

JEE MAIN SIMPLE HARMONIC MOTION **REVISION**

Now that's how you REVISE

List of Content on Eduniti YouTube Channel:

1. PYQs Video Solution Topic Wise:
 - (a) JEE Main 2018/2020/2021 Feb & March
2. Rank Booster Problems for JEE Main
3. Part Test Series for JEE Main
4. JEE Advanced Problem Solving Series
5. Short Concept Videos
6. Tips and Tricks Videos
7. JEE Advanced PYQs
8. Formulae Revision Series

.....and many more to come



EDUNITI



Eduniti for Physics

TOPICS COVERED

1. Kinematics and Energy of SHM
2. Steps to Find Time Period (Linear/Angular SHM)
3. Spring Block and Simple Pendulum
4. T of Spring Block (under constant force)
5. Combination of Spring
6. Spring Cut
7. Two Block System (Reduced Mass)
8. SHM of Block in a Liquid
9. SHM of Piston in Cylinder
10. SHM in Tunnel of Planet
11. SHM of Charge
12. Physical Pendulum
13. Torsional Pendulum
14. SHM of Dipole in Field (Electric/Magnetic Dipole)
15. Time Period of Simple Pendulum (Different Conditions)
16. Superposition of SHM



1. KINEMATICS/ENERGY OF SHM

$$F \propto -x$$

$$\Rightarrow F = -kx$$

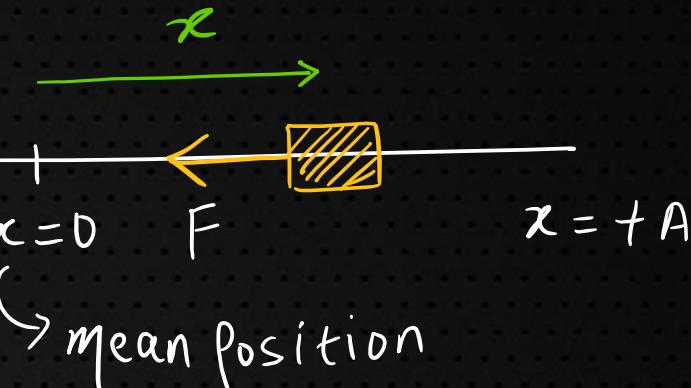
$$a = -\left(\frac{k}{m}\right)x$$

$$\frac{d^2x}{dt^2} + \frac{k}{m}x = 0 \Rightarrow x = A \sin(\omega t + \phi)$$

$$\therefore \omega^2 = \frac{k}{m} \text{ or } T = 2\pi \sqrt{\frac{m}{k}}$$

(a) $V(x) = \omega \sqrt{A^2 - x^2}$

$$V(t) = A\omega \cos \omega t$$



$$V_{\max} = \pm \omega A, x = 0$$

$$V_{\min} = 0, x = \pm A$$

(b) $a(x) = -\omega^2 x$

$$a(t) = -\omega^2 A \sin \omega t$$

$$a_{\max} = \pm \omega^2 A, x = \mp A$$

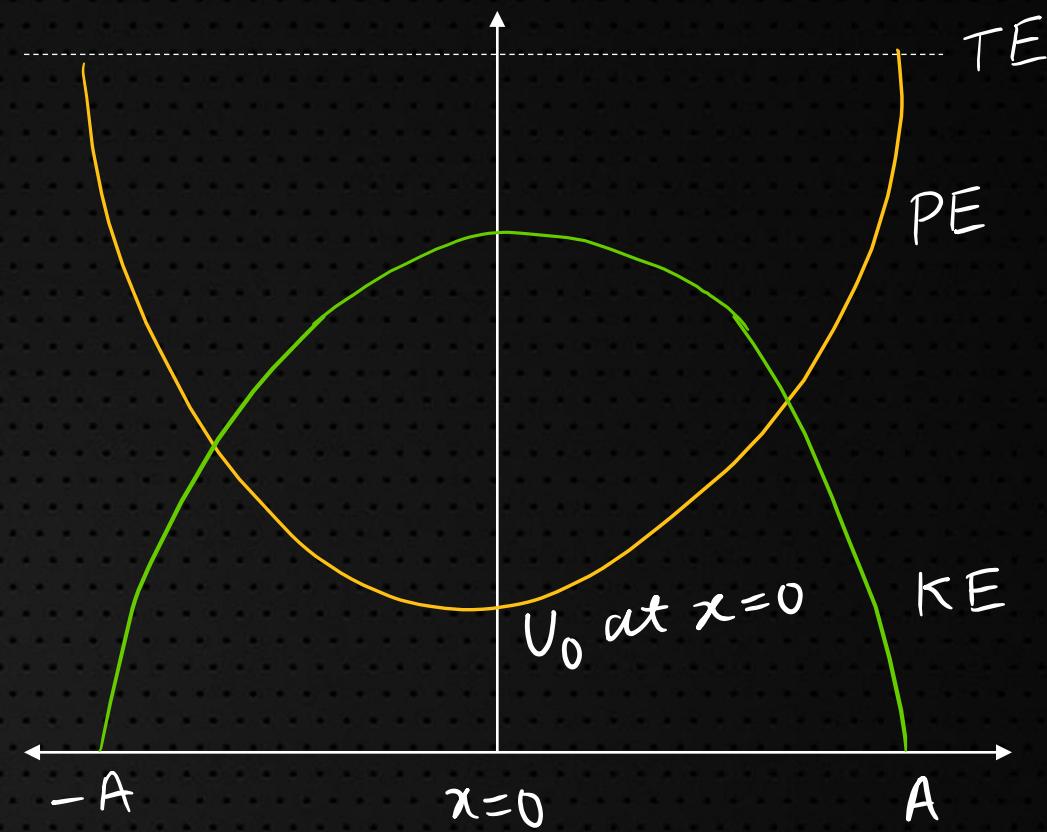
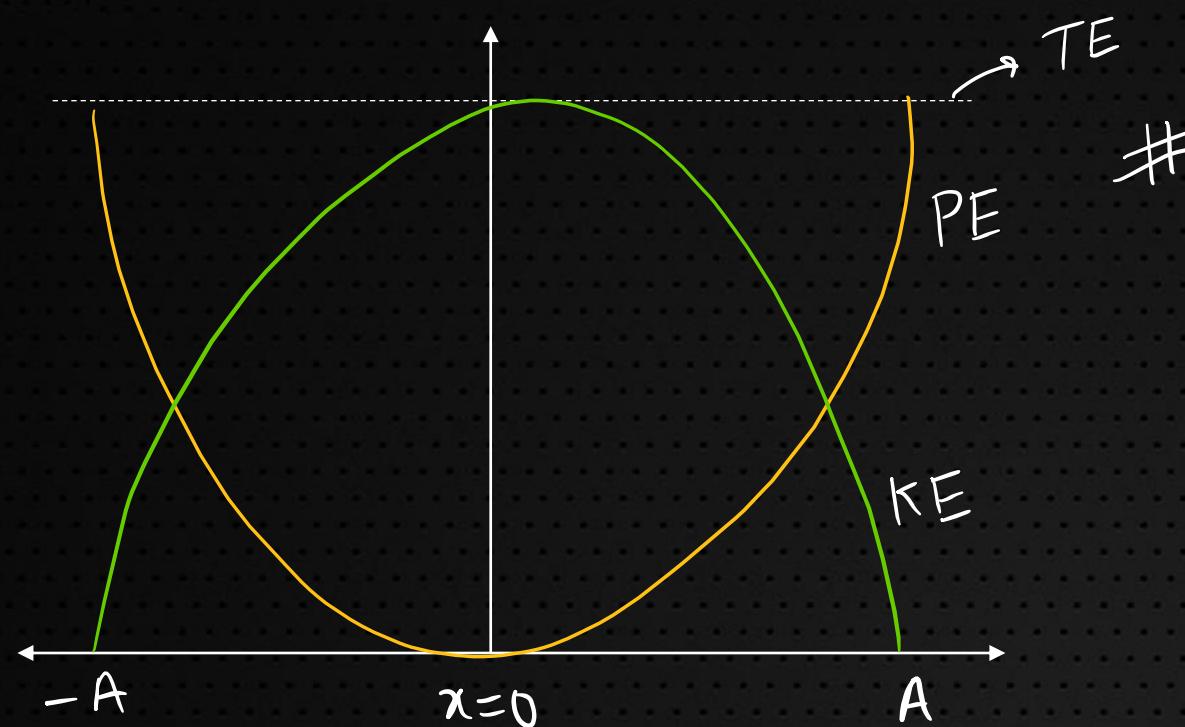
$$a_{\min} = 0, x = 0$$

(c) $K.E(x) = \frac{1}{2} m \omega^2 (A^2 - x^2), P.E(x) = \frac{1}{2} m \omega^2 x^2$

$$T.E = K.E + P.E = \frac{1}{2} m \omega^2 A^2$$

Constant.

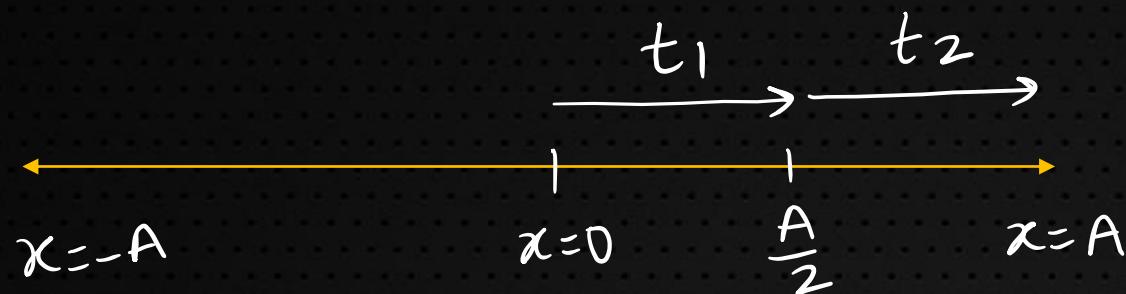
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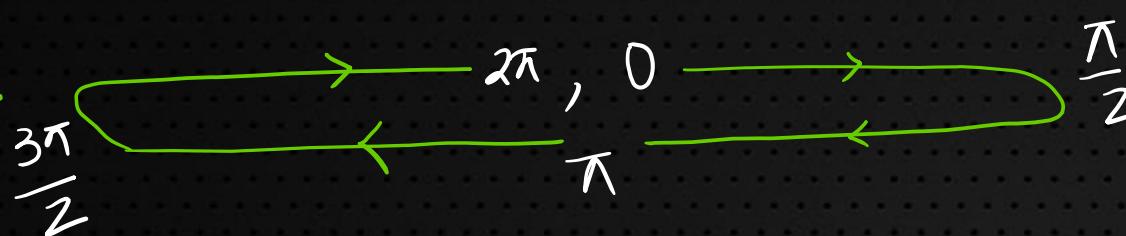
→ At mean position
system has PE.



