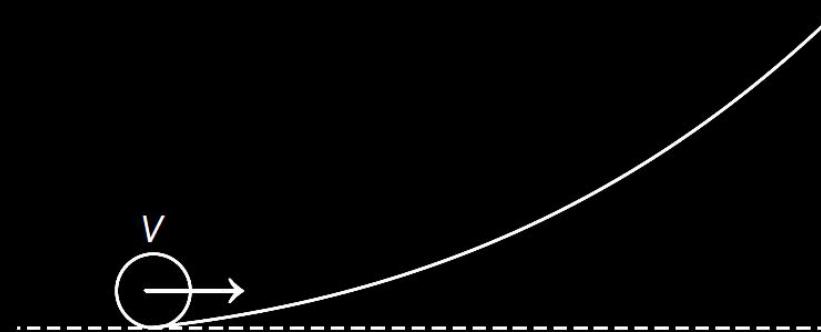
NOTE : (i) $v \uparrow$ due to gravity
 (ii) Thus ω must \uparrow so that $v = \omega R$
 (iii) Thus f acts (creating Torque about C)

$$\downarrow \text{Static} \Rightarrow W_f = 0$$

\Downarrow
 Energy Cons. is applicable



Ex 5. A small object of uniform density rolls up a curved surface with an initial velocity v . It reaches up to a maximum height of $\frac{3v^2}{4g}$ with respect to the initial position. The object is (2007, 3M)



- (a) ring
- (b) solid sphere
- (c) hollow sphere
- (d) disc



... Continued

Soln: Loss in K.E. = Gain in PE

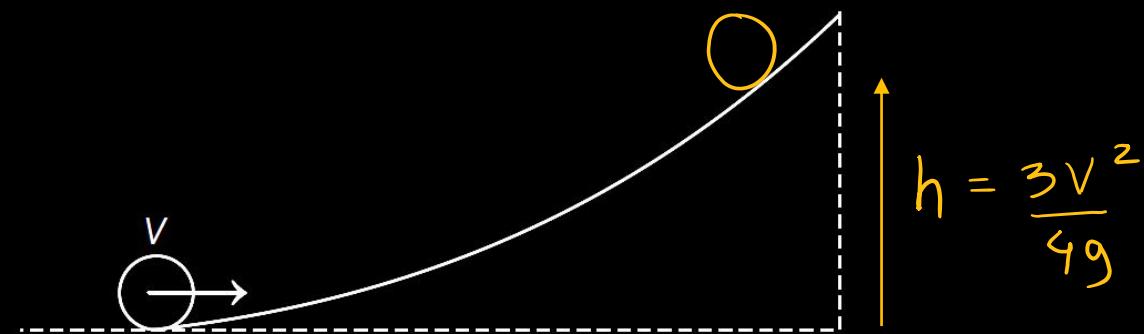
$$\Rightarrow \frac{1}{2}mv^2(K+1) = mg \times \frac{3v^2}{4g}$$

$$\Rightarrow K+1 = \frac{3}{2} \quad \therefore \boxed{K = \frac{1}{2}}$$

Disc or

Solid cylinder

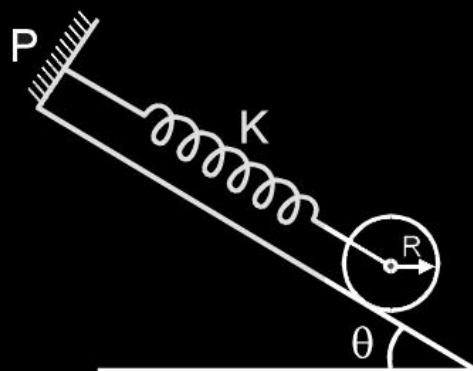
- Ex 5. A small object of uniform density rolls up a curved surface with an initial velocity v . It reaches up to a maximum height of $\frac{3v^2}{4g}$ with respect to the initial position. The object is (2007, 3M)



- (a) ring
- (b) solid sphere
- (c) hollow sphere
- (d) disc

... Continued

Ex 6. A uniform cylinder of mass M and radius R rolls without slipping down a slope of angle θ to the horizontal. The cylinder is connected to a spring constant K while the other end of the spring is connected to a rigid support at P. The cylinder is released when the spring is unstretched. The maximum distance that the cylinder travels is



(a) $\frac{3}{4} \frac{Mg\sin\theta}{K}$

(b) $\frac{Mgtan\theta}{K}$

(c) $\frac{2Mg\sin\theta}{K}$

(d) $\frac{4}{3} \frac{Mg\sin\theta}{K}$



... Continued

Solⁿ: Initial & Finally system at rest.