#



Phase:



$$(i) \quad t_{x=0 \rightarrow x=A} = T/4$$

$$(ii) \quad x = A \sin \omega t$$

$$\Rightarrow \frac{A}{2} = A \sin \omega t_1$$

$$\Rightarrow \frac{1}{2} = \sin \omega t_1 \Rightarrow \frac{\pi}{6} = \frac{2\pi}{T} t_1$$

$$\therefore t_1 = \frac{T}{12}$$

$$(iii) \quad t_2 = \frac{T}{4} - t_1 = \frac{T}{6}$$



2. STEPS TO FIND TIME PERIOD

LINEAR SHM

- (1.) Give linear displacement of x from mean position
- (1.) Give angular displacement of θ (small) from mean position.

- (2.) Find linear acceleration. $F=ma$
- (2.) Find angular acceleration $\tau = I\alpha$

(3.) you will get

$$\alpha = - \underbrace{(\text{some constant})}_{\omega^2} \times x$$

$$\therefore T = 2\pi/\omega$$

ANGULAR SHM

- (1.) Give angular displacement of θ (small) from mean position.

- (2.) Find angular acceleration $\alpha = - (\text{some const.}) \times \theta$

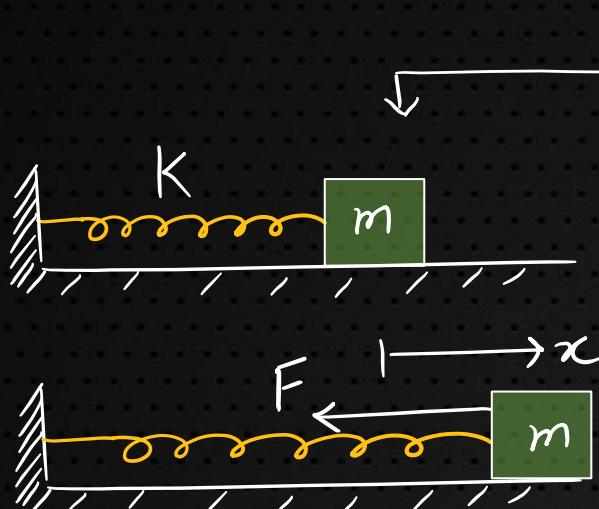
(3.) you will get

$$\alpha = - \underbrace{(\text{some const.})}_{\omega^2} \times \theta$$

$$\therefore T = 2\pi/\omega$$



3. SPRING BLOCK AND SIMPLE PENDULUM



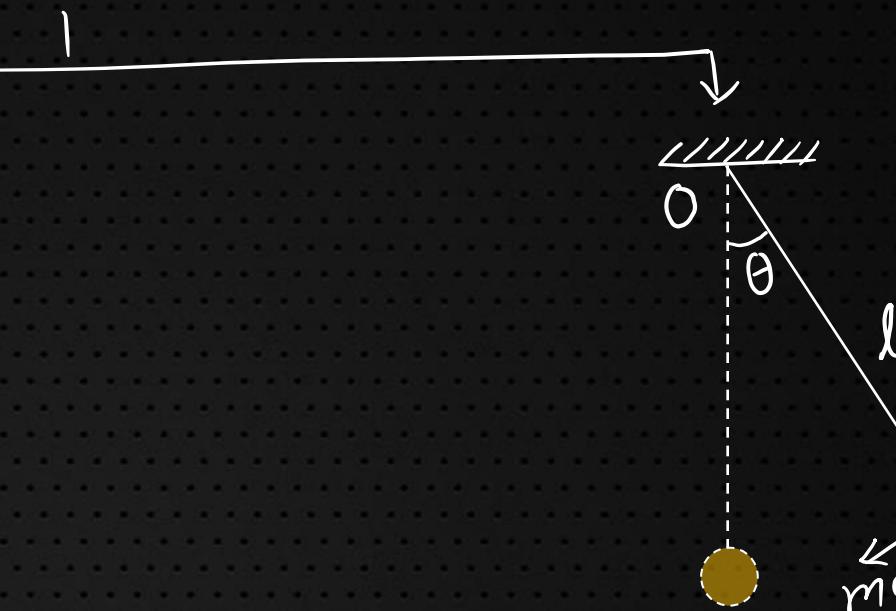
$$F = -Kx$$