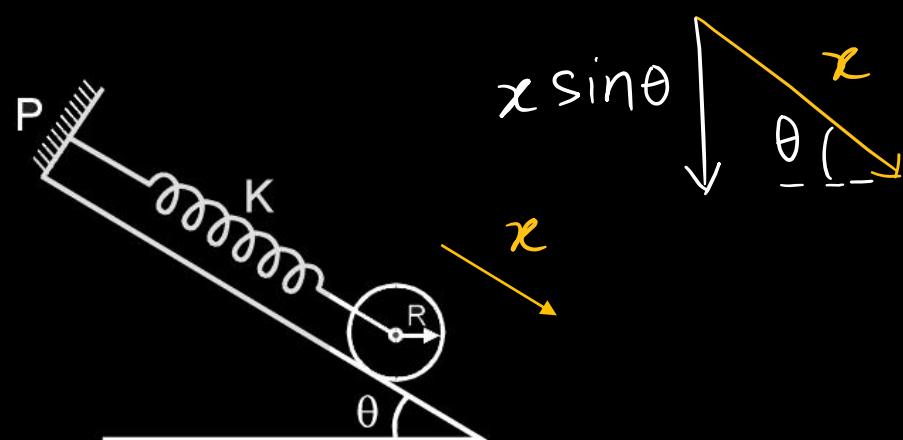
Loss in Grav P.E. = Gain in Spring P.E.

$$\Rightarrow mgx \sin\theta = \frac{1}{2} Kx^2$$

$$\therefore x = \frac{2mg \sin\theta}{K}$$

Ex 6.

A uniform cylinder of mass M and radius R rolls without slipping down a slope of angle θ to the horizontal. The cylinder is connected to a spring constant K while the other end of the spring is connected to a rigid support at P. The cylinder is released when the spring is unstretched. The maximum distance that the cylinder travels is



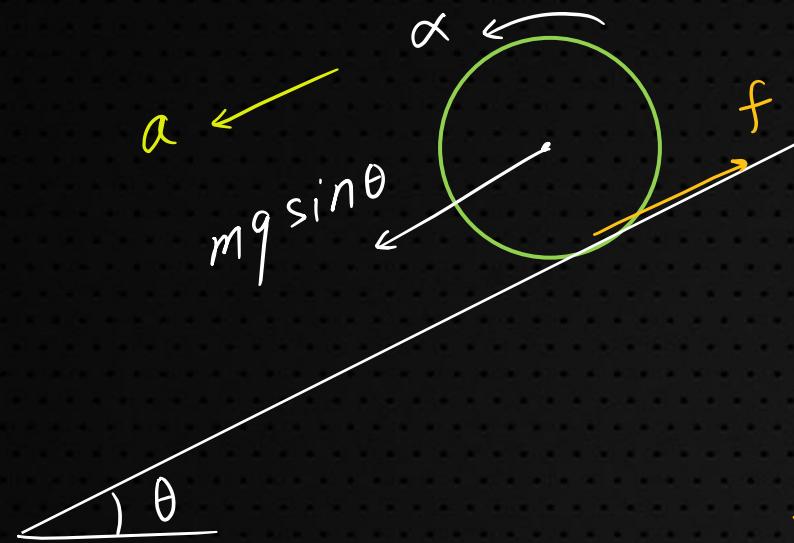
(a) $\frac{3}{4} \frac{Mg \sin\theta}{K}$

(c) $\frac{2Mg \sin\theta}{K}$

(b) $\frac{Mgtan\theta}{K}$

(d) $\frac{4}{3} \frac{Mg \sin\theta}{K}$

8. Acceleration & Friction - Rolling on Inclined Plane



$$mg \sin \theta - f = ma \quad \text{--- (1)}$$

$$fR = kmR^2 \cdot \alpha \quad \left\{ \alpha = \frac{a}{R} \right\}$$

$$\Rightarrow fR = kmR^2 \cdot \frac{a}{R} \Rightarrow f = kma \quad \text{--- (2)}$$

From (1) and (2) :

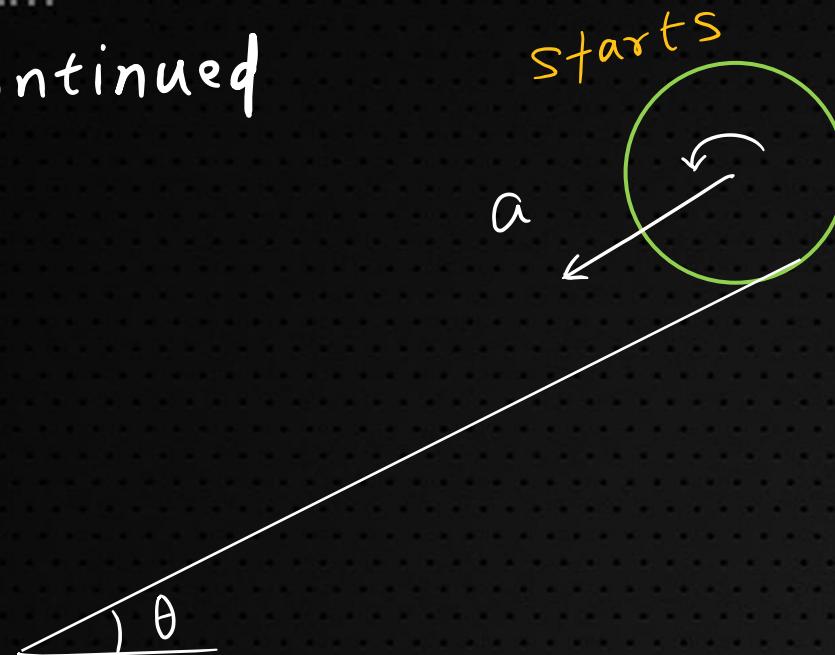
$$a = \frac{g \sin \theta}{1 + K}$$

&

$$f = \frac{km g \sin \theta}{1 + K}$$



...Continued



$$a = \frac{gs \sin \theta}{1 + k} \quad \left\{ \text{lower } k \Rightarrow \text{higher } a \right.$$

$$\begin{array}{cccc} \downarrow & \downarrow & \downarrow & \downarrow \\ \text{Ring} & \text{Disc} & \text{H. Sphere} & \text{S. Sphere} \\ k=1 & k=\frac{1}{2} & k=\frac{2}{3} & k=\frac{2}{5} \end{array}$$

$$\Rightarrow a_{\text{S.S.}} > a_{\text{disc}} > a_{\text{H.S.}} > a_{\text{ring}}$$