$$\Rightarrow ma = -Kx$$

$$\Rightarrow a = -\left(\frac{K}{m}\right)x$$

$\downarrow \omega^2$

$$\therefore T = 2\pi \sqrt{\frac{m}{K}}$$



θ is very small

$mg \sin \theta$

$$\tau = -mg \sin \theta \times l$$

$$\Rightarrow I \alpha = -mg l \times \theta$$

$$\Rightarrow ml^2 \alpha = -mg l \times \theta$$

$$\Rightarrow \alpha = -\left(\frac{g}{l}\right)\theta$$

$\downarrow \omega^2$

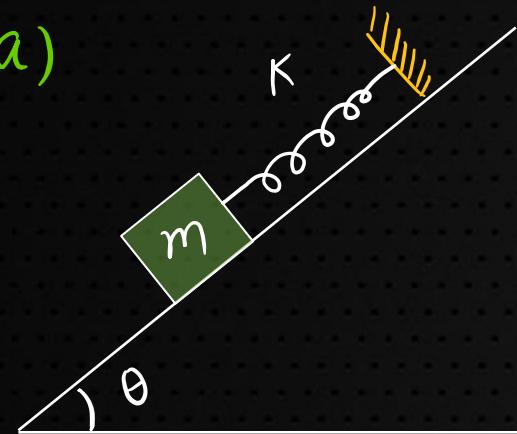
$$\therefore T = 2\pi \sqrt{\frac{l}{g}}$$



4. SPRING BLOCK (under presence of Constant force)

NOTE: Result remains same (only mean position changes)

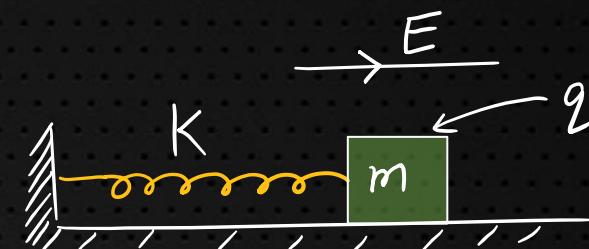
(a)



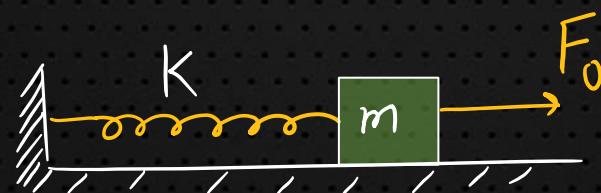
(b)



(c)



(d)



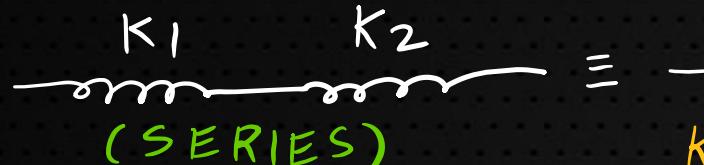
F_0 is external constant force

(i) In all cases

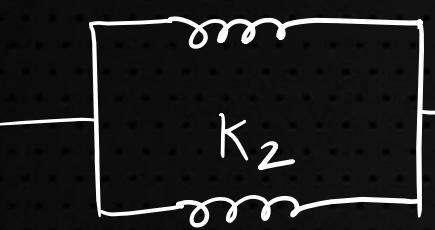
$$T = 2\pi \sqrt{\frac{m}{K}}$$

(ii) Mean position changes.

5. COMBINATION OF SPRING

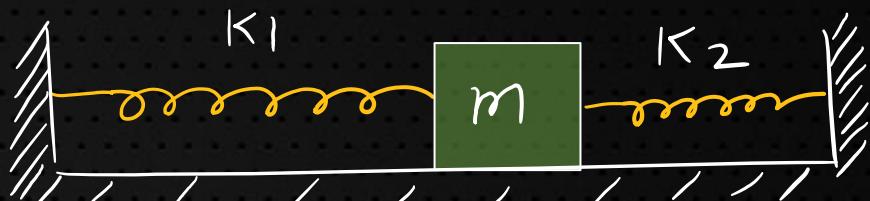
(a)  \equiv 

$$K_{eq} = \frac{K_1 K_2}{K_1 + K_2}$$

(b)  \equiv 

$$K_{eq} = K_1 + K_2$$

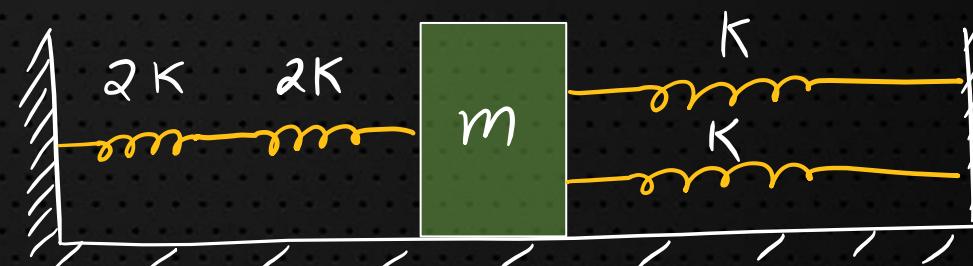
ex: 1



Here still K_1 and K_2 are in parallel.

$$T = 2\pi \sqrt{\frac{m}{K_1 + K_2}}$$

ex: 2



$$K_{eq} = \frac{2K}{2} + 2K = 3K$$

$$T = 2\pi \sqrt{\frac{m}{3K}}$$

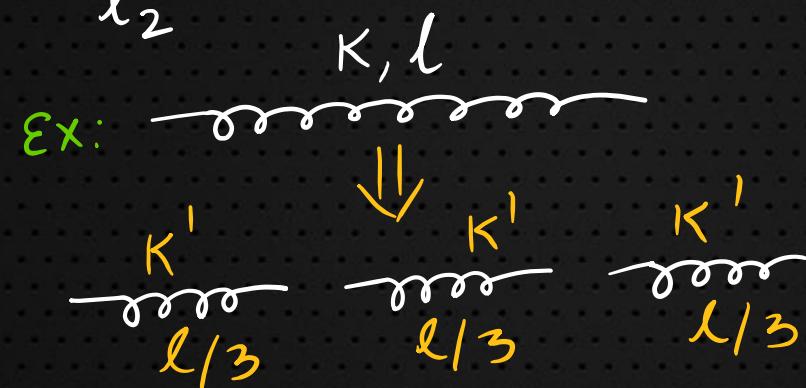


6. SPRING CUT ($K \cdot l = \text{const.}$)

$$\frac{\text{---}}{K, l} = \frac{\text{---}}{K_1, l_1} + \frac{\text{---}}{K_2, l_2}$$

$$Kl = K_1 l_1 = K_2 l_2$$

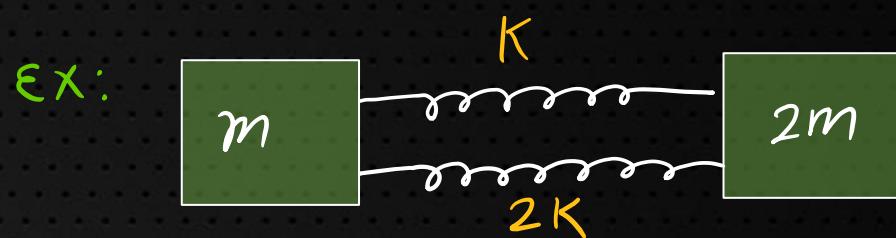
$$\therefore K_1 = \frac{Kl}{l_1}, \quad K_2 = \frac{Kl}{l_2}$$



$$\therefore \text{Each } K' = 3K$$

7. TWO BLOCK SYSTEM

(Reduced mass, $M_{\text{red}} = \frac{m_1 m_2}{m_1 + m_2}$)



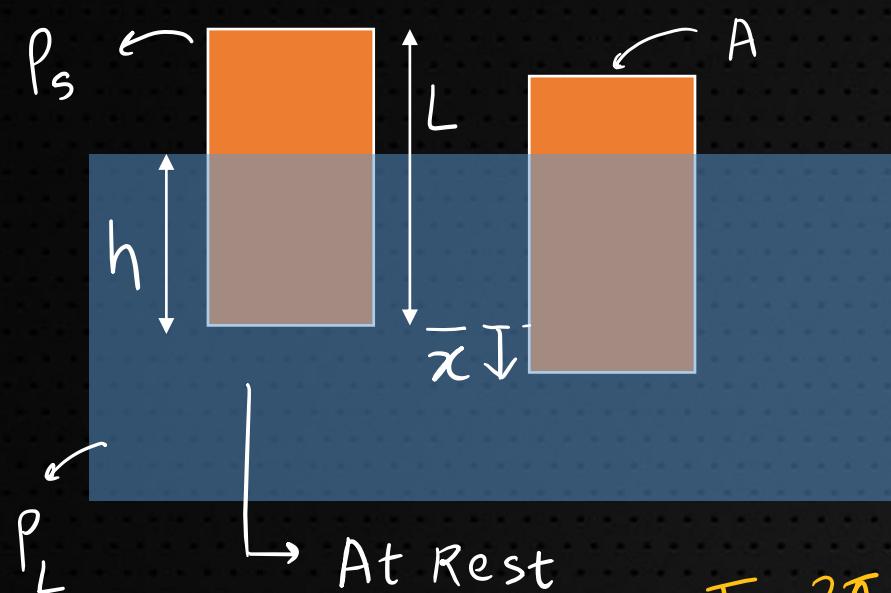
$$T = 2\pi \sqrt{\frac{M_{\text{red}}}{K_{\text{eq}}}}$$

$$\# M_{\text{red}} = \frac{m \times 2m}{m + 2m} = \frac{2m}{3}$$

$$K_{\text{eq}} = K + 2K = 3K$$

$$\therefore T = 2\pi \sqrt{\frac{2m}{9K}}$$



8. BLOCK IN LIQUID ($P_s < P_L$)

At Rest

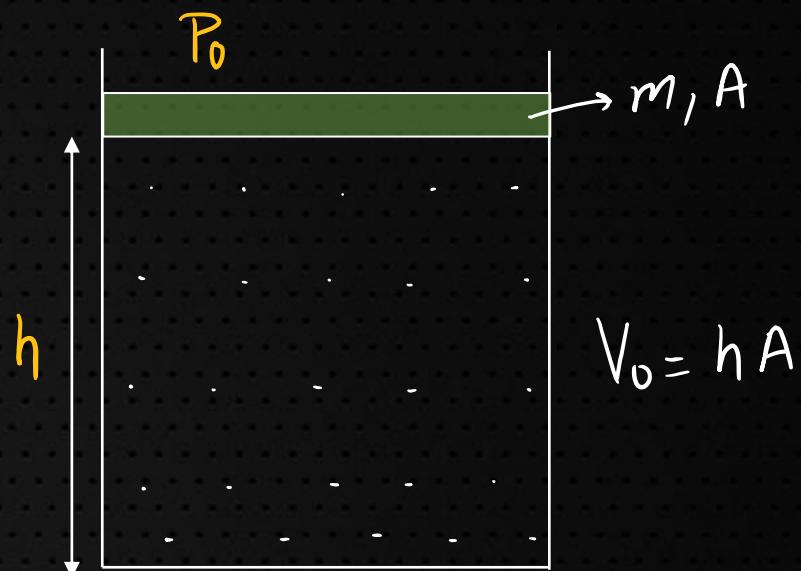
$$T = 2\pi \sqrt{\frac{h}{g}} \quad \text{or} \quad T = 2\pi \sqrt{\frac{m}{A P_L g}}$$