\Downarrow
Solid sphere reaches 1st if
all starts together



q. Questions on accⁿ & friction - Rolling on Incline

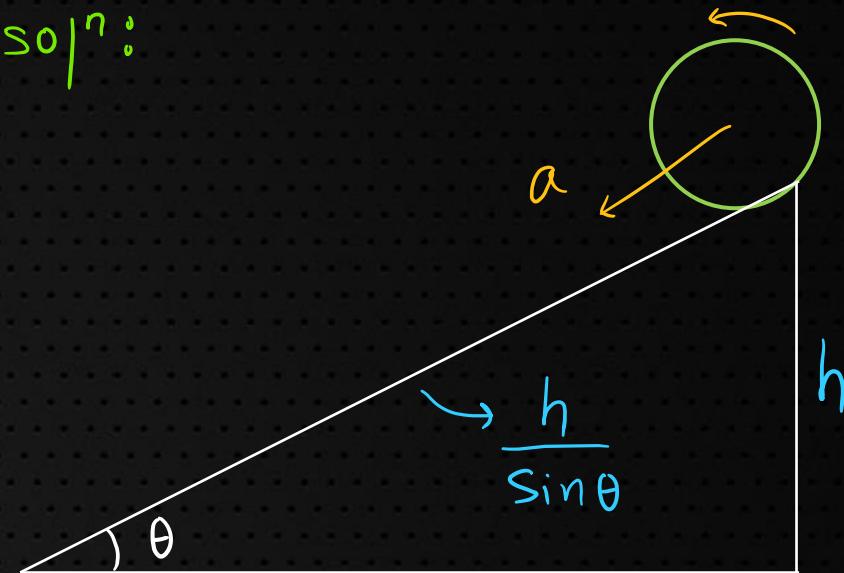
Ex7. A ring and a disc are initially at rest, side by side, at the top of an inclined plane which makes an angle 60° with the horizontal. They start to roll without slipping at the same instant of time along the shortest path. If the time difference between their reaching the ground is $(2 - \sqrt{3})/\sqrt{10}$ s, then the height of the top of the inclined plane, in metres, is (Take, $g = 10\text{ms}^{-2}$) (2018 Adv)



q. Questions on accⁿ & friction - Rolling on Incline

Ex7. A ring and a disc are initially at rest, side by side, at the top of an inclined plane which makes an angle 60° with the horizontal. They start to roll without slipping at the same instant of time along the shortest path. If the time difference between their reaching the ground is $(2 - \sqrt{3})/\sqrt{10}$ s, then the height of the top of the inclined plane, in metres, is (Take, $g = 10\text{ms}^{-2}$) (2018 Adv)

Solⁿ:



$$\frac{h}{\sin \theta} = \frac{1}{2} \times \frac{g \sin \theta}{1+k} \cdot t^2 \Rightarrow t = \sqrt{\frac{2h(1+k)}{g \sin^2 \theta}} \quad K=1, \text{ring}$$

$$\therefore \sqrt{\frac{8h}{15}} - \sqrt{\frac{2h}{5}} = \frac{2}{\sqrt{10}} - \frac{\sqrt{3}}{\sqrt{10}}$$

Solving, $h = 0.75$

$$K=\frac{1}{2}, \text{disc}$$

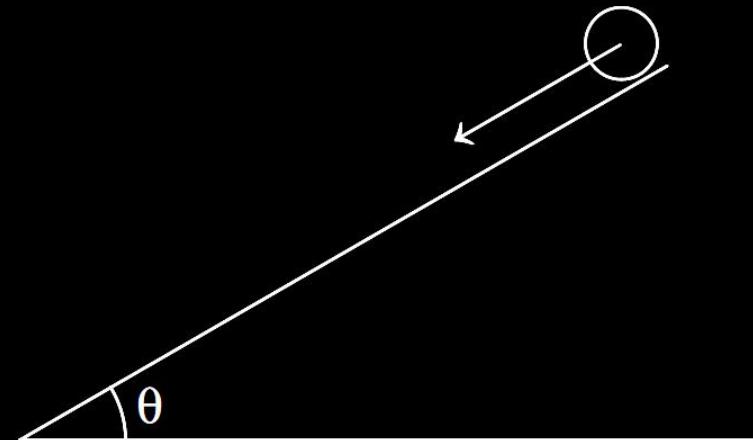
$$t_{\text{disc}} = \sqrt{2h/5}$$

$$t_{\text{ring}} = \sqrt{8h/15}$$

... continued

Ex 8.

A solid sphere is in pure rolling motion on an inclined surface having inclination θ (2006, 5M)



- (a) frictional force acting on sphere is $f = \mu mg \cos \theta$
- (b) f is dissipative force
- (c) friction will increase its angular velocity and opposes its linear velocity
- (d) If θ decreases, friction will decrease



... continued

$$\text{Sol}^n: f_{\text{static}} = \frac{kmg \sin \theta}{1+k}$$

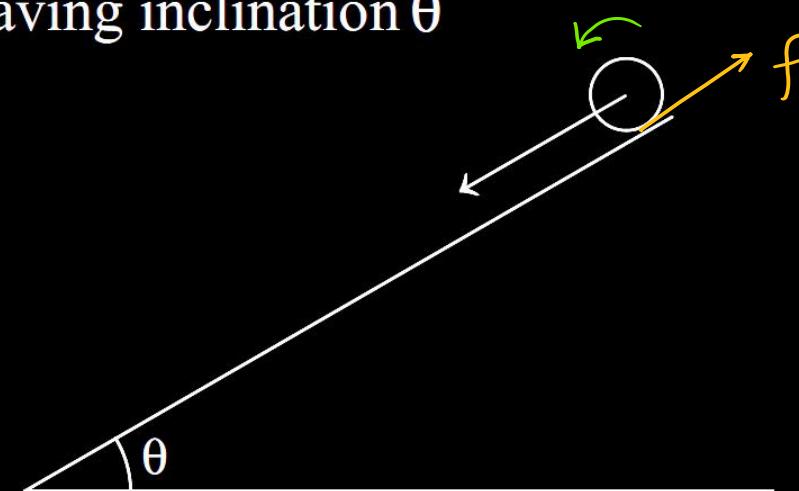
$$= \frac{2}{7} mg \sin \theta$$

$$\hookrightarrow w_f = 0$$

$$\begin{aligned} \hookrightarrow \theta \downarrow &\Rightarrow \sin \theta \downarrow \\ &\Rightarrow f \downarrow \end{aligned}$$

Ex 8.

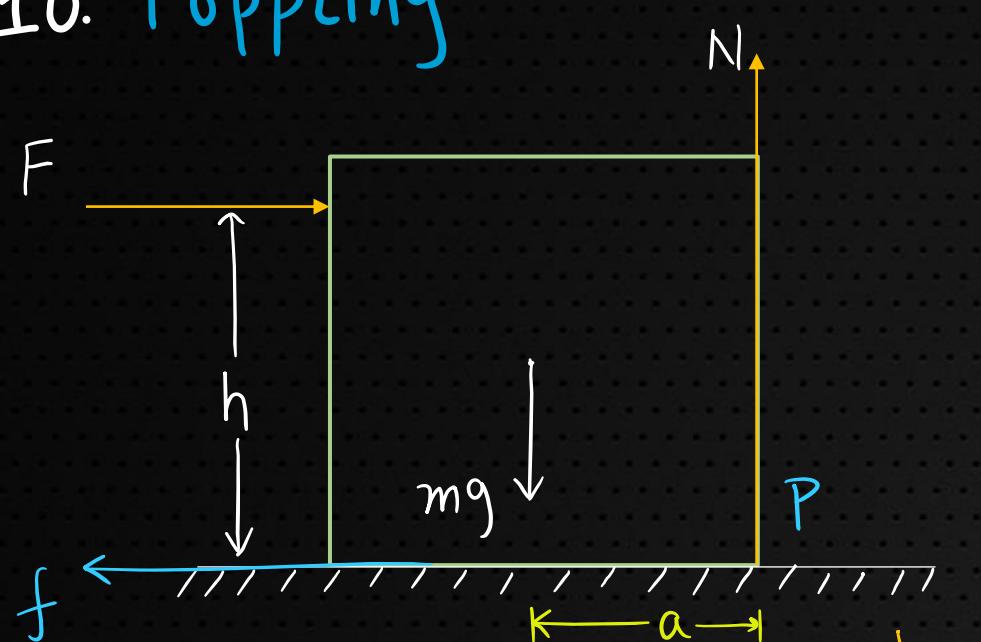
A solid sphere is in pure rolling motion on an inclined surface having inclination θ (2006, 5M)



- (a) frictional force acting on sphere is $f = \mu mg \cos \theta$
- (b) f is dissipative force
- (c) friction will increase its angular velocity and opposes its linear velocity
- (d) If θ decreases, friction will decrease