A : cross-section
area

At equilibrium:

$$\frac{P_s}{P_L} = \frac{h}{L}$$

9. SHM OF PISTON IN CYLINDER



Piston given small displacement

\downarrow Isothermal \downarrow Adiabatic

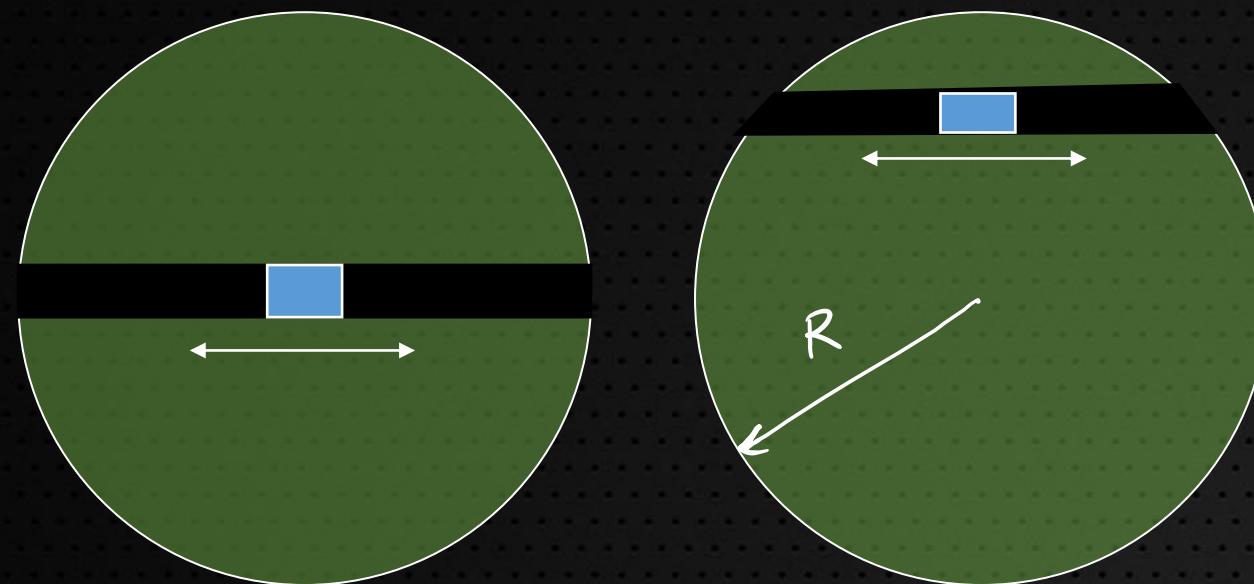
$$T = 2\pi \sqrt{\frac{m V_0}{P_0 A^2}}$$

$$T = 2\pi \sqrt{\frac{m V_0}{\gamma P_0 A^2}}$$

\downarrow C_P / C_V



10. SHM IN TUNNEL IN A PLANET

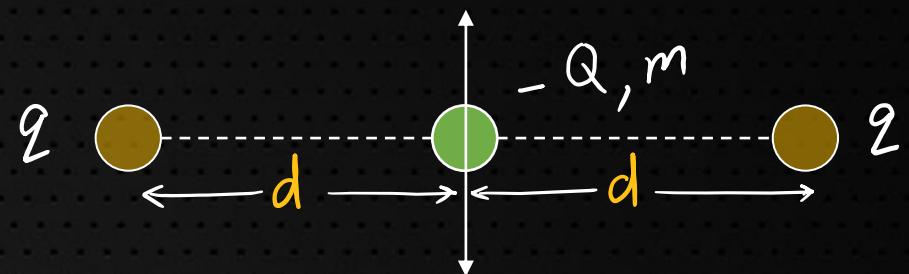


$$T = 2\pi \sqrt{\frac{R}{g}}$$

where $g = \frac{GM}{R^2}$

11. SHM OF CHARGE

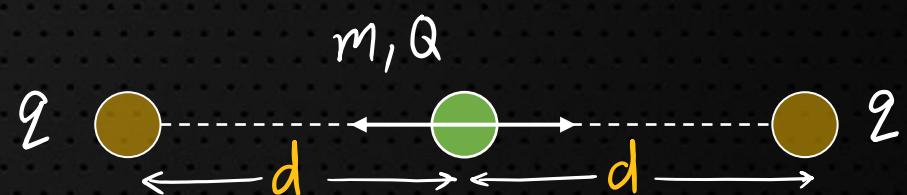
(a)