10. TOPPLING



Condition for TOPPLING to begin

at limiting case N passes pt. P

for toppling about P

$$\tau_F > \tau_{mg}$$

$$\Rightarrow Fh > mg a$$

$$\Rightarrow F > mg \frac{a}{h}$$

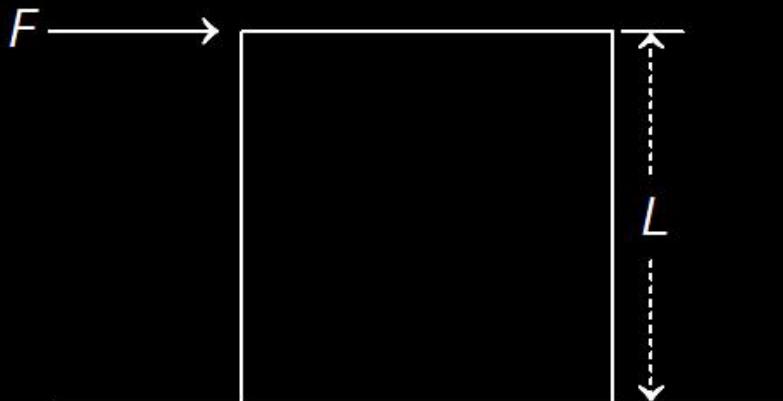
friction
enough to
prevent
sliding

$$\therefore F_{min} = \frac{mg a}{h}$$



...Continued

Ex9. A cubical block of side L rests on a rough horizontal surface with coefficient of friction μ . A horizontal force F is applied on the block as shown. If the coefficient of friction is sufficiently high, so that the block does not slide before toppling, the minimum force required to topple the block is (2000)



- (a) infinitesimal
- (b) $mg/4$
- (c) $mg/2$
- (d) $mg(1 - \mu)$



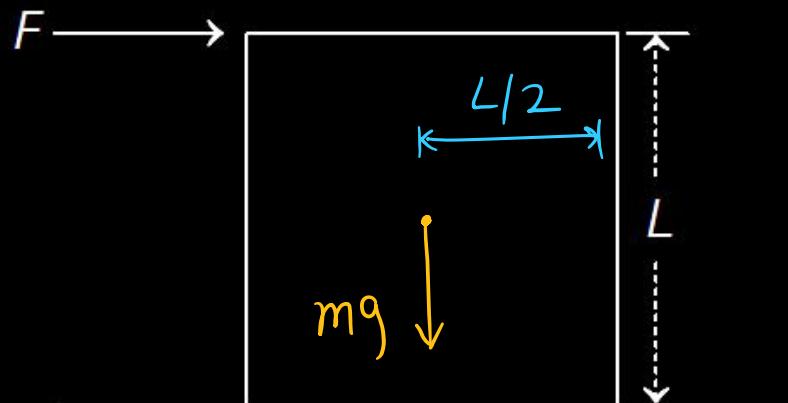
•• Continued

Solⁿ:

$$F_{\min} = \frac{mg \times L/2}{L}$$

$$= \boxed{\frac{mg}{2}}$$

Ex9. A cubical block of side L rests on a rough horizontal surface with coefficient of friction μ . A horizontal force F is applied on the block as shown. If the coefficient of friction is sufficiently high, so that the block does not slide before toppling, the minimum force required to topple the block is (2000)