For small disturbance

$$T = 2\pi \sqrt{\frac{md^3}{2KQ^2}}, \quad K = \frac{1}{4\pi\epsilon_0}$$

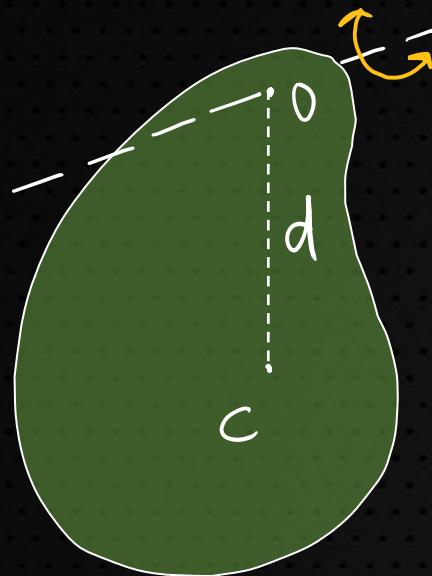
(b)



$$T = 2\pi \sqrt{\frac{md^3}{4KQ^2}}, \quad K = \frac{1}{4\pi\epsilon_0}$$



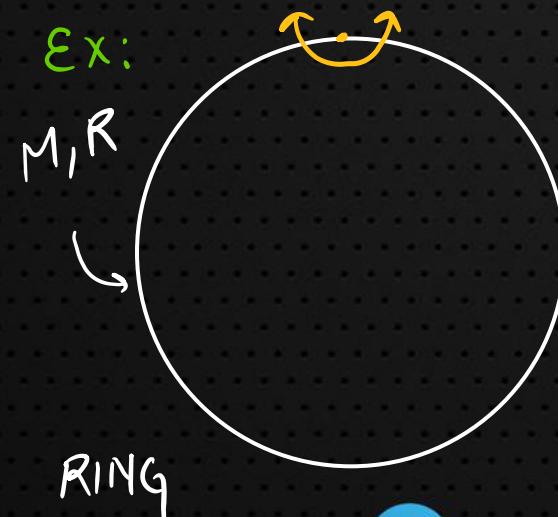
12. PHYSICAL PENDULUM



$$T = 2\pi \sqrt{\frac{I}{mgd}}$$

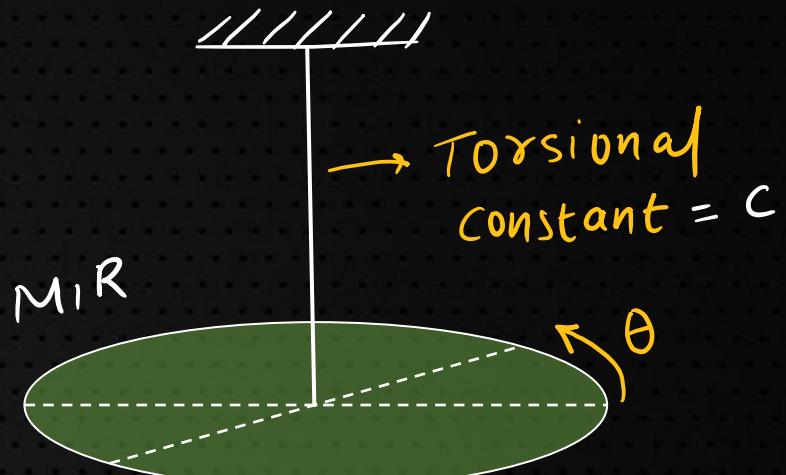
I : MOI of body about
O (Point of suspension)

d : Distance between O
and C (centre of mass)



$$\begin{aligned} I &= MR^2 + MR^2 \\ &= 2MR^2 \\ d &= R \\ \therefore T &= 2\pi \sqrt{\frac{2MR^2}{MgR}} \\ \Rightarrow T &= 2\pi \sqrt{2R/g} \end{aligned}$$

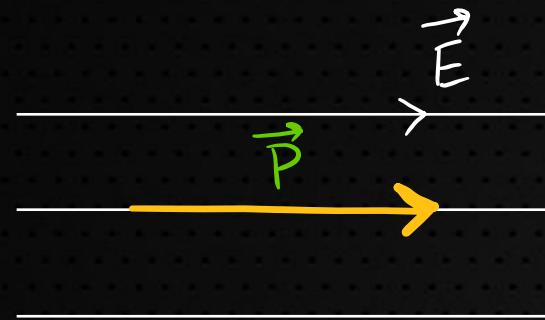
13. TORSIONAL PENDULUM



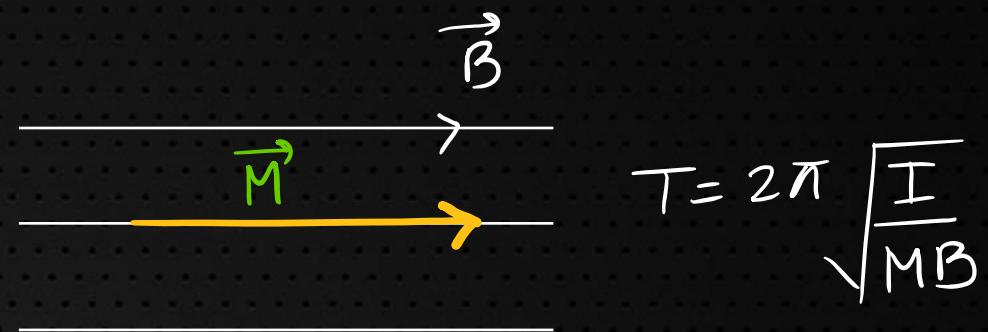
$$\begin{aligned} \tau &= -C\theta \\ \Rightarrow I\alpha &= -C\theta \\ \therefore \alpha &= -\left(\frac{C}{I}\right)\theta \\ \downarrow \omega^2 & \\ \therefore T &= 2\pi \sqrt{\frac{I}{C}} \end{aligned}$$



14. SHM OF DIPOLE IN FIELD (small angular displacement)



$$T = 2\pi \sqrt{\frac{I}{PE}}$$



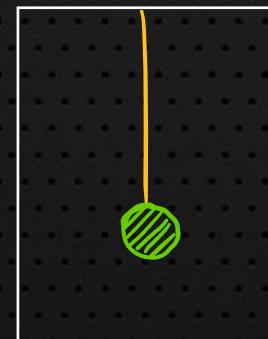
$$T = 2\pi \sqrt{\frac{I}{MB}}$$

I : Moment of Inertia

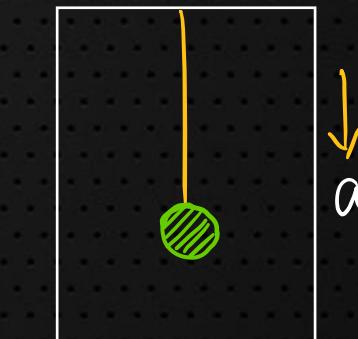
I : Moment of Inertia

15. T OF SIMPLE PENDULUM (Different Condition)

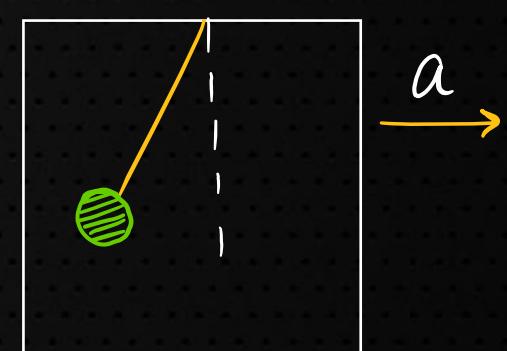
$$T = 2\pi \sqrt{\frac{L}{g_{eff}}}$$



$$g_{eff} = a + g$$



$$g_{eff} = g - a$$



$$g_{eff} = \sqrt{a^2 + g^2}$$



16. SUPERPOSITION OF SHM

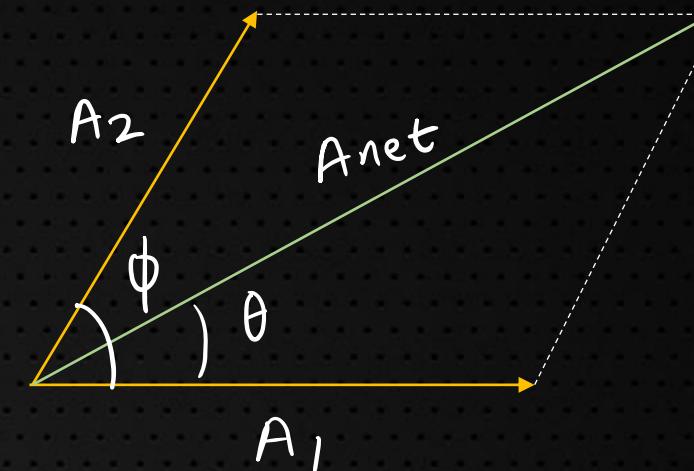
$$Y = A_1 \sin \omega t + A_2 \sin(\omega t + \phi)$$

$$= A_{\text{net}} \sin(\omega t + \theta)$$

↓

$$\sqrt{A_1^2 + A_2^2 + 2A_1 A_2 \cos \phi}$$

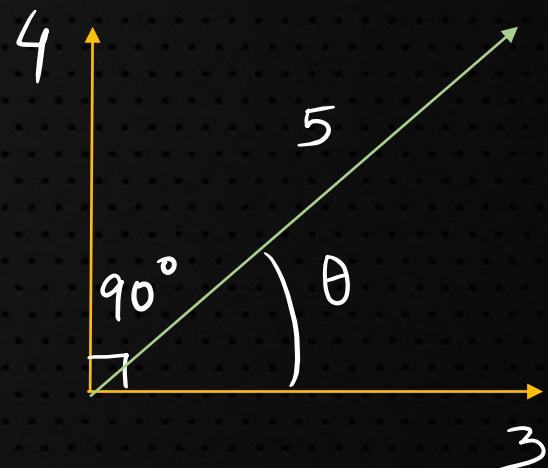
$$\tan^{-1} \left(\frac{A_2 \sin \phi}{A_1 + A_2 \cos \phi} \right)$$



Ex: $Y = 3 \sin(\omega t + 30^\circ) + 4 \sin(\omega t + 120^\circ)$

$$\Rightarrow Y = 5 \sin(\omega t + 30^\circ + \theta)$$

where $\theta = \tan^{-1} \frac{4}{3}$



LINK IN DESCRIPTION
in 55 sec

#8 - SHM

$$A(t) = A_0 e^{-bt/2m}$$

Amplitude Variation in Damped Oscillation