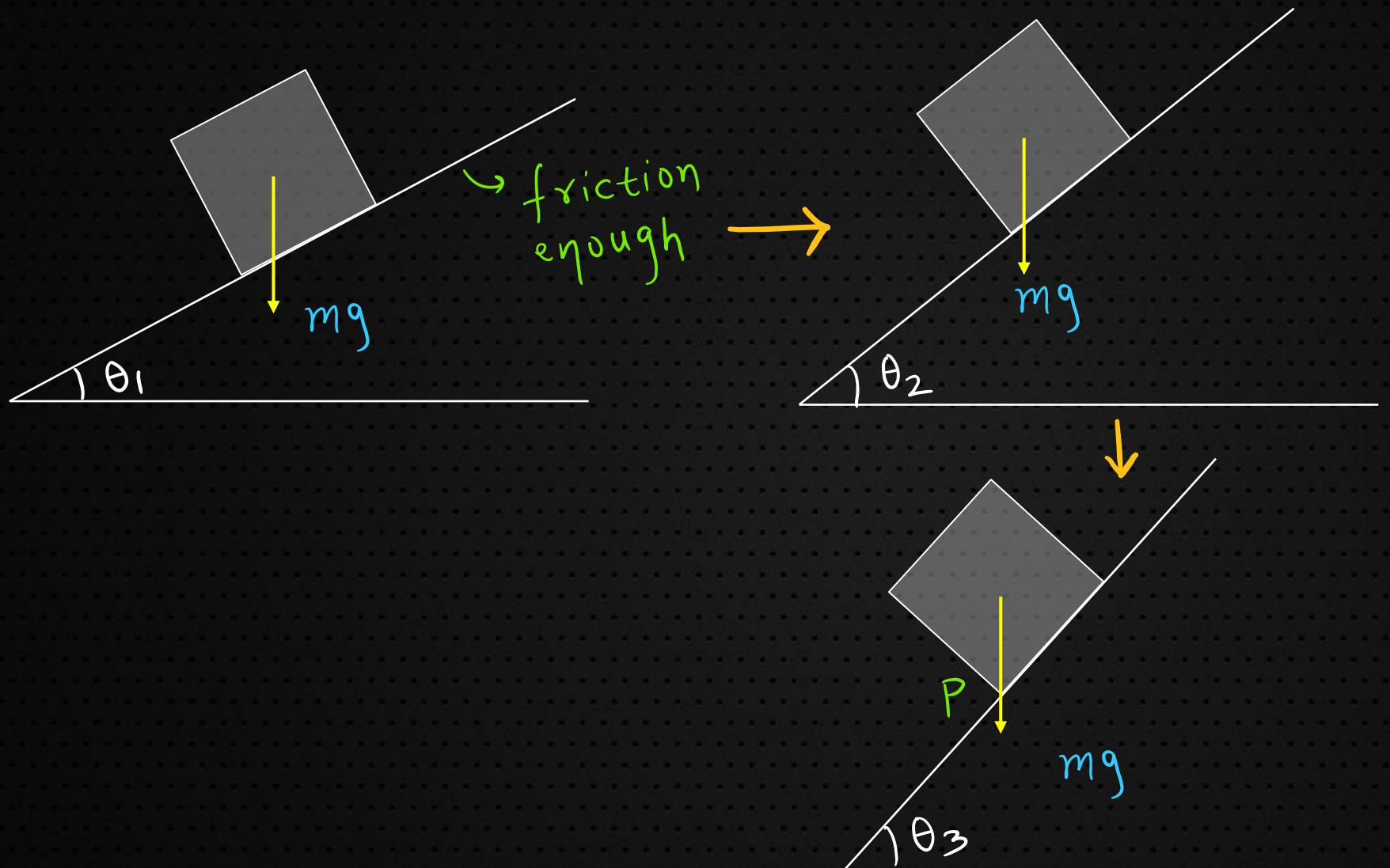


- (a) infinitesimal
- (b) $mg/4$
- (c) $mg/2$
- (d) $mg(1 - \mu)$



...Continued

Increase θ (TOPPLING on incline)



θ_3 is limiting angle.



PYQs LINKS (JEE MAIN)

2021 Feb	2021 March	2021 July	2021 August	2020	Selected Problems
https://youtu.be/2hqJnity2_o	https://youtu.be/6CsOsazSv_mA	https://youtu.be/H_jH3GtD4_Bs	https://youtu.be/wmlghKW_PUQ	https://youtu.be/zWddLCEI_wWE	https://youtu.be/wjBRV_Qih400

CLICK (Practice these Questions)

HCV Rotation Solution Q1-Q70

<https://bit.ly/3fM9fCC>



Revision Series Playlist Link <https://bit.ly/3eBbib9>

JEE Main PYQs Link <https://bit.ly/2S54jzh>

Chapter wise 2021, 2020, 2018

GoldMine Link <https://bit.ly/2VhOGFF>

